

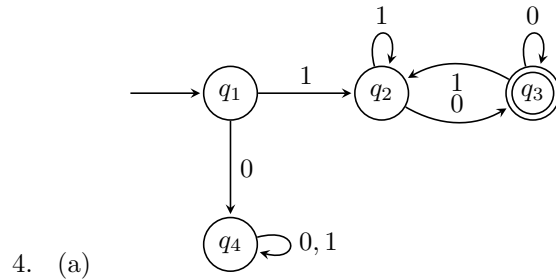
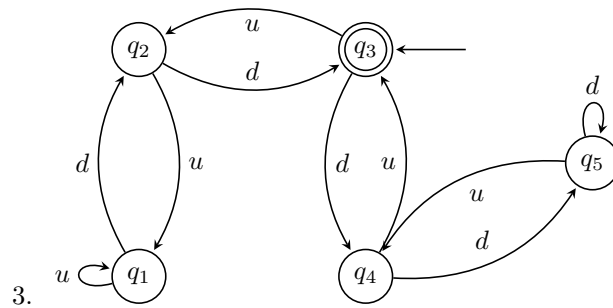
Introduction to the Theory of Computation

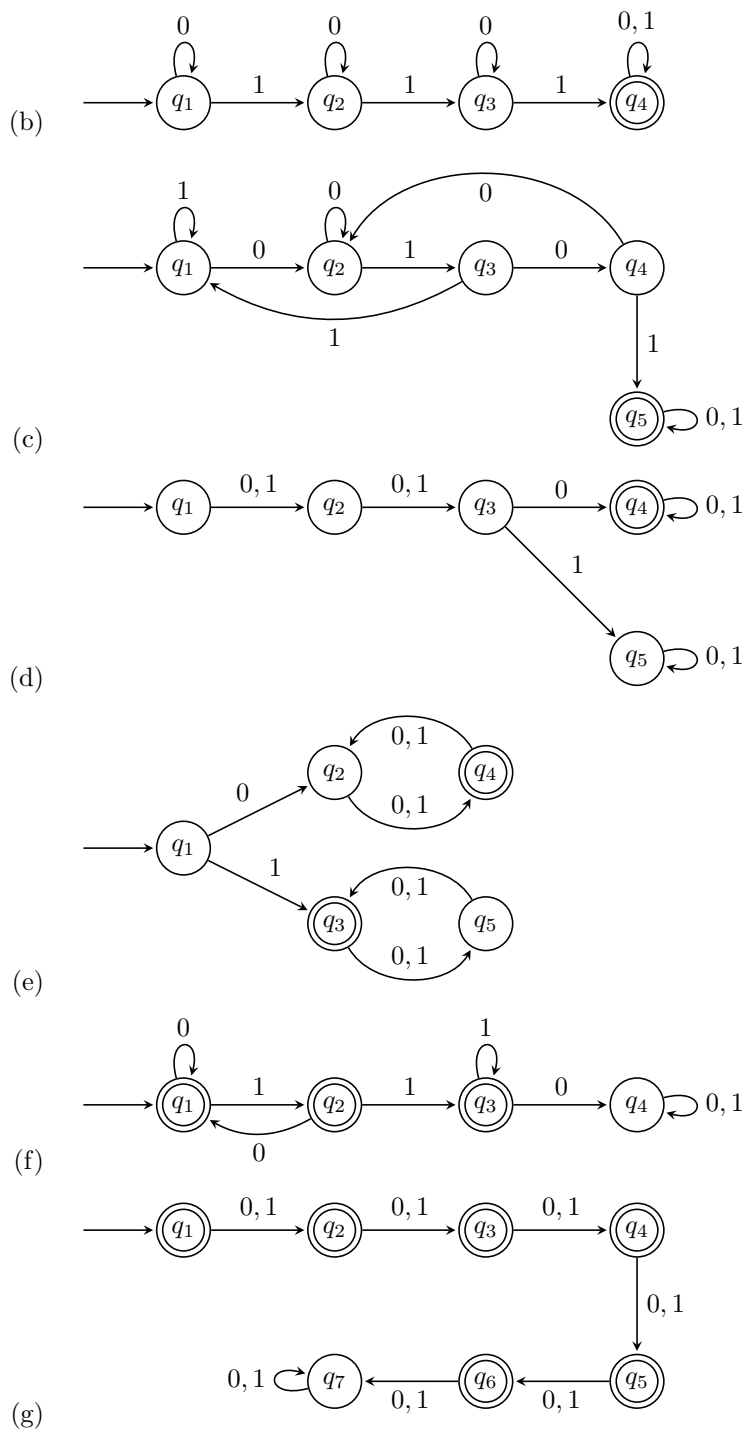
Chapter 1 Exercises

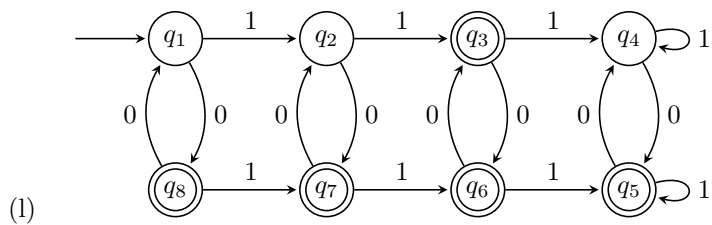
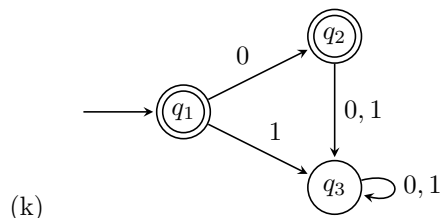
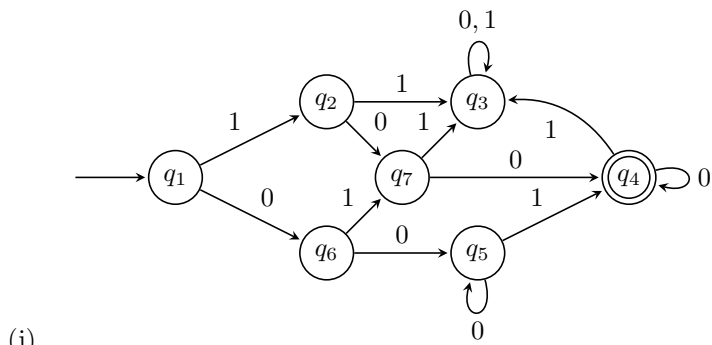
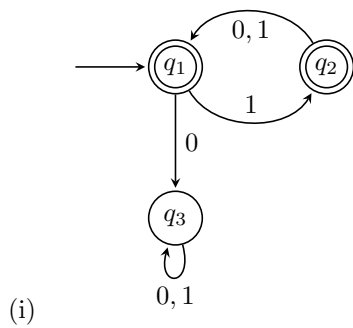
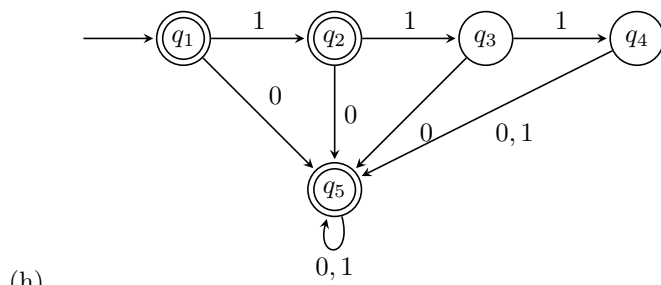
Balachandar Kesavan

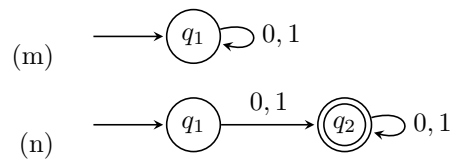
June 5, 2016

1. (a) q_1
 (b) $\{q_2\}$
 (c) q_1
 (d) $\{q_1, q_4\}$
 (e) q_1, q_2, q_3, q_1, q_1
 (f) No
 (g) Yes
2. $M_1 = (\{q_1, q_2, q_3\}, \{a, b\}, \delta, q_1, \{q_2\})$
 where $\delta(q_1, a) = q_2, \delta(q_1, b) = q_1, \delta(q_2, a) = q_3, \delta(q_2, b) = q_1, \delta(q_3, a) = q_2, \delta(q_3, b) = q_1$
 $M_2 = (\{q_1, q_2, q_3, q_4\}, \{a, b\}, \delta, q_1, \{q_1, q_4\})$
 where $\delta(q_1, a) = q_1, \delta(q_1, b) = q_2, \delta(q_2, a) = q_3, \delta(q_2, b) = q_4, \delta(q_3, a) = q_2, \delta(q_3, b) = q_1, \delta(q_4, a) = q_3, \delta(q_4, b) = q_4$









5. (a) **TODO**