

## EECS2011A: Fundamentals of Data Structures

### Assignment 4

**Due: 10 pm, Tuesday, December 5, 2017**

- **Print your name, eecs account and student ID# on top of every file you submit.**
- **You may give your algorithms in either java code or precise pseudo-code.**
- **Make sure you also submit a4sol.pdf.**

#### **Problem 1: [35%] ( [GTG] Exercise C-11.35, page 527)**

Consider a sorted map that is implemented by means of a standard Binary Search Tree  $T$ . Give an algorithm (in pseudo-code) to perform the operation  $removeSubMap(k_1, k_2)$  that removes all entries whose keys fall within  $SubMap(k_1, k_2)$ , in worst-case time  $O(s + h)$ , where  $s$  is the number of entries removed and  $h$  is the height of  $T$ . Analyze and prove the claimed time complexity.

[See also Exercise C-11.34. Note that keys  $k_1$  and  $k_2$  may or may not be in  $T$ . Note also that the required time bound is  $O(s + h)$ , not  $O(s * h)$ . You may give a less efficient algorithm for partial credit. ]

#### **Problem 2: [25%] ( [GTG] Exercise C-12.49, page 570 )**

Bob has a set  $A$  of  $n$  nuts and a set  $B$  of  $n$  bolts, such that each nut in  $A$  has a unique matching bolt in  $B$ . Unfortunately, the nuts in  $A$  all look alike, and the bolts in  $B$  all look alike as well. The only kind of a comparison that Bob can make is to take a nut-bolt pair  $(a, b)$ , such that  $a$  is in  $A$  and  $b$  is in  $B$ , and test to see if the threads of  $a$  are larger, smaller, or a perfect match with the threads of  $b$ . Describe and analyze an efficient algorithm in pseudo-code for Bob to match up all of his nuts and bolts.

[Here efficiency is measured in terms of the number of nut-bolt comparisons. Note that we cannot have any nut-nut or bolt-bolt type comparisons. We can obviously compare every nut against every bolt, but that would require  $\Omega(n^2)$  comparisons. Can we do better? Hint: think about QuickSort.]

**Problem 3: [40%] (Center of a Graph)**

Consider a given connected undirected graph  $G$ . (Here for simplicity we assume each edge has unit length.) The *eccentricity* of a vertex  $v$  in  $G$  is the length of the shortest path from  $v$  to the vertex farthest from  $v$ . The *diameter* of  $G$  is the maximum eccentricity of any vertex in  $G$ . The *radius* of  $G$  is the smallest eccentricity of any vertex in  $G$ . A *center* is a vertex whose eccentricity is the radius.

- a) Prove that for every graph  $G$  :  $radius \leq diameter \leq 2 radius$ .
- b) Design and analyze efficient algorithms (in pseudo-code) that implement the following graph instance methods for any instance graph  $G$ :

*eccentricity*( $v$ ): returns eccentricity of vertex  $v$  in  $G$ . [Hint: Use BFS.]

*diameter*( ): returns diameter of  $G$ .

*radius*( ): returns radius of  $G$ .

*center*( ): returns a center vertex of  $G$ . (Break ties arbitrarily.)

**Problem 4: [20% Extra Credit and Optional] ([GTG] Exercise C-14.67, page 683)**

Consider a diagram of a telephone network, which is an undirected graph  $G$  whose vertices represent switching centers, and whose edges represent communication lines joining pairs of centers. Edges are marked by their bandwidth (which are arbitrary positive numbers), and the bandwidth of a path is equal to the lowest bandwidth among the path's edges. Design and analyze an efficient algorithm (in pseudo-code) that, given such a network and two switching centers  $a$  and  $b$ , outputs the bandwidth of a maximum bandwidth path between  $a$  and  $b$ .

[Hint: Use a suitable adaptation of Dijkstra's algorithm.]

