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In [3]:
        Created on Thu Mar 29 15:26:43 2018
        @author: Raj Mehta
        from itertools import count
        import torchvision
        import torch
        import torch.autograd
        import torch.nn.functional as F
        import torch.optim as optim
        from torch.autograd import Variable
        import torch.utils.data as D
        import numpy as np
        import matplotlib.pyplot as plt
        from torchvision import datasets, transforms
        class data loaderD(D.Dataset):
            def __init__(self, data, label):
                self.data = data
                self.label = label
            def __getitem__(self, index):
                return self.data[index], self.label[index]
            def len (self):
                return len(self.data)
        def get zeros ones():
            train data =datasets.MNIST('./Data/mnist', train = True, download=True,
                                        transform = transforms.Compose([transforms.To
                                                                         transforms.No
            train loader = D.DataLoader(train data, batch size = 10000, shuffle = Ti
            X 0 = []
            X 1 = []
            X_2 = []
            y_0 = []
            y_1 = []
            y_2 = []
            for (X,y) in train loader:
                 for i in range(len(y)):
                     if y[i]==0:
                         X 0.append(X[i,:,:,:].numpy())
                         y \ 0.append(y[i])
                     elif y[i]==1:
                         X 1.append(X[i,:,:,:].numpy())
                         y_1.append(y[i])
                    elif y[i]==2:
                         X_2.append(X[i,:,:,:].numpy())
                         y_2.append(y[i])
```

```
X_0 = torch.FloatTensor(np.asarray(X_0)[:2000])
   X_1 = torch.FloatTensor(np.asarray(X_1)[:2000])
   X 2 = torch.FloatTensor(np.asarray(X 2)[:2000])
   y_0 = torch.FloatTensor(np.asarray(y_0)[:2000])
   y_1 = torch.FloatTensor(np.asarray(y_1)[:2000])
   y_2 = torch.FloatTensor(np.asarray(y_2)[:2000])
   X_{train} = torch.cat((X_0, X_1, X_2), 0)
   y_train = torch.cat((y_0,y_1,y_2),0)
   print(X train.shape)
   print(y train.shape)
   train = data_loaderD(X_train, y_train)
   return train
#Getting Generator Input
#_____
#-----
class Discriminator(torch.nn.Module):
   def __init__(self):
       super(Discriminator, self).__init__()
       self.conv1 = torch.nn.Conv2d(1, 32, 5, 1, 0, bias = False) #24
       self.conv2 = torch.nn.Conv2d(32, 64, 4, 2, 1, bias = False) #12
       self.conv3 = torch.nn.Conv2d(64, 128, 5, 1, 0, bias = False) #8
       self.conv4 = torch.nn.Conv2d(128, 256, 4, 2, 1, bias = False) #4
       self.conv5 = torch.nn.Conv2d(256, 1, 4, 1, 0, bias = False) #1
       self.batchnorm1 = torch.nn.BatchNorm2d(32)
       self.batchnorm2 = torch.nn.BatchNorm2d(64)
       self.batchnorm3 = torch.nn.BatchNorm2d(128)
       self.batchnorm4 = torch.nn.BatchNorm2d(256)
   def forward(self,x):
       x = F.elu(self.batchnorm1(self.conv1(x)), 0.2) #12
       x = F.elu(self.batchnorm2(self.conv2(x)), 0.2) #8
       x = F.elu(self.batchnorm3(self.conv3(x)), 0.2) #3
       x = F.elu(self.batchnorm4(self.conv4(x)), 0.2) #1
       x = F.elu(self.conv5(x))#1
       return F.sigmoid(x)
#-----
class Generator(torch.nn.Module):
   def init (self):
       super(Generator, self).__init__()
       self.deconv1 = torch.nn.ConvTranspose2d(100,256,4,1,0, bias = False
       self.deconv2 = torch.nn.ConvTranspose2d(256,512,4,2,1, bias = Fals€
       self.deconv3 = torch.nn.ConvTranspose2d(512,1024,5,1,0, bias = Fals
       self.deconv4 = torch.nn.ConvTranspose2d(1024,2048,4,2,1, bias = Fal
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self.deconv5 = torch.nn.ConvTranspose2d(2048,1,5,1,0, bias = False)
       self.batchnorm1 = torch.nn.BatchNorm2d(256)
       self.batchnorm2 = torch.nn.BatchNorm2d(512)
       self.batchnorm3 = torch.nn.BatchNorm2d(1024)
       self.batchnorm4 = torch.nn.BatchNorm2d(2048)
   def forward(self,x):
       x = F.elu(self.batchnorm1(self.deconv1(x))) #12
       x = F.elu(self.batchnorm2(self.deconv2(x))) #8
       x = F.elu(self.batchnorm3(self.deconv3(x))) #3
       x = F.elu(self.batchnorm4(self.deconv4(x))) #1
       x = self.deconv5(x)#1
       return F.tanh(x)
class Classifier(torch.nn.Module):
   def __init__(self):
       super(Classifier, self).__init__()
       self.conv1 = torch.nn.Conv2d(1, 32, 5, 1, 0, bias = False) #24
       self.conv2 = torch.nn.Conv2d(32, 64, 4, 2, 1, bias = False) #12
       self.conv3 = torch.nn.Conv2d(64, 128, 5, 1, 0, bias = False) #8
       self.conv4 = torch.nn.Conv2d(128, 256, 4, 2, 1, bias = False) #4
       self.conv5 = torch.nn.Conv2d(256, 10, 4, 1, 0, bias = False) #1
       self.batchnorm1 = torch.nn.BatchNorm2d(32)
       self.batchnorm2 = torch.nn.BatchNorm2d(64)
       self.batchnorm3 = torch.nn.BatchNorm2d(128)
       self.batchnorm4 = torch.nn.BatchNorm2d(256)
       self.Linear1 = torch.nn.Linear(10,100)
       self.Linear2 = torch.nn.Linear(100,3)
   def forward(self,x):
       x = F.elu(self.batchnorm1(self.conv1(x)), 0.2) #12
       x = F.elu(self.batchnorm2(self.conv2(x)), 0.2) #8
       x = F.elu(self.batchnorm3(self.conv3(x)), 0.2) #3
       x = F.elu(self.batchnorm4(self.conv4(x)), 0.2) #1
       x = F.elu(self.conv5(x))#1
       x = x.view(-1,10)
       x = self.Linear1(x)
       x = self.Linear2(x)
       return F.softmax(x)
#-----
gen1 = Generator()
gen2 = Generator()
gen3 = Generator()
dis = Discriminator()
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cla = Classifier()
if torch.cuda.is available():
   gen1 = gen1.cuda()
   gen2 = gen2.cuda()
   gen3 = gen3.cuda()
   dis = dis.cuda()
   cla = cla.cuda()
optimizerD = optim.SGD(dis.parameters(), lr = 0.005, momentum=0.1)
optimizerG1 = optim.SGD(gen1.parameters(), lr = 0.005, momentum=0.1)
optimizerG2 = optim.SGD(gen2.parameters(), lr = 0.005, momentum=0.1)
optimizerG3 = optim.SGD(gen3.parameters(), lr = 0.005, momentum=0.1)
optimizerC = optim.SGD(cla.parameters(), lr = 0.005, momentum = 0.1)
#-----
def get_generator_data():
   noise1 = torch.FloatTensor(10, 100, 1, 1)
   noise1 = noise1.cuda()
   noise2 = torch.FloatTensor(12,100,1,1)
   noise2 = noise2.cuda()
   noise1.copy_(torch.FloatTensor(10, 100, 1, 1).normal (0,1))
   noise2.copy (torch.FloatTensor(12, 100, 1, 1).normal (0,1))
   noiselv = Variable(noisel)
   noise2v = Variable(noise2)
   fake1 = gen1(noise1v)
   fake2 = gen2(noise1v)
   fake3 = gen3(noise2v)
   ygen1 = torch.zeros(10)
   ygen2 = torch.ones(10)
   ygen3 = torch.ones(12)*2
   a = 10
   b = 12
   genlabel1 = torch.cat((ygen1,ygen2,ygen3),0)
   gendata1 = torch.cat((fake1,fake2,fake3),0)
   Gdata = data loaderD(gendata.data, genlabel)
   genloader = D.DataLoader(Gdata, batch size = 32, shuffle = True)
   G k, labelg = next(iter(genloader))
   return gendata1, genlabel1.cuda()
#-----Train Classifier---------
def train classifier(epoch):
   batch size = 32
   number = torch.FloatTensor(batch size, 1, 28, 28)
   label = torch.LongTensor(batch size)
   criterion = torch.nn.CrossEntropyLoss()
   if torch.cuda.is_available():
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number = number.cuda()
        label = label.cuda()
        criterion = criterion.cuda()
   train D = get zeros ones()
   loader = D.DataLoader(train D, batch_size = batch_size,drop_last = True,
   for i in range(epoch):
        for batch_idx,(X,Y) in enumerate(loader):
            cla.zero_grad()
            number.copy (X)
            label.copy_(Y)
            numberv = Variable(number)
            label v = Variable(label)
            output = cla(numberv)
            Loss = criterion(output, label_v)
            Loss.backward()
            print(Loss.data)
            optimizerC.step()
   print('=========Classifier Trained========')
def train(epoch):
   batch size = 32
   train_data = get_zeros_ones()
   noise = torch.FloatTensor(batch size, 100, 1, 1)
   fixed noise = torch.FloatTensor(batch size, 100, 1, 1).normal (0,1)
   label fake = torch.FloatTensor(batch size)
   label_one = torch.ones(batch_size)
   label two = torch.ones(batch size)*2
   label three = torch.ones(batch size)*3
   label zero = torch.zeros(batch size)
   label one = label one.float()
   label two = label two.float()
   label_zero = label_zero.float()
   label zeroL = label zero.long()
   label oneL = label one.long()
   label twoL = label two.long()
   label real = torch.FloatTensor(32)
   label = torch.FloatTensor(batch size)
   image = torch.FloatTensor(batch size, 1, 28, 28)
   criterion1 = torch.nn.CrossEntropyLoss()
   criterion2 = torch.nn.BCELoss()
   if torch.cuda.is available():
        image = image.cuda()
        label_zero, label_one, label_two = label_zero.cuda(), label_one.cuda
        label zeroL, label oneL, label twoL = label zeroL.cuda(), label oneI
       noise, fixed noise = noise.cuda(), fixed noise.cuda()
        label real, label fake = label real.cuda(), label fake.cuda()
       criterion1 = criterion1.cuda()
        criterion2 = criterion2.cuda()
```

```
train_loader = D.DataLoader(train_data, batch_size = 32, drop_last = Tru
for i in range(1, epoch+1):
    for batch_idx,(X, y) in enumerate(train loader):
        #-----Train discriminator with real data-----
        dis.zero_grad()
        label_real.copy_(y.float())
        image.copy_(X)
        imagev = Variable(image)
        labelv = Variable(label_one)
        output = dis(imagev)
        real = output.data.mean()
        loss_real = criterion2(output, labelv)
        loss real.backward()
        optimizerD.step()
        #-----Train Discriminator with fake data of Generators
        fakev1, labelg1= get_generator_data()
        labelv = Variable(label_zero)
        output1 = dis(fakev1.detach())
        #out = clas(output0)
        loss_fake = criterion2(output1, labelv)
        #loss clas1 = criterion1(out, Variable(label zeroL))
        loss_fake.backward()
        #loss clas1.backward(retain graph = True)
       DG z1 = output.data.mean()
        #loss = loss real + loss fake
        print(output.grad)
        optimizerD.step()
        print("Mean of Discriminator = %f" %DG z1)
       #----Train with fake data from gen2-----
       #noise.copy_(torch.FloatTensor(32, 100, 1, 1).normal_(0,1))
       noisev = Variable(noise)
       fake2 = gen2(noisev)
       labelv = Variable(label zero)
       output = dis(fake2.detach())
       #out = clas(output0)
        loss fake2 = criterion2(output, labelv)
       #loss clas2 = criterion1(out, Variable(label oneL))
        loss fake2.backward()
        #loss clas2.backward(retain graph = True)
       DG_z1 = output.data.mean()
       #loss = loss real + loss fake
        #----Train with fake data from gen3-----
       #noise.copy (torch.FloatTensor(32, 100, 1, 1).normal (0,1))
       noisev = Variable(noise)
        fake3 = gen3(noisev)
        labelv = Variable(label zero)
        output = dis(fake3.detach())
       #out = clas(output0)
        loss_fake3 = criterion2(output, labelv)
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#loss_clas3 = criterion1(out, Variable(label twoL))
loss fake3.backward()
#loss_clas3.backward()
DG z1 = output.data.mean()
#loss = loss_real + loss_fake
optimizerD.step()
#optimizerC.step()
1 1 1
#-----Generator with discrim
gen1.zero_grad()
gen2.zero_grad()
gen3.zero_grad()
labelv = Variable(label_one)
output1 = dis(fakev1)
loss_G1 = criterion2(output1[:10], labelv[:10])
#loss Gclas1 = criterion1(out, Variable(label zeroL))
loss G1.backward(retain graph = True)
optimizerG1.step()
#loss Gclas1.backward()
loss_G2 = criterion2(output1[10:20], labelv[10:20])
loss_G2.backward(retain_graph = True)
optimizerG2.step()
loss G3 = criterion2(output1[20:], labelv[20:])
loss G3.backward(retain graph = True)
optimizerG3.step()
DG1 z2 = output1.data.mean()
print("Mean of generators = %f" %DG1 z2)
#-----
                  ----- with class
label v = Variable(label zeroL)
output2 = cla(fakev1)
loss cG1 = criterion1(output2[:10], label v[:10])
#loss Gclas1 = criterion1(out, Variable(label zeroL))
loss cG1.backward(retain graph = True)
optimizerG1.step()
#loss Gclas1.backward()
label v = V ariable(label oneL)
loss cG2 = criterion1(output2[10:20], label v[10:20])
loss cG2.backward(retain graph = True)
optimizerG2.step()
label v = Variable(label twoL)
loss_cG3 = criterion1(output2[20:], label_v[20:])
loss cG3.backward()
```

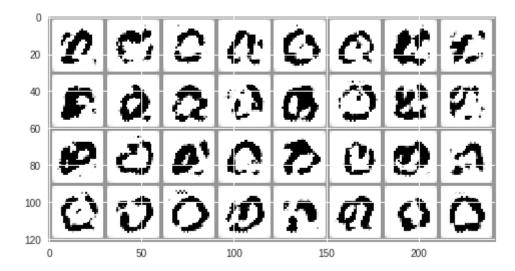
```
optimizerG3.step()
           1 1 1
          #-----Generator 2
           gen2.zero_grad()
           labelv = Variable(label one)
          output = dis(fake2)
           loss G2 = criterion2(output, labelv)
           #loss_Gclas1 = criterion1(out, Variable(label_zeroL))
           loss G2.backward()
           #loss_Gclas1.backward()
           DG1_z2 = output.data.mean()
          #-----Generator 3
           gen3.zero_grad()
           labelv = Variable(label_one)
           output = dis(fake3)
           loss G3 = criterion2(output, labely)
           #loss Gclas1 = criterion1(out, Variable(label zeroL))
           loss G3.backward()
          #loss Gclas1.backward()
          DG1 z2 = output.data.mean()
           optimizerG1.step()
          optimizerG2.step()
           optimizerG3.step()
           if(batch idx%10):
            print('batch %d'%batch idx)
       print('----- %i)
train classifier(6)
train(5)
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz
```

```
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz (http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz)
Downloading http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz (http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz)
Downloading http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz (http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz)
Downloading http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz (http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz)
Processing...
Done!
torch.Size([6000, 1, 28, 28])
torch.Size([6000])
```

/usr/local/lib/python3.6/dist-packages/ipykernel\_launcher.py:155: UserWar ning: Implicit dimension choice for softmax has been deprecated. Change the call to include dim=X as an argument.

```
In [4]: fake = gen1(Variable(torch.FloatTensor(32, 100, 1, 1).normal_(0,1).cuda()))
    a = torchvision.utils.make_grid(fake.data)
    plt.imshow(a[0,:,:])
```

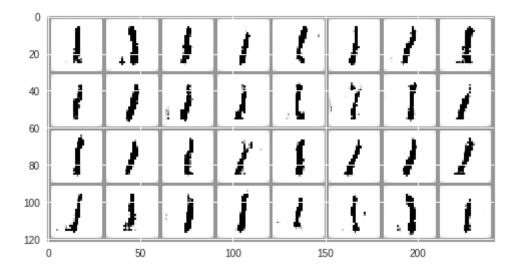
Out[4]: <matplotlib.image.AxesImage at 0x7f84ac8515c0>



In [0]: 3# http://pytorch.org/
from os import path
from wheel.pep425tags import get\_abbr\_impl, get\_impl\_ver, get\_abi\_tag
platform = '{}{}-{}'.format(get\_abbr\_impl(), get\_impl\_ver(), get\_abi\_tag())
accelerator = 'cu80' if path.exists('/opt/bin/nvidia-smi') else 'cpu'
!pip install -q http://download.pytorch.org/whl/{accelerator}
 /torch-0.3.0.post4-{platform}-linux\_x86\_64.whl torchvision
import torch

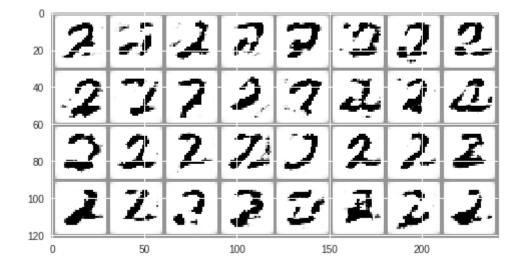
In [5]: fake = gen2(Variable(torch.FloatTensor(32, 100, 1, 1).normal\_(0,1).cuda()))
 a = torchvision.utils.make\_grid(fake.data)
 plt.imshow(a[0,:,:])

Out[5]: <matplotlib.image.AxesImage at 0x7f84ac7c24e0>



In [7]: fake = gen3(Variable(torch.FloatTensor(32, 100, 1, 1).normal\_(0,1).cuda()))
 a = torchvision.utils.make\_grid(fake.data)
 plt.imshow(a[0,:,:])

Out[7]: <matplotlib.image.AxesImage at 0x7f84acb8e668>



In [0]: