CSC5800 - Class Project Report

Vehicular Queue Length Classification from High Resolution Stop Bar Detection Data

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Abstract:

This project uses high resolution (HiRes) data obtained from a real-life City of Detroit Intersection and attempts to predict the classification under which the vehicle queue for that approach falls (No Queue, Low Queue, or High Queue). This helps the decision makers in understanding the performance of the signal and potentially adjust traffic signal timing (cycle and phase times) in order to improve signal performance. The high resolution data is collected from a single source 360° fisheye camera providing high-accuracy stop bar pulse and presence data paired with high resolution traffic signal telemetry (phase status and timings).

An extensive data extraction procedure was conducted through APIs, data was converted into usable formats, sorted and tabulated, and finally processed under multiple detailed tables in order to make reflective of the conditions it was measuring. Outliers were eliminated, and a final per-cycle amalgamation of a series of different data features were combined into a single data set for statistical evaluation and model development. The Final data set consisted of 21 features and one classifier.

This project attempted to be a first step in that direction by processing a one-day long set of data for an approach at an intersection and deriving the statistical relationships between the chosen attributes. Additionally, various prediction classification models were test to provide a comparison (Logistic Regression, Decision Tree, Linear Discriminant Analysis, K Nearest Neighbors, Gaussian Naïve Bayes, SVM, and NN -Multilayer Perceptron).

Based on the statistical analyses performed, we reached interesting inferences regarding intersection queue formation and the potential implication on traffic signal performance. For instance, some of the investigated analyses: highly correlated continuous input Attributes, distribution pattern for attributes, models that predict our objective accurately, the decision boundaries, and the Receiver operating characteristic curve (ROC) for two class-problem.

Based on the classification prediction models developed we managed to predict the three classes of Queue Status – No Queue (NQ=1), Light Queue (LQ=2), Full Queue (FQ=3) with varying degrees of success for a balanced accuracy. Out of the tested methods, **K nearest neighbor (KNN) seems to be outperforming the other methods** (even the Neural Network based Multi-Level Perceptron). However, due to a ramification of an uneven class distribution (with much lower instances of FQ compared with the other two classes), potential data accuracy issues, review of analysis methods and configurations, and the need for a larger data pool, the results were not as strongly along the entire data range. Prediction of the FQ class specifically fell short in all methods and needs further investigation. However, for the NQ and LQ, the model seems to be highly accurate.

I. INTRODUCTION

Understanding traffic signal performance (TSP) has been one of traffic engineering's most challenging problems. In order to do so, traffic engineers need to have a number of detectors set up at various locations of the intersection in order to completely and accurately translate real-life conditions into quantifiable and useful metrics. Data is then converted into Traffic Signal Performance Measures (TSPM) to directly enhance the operational performance and to indirectly improve upon the safety of a traffic signal. The TSPMs could be used either for real-time traffic operations or for after-the-fact evaluation or assessment of the performance of a traffic signal. Traffic operations is usually assessed by the common Level-of-Service ranking based on intersection or approach delay. However, in recent years Perdu University, Iowa State, and Utah DOT amongst others have been developing and innovating with automating the process of those TSPM in order to make them practical and useful. In addition to the basic performance measures of Approach Volume and turning movement counts, there's been a number of more advanced Automated Traffic Signal Performance Measures (ATSPM) that have been developed such as the Purdue Phase Determination, Split Monitoring, Pedestrian Delay, Preemption, Split Failures, Approach Delay, and Arrivals on Red. However, there are a few others that are a little more involved that haven't been as popular such as Yellow-and-Red actuation, Headway, and Speed.



Figure: Miovision provided ATSPM's (Central & Vernor)

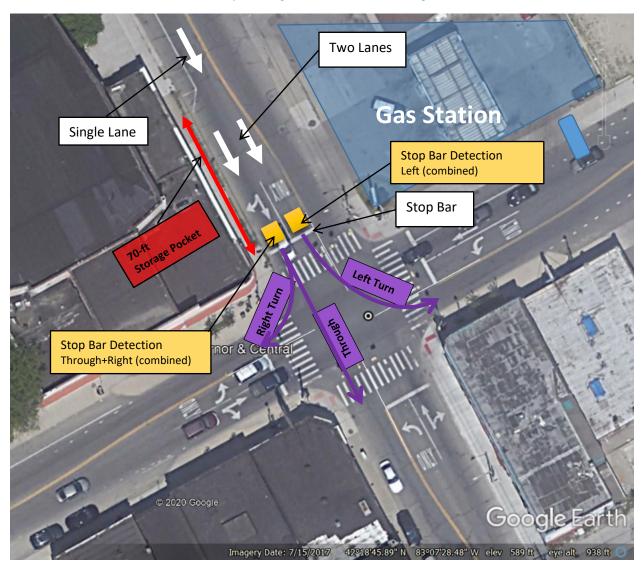
As powerful as those measures are, they come at a very hefty resource investment and cost for installation, operations, and maintenance in order to achieve their accuracy levels. In order to predict all those TSPM, at a minimum a set of two detectors are needed per approach and then connected to a data collection device in the cabinet. Many agencies may not have the financial means to initiate such a solution regardless of the benefit it may bring. However, stop-bar detection alone is more attainable and cheaper for smaller agencies. Those could be in the form of in-pavement detection pucks, loops, or single source 360° fisheye cameras and they provide high-accuracy stop bar pulse and presence data. This project aims at using high resolution (HiRes) stop bar detection data alone to try identifying features with the highest correlation to queue and which could potentially predict the queue with the highest accuracy (without the hefty investment in infrastructure).

a. Chosen location, configuration, and timing

The intersection location of Central Ave and Vernor Hwy in the southwest side of Detroit was chosen as the test location. This intersection was chosen for its typical 4-leg configuration and two-phase signal timing. In order to simplify the evaluation development process, one approach was selected:

Southbound Central Avenue approach. This approach

The 60-second pre-timed cycle with a 40/20 Red/Green split. i.e.: for the southbound approach, every 60 second cycle consisted of 40 seconds of red and 20 seconds of green. This pre-timed cycle information makes it easier to identify missing information and timing errors.



The lane configurations of this approach consist of one approach lane that branches out into two lanes about 70 feet from the stop bar. In the most ideal of situations, this allows for approximately a storage pocket capacity of two (2) vehicles for the left turn lane (permissive movement) and five (5) vehicles for the through+right turn lane. In order for the approach to be considered blocked (maximum queue), there would need to be between 5 to 7 vehicles in the storage pockets. That is dependent on which movement lane the cars are stacking up in.

To add more complexity and potential error to the configuration, there is a gas station in the northeast quadrant of the intersection which has vehicles accessing it from Central Avenue and potentially disrupting typical flow and operation of the signal.

b. Detection and Data Accuracy

For this project a single source 360° fisheye camera providing high-accuracy stop bar pulse and presence data was used paired with high resolution traffic signal telemetry (phase status and timings). Additionally, the Camera capabilities were used to get accurate vehicle type classification (car, heavy, pedestrian, or bicycle) and Turning Movement Count (TMC) data in order to be used for the analyses and for the actual queue calculations used in training the model. The team attempted to use an advance detection box for this purpose however, the camera was exceeding its detection ranges and the data was inaccurate and unusable.

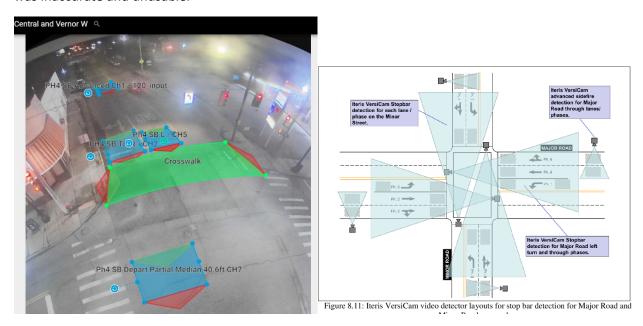


Figure: Single Camera Detection Box Configuration (left) vs. full lane-specific detection configuration (right)

Limited stop-bar detection, allows the traffic engineer to get a sense of what's happening at the stop-bar of the signal. When paired with traffic signal telemetry (signal phase and time) data, a better replication of the signal is possible. And just like with forensic evidence, the pieces of the puzzle are put together to try to come up with the intended queue prediction. The concern here is the limited view of the intersection that this approach starts with and the consequential limitation in accuracy. In order to offset those it was necessary to interpret the raw high resolution detector data and pair it with the high resolution signal telemetry to better tell the story of the arrival and departure of the vehicles. C

c. Problem statement (Research Question)

- i. How can we leverage existing HiRes stop bar video detection in the City of Detroit to predict performance (queuing[TG1]) at Urban intersections?
- ii. If so, how accurately can that be done relative to existing state of the practice metrics?

iii. Are there other existing data that can be leveraged to improve the accuracy of the performance metrics[TG2]?

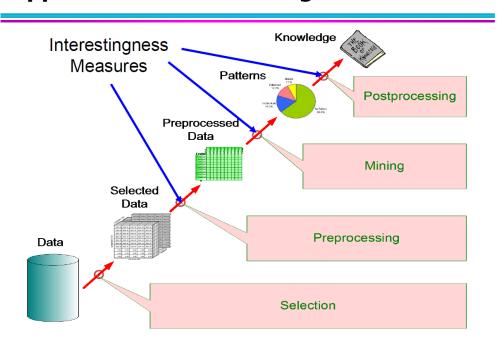
d. Objective statement

- i. Collect and Visualize existing High Resolution Signal Controller data at an intersections in the city of Detroit.
- ii. Attempt to create a Methodology to define the performance measure logic using stop bar detection
- iii. Compare performance measures using advanced detection (real world) with performance measures using stop bar detection
- iv. Allow method to be able to Scale and measure the performance difference between advanced and stop bar logic.

II. METHODOLOGY

The entire data development process is described below in bullet points up to the data analysis and modeling section. The entire process was very cumbersome as it accounted for a full effort to select the data, extract it, preprocess it, process it to make it usable and relevant, and organize the tables with usable attributes. The data set was preprocessed using excel, however, it is recommended for this process to be automated using python in the future.

Application of Interestingness Measure

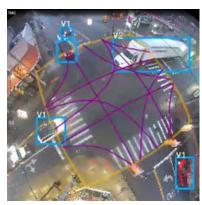


Source: Steven F. Ashby Center for Applied Scientific Computing Month DD, 1997 (Lecture Notes - Introduction to Data Mining)

- Data Extracted from Miovision API
 - November 30th was chosen
 - Day within the last month with highest southbound movement and overall signal volume for the day and per hour to account for worst case scenario.
 - High Resolution (HiRes) Data Extracted:
 - Stop-Bar Detection data
 - Advance Pulse-Box Detection data
 - Turning Movement Counts data (TMC)
 - Aggregated 1-minute Data Extracted"
 - Turning Movement Counts
- Account for Timestamp time in extraction (based on UTC time for the HiRes data and local time for the TMC) – HiRes had to be converted to local time.
- Extracted HiRes files were a series of 1-hr groups in JSON format that needed conversion and joining
- JSON converted to .txt files then worked with as .csv
- Timestamp converted to regular time with millisecond precision (functional time accuracy is to 100 millisecond [i.e.: 0.1 seconds])
- Data was checked for errors and gaps (missing data)
- A queue estimation model was built from advanced and stop-bar detection boxes (paired with the traffic signal status [red or green]). However, error was high.
 - Alternatively, a queue estimation model was used from the HiRes TMC data.
- Visualization:
 - HiRes Stop Bar Detection data was graphed for visual inspection of the arrivals on Red and Green.
- Recreated Stop-Bar Detection, signal status (and time left on red or green), headway (closeness of vehicles), speed, and historical TMC (some of those items were not accurate enough and were not used in the model).
- Model Queue prediction (classification) discussed next section



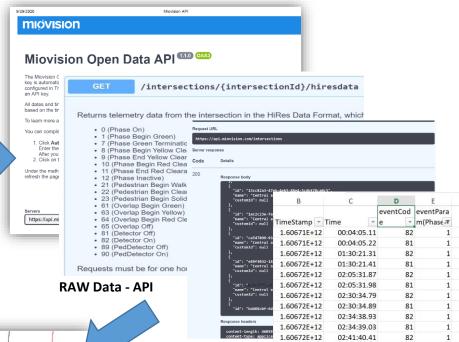
Approach Detection Configuration

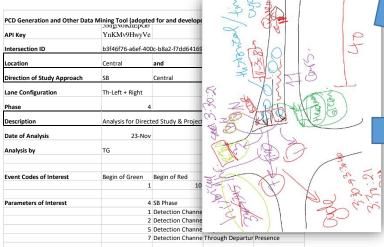


TMC Configuration



Raw Video – Single 360 Camera





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Plan and execute data processing, data mining, and data post-processing and Analysis

-								SGN_Gr	StobBar	rreq.	Freq.	Freq.	Freq.	StopBar	Depart	Freq.	Freq.	Freq.	Freq.			MaxU_
		DayofWee				Cycl_Leng	SGN_Re	een_Ti	_LEFT_T	AOR by	AOG by	DOR by	DOG by	_RtTh_T	(assump	AOR by	AOG by	DOR by	DOG by	Truck_P		NotNee
day	month	k	Hour	minutes	H_M	th	d_Time	me	rigger	Cycle	Cycle	Cycle	Cycle	rigger	tion)	Cycle	Cycle	Cycle	Cycle	resent	Q_filled	ded
30	11	2	0	0	0.00	59.97	40.45	19.52	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	1	0.02	59.98	40.46	19.52	1.00	0.00	1.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	2	0.03	60.00	40.46	19.54	1.00	0.00	2.00	1.00	2.00	1.00	2.00	2.00	2.00	2.00	2.00	0.00	NQ	0.00
30	11	2	0	3	0.05	59.97	40.44	19.52	1.00	0.00	1.00	0.00	1.00	1.00	0.00	0.00	2.00	0.00	2.00	0.00	LQ	1.00
30	11	2	0	4	0.07	59.97	40.45	19.52	1.00	0.00	1.00	0.00	1.00	1.00	0.00	1.00	4.00	0.00	5.00	0.00	LQ	2.00
30	11	2	0	5	0.08	60.06	40.54	19.52	1.00	0.00	3.00	0.00	3.00	1.00	0.00	0.00	4.00	0.00	4.00	0.00	NQ	0.00
30	11	2	0	6	0.10	59.98	40.45	19.52	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	7	0.12	59.96	40.44	19.53	0.00	0.00	0.00	0.00	0.00	1.00	1.00	1.00	2.00	1.00	2.00	0.00	LQ	2.00
30	11	2	0	8	0.13	59.98	40.46	19.52	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	9	0.15	60.09	40.56	19.52	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	10	0.17	59.95	40.43	19.52	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	11	0.18	59.97	40.54	19.42	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	12	0.20	60.02	40.57	19.44	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00
30	11	2	0	13	0.22	60.03	40.50	19.53	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	NQ	0.00

III. ANALYSIS (entire workbook can be found on GitHub)

https://github.com/rajratnapatil9/TRAFFIC-QUEUE-PREDICTION/blob/main/Queue%20Prediction.ipynb

DATA DIMENSION: 1343 x 19 (final set)

a. Schema:

List of Attributes and classifier are listed below with a short description and an example. Outliers and erroneous data points were eliminated from the original data set based on missing and off cycles. That reduced the data points from 1440 to 1343 over two steps.

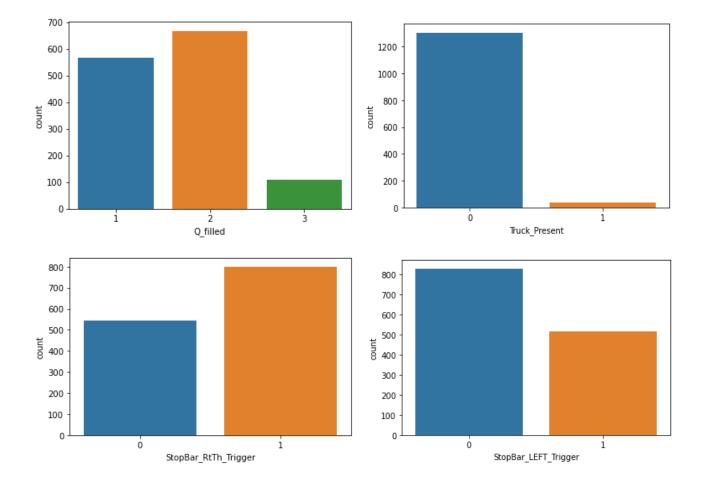
#	Attributes	Description	Example
1	Hour	Hour during which the data point occurred	10
2	minutes	Minute during which the data point occurred	20
3	H_M	Hour+Minute (fraction) during which the data point occurred	10.33
4	Cycl_Length	Cycle length in Seconds (to the 1/10th of a second)	59.97
5	SGN_Red_Time	Red Time in Seconds (to the 1/10th of a second)	40.55
6	SGN_Green_Time	Green Time in Seconds (to the 1/10th of a second)	19.42
7	StopBar_LEFT_Trigger	Trigger of detector box at stop bar during the cycle for the Left Turn lane	1
8	Freq. AOR by Cycle	Number of Vehicles Arriving on Red during Cycle (Left Turn)	1
9	Freq. AOG by Cycle	Number of Vehicles Arriving on Green during Cycle (Left Turn)	0
10	Freq. DOR by Cycle	Number of Vehicles Departing on Red during Cycle (Left Turn)	0
11	Freq. DOG by Cycle	Number of Vehicles Departing on Green during Cycle (Left Turn)	1
12	StopBar_RtTh_Trigger	Trigger of detector box at stop bar during the cycle for the Through+Right Turn lane	1
13	RTOR Depart (assumption)	Number of Vehicles Turning Right on Red (RTOR) during Cycle (Th+Rt lane)	0
14	Freq. AOR by Cycle	Number of Vehicles Arriving on Red during Cycle (Th+Rt lane)	1
15	Freq. AOG by Cycle	Number of Vehicles Arriving on Green during Cycle (Th+Rt lane)	0
16	Freq. DOR by Cycle	Number of Vehicles Departing on Red during Cycle (Th+Rt lane)	0
17	Freq. DOG by Cycle	Number of Vehicles Departing on Green during Cycle (Th+Rt lane)	1
18	Truck_Present	Presence of trucks during cycle	0
19	Q_filled	Classification: NQ, LQ, FQ (see provided table)	LQ

b. Distribution of Variables: NQ=1, LQ=2, FQ=3

Queue Classification Category	NQ	LQ	FQ
Category Numerical Code	1	2	3
Category Values	0	1-5	6 and above
Description	No cars during	1 to 5 vehicles queued	6 or more vehicles
	cycle	during cycle	queued during cycle
frequency	570	677	111

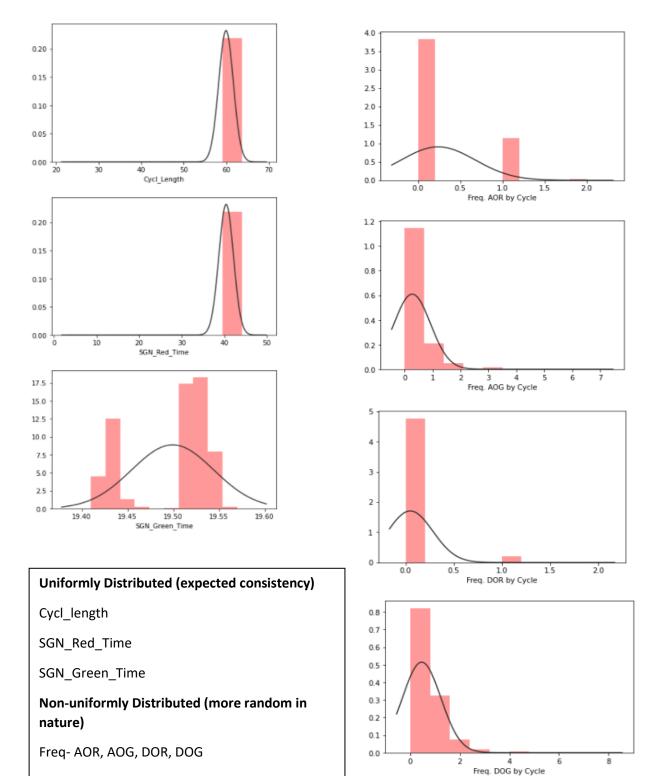
The derived actual queue lengths were categorized into three classes: NQ, LQ, and FQ (described above). Some basic descriptive statistics were performed to attempt to identify the class range, however, it was more crucial to follow a more practical approach that would yield useful results. The frequency of FQ is lower than LQ and NQ for our dataset. But we can't avoid this, as we need this information to accurately predict to improve traffic signal systems. NQ was used for when there are no queues present. FQ is used when the queue is expected to be full (backed up), and the LQ is the level incorporating everything in between. And because this is a sample data set, we didn't have a big data representation for the FQ level. However, with more days and locations to review in the future, it is expected that this category would be better represented.

MaxQ_NotNeeded								
Mean	1.865243							
Standard Error	0.058582							
Median	1							
Mode	0							
Standard Deviation	2.158826							
Sample Variance	4.66053							
Kurtosis	0.039275							
Skewness	1.010565							
Range	8							
Minimum	0							
Maximum	8							
Sum	2533							
Count	1358							
Confidence Level(95.0%)	0.114922							



c. Histograms of select Independent Variables:

The following represent a set of histograms for a select number of independent variables.



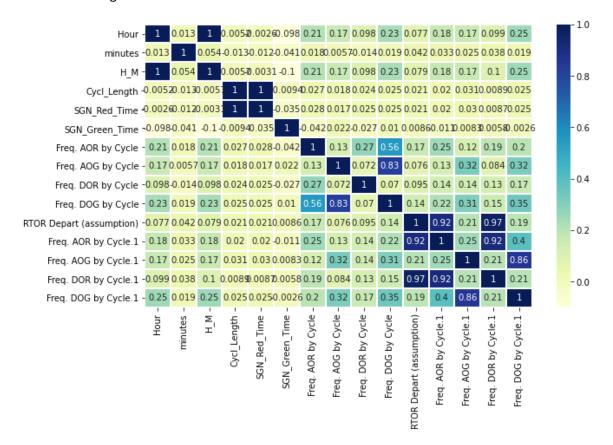
d. Correlations Analysis

According to the correlation coefficient matrix, there were six highly correlated attributes that stood out between. The most significant of which is: RTOR Depart (assumption): Frequency DOR by Cycle.1 (0.97). This correlation is justified when the practical explanation of the Attribute is delved into. In this case the RTOR was derived from any DOR that occurs after 3 seconds. Additionally, RTOR seems to be occurring in correlation with vehicles arriving on red and departing on red (DOR).

Additionally, the data is indicating that most vehicles are arriving on green and departing on green for both lanes (that is a good value but could be improved with coordination with signals upstream). However, the final relationship is showing a high correlation between vehicles arriving on red (AOR) and departing on green (DOG) which is not a good indication of signal performance.

ATTRIBUTES	CORRELATION
RTOR Depart (assumption): Frequency DOR by Cycle.1	0.97
RTOR Depart (assumption): Frequency AOR by Cycle.1	0.92
Freq. AOR by Cycle.1 : Frequency DOR by Cycle.1	0.92
Freq. DOG by Cycle.1 : Freq. AOG by Cycle.1	0.86
Freq. DOG by Cycle : Freq. AOG by Cycle	0.83
Freq. DOG by Cycle: Freq. AOR by Cycle	0.56

The below correlation coefficient matrix represents the full relationship between the various continuous attributes. Categorical variables are not included.



e. MODEL BUILDING:

For Model Building, as our data is non-linear, we used these classification methods to search for accurate model. Seven models were investigated. The accuracy between the training and testing data sets for the following seven models is shown in the following table.

1. Logistic Regression 5. Gaussian Naïve Bayes

2. Decision Tree 6. SVM

3. Linear Discriminant Analysis 7. NN -Multilayer Perceptron

4. K nearest Neighbors

MODEL	TRAINING ACCURACY	TESTING ACCURACY
1. Logistic Regression	0.82	0.83
2. Decision Tree	1	0.75
3. Linear Discriminant Analysis	0.81	0.82
4. K Nearest Neighbors	0.85	0.82
5. Gaussian Naïve Bayes	0.52	0.52
6. SVM	0.85	0.85
7. NN -Multilayer Perceptron	0.85	0.85

f. Comparing the top performing classifiers

If we compare only the testing accuracies, then we have the following Top-3 Classifiers:

- SVM
- NN-Perceptron
- KNN-K-Nearest Neighbors

Inferences:-

- If we compare other measures like confusion metrics, F-measure, Precision and Recall, then we see that KNN wins
- Also if we closely observe, KNN gives us a balanced classification accuracy, for instance it predicts class FQ=3 more accurately than other two classifiers.

```
▶ print('Confusion Matrix and Precision-Recall for SVM')
  from sklearn.metrics import classification_report
  from sklearn.metrics import confusion_matrix
  pred3 = svm.predict(X_test)
  print(confusion_matrix(y_test, pred3))
  print(classification_report(y_test, pred3))
  Confusion Matrix and Precision-Recall for SVM
  [[160 8
              01
   [ 22 180
[ 2 27
              11
              3]]
                 precision
                              recall f1-score
                                                  support
                                0.95
                                           0.91
                      0.87
              2
                      0.84
                                0.89
                                           0.86
                                                      203
              3
                      0.75
                                0.09
                                           0.17
                                                      32
                                                      403
                                           0.85
      accuracy
      macro avg
                      0.82
                                0.64
                                           0.65
                                                      403
  weighted avg
                      0.84
                                0.85
                                           0.83
                                                      403
```

```
print('Confusion Matrix and Precision-Recall for MLP')
from sklearn.metrics import classification_report
from sklearn.metrics import confusion_matrix
pred = clf.predict(X_test)
print(confusion_matrix(y_test, pred))
print(classification_report(y_test, pred))
Confusion Matrix and Precision-Recall for MLP
[[160
       8
           0]
   22 179
           21
   0 28
              precision
                           recall f1-score
                                              support
                             0.95
                                       0.91
                   0.88
                                                   168
                                                   203
                   0.83
                             0.88
                                       0.86
                   0.67
                             0.12
                                       0.21
                                                    32
                                       0.85
                                                   403
    accuracy
                   0.79
                             0.65
                                                   403
                                       0.66
   macro avg
                                                   403
weighted avg
                   0.84
                             0.85
                                       0.83
```

```
#KNN
  print('Confusion Matrix and Precision-Recall for KNN')
  from sklearn.metrics import classification report
  from sklearn.metrics import confusion_matrix
  pred2 = knn.predict(X_test)
  print(confusion_matrix(y_test, pred2))
  print(classification_report(y_test, pred2))
  Confusion Matrix and Precision-Recall for KNN
  [[150 18
              01
   [ 21 174
              8]
   [ 0 24
              8]]
                precision
                              recall f1-score
                                                 support
                     0.88
                                0.89
                                          0.88
                                                     168
             1
             2
                     0.81
                               0.86
                                          0.83
                                                     203
             3
                     0.50
                               0.25
                                          0.33
                                                      32
      accuracy
                                          0.82
                                                     403
     macro avg
                     0.73
                                0.67
                                          0.68
                                                     403
  weighted avg
                     0.81
                                0.82
                                          0.81
                                                     403
```

	Correctly classified SVM	Correctly classified MLP	Correctly classified KNN
NQ=1	160	160	150
LQ=2	180	179	174
FQ=3	3	4	8

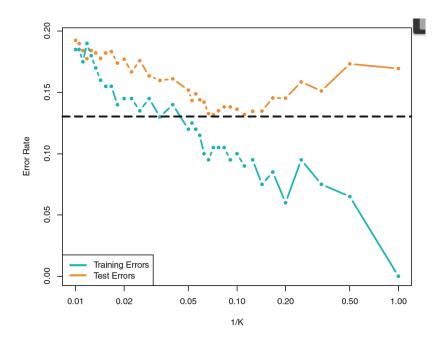
As we can see, although Accuracy of other models are equivalent for NQ=1 and LQ=2, Class FQ=3 is lagging behind with only a fraction of the data points correctly classified. Out of the three methods, FQ is more accurately classified under KNN (8 out of 32) which is a very important factor for Traffic signal regularization.

K Nearest Neighbors **

We used k=5 because we felt it optimized the confusion matrix better for our test results

Theoretically: At K= 5, most case scenario observes a min Training and testing error rates. At K=5, 1/K = 0.2

PG 42 of Textbook - An Introduction to Statistical Learning with Applications in R



Practically:

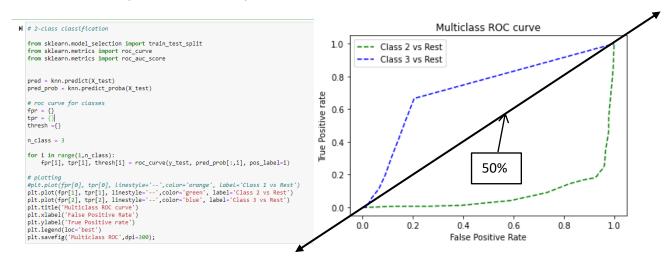
After plotting the graph we observed that at K=5, both Training and testing errors are minimum.

```
k-NN Varying number of neighbors
neighbors = np.arange(1,20)
train_accuracy =np.empty(len(neighbors))
test_accuracy = np.empty(len(neighbors))
                                                                                                                1.00
                                                                                                                                                                                                          Testing Accuracy
                                                                                                                                                                                                          Training accuracy
    for i,k in enumerate(neighbors):
          #Setup a knn classifier with k neighbors
knn = KNeighborsClassifier(n_neighbors=k)
                                                                                                                0.95
          knn.fit(X_train, y_train)
                                                                                                                0.90
          #Compute accuracy on the training set
train_accuracy[i] = knn.score(X_train, y_train)
          #Compute accuracy on the test set
test_accuracy[i] = knn.score(X_test, y_test)
                                                                                                                0.85
    plt.title('k-NN Varying number of neighbors')
plt.plot(neighbors, test_accuracy, label='Testing Accuracy')
plt.plot(neighbors, train_accuracy, label='Training accuracy')
                                                                                                                0.80
    plt.legend()
plt.xlabel('Number of neighbors')
                                                                                                                                     2.5
                                                                                                                                                   5.0
                                                                                                                                                                 7.5
                                                                                                                                                                              10.0
                                                                                                                                                                                             12.5
                                                                                                                                                                                                           15.0
                                                                                                                                                                                                                         17.5
    plt.ylabel('Accuracy')
plt.show()
                                                                                                                                                                 Number of neighbors
```

ROC-CURVE

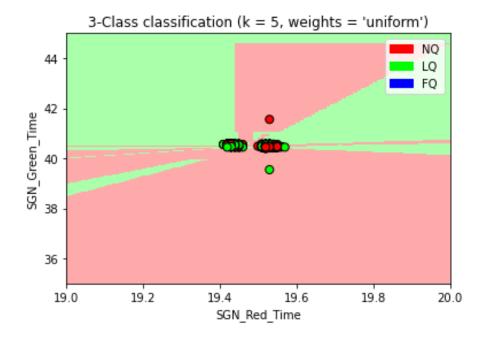
From ROC curve, we see for LQ=2 the KNN model is a very good model (above 50% chance) but for FQ=3, the KNN model current is a bad model (below 50%). But it is much better and balanced than any other model tried so far.

In this case, the penalization of one class prediction vs the other is subject to the objective and the cost function associated with it. This signifies that both of them are penalizing each other and tradeoff between these need to be decided based on the objective of the analysis. For our Analysis, we want both of these to be predicted accurately.



Decision Boundary

For NQ=1, LQ=2, FQ=3, as we can see, a clear boundary for FQ is missing which needs to improvised.



V. CONCLUSION

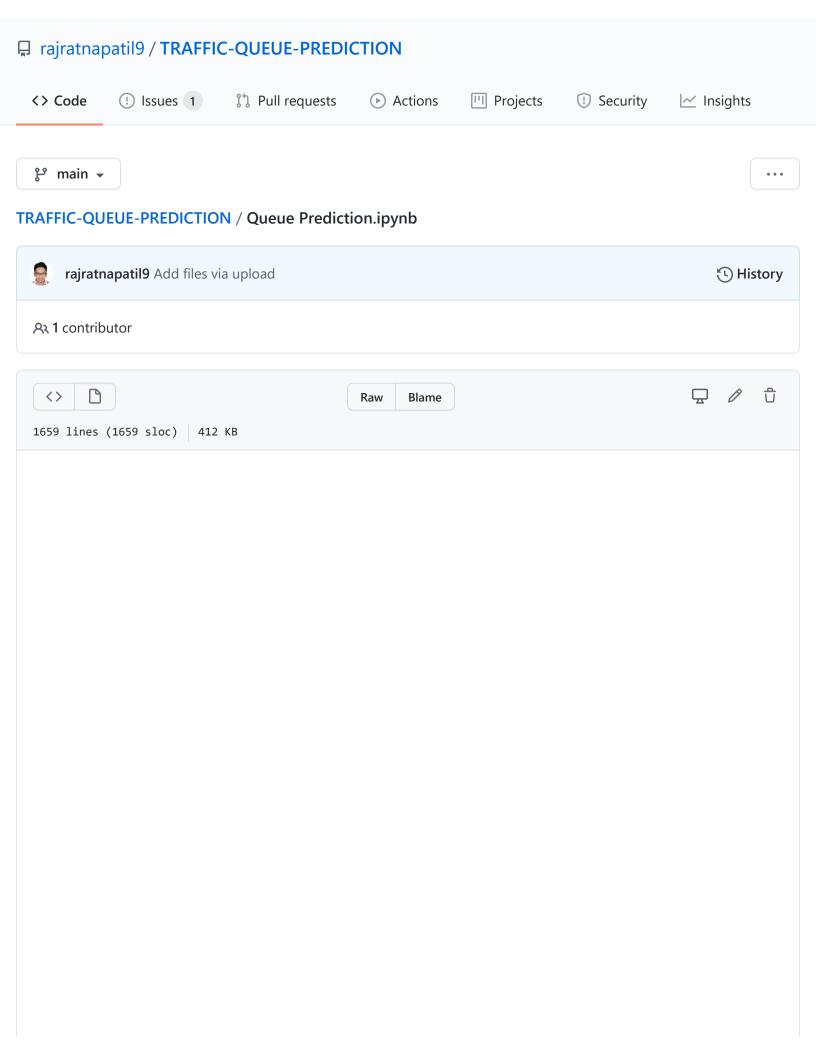
The issue of predicting queue classification solely from stop bar detection high resolution data is a hurdle that has not been addressed or resolved through research and industry due to the complexity it requires and the large set of data required to come to a reasonable selection process, method, and result interpretation. This project attempted to be a first step in that direction by processing a one-day long set of data for an approach at an intersection and deriving the statistical relationships between the chosen attributes. Additionally, various prediction classification models were test to provide a comparison (Logistic Regression, Decision Tree, Linear Discriminant Analysis, K Nearest Neighbors, Gaussian Naïve Bayes, SVM, and NN -Multilayer Perceptron).

Out of those methods, **K** nearest neighbor (KNN) seems to be outperforming the other methods (even the Neural Network based Multi-Level Perceptron). However, due to a ramification of an uneven class distribution (with much lower instances of FQ compared with the other two classes), potential data accuracy issues, review of analysis methods and configurations, and the need for a larger data pool, the results were not as strongly along the entire data range. Prediction of the FQ class specifically fell short in all methods and needs further investigation. However, for the NQ and LQ, the model seems to be highly accurate.

VI. REFERENCES

The following references were used throughout this report:

- Model Analysis: https://github.com/rajratnapatil9/TRAFFIC-QUEUE-PREDICTION/blob/main/Queue%20Prediction.ipynb
- PG 42 of Textbook An Introduction to Statistical Learning with Applications in R http://faculty.marshall.usc.edu/gareth-james/ISL/
- Steven F. Ashby Center for Applied Scientific Computing Month DD, 1997 (Lecture Notes Introduction to Data Mining)
- Rahman, R., Hasan, S. Real-time signal queue length prediction using long short-term memory neural network. *Neural Comput & Applic* (2020). https://doi.org/10.1007/s00521-020-05196-9
- Solving A Simple Classification Problem with Python Fruits Lovers' Edition
 https://towardsdatascience.com/solving-a-simple-classification-problem-with-python-fruits-lovers-edition-d20ab6b071d2
- K-Nearest Neighbors, Boxplot, Standard Score, Feature Scaling, Curse of Dimensionality, Missing Values, Confusion Matrix, Classification Report, ROC-Curve, AUROC https://limebit-jupyter-notebooks.s3.eu-central-1.amazonaws.com/jupyter-KNN-und-SVM.html
- AUC-ROC Curve in Machine Learning Clearly Explained https://www.analyticsvidhya.com/blog/2020/06/auc-roc-curve-machine-learning/
- KNN for Classification using Scikit-learn https://www.kaggle.com/amolbhivarkar/knn-for-classification-using-scikit-learn
- ROC Curve explained using a COVID-19 hypothetical example: Binary & Multi-Class Classification Tutorial https://towardsdatascience.com/roc-curve-explained-using-a-covid-19-hypothetical-example-binary-multi-class-classification-bab188ea869c



```
In [2]: import numpy as np
import csv
import matplotlib.pyplot as plt
import pandas as pd
```

```
In [117]: data = pd.read_csv("Data_CSV.csv")
    data.head()
```

Out[117]:

	Hour	minutes	н_м	Cycl_Length	SGN_Red_Time	SGN_Green_Time	StopBar_LEFT_Trig
0	0	0	0.00	59.97	40.45	19.52	0
1	0	1	0.02	59.98	40.46	19.52	1
2	0	2	0.03	60.00	40.46	19.54	1
3	0	3	0.05	59.97	40.44	19.52	1
4	0	4	0.07	59.97	40.45	19.52	1

In [3]: data.info()

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 1343 entries, 0 to 1342
Data columns (total 19 columns):
```

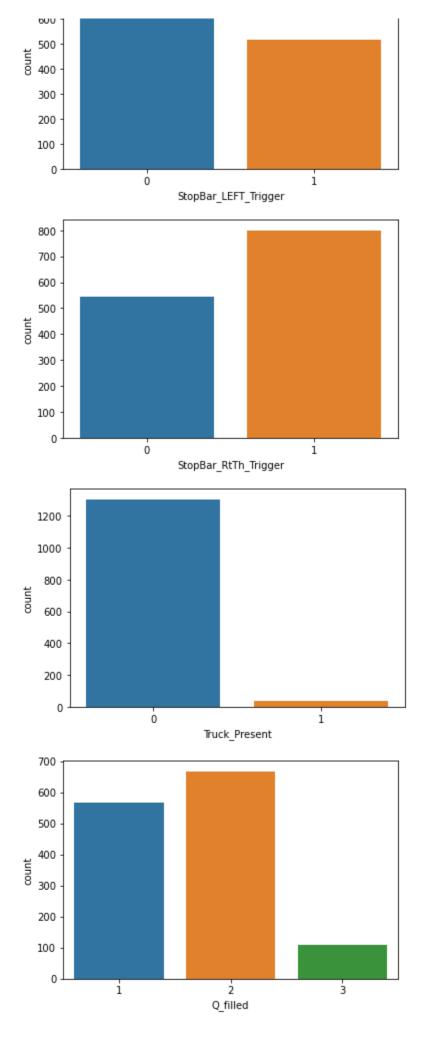
```
#
   Column
                              Non-Null Count Dtype
    -----
                              -----
0
   Hour
                              1343 non-null
                                              int64
1
   minutes
                              1343 non-null
                                              int64
2
   н м
                              1343 non-null
                                              float64
3
   Cycl Length
                              1343 non-null
                                              float64
4
   SGN Red Time
                              1343 non-null
                                              float64
5
   SGN Green Time
                              1343 non-null
                                              float64
6
   StopBar_LEFT_Trigger
                              1343 non-null
                                              int64
7
   Freq. AOR by Cycle
                              1343 non-null
                                              int64
8
   Freq. AOG by Cycle
                              1343 non-null
                                              int64
9
   Freq. DOR by Cycle
                              1343 non-null
                                              int64
10 Freq. DOG by Cycle
                              1343 non-null
                                              int64
11
   StopBar RtTh Trigger
                              1343 non-null
                                              int64
12 RTOR Depart (assumption)
                             1343 non-null
                                              int64
13 Freq. AOR by Cycle.1
                              1343 non-null
                                              int64
14 Freq. AOG by Cycle.1
                              1343 non-null
                                              int64
15 Freq. DOR by Cycle.1
                              1343 non-null
                                              int64
16 Freq. DOG by Cycle.1
                              1343 non-null
                                              int64
   Truck Present
17
                              1343 non-null
                                              int64
18 Q filled
                              1343 non-null
                                              int64
```

dtypes: float64(4), int64(15) memory usage: 199.5 KB

```
In [118]: data['StopBar_LEFT_Trigger'] = data['StopBar_LEFT_Trigger'].astype('category')
    data['StopBar_RtTh_Trigger']=data['StopBar_RtTh_Trigger'].astype('category')
    data['Truck_Present']=data['Truck_Present'].astype('category')
    data['Q_filled']=data['Q_filled'].astype('category')
```

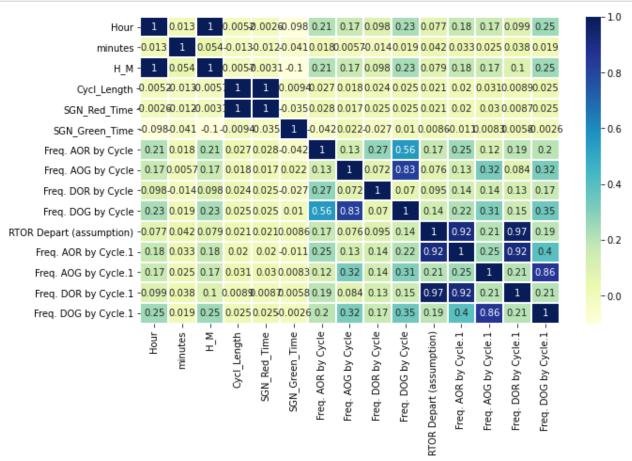
```
data.into()
          <class 'pandas.core.frame.DataFrame'>
          RangeIndex: 1343 entries, 0 to 1342
          Data columns (total 19 columns):
               Column
                                          Non-Null Count Dtype
           - - -
           0
               Hour
                                          1343 non-null
                                                          int64
           1
               minutes
                                          1343 non-null
                                                          int64
           2
               \mathsf{H}\ \mathsf{M}
                                          1343 non-null
                                                          float64
           3
               Cycl Length
                                          1343 non-null
                                                          float64
           4
               SGN_Red_Time
                                          1343 non-null
                                                          float64
           5
               SGN_Green_Time
                                          1343 non-null
                                                          float64
           6
               StopBar LEFT Trigger
                                          1343 non-null
                                                          category
           7
               Freq. AOR by Cycle
                                          1343 non-null
                                                          int64
           8
               Freq. AOG by Cycle
                                          1343 non-null
                                                          int64
           9
               Freq. DOR by Cycle
                                          1343 non-null
                                                          int64
           10 Freq. DOG by Cycle
                                          1343 non-null
                                                          int64
           11 StopBar_RtTh_Trigger
                                          1343 non-null
                                                          category
           12 RTOR Depart (assumption)
                                          1343 non-null
                                                          int64
           13 Freq. AOR by Cycle.1
                                          1343 non-null
                                                          int64
           14 Freq. AOG by Cycle.1
                                          1343 non-null
                                                          int64
           15 Freq. DOR by Cycle.1
                                          1343 non-null
                                                          int64
           16 Freq. DOG by Cycle.1
                                          1343 non-null
                                                          int64
           17 Truck_Present
                                          1343 non-null
                                                          category
           18 Q filled
                                          1343 non-null
                                                          category
          dtypes: category(4), float64(4), int64(11)
          memory usage: 163.1 KB
In [321]: (data['Q filled']==1).sum()
Out[321]: 567
In [322]: (data['Q filled']==2).sum()
Out[322]: 668
In [323]: | (data['Q_filled']==3).sum()
Out[323]: 108
  In [5]:
          import seaborn as sns
           sns.countplot(data['StopBar LEFT Trigger'],label="Count of NT/T")
           plt.show()
           import seaborn as sns
           sns.countplot(data['StopBar_RtTh_Trigger'],label="Count of NT/T")
           plt.show()
           import seaborn as sns
           sns.countplot(data['Truck Present'],label="Count of NT/T")
          plt.show()
           sns.countplot(data['Q filled'],label="Count of NT/T")
           plt.show()
```

800 -700 -

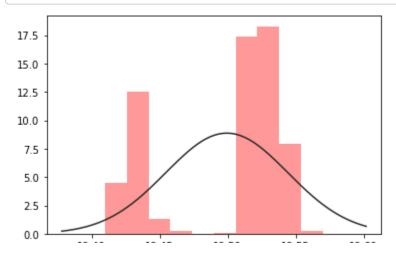


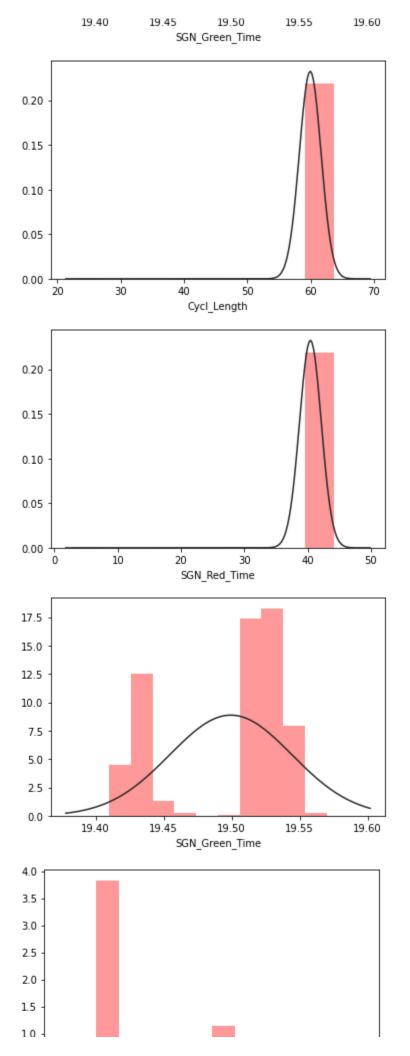
Correlation Plot for Continuous Attributes

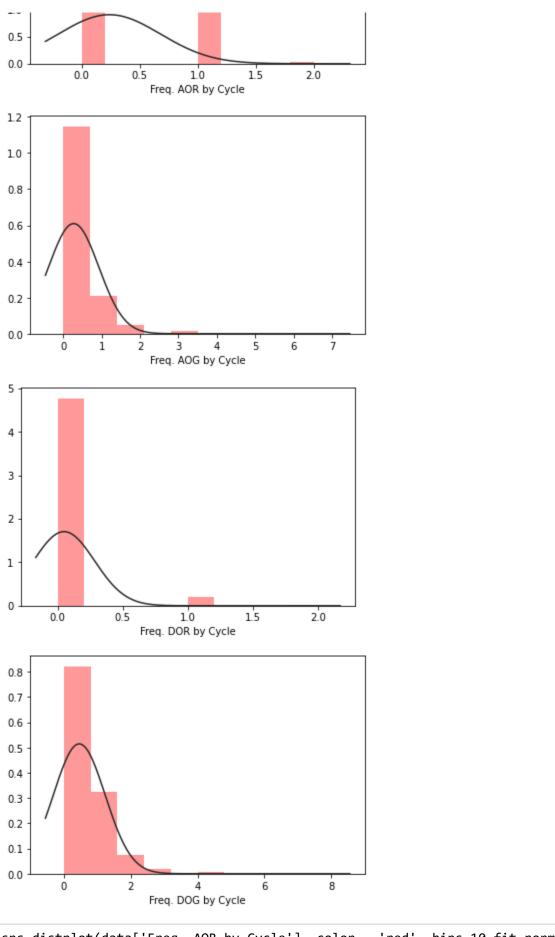
```
In [324]: plt.figure(figsize=(10,6))
    sns.heatmap(data.corr(), annot=True, linecolor = 'white', linewidths = 1, cmap="Y
    lGnBu")
    plt.show()
```



```
In [316]: sns.distplot(data.SGN_Green_Time, color = 'red', bins=10,fit=norm, kde=False)
plt.show()
sns.distplot(data.Cycl_Length, color = 'red', bins=10,fit=norm, kde=False)
plt.show()
sns.distplot(data.SGN_Red_Time, color = 'red', bins=10,fit=norm, kde=False)
plt.show()
sns.distplot(data.SGN_Green_Time, color = 'red', bins=10,fit=norm, kde=False)
plt.show()
```

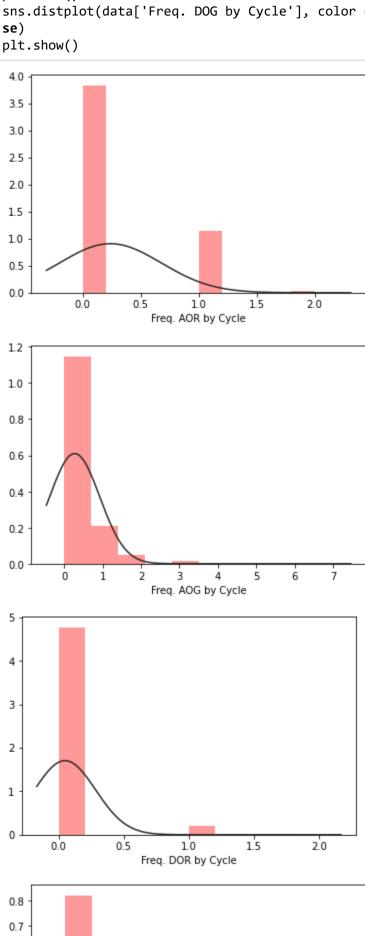




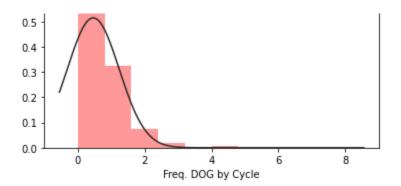


In [317]: sns.distplot(data['Freq. AOR by Cycle'], color = 'red', bins=10,fit=norm, kde=Fal
se)
plt.show()
sns.distplot(data['Freq. AOG by Cycle'], color = 'red', bins=10,fit=norm, kde=Fal
se)
plt.show()

```
sns.distplot(data['Freq. DOR by Cycle'], color = 'red', bins=10,fit=norm, kde=Fal
se)
plt.show()
sns.distplot(data['Freq. DOG by Cycle'], color = 'red', bins=10,fit=norm, kde=Fal
se)
plt.show()
```



0.6



1. Splitting data into continuous and categorical **Attributes**

2. Scaling and Normalizing COntinous Attributes

3. Combining them into single dataset

```
In [119]:
          data.catX= data[['StopBar_LEFT_Trigger', 'StopBar_RtTh_Trigger', 'Truck_Present'
          ,'Q_filled']]
          data.continuous = data[['Hour','minutes','H_M', 'Cycl_Length','SGN_Red_Time','SGN
           Green Time', 'Freq. AOR by Cycle', 'Freq. AOG by Cycle', 'Freq. DOR by Cycle', 'Fr
          eq. DOG by Cycle', 'RTOR Depart (assumption)', 'Freq. AOR by Cycle.1', 'Freq. AOG
           by Cycle.1', 'Freq. DOR by Cycle.1', 'Freq. DOG by Cycle.1']]
          data.catX.head()
          data.continuous.head()
          from sklearn.preprocessing import MinMaxScaler
          scaler = MinMaxScaler()
          data.continuous = scaler.fit_transform(data.continuous)
          data.continuous = scaler.transform(data.continuous)
          data.continuous = pd.DataFrame(data=data.continuous, columns=['Hour','minutes','H
           _M', 'Cycl_Length','SGN_Red_Time','SGN_Green_Time', 'Freq. AOR by Cycle','Freq. A
          OG by Cycle', 'Freq. DOR by Cycle', 'Freq. DOG by Cycle', 'RTOR Depart (assumptio
          n)', 'Freq. AOR by Cycle.1', 'Freq. AOG by Cycle.1', 'Freq. DOR by Cycle.1', 'Freq.
          DOG by Cycle.1'])
          data.continuous.head()
          data.norm=(data.continuous-data.continuous.min())/(data.continuous.max()-data.con
          tinuous.min())
          data.norm.head(2)
          data1 = pd.concat([data.norm, data.catX],axis=1)
          data1.head(2)
          <ipython-input-119-270207f77d5e>:1: UserWarning: Pandas doesn't allow columns to
          be created via a new attribute name - see https://pandas.pydata.org/pandas-docs/s
          table/indexing.html#attribute-access
```

data.catX= data[['StopBar LEFT Trigger', 'StopBar RtTh Trigger', 'Truck Presen t','Q_filled']]

<ipython-input-119-270207f77d5e>:2: UserWarning: Pandas doesn't allow columns to be created via a new attribute name - see https://pandas.pydata.org/pandas-docs/s table/indexing.html#attribute-access

data.continuous = data[['Hour','minutes','H_M', 'Cycl_Length','SGN_Red_Time','S GN_Green_Time', 'Freq. AOR by Cycle', 'Freq. AOG by Cycle', 'Freq. DOR by Cycl e','Freq. DOG by Cycle', 'RTOR Depart (assumption)', 'Freq. AOR by Cycle.1','Fre

q. AOG by Cycle.1', 'Freq. DOR by Cycle.1', 'Freq. DOG by Cycle.1']] <ipython-input-119-270207f77d5e>:12: UserWarning: Pandas doesn't allow columns to be created via a new attribute name - see https://pandas.pydata.org/pandas-docs/stable/indexing.html#attribute-access

data.norm=(data.continuous-data.continuous.min())/(data.continuous.max()-data.c
ontinuous.min())

Out[119]:

	Hour	minutes	Н_М	Cycl_Length	SGN_Red_Time	SGN_Green_Time	Freq. AOR by Cycle	Freq. AOG by Cycle
0	0.0	0.000000	0.000000	0.820153	0.820333	0.6875	0.0	0.00000
1	0.0	0.016949	0.000834	0.820372	0.820552	0.6875	0.0	0.14285
4								•

Splitting data into Training and Testing sets.

In [139]: from sklearn.model_selection import train_test_split
X= data1.iloc[0:,0:18]
y= data1["Q_filled"]

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.30, random_state=0)
X train.head()

Out[139]:

	Hour	minutes	н_м	Cycl_Length	SGN_Red_Time	SGN_Green_Time	AOR by	F A b
467	0.347826	0.118644	0.338757	0.820591	0.822743	0.1250	0.0	0
477	0.347826	0.593220	0.357947	0.820591	0.820771	0.7500	0.0	0
472	0.347826	0.254237	0.344180	0.820372	0.820552	0.6875	0.0	0
503	0.391304	0.050847	0.377555	0.820372	0.820552	0.6875	0.0	0
97	0.043478	0.677966	0.069670	0.820153	0.822524	0.1250	0.0	0

1. Logistic Regression

Accuracy of Logistic regression classifier on training set: 0.82 Accuracy of Logistic regression classifier on test set: 0.83

Z. Decision Tree

3. K-Nearest Neighbors

Accuracy of K-NN classifier on training set: 0.85 Accuracy of K-NN classifier on test set: 0.82

Accuracy of Decision Tree classifier on test set: 0.75

4. Linear Discriminant Analysis

Accuracy of LDA classifier on training set: 0.81 Accuracy of LDA classifier on test set: 0.82

5. Gaussian Naive Bayes

Accuracy of GNB classifier on training set: 0.52 Accuracy of GNB classifier on test set: 0.52

6. Support Vector Machine

Accuracy of SVM classifier on training set: 0.85 Accuracy of SVM classifier on test set: 0.85

7. NN-Multilayer Perception

Accuracy of MLP classifier on training set: 0.85 Accuracy of MLP classifier on test set: 0.85

WINNER MODEL -- MLP VS KNN VS SVM

3

0.67

MLP

```
In [218]:
          print('Confusion Matrix and Precision-Recall for MLP')
          from sklearn.metrics import classification report
          from sklearn.metrics import confusion matrix
          pred = clf.predict(X test)
          print(confusion_matrix(y_test, pred))
          print(classification_report(y_test, pred))
          Confusion Matrix and Precision-Recall for MLP
          [[160
                      0]
           [ 22 179
                      2]
           [ 0 28
                      4]]
                        precision recall f1-score
                                                       support
                             0.88
                                       0.95
                                                 0.91
                     1
                                                            168
                     2
                             0.83
                                       0.88
                                                 0.86
                                                            203
```

0.12

0.21

32

```
accuracy 0.85 403
macro avg 0.79 0.65 0.66 403
weighted avg 0.84 0.85 0.83 403
```

KNN

```
In [217]:
          #KNN
          print('Confusion Matrix and Precision-Recall for KNN')
           from sklearn.metrics import classification_report
           from sklearn.metrics import confusion_matrix
           pred2 = knn.predict(X test)
           print(confusion_matrix(y_test, pred2))
          print(classification_report(y_test, pred2))
          Confusion Matrix and Precision-Recall for KNN
          [[150 18
                       0]
           [ 21 174
                       8]
              0 24
                       8]]
                         precision
                                       recall f1-score
                                                          support
                      1
                              0.88
                                         0.89
                                                   0.88
                                                               168
                      2
                              0.81
                                         0.86
                                                   0.83
                                                               203
                      3
                              0.50
                                         0.25
                                                   0.33
                                                                32
                                                   0.82
                                                               403
               accuracy
             macro avg
                              0.73
                                         0.67
                                                   0.68
                                                               403
          weighted avg
                              0.81
                                         0.82
                                                   0.81
                                                               403
```

SVM

```
In [221]: #SVM
    print('Confusion Matrix and Precision-Recall for SVM')
    from sklearn.metrics import classification_report
    from sklearn.metrics import confusion_matrix
    pred3 = svm.predict(X_test)
    print(confusion_matrix(y_test, pred3))
    print(classification_report(y_test, pred3))
```

```
Confusion Matrix and Precision-Recall for SVM
[[160
        8
            01
 [ 22 180
            1]
    2 27
            3]]
               precision
                             recall f1-score
                                                 support
           1
                    0.87
                               0.95
                                          0.91
                                                      168
           2
                                                      203
                    0.84
                               0.89
                                          0.86
           3
                    0.75
                               0.09
                                          0.17
                                                      32
    accuracy
                                         0.85
                                                      403
   macro avg
                    0.82
                               0.64
                                          0.65
                                                      403
                    0.84
                               0.85
                                          0.83
                                                      403
weighted avg
```

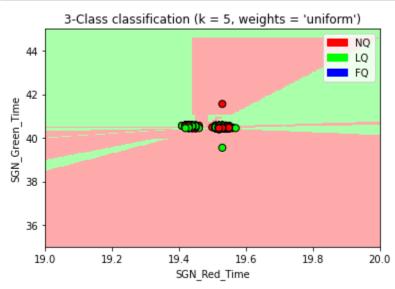
Comparing other scores for KNN vs MLP vs SVM

KNN wins as it balances the prediction for all three classes more correctly.

Drawing Decision Boundary

```
In [223]:
          import matplotlib.cm as cm
           from matplotlib.colors import ListedColormap, BoundaryNorm
           import matplotlib.patches as mpatches
           import matplotlib.patches as mpatches
          #X = fruits[['mass', 'width', 'height', 'color_score']]
          #y = fruits['fruit_label']
           #X train, X test, y train, y test = train test split(X, y, random state=0)
          #X1= X_train.to_numpy(X_train)
          #y1=y_train.to_numpy(y_train)
           def plot_Queue_knn(X_train, y_train, n_neighbors, weights):
               #XX1= pd.DataFrame(X train)
               #XXX= XX1.iloc[0:,0:18]
               #yy1= pd.DataFrame(y_train)
              #yyy= yy1.iloc[0:19]
               #XXX= XXX.to_numpy()
              #yyy= yyy.to_numpy()
              XXX= data[['SGN_Green_Time', 'SGN_Red_Time']]
               #XXX= X_train.iloc[0:,3:4]
               yyy= data['Q filled']
               #X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
              X_mat = XXX.to_numpy()
               y_mat = yyy.to_numpy()
               # Create color maps
               cmap light = ListedColormap(['#FFAAAA', '#AAFFAA', '#AAAAFF'])
               cmap bold = ListedColormap(['#FF0000', '#00FF00', '#0000FF'])
               knn2 = KNeighborsClassifier(n neighbors, weights=weights)
               knn2.fit(X_mat, y_mat)
               # Plot the decision boundary by assigning a color in the color map
               # to each mesh point.
              mesh_step_size = .01 # step size in the mesh
               plot_symbol_size = 50
              x_{min}, x_{max} = X_{mat}[:, 0].min() - 1, <math>X_{mat}[:, 0].max() + 1
              y_min, y_max = X_mat[:, 1].min() - 1, X_mat[:, 1].max() + 1
              xx, yy = np.meshgrid(np.arange(x_min, x_max, mesh_step_size),
                                    np.arange(y min, y max, mesh step size))
               Z = knn2.predict(np.c_[xx.ravel(), yy.ravel()])
               # Put the result into a color plot
```

```
Z = Z.reshape(xx.shape)
   plt.figure()
   plt.pcolormesh(xx, yy, Z, cmap=cmap_light)
   # Plot training points
   plt.scatter(X_mat[:, 0], X_mat[:, 1], s=plot_symbol_size, c=y, cmap=cmap_bold
, edgecolor = 'black')
   #plt.xlim(xx.min(), xx.max())
   plt.xlim(19, 20)
   plt.ylim(35, 45)
   patch0 = mpatches.Patch(color='#FF0000', label='NQ')
   patch1 = mpatches.Patch(color='#00FF00', label='LQ')
   patch2 = mpatches.Patch(color='#0000FF', label='FQ')
   #patch3 = mpatches.Patch(color='#AFAFAF', label='lemon')
   plt.legend(handles=[patch0, patch1, patch2])
   plt.xlabel('SGN_Red_Time')
   plt.ylabel('SGN_Green_Time')
   plt.title("3-Class classification (k = %i, weights = '%s')"
              % (n neighbors, weights))
   plt.show()
plot_Queue_knn(X_train,y_train, 5, 'uniform')
```



Drawing Nearest Neighbours VS Accuracy

We find k=5 to be optimum for modelling

```
In [264]: neighbors = np.arange(1,20)
    train_accuracy =np.empty(len(neighbors))
    test_accuracy = np.empty(len(neighbors))

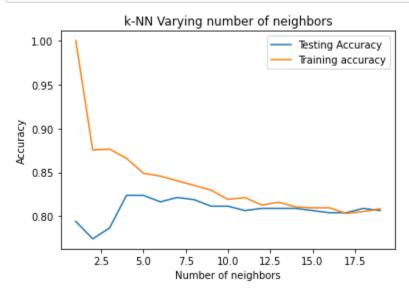
for i,k in enumerate(neighbors):
    #Setup a knn classifier with k neighbors
    knn = KNeighborsClassifier(n_neighbors=k)

#Fit the model
    knn.fit(X train, v train)
```

```
#Compute accuracy on the training set
train_accuracy[i] = knn.score(X_train, y_train)

#Compute accuracy on the test set
test_accuracy[i] = knn.score(X_test, y_test)

plt.title('k-NN Varying number of neighbors')
plt.plot(neighbors, test_accuracy, label='Testing Accuracy')
plt.plot(neighbors, train_accuracy, label='Training accuracy')
plt.legend()
plt.xlabel('Number of neighbors')
plt.ylabel('Accuracy')
plt.show()
```



Plotting ROC curve for LQ=2 and FQ=3

```
In [291]: # 2-class classification

from sklearn.model_selection import train_test_split
    from sklearn.metrics import roc_curve
    from sklearn.metrics import roc_auc_score

pred = knn.predict(X_test)
    pred_prob = knn.predict_proba(X_test)

# roc curve for classes
fpr = {}
    tpr = {}
    thresh ={}

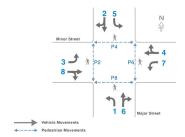
n_class = 3
```

PCD Generation and Other Data Mining Tool (adopted for and developed for CSCS800) $\frac{3MgN0MnEpU}{5MNNM}$ API Key bYnKMv9Hwyb3f46f76-a6ef-400c-b8a2-f7dd64169b8d Intersection ID Vernor Direction of Study Approach Description Analysis for Directed Study & Project for CSC5800 Date of Analysis 23-Nov Analysis by Event Codes of Interest
 Begin of Green
 Begin of Red
 Detector on
 Detector Off

 1
 10
 82
 81

4 SB Phase
1 Detection Channe Advanced Pulse
2 Detection Channe Stop-bar RT+TH Presence
5 Detection Channe Stop-bar LT Presence
7 Detection Channe Through Departuri Presence

Assumtions and Configurations
Red or Green
30 mph ~ 45 ft/sec
~150 ft advance pulse Detector
No residual queue assumed



Notes from Dec-3 2020 check for: should a Protected left term be required? LT Permit? We also have TMC for oposing traffic (allowing us to look at gap and ability to turn left)

Performance Measure
Data driven approach
Cross product HCM method vs. Actual data driven method.

Sensitivity Analysis is it with in a percentage? (~10%)

Training Set

We need to fill in the blanks (Asume Missing Data) for the cycles highlighted in yellow and marked as Missing or identify and ingrore the outliers (just as spikes in TMC/Queue when some data is missing) input attributes (features) are marked in green "use" on top groral flockimums with a balck "No" or "Do not Use"

Neural Network.

Test Set to follow Do we need a validation set as well?

Big questions for later:

Distinguish between Arival on Green (AOG) and Pass of Green (POG)

POG is when the weithvile is already in the queue but passes on green

AOG indicates that it arived and crosed on Green

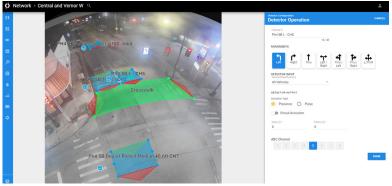
AOG indicates that it arived and crosed on Green

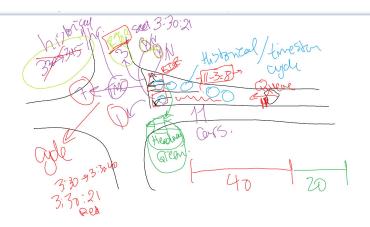
When the Vehicle arrives on Green or Red at the Channel box is very important to the decision on the Queue.

for Ch-21' there is much DOR, then the length of presence for the last AOR is important to identify wehicle status

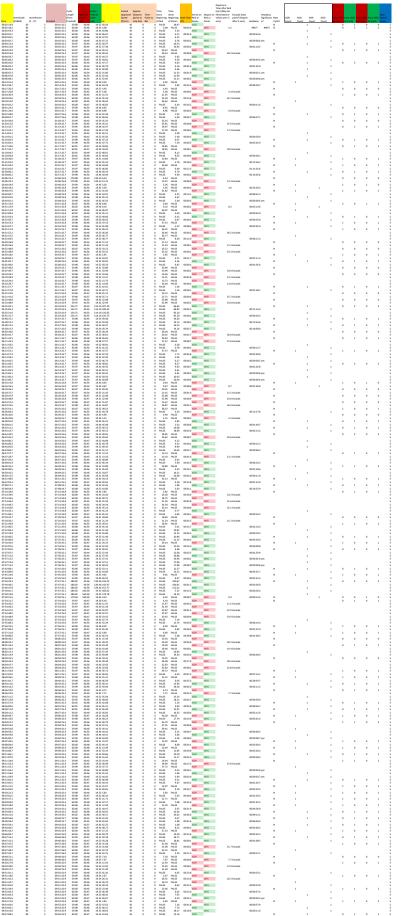
ere's a very credible corelation between the RTOR achieved from the TMC and that identified from movement on RED at CH2 detector that need to be investigated (LATER)







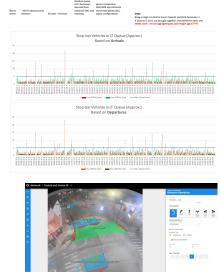
						Adds needs a Reduc Reduc 33 et et queue i queue queue		Reduces: Adds neutra Reduc Reduc SS es es Queue gueue gueue gueue			Need to check convisat ion with RTOR from the CHI detector g			
582	Time- stamp groups	Green & Red Info: Telemetry		quius	127 68	opitar FT (Ch- 5) 275 638	Stopmar Thru- Hight (Ch- 2)	620 1700	TMC 1000 462 1257 825	S	TMC Miller 492 1251	1214 Court	(Max no (Max	
t event. New "h" Faram Missing Cycle (4) 03037 Used	Day of week (2) Min of worth aday month aday Time H	time (brs.mi As Current decima (gclie And our minutes: I) Time Stant St	Current Signal Cycle RID Signal Current Greek Law Cycle (Previted to Trans in Greek Cycle Greek Greek Cycle Cycle Afficial Greek Cycle Cycle (Previted to Trans in Greek Cycle Cycle (Previted to Trans in Greek) Cycle (Previted to Trans to Trans Mincheld) Cycle (Previted to Trans to Trans Mincheld to Trans to	Queue - Advitor_Tr o identifier igger	Queue-Queue-	opikar Stopikar, Arma, Fred. Fred. Stock LEFT_Virig by by by by children ger Cycle Cycle Cycle Cycle Cycle Cycle	Stopker Stopker_k RT-th tth_Togg Identifier er	RTOR Free, Free, Free, Free, Congress of C	TINC Smin - New Freq. Freq. Freq. Freq. by Cycle (Right) Shoul (set) (Ped) Seet by by by See Cycle Cycle Cycle Cycle Cycle	by Count nt Vehicle by cliest-Vehicle cle Heavy Class- Vehicle x- Combin Pedezir Class- r ed ian Bicycle	Thic Hilbert Freq. Stee, Stee, Stee, Cook Cook Cook Cook Cook Cook Cook Coo	From From Count Which by Count Dy Count	potenti queue potenti al from al estimat red estimat QFilled ed Reducti ed (Catego Operar) on Queue) ries)	
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4 N	30 11 2 00615.5 30 11 2 00715.4 30 11 2 00815.4 30 11 2 00815.4	0 6.0 0.10 00:06:15.5 00 0 7.0 0.12 00:07:15.4 00 0 8.0 0.13 00:08:15.4 00	106553 98.98 40.45 19.52 107553 98.96 40.46 19.53 108553 98.96 40.46 19.52	0	NN NN NN NN		N 1	105 105 105 105 105 1 1 2 1 2 105 105 105 105 105		0 0 0 0 0 0 6 NN NN NN		90. 90. 90. 90. 90. 90. 90. 90. 90. 90.	0 0 NQ 2 2 LQ 0 0 NQ	
1	30 11 2 010155 30 11 2 011154 30 11 2 012154	0 100 0.17 00:10:15:5 00 0 110 0.18 00:11:15:4 00 0 120 0.20 00:12:15:4 00	110553 59.95 40.48 1932 111560 59.97 40.56 19.42 111560 60.02 40.57 19.44	0	NN NN NN NN NN NN	0 No.	0	1	Section Sect	1	NS NS NS NS NS NS NS NS	No.	0 0 NQ 0 0 NQ 0 0 NQ	
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4 N N	80 11 2 017:164 80 11 2 018:164 80 11 2 018:164 80 11 2 020:164	0 17.0 0.28 00.17.15.4 00 0 18.0 0.30 00.18.15.4 00 0 18.0 0.32 00.18.15.4 00	127558 98.99 40.45 1953 128558 60.00 40.47 1953 128558 98.99 40.47 1952	0 0	NN NN NN NN NN NN	N 0 0 0 0 0 N 1 1 0 0 1 0 506 506 506 506	N 1 N 1	0 1 0 0 1 3 3 0 3 0 50 50 50 50 50	N 4 0 0 0 1 N 0 0 1 0 1 NN NN NN NN NN	0 0 0 0 0 0 6 NN NN NN	N 0 2 0 0 N 2 0 0 0 NN 5N 5N 5N 5N	0 0 2 2 0 0 0 NN 0 1 2 2 0 0 0 NN 50 50 50 50 50 NN NN NN NN NN 50 50 50 50 NN NN NN NN NN	3 0 3 LQ 1 1 LQ 0 0 NQ	
4 N N	80 11 2 021154 80 11 2 022155 80 11 2 022155 80 11 2 028155	0 210 0.85 00:21:25.4 00 0 22.0 0.87 00:22:25.5 00 0 28.0 0.88 00:28:25.5 00	121553 60.09 40.56 1953 122553 60.01 40.46 1955 122553 60.00 40.46 1954	0	NN NN NN NN NN NN	0 505 505 505 505 0 505 505 505 505 0 505 505	0 0 N 1	NN NN NN NN NN NN NN NN NN NN 0 1 0 1 0	NN	6 NN NN NN 6 NN NN NN 6 NN NN NN 0 0 0	NN NN NN NN NN NN NN NN N 0 0 1 0	906 906 906 906 908 906	0 0 NQ 0 0 NQ 2 2 LQ	
4	80 11 2 02616.5 80 11 2 02616.6 80 11 2 02616.6 80 11 2 02716.6	0 250 0.40 00.2615.5 00 0 250 0.42 00.2515.5 00 0 260 0.43 00.2615.6 00 0 270 0.45 00.2715.6 00	125554 60.00 60.66 1958 126560 60.00 60.67 1958 126560 60.00 60.67 1958 127561 60.00 60.68 1952	0 0	NN NN NN NN NN NN	0 505 505 505 505 0 505 505 505 505 0 505 505	0	NN NN NN NN NN NN NN NN NN NN NN NN NN NN	NN NN NN NN NN NN NN NN NN NN NN NN NN N	6 NN NN NN 6 NN NN NN 6 NN NN NN	NN NN NN NN NN NN NN NN NN	506 506 506 506 506 506 506 506 506 506	0 0 NQ 0 0 NQ 0 0 NQ	
4 4	30 11 2 02815.6 30 11 2 02815.6 30 11 2 03015.5 30 11 2 03115.5	0 280 0.47 00.2815.6 00 0 280 0.48 00.2815.6 00 0 300 0.50 00.3015.5 00 0 310 0.52 00.3015.5 00	12856.0 59.98 40.46 1932 12956.0 59.99 40.46 1934 13056.1 59.99 40.57 19.42 13156.1 60.08 40.56 1932	0 0	NN NN NN NN NN NN	0 506 506 506 506 0 506 506 506 506 0 506 506 506 506 0 506 506 506 506	0	NN	NN NN NN NN NN NN NN NN NN NN NN NN NN N	6 NN NN NN 6 NN NN NN 6 NN NN NN 6 NN NN NN	NN NN NN NN NN NN NN NN NN NN NN NN NN N	9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	0 0 NQ 0 0 NQ 0 0 NQ 0 0 NQ	
4 N A	30 11 2 032156 30 11 2 038156 30 11 2 036156 30 11 2 036156	0 32.0 0.53 00.32.15.6 00 0 33.0 0.55 00.33.15.6 00 0 34.0 0.57 00.34.15.6 00	192561 60:01 60:47 1954 192561 59:99 60:45 1954 198561 59:98 60:46 1952	0 0	NN NN NN NN NN NN	0 506 506 506 506 0 506 506 506 506 0 506 506 506 506	N 1 0 N 1	0 0 1 0 1 NN NN NN NN NN 0 1 1 0 2	N 0 1 0 0 1 NN NN NN NN NN N 1 1 0 0 2	0 0 0 6 NN NN NN 0 0 0	N 0 0 0 1 NN 506 506 506 N 0 1 0 1	0 0 1 1 0 1 0 10 50 50 50 50 50 50 50 50 50 0 0 2 2 0 0 0 50 50 50 50 50 50 50 50 50	1 1 LQ 0 0 NQ 3 3 LQ	
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4 N N	30 11 2 08215.6 30 11 2 08615.7 30 11 2 08715.6 30 11 2 08815.6	0 48.0 0.72 00.48156.6 00 0 46.0 0.77 00.46156.7 00 0 47.0 0.78 00.47156.6 00 0 48.0 0.80 00.48156.6 00	186082 18008 17234 750 messg-2 186562 59.98 40.86 1952 187562 59.98 40.86 1958 188562 59.96 40.48 1952	0 0	NN NN NN NN NN NN	0 506 506 506 506 0 506 506 506 506 N I 0 I 0 I 0 506 506 506 506	0	No. No. No. No.	No. No.	6 NN NN NN 6 NN NN NN 0 0 0 6 NN NN NN	NN 506 506 506 NN 506 506 506 N 0 0 0 0 NN 506 506 506	\$50. \$50. \$50. \$50. \$50. \$50. \$50. \$50.	0 0 NQ 0 0 NQ 1 -1 0 NQ 0 0 NQ	
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1	30 11 2 127.15.8 30 11 2 128.15.7 30 11 2 128.15.7	1 270 145 0127:58 00 1 280 147 0128:57 00 1 280 148 0128:57 00	127562 59.96 60.46 19.53 128562 59.97 60.45 19.52 129562 60.08 60.46 19.56	0	NN NN NN NN NN NN	0 505 505 505 505 0 505 505 505 505 0 505 505	0	NK NX NX NX NX NX NX NX NX NX NX NX NX NX NX	NN NN NN NN NN NN NN NN NN NN NN NN NN N	6 NN NN NN 6 NN NN NN 6 NN NN NN	NN NN NN NN NN NN NN NN NN NN NN NN NN N	\$06 \$06 \$06 \$08 \$08 \$08 \$08 \$08 \$08 \$08 \$08 \$08 \$08	0 0 NQ 0 0 NQ 0 0 NQ	
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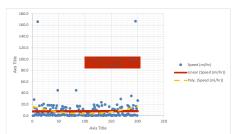
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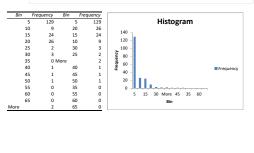


s=d/t 20.64 ft/sec 14.0727 mph Make sure the Signal is green when then moved (Eliminatirn RTOR)
Maybe: Speed measurement with differnet ways (validation) - but the 5 10 15 20 25 30 35 40 45 50 55 60 65

Can we add this to the calc for approximate speed? Can the TMc be used to eliminate RTOR movement?

Has to be speed when Signal is Green - for find beginning of Red and only account for through movement in that cycle





datetime bin entry_	dir_exit_dir_na classificati	to look the money when the	Through Dight Left Tat	Cycle Tre	(Red Estimated Ap	Crossing on Red or							Count by Vehicle			Count by
name_oni	e me on confide	nce laneID time movement volume	Thiodyn Right Cent Toe	Provided Provided Sect Outle Sect	Movement (pr	ulse to to mid- Beginning Beginning Green New	COR Right COG Right COR Thru Count Count Count	COG Thru COR Left COG Left COR Count Count Count Count	R Ped COG Ped (R	req. COR Freq. COG light) by (Right) by cycle Cycle	Freq. COR Freq. COG Freq. COR Freq. COG (thru) by (Thru) by (Left) by (Left) by Cycle Cycle Cycle	Freq. COR Freq. COG Co (Ped) by (Ped) by Ve Cycle Cycle Cla	unt by Class - Vehicle Heavy Art	hicle Class - ticulated Vehi	cle Class - Vehicle k Bus	vehicle Class - Class - Pedestrian
2020-11-30 00:02:19:000-05:00 N 2020-11-30 00:02:42:000-05:00 N	E Light W Light	00:02:19.0 left 00:02:42.0 right 00:02:42.0 thru 00:04:14.0 right 00:04:14.0	1 1	1 88:82:15.5 60.00 40.45 19.54 1 88:82:15.5 60.00 40.46 19.54 1 88:82:15.5 60.00 40.46 19.54 1 88:82:15.5 59.97 40.44 19.52 1 88:84:15.4 59.97 40.45 19.52		37 1.681818 3.54 FALSE COR N	1	1	-	1 0	0 1 1 0	0 0	3.00 0.00	0.00	0.00 0	.00 0.00
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2020-11-30 00:05:03:000-05:00 N 2020-11-30 00:06:07:000-05:00 N	S Light W Light	88:85:83.8 thru 88:86:87.8 right	1 1	1 08:04:15.4 59.97 40.45 19.52 1 08:05:15.4 60.06 40.54 19.52	47.57 44 51.60 22	37 0.840909 FALSE 7.12 COG 23 1.045455 FALSE 11.06 COG N	1	1		0 2	0 0 0		2.00 0.00			0.00
2020-11-30 00:06:11:000-05:00 N 2020-11-30 00:07:34:000-05:00 N	W Light W Light	88:86:11.8 right 88:87:34.8 right	1 1	1 08:05:15.4 60.06 40.54 19.52 1 08:07:15.4 59.96 40.45 19.51	55.60 22 18.56 22	23 1.045455 18.56 FALSE COR N	1			1 1	0 1 0 0	0 0	3.00 0.00			0.00
2020-11-30 00:08:11.000-05:00 N 2020-11-30 00:08:13.000-05:00 N 2020-11-30 00:15:00.000-05:00 N	W Light S Light	88:88:11.0 right 88:88:13.0 thru 88:15:88.0 left	1 1	1 08:07:15.4 59.96 40.44 19.53 1 08:07:15.4 59.96 40.44 19.53 1 08:14:15.4 59.99 40.45 19.54	55.56 22 57.56 44 44.56 22	23 1.045455 FALSE 15.12 COG 37 0.840909 FALSE 17.12 COG 37 1.681818 FALSE 4.11 COG N	1	1						0.00	0.00 0.	0.00
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2020-11-30 00:41:28.000-05:00 N 2020-11-30 00:48:04.000-05:00 N	W Light E Light	88:41:81.8 right 88:41:28.8 right 88:48:84.8 left	i i	1 08:48:15.6 60.08 40.54 19.54 1 08:41:15.7 59.99 40.54 19.44 1 08:47:15.6 59.98 40.45 19.53 1 08:49:15.6 59.96 40.55 19.42	45.42 22 12.34 22 48.35 22 47.43 22	37 0.840909 FALSE 18.85 COG N 23 1.045455 FALSE 4.88 COG N 23 1.045455 12.34 FALSE COR N 37 1.681818 FALSE 7.90 COG N 23 1.045455 FALSE 6.88 COG N	1	i	<u> </u>	1 0	0 0 0 0	0 0	1.00 0.00 1.00 0.00	0.00 0.00 0.00 0.00	0.00 0. 0.00 0. 0.00 0.	0.00 0.00 0.00 0.00
2020-11-30 00:50:03.000-05:00 N 2020-11-30 00:52:33.000-05:00 N	w ugnt	00:50:03.0 right 00:52:33.0 CCW	1 1	1 08:49:15.6 59.96 40.55 19.42 0 1 08:52:15.6 59.96 40.46 19.50	47.43 22 17.38	23 1.046455 1.234 FALSE COR N 37 1.681818 FALSE 7.00 COG N 23 1.045455 FALSE 6.88 COG N 37 0.840009 FALSE 4.89 COG N 37 0.840009 FALSE 4.89 COG N 37 0.140005 FALSE 4.89 COG N 23 1.046555 FALSE 1.84 COG N 23 1.04655 5 40.24 FALSE COR N 23 1.04655 8.37 FALSE COR N 37 0.8455 8.37 FALSE COR N	1		0	0 1	0 0 0 0	0 0	1.00 0.00 0.00 0.00	0.00	0.00 0.	0.00
2020-11-30 005-03-000-05-00 N 2020-11-30 005-23-30-00-05-00 N 2020-11-30 01:00-01:000-05-00 N 2020-11-30 01:00-01:000-05-00 N 2020-11-30 01:005-24-000-05-00 N 2020-11-30 01:005-24-000-05-00 N	N Pedestrian S Light W Light W Light	00:50:03.0 right 00:52:33.0 CCW 01:00:01.0 thru 01:02:12.0 right 01:03:55.6 right 01:05:24.0 right	1 1	1 08:49:15.6 59.96 40.55 19.42 19.50 1 08:59:15.6 60.00 40.46 19.54 1 01:01:15.6 60.00 40.46 19.54 1 01:01:15.7 59.99 40.45 19.54 1 01:03:15.7 59.99 40.45 19.54 1 01:03:15.7 59.99 40.45 19.54 1 01:05:15.6 60.00 40.56 19.44	45.35 44 56.37 22 40.34 22	23 1.045455 FALSE 15.84 COG N 23 1.045455 40.34 FALSE COR N	1	1		0 1	0 0 0 0	0 0	1.00 0.00 1.00 0.00	0.00 0.00 0.00 0.00 0.00	0.00 0. 0.00 0. 0.00 0. 0.00 0. 0.00 0. 0.00 0.	.00 0.00
	W Light S Light		1 1 1 1		48.35 22 47.43 22 17.38 45.35 44 56.37 22 40.34 22 8.37 22 45.34 44 46.29 44	37 U.84U9U9 FALSE 4.81 COG N	1	1		1 0 0 0	0 0 0 0	0 0	1.00 0.00 1.00 0.00	0.00	0.00 0	.00 0.00 1.00 0.00
2020-11-30 01:13:02:000-05:00 N 2020-11-30 01:14:02:000-05:00 N 2020-11-30 01:16:05:000-05:00 N	S Light S Light S Light	81:13:82.8 thru 81:14:82.8 thru 81:16:85.8 thru	1 1	1 01:12:15.7 59.99 40.45 19.54 1 01:13:15.7 59.95 40.42 19.52	46.28 44 46.29 44 49.32 44	37 0.840909 FALSE 5.87 COG N		1 1	<u> </u>	0 0	0 1 0 0	0 0	1.00 0.00 1.00 0.00	0.00	0.00 0. 0.00 0.	0.00
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2020-11-30 01:43:02.000-05:00 N 2020-11-30 01:46:04.000-05:00 N 2020-11-30 01:46:14.000-05:00 N	W Light W Light S Light S Light S Light S Light S Light S Light U Light W Light E Light S Light S Light S Light S Light U Light S Light S Light U Light	81:43:82.8 right 81:46:84.8 thru 81:46:14.8 thru	. 1 1 1 1 1	1 01:18:15.7 90.97 40.44 19.53 1 01:19:15.7 90.00 40.46 19.55 1 01:19:15.7 99.97 40.45 19.52 1 01:42:15.6 90.05 40.54 19.53 1 01:45:15.6 99.98 40.45 19.53 1 01:45:15.6 99.98 40.45 19.53 1 01:45:15.5 99.98 40.45 19.53 1 01:45:15.5 190.98 40.45 19.53 1 01:45:15.5 190.98 40.45 19.53	49.32 44 51.27 44 55.26 22 46.29 44 45.27 22 46.40 22 48.38 44 58.38 44 46.44 22 56.53 22 47.50 44 46.42 44 56.31 44	23 1.04645 FAISE 15.82 COG N 7.2 O A00909 FAISE 5.83 COG N 7.2 O A00909 FAISE 5.83 COG N 7.2 O A00909 FAISE 5.83 COG N 7.2 O A00909 FAISE 7.93 COG N 7.2 O A00909 FAISE 7.2 O A00909 FA	1	1 1		0 0	0 2 0 0	0 0	2.00 0.00			0.00
2020-11-30 01-46:04-000-05:00 N 2020-11-30 01-46:14-000-05:00 N 2020-11-30 01-51:02-000-05:00 N 2020-11-30 01-55:12-000-05:00 N	E Light W Light	81:46:14.0 thru 81:51:82.0 left 81:55:12.0 right	1 1 1 1	1 01:45:15.6 59.98 40.45 19.53 1 01:59:15.6 59.98 40.46 19.53 1 01:59:15.6 59.98 40.46 19.53 1 01:54:15.5 180.06 40.55 139.51	46.44 22 56.53 22	37 1.681818 FALSE 5.98 COG N 23 1.045455 FALSE 15.97 COG N	1	1		0 0 0 1	0 0 0 1	0 0	1.00 0.00 1.00 0.00	0.00	0.00 0. 0.00 0.	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
2020-11-30 02:01:03.000-05:00 N 2020-11-30 02:06:02.000-05:00 N 2020-11-30 02:27:12:000-05:00 N	S Light S Light	82:81:83.8 thru 82:86:82.8 thru 82:27:12.8 thru	1 1	1 02:00:15.5 59.99 40.47 19.52 1 02:05:15.6 59.98 40.46 19.52 1 02:26:15.7 60.00 40.46 19.53	47.50 44 46.42 44	37 0.840909 FALSE 7.03 COG N 37 0.840909 FALSE 5.96 COG N 37 0.840909 FALSE 15.84 COG N		1 1		0 0	0 1 0 0	0 0	1.00 0.00 1.00 0.00	0.00	0.00 0. 0.00 0. 0.00 0.	1.00 0.00
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2020-11-30 03:47:01.000-05:00 N 2020-11-30 03:49:02.000-05:00 N 2020-11-30 03:51:16.000-05:00 N	S Light E Light	03:47:01.0 thru 03:49:02.0 left 03:51:16.0 thru	1 1	1 03:46:15.8 59.97 40.45 19.52 1 03:48:15.8 59.98 40.56 19.42 1 03:51:15.8 60.02 40.46 19.56	45.17 44 46.21 22 0.22 44			. 1		0 0	0 1 0 0	0 0	1.00 0.00 1.00 0.00	0.00 0.00 0.00	0.00 0. 0.00 0. 0.00 0.	0.00 0.00 0.00 0.00
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2020-11-30 03:55:00:000-05:00 N 2020-11-30 03:55:02:000-05:00 N	W Light S Light	83:53:61.6 thru 83:55:08.6 right 83:55:08.6 thru 83:55:41.6 right 84:96:83.6 thru 84:88:01.6 right 84:11:52.6 right	1 1	1 83:54:15.8 5998 40.46 19.53 1 83:54:15.8 5998 40.46 19.53 1 83:54:15.8 5998 40.46 19.53 1 83:59:15.7 5999 40.45 19.55 1 64:69:15.8 60.00 40.47 19.53 1 64:67:15.8 5998 40.45 19.53 1 64:47:15.8 5998 40.45 19.53 1 64:47:15.8 60.00 40.55 19.45	44.24 22 46.24 44	37 0.840009 FALSE 4.76 COG N 23 1.045455 FALSE 3.79 COG N 37 0.840009 FALSE 5.79 COG N 37 0.840009 FALSE 5.79 COG N 37 0.840009 FALSE 6.76 COG N 37 0.840009 FALSE 6.76 COG N 32 1.045455 FALSE 6.76 COG N 32 1.045455 36.24 FALSE COB N 32 1.045455 36.24 FALSE COB N 32 1.045455 22.31 FALSE COB N 37 0.840009 FALSE COB N 38 0.740009 FALSE COB N 38 0.74	1	1		0 1	0 1 0 0	0 0	2.00 0.00			0.00
2020-11-30 03:55:00.000-05:00 N 2020-11-30 03:55:00.000-05:00 N 2020-11-30 03:59:41.000-05:00 N 2020-11-30 04:06:03.000-05:00 N 2020-11-30 04:06:01.000-05:00 N 2020-11-30 04:06:01.000-05:00 N	W Light S Light W Light	83:59:41.0 nght 84:86:83.0 thru 84:88:81.0 right	1 1 1 1	1 03:54:15.8 59.98 40.46 19.33 1 03:59:15.7 59.99 40.45 19.55 1 04:07:15.8 60.00 40.47 19.53 1 04:07:15.8 59.98 40.45 19.33 1 04:11:15.8 60.00 40.55 19.45	47.23 44 45.25 22	23 1.045455 25.27 FALSE COR N 37 0.840909 FALSE 6.76 COG N 23 1.045455 FALSE 4.80 COG N	1 1	1		0 0	0 1 0 0	0 0	1.00 0.00 1.00 0.00 1.00 0.00	0.00 0.00 0.00 0.00 0.00	0.00 0. 0.00 0. 0.00 0. 0.00 0. 0.00 0. 0.00 0.	0.00
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2020-11-30 04:23:38.000-05:00 N 2020-11-30 04:23:41.000-05:00 N 2020-11-30 04:28:04.000-05:00 N	W Light E Light	84:23:38.0 right 84:23:41.0 right 84:28:84.0 left	1 1	1 84:23:15.7 59.95 40.55 19.40 1 84:23:15.7 59.95 40.55 19.40 1 84:27:15.7 59.96 40.44 19.52	25.31 22 48.32 22	23 1.045455 22.31 FALSE COR N 23 1.045455 25.31 FALSE COR 37 1.681818 FALSE 7.88 COG N	1	1	<u> </u>	0 0	0 0 0 1		1.00 0.00			
2020-11-30 04:32:05:000-05:00 N 2020-11-30 04:32:07:000-05:00 N	E Light W Light	04:32:05.0 left 04:32:07.0 right 04:39:01.0 right	1 1	1 84:31:15.7 59.99 40.47 19.52 1 84:31:15.7 59.99 40.47 19.52 1 84:38:15.7 59.97 40.45 19.53	49.30 22 51.30 22 45.32 22	37 1.681818 FALSE 8.83 COG N 23 1.045455 FALSE 10.83 COG	1	i	<u> </u>	0 1	0 0 0 1	0 0	2.00 0.00	0.00		0.00
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2020-11-30 05:02:44.000-05:00 N 2020-11-30 05:04:09.000-05:00 N 2020-11-30 05:06:03.000-05:00 N	W Light W Light	85:82:44.0 right 85:84:89.0 right 85:86:83.0 right 85:18:31.0 left	1 1 1 1	1 05:02:15.7 59.98 40.54 19.43 1 05:03:15.7 60.00 40.48 19.52 1 05:05:15.6 60.05 40.54 19.51 1 05:10:15.7 59.98 40.45 19.52	53.34 22 47.36 22 15.30 22		1 1			0 1 0 1	0 0 0 0	0 0	1.00 0.00 1.00 0.00	0.00	0.00 0. 0.00 0. 0.00 0. 0.00 0.	0.00 0.00 0.00 0.00
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