Machine Learning 1 WS18/19

Submission for Exercise Sheet 9

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Exercise Sheet 9

$$|a\rangle \wedge (\omega,\theta,\alpha) = \frac{1}{2}\omega^{T}\omega - \sum_{i=1}^{N} \alpha_{i}(y_{i}(\omega^{T}x_{i}+\theta)-1)$$

b) Primal Problem is min max 1 (w, 0, d)

Dual Problem is max min (w.O.d)

Express $\underset{w,\theta}{\text{min}} \Lambda(w,\theta,\alpha)$ in terms of d:

$$\int_{\Omega} \sqrt{|\omega,\theta,d\rangle} = \omega - \sum_{i=1}^{N} d_i y_i \chi_i = 0 \Rightarrow \omega = \sum_{i=1}^{N} d_i y_i \chi_i = 0$$

$$\frac{\partial}{\partial \theta} \sqrt{(\omega,\theta,d)} = \sum_{i=1}^{N} d_i y_i = 0$$

$$\frac{\partial}{\partial \theta} \sqrt{(\omega,\theta,d)} = \sum_{i=1}^{N} d_i y_i = 0$$

$$\frac{\partial}{\partial \theta} \sqrt{(\omega,\theta,d)} = \sum_{i=1}^{N} d_i y_i = 0$$

Ratting (1) into Alw, O, d):

$$\min_{\omega,\theta} \Lambda(\omega,\theta,\lambda) =$$

 $= \Lambda(\omega^*(\omega), \theta^*(\omega), \lambda)$

$$=\frac{1}{2}\left(\sum_{i=1}^{N}d_{i}y_{i}\chi_{i}\right)\left(\sum_{j=1}^{N}d_{j}y_{j}\chi_{j}\right)-\sum_{i=1}^{N}d_{i}y_{i}\left(\sum_{j=1}^{N}d_{j}y_{j}\chi_{j}\right)\chi_{i}-\hat{\theta}\omega\right)\sum_{i=1}^{N}d_{i}y_{i}+\sum_{i=1}^{N}d_{i}$$

$$=0 \text{ by } \textcircled{2}$$

$$= \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} a_i a_j y_i y_j x_i^{T} x_j - \sum_{i=1}^{n} \sum_{j=1}^{n} a_i a_j y_i y_j x_i^{T} x_j + \sum_{i=1}^{n} a_i$$

$$=\sum_{i=1}^{N} \alpha_i - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j y_i y_j x_i^{\mathsf{T}} x_j$$

2) From ①: Dual: $\max_{X} \sum_{i=1}^{N} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j})$ Subject to $\alpha_{i} \geq 0$ for $1 \leq i \leq N$ Since $\max_{X} \sum_{i=1}^{N} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j})$ $= \underset{\alpha}{\operatorname{argmax}} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{i}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{i} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{i}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{i} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{i}) - \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} y_{j} K(x_{i}, x_{i}) - \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} y_{j} K(x_{i}, x_{i}) - \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i})$ $= \underset{\alpha}{\operatorname{argmin}} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i}, x_{i}) + \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{j} K(x_{i},$

[P]; = y:y; K(x;,x;) q =-11 = (-1,-1,...,-1)

G := -I $h := \vec{0} = (0, \dots, 0)^T$

 $A := (y_1, y_2, ..., y_N)$ b := 0

The output of is exactly the of we are looking for

Programming Part

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1 Support Vector Machines

In this exercise sheet, you will experiment with training various support vector machines on a subset of the MNIST dataset composed of digits 5 and 6. First, download the MNIST dataset from http://yann.lecun.com/exdb/mnist/, uncompress the downloaded files, and place them in a data/ subfolder. Install the optimization library CVXOPT (python-cvxopt package, or directly from the website www.cvxopt.org). This library will be used to optimize the dual SVM in part A.

1.1 Part A: Kernel SVM and Optimization in the Dual

We would like to learn a nonlinear SVM by optimizing its dual. An advantage of the dual SVM compared to the primal SVM is that it allows to use nonlinear kernels such as the Gaussian kernel, that we define as:

$$k(x, x') = \exp\left(-\frac{\|x - x'\|^2}{\sigma^2}\right)$$

The dual SVM consists of solving the following quadratic program:

$$\max_{\alpha} \sum_{i=1}^{N} \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j k(x_i, x_j)$$

subject to:

$$0 \le \alpha_i \le C$$
 and $\sum_{i=1}^N \alpha_i y_i = 0$.

Then, given the alphas, the prediction of the SVM can be obtained as:

$$f(x) = \begin{cases} 1 & \text{if } \sum_{i=1}^{N} \alpha_i y_i k(x, x_i) + \theta > 0 \\ -1 & \text{if } \sum_{i=1}^{N} \alpha_i y_i k(x, x_i) + \theta < 0 \end{cases}$$

where

$$\theta = \frac{1}{\#SV} \sum_{i \in SV} \left(y_i - \sum_{j=1}^N \alpha_j y_j k(x_i, x_j) \right)$$

and SV is the set of indices corresponding to the unbound support vectors.

1.1.1 Implementation (25 P)

We will solve the dual SVM applied to the MNIST dataset using the CVXOPT quadratic optimizer. For this, we have to build the data structures (vectors and matrices) to must be passed to the optimizer.

- *Implement* a function gaussianKernel that returns for a Gaussian kernel of scale σ , the Gram matrix of the two data sets given as argument.
- Implement a function getQPMatrices that builds the matrices P, q, G, h, A, b (of type cvxopt.matrix) that need to be passed as argument to the optimizer cvxopt.solvers.qp.
- *Run* the code below using the functions that you just implemented. (It should take less than 3 minutes.)

```
In [8]: import utils,numpy,cvxopt,cvxopt.solvers
        Xtrain,Ttrain,Xtest,Ttest = utils.getMNIST56()
        cvxopt.solvers.options['show_progress'] = False
        def gaussianKernel(X, XP, Scale):
            distance = -2 * numpy.dot(X, XP.T) + numpy.sum(XP ** 2, axis=1) + numpy.sum(X ** 2)
            K = numpy.exp(-distance / (Scale ** 2))
            return K
        def getQPMatrices(Ktrain, Ttrain, C):
            n = len(Ttrain)
            P = cvxopt.matrix(numpy.outer(Ttrain, Ttrain) * Ktrain)
            q = cvxopt.matrix(numpy.zeros(n)-1)
            A = cvxopt.matrix(Ttrain, (1, n))
            b = cvxopt.matrix(0.0)
            G = cvxopt.matrix(numpy.vstack((numpy.diag(numpy.repeat(-1, n)), numpy.identity(n)
            h = cvxopt.matrix(numpy.hstack((numpy.zeros(n), numpy.repeat(C, n))))
            return P, q, G, h, A, b
        for scale in [10,30,100]:
            for C in [1,10,100]:
                # Prepare kernel matrices
                ### TODO: REPLACE BY YOUR OWN CODE
                Ktrain = gaussianKernel(Xtrain, Xtrain, scale)
                Ktest = gaussianKernel(Xtest, Xtrain, scale)
                ###
                # Prepare the matrices for the quadratic program
                ### TODO: REPLACE BY YOUR OWN CODE
```

```
P,q,G,h,A,b = getQPMatrices(Ktrain,Ttrain,C)
               ###
               # Train the model (i.e. compute the alphas)
               alpha = numpy.array(cvxopt.solvers.qp(P,q,G,h,A,b)['x']).flatten()
               # Get predictions for the training and test set
               SV = (alpha>1e-6)
               uSV = SV*(alpha<C-1e-6)
               theta = 1.0/sum(uSV)*(Ttrain[uSV]-numpy.dot(Ktrain[uSV,:],alpha*Ttrain)).sum()
               Ytrain = numpy.sign(numpy.dot(Ktrain[:,SV],alpha[SV]*Ttrain[SV])+theta)
               Ytest = numpy.sign(numpy.dot(Ktest [:,SV],alpha[SV]*Ttrain[SV])+theta)
               # Print accuracy and number of support vectors
               Atrain = (Ytrain==Ttrain).mean()
               Atest = (Ytest ==Ttest ).mean()
               print('Scale=%3d C=%3d SV: %4d Train: %.3f Test: %.3f'%(scale,C,sum(SV),At:
           print('')
Scale= 10 C= 1 SV: 1000 Train: 1.000 Test: 0.937
Scale= 10 C= 10 SV: 1000 Train: 1.000 Test: 0.937
Scale= 10 C=100 SV: 1000 Train: 1.000 Test: 0.937
Scale= 30 C= 1 SV: 254 Train: 1.000 Test: 0.985
Scale= 30 C= 10 SV: 274 Train: 1.000 Test: 0.986
Scale= 30 C=100 SV: 256 Train: 1.000 Test: 0.986
Scale=100 C= 1 SV: 317 Train: 0.973 Test: 0.971
Scale=100 C= 10 SV: 159 Train: 0.990 Test: 0.975
Scale=100 C=100 SV: 136 Train: 1.000 Test: 0.975
```

1.1.2 Analysis (10 P)

• *Explain* which combinations of parameters σ and C lead to good generalization, underfitting or overfitting?

With large σ or variance of the gaussian kernel, the border curve we obtain has less curvature, while small C may also prevents the function from reaching optimal value when the optimal alpha would have been bigger. Therefore, σ and small C lead to underfitting. On the other hand, the border curves have greater versatility with small σ , which leads to overfitting. With $\sigma=30$ and C=10 or 100, we seem to get the best accuracy in test data set and it is a sign of good generalization.

• *Explain* which combinations of parameters *σ* and *C* produce the fastest classifiers (in terms of amount of computation needed at prediction time)?

The number of computations for θ depends on the number of support vectors. We can see that the number of support vectors decreases when σ or C increases. It is because we tend to have more samples lying close to the border line in better fitted model.

1.2 Part B: Linear SVMs and Gradient Descent in the Primal

The quadratic problem of the dual SVM does not scale well with the number of data points. For large number of data points, it is generally more appropriate to optimize the SVM in the primal. The primal optimization problem for linear SVMs can be written as

$$\min_{w,\theta} ||w||^2 + C \sum_{i=1}^N \xi_i \quad \text{where} \quad \forall_{i=1}^N : y_i(w \cdot x_i + \theta) \ge 1 - \xi_i \quad \text{and} \quad \xi_i \ge 0.$$

It is common to incorporate the constraints directly into the objective and then minimizing the unconstrained objective

$$J(w,\theta) = ||w||^2 + C \sum_{i=1}^{N} \max(0, 1 - y_i(w \cdot x_i + \theta))$$

using simple gradient descent.

1.2.1 Implementation (15 P)

- *Implement* the function J computing the objective $J(w, \theta)$
- *Implement* the function DJ computing the gradient of the objective $J(w, \theta)$ with respect to the parameters w and θ .
- *Run* the code below using the functions that you just implemented. (It should take less than 1 minute.)

```
In [5]: import utils, numpy
        C = 10.0
        lr = 0.001
        def J(w, theta, C, X, T):
             Xi = numpy.matmul(w, numpy.transpose(X))
             Xi = [xi + theta for xi in Xi]
             Xi = T * Xi
            Xi = [max(0, 1 - xi) \text{ for } xi \text{ in } Xi]
             J = sum (w * w) + C * sum (Xi)
             return J
        def DJ(w, theta, C, X, T):
             dw = 2 * w
             dtheta = 0
             for i in range (len(T)):
                 if T[i] * (sum(w * X[i]) + theta) <= 1:</pre>
                     dw = dw - C * T[i] * X[i]
                     dtheta = dtheta - C * T[i]
```

return dw, dtheta

It= 0

It= 5

It= 10 It= 15

Tt=20

It= 25

It=30

It=35

It= 40 It= 45

It=50

It=55

It= 60

It=65

It=70

It=75

It= 80

```
Xtrain,Ttrain,Xtest,Ttest = utils.getMNIST56()
n,d = Xtrain.shape
w = numpy.zeros([d])
theta = 1e-9
for it in range(0,101):
    # Monitor the training and test error every 5 iterations
    if it%5==0:
        Ytrain = numpy.sign(numpy.dot(Xtrain,w)+theta)
        Ytest = numpy.sign(numpy.dot(Xtest ,w)+theta)
        ### TODO: REPLACE BY YOUR OWN CODE
        Obj
              = J(w,theta,C,Xtrain,Ttrain)
        ###
        Etrain = (Ytrain==Ttrain).mean()
        Etest = (Ytest ==Ttest ).mean()
        print('It=%3d
                     J: %9.3f Train: %.3f Test: %.3f'%(it,Obj,Etrain,Etest))
    ### TODO: REPLACE BY YOUR OWN CODE
    dw,dtheta = DJ(w,theta,C,Xtrain,Ttrain)
    ###
    w = w - lr*dw
    theta = theta - lr*dtheta
J: 10000.000 Train: 0.471 Test: 0.482
              Train: 0.961 Test: 0.958
 J: 68520.417
J: 49918.674 Train: 0.973 Test: 0.961
 J: 37473.229 Train: 0.973 Test: 0.963
J: 28590.129 Train: 0.974 Test: 0.965
 J: 21746.877 Train: 0.977 Test: 0.967
 J: 16987.200 Train: 0.980 Test: 0.968
J: 13646.095 Train: 0.986 Test: 0.967
 J: 11187.127 Train: 0.986 Test: 0.967
 J:
    9182.940 Train: 0.991 Test: 0.967
    7692.273 Train: 0.990 Test: 0.968
    6437.609 Train: 0.988 Test: 0.966
 J:
    5253.071 Train: 0.995 Test: 0.966
 J:
 J: 4515.520 Train: 0.992 Test: 0.967
    4016.851 Train: 0.996 Test: 0.966
 J:
    3647.983 Train: 0.997 Test: 0.965
 J:
 J: 3497.204 Train: 0.998 Test: 0.966
```

```
It= 85    J: 3404.280    Train: 1.000    Test: 0.966
It= 90    J: 3336.804    Train: 1.000    Test: 0.966
It= 95    J: 3270.665    Train: 1.000    Test: 0.966
It=100    J: 3205.837    Train: 1.000    Test: 0.966
```

In []: