Parallel I/O — II and SLURM

Lecture 17

March 26, 2025

Revision of MPI Independent I/O

Write to Different Files

Independent writes

```
#include "mpi.h"
#include <stdio.h>
#define BUFSIZE 1000
int main(int argc, char *argv[]) {
        int i, myrank, buf[BUFSIZE];
        char filename[128];
        FILE *myfile;
        MPI_Init(&argc, &argv);
        MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
        sprintf(filename, "testfile.%d", myrank);
        myfile = fopen(filename, "w");
        for (i=0; i<BUFSIZE; i++) {</pre>
           buf[i] = myrank + i;
           fprintf(myfile, "%d ", buf[i]);
        fprintf(myfile, "\n");
        fclose(myfile);
        MPI_Finalize();
        return 0;
```

Simple Parallel I/O Code – Shared File

```
MPI_File fh
file size per proc = FILESIZE / nprocs
MPI File open (MPI COMM WORLD, "/scratch/largefile",
                                                            Returns file handle
MPI MODE RDONLY, MPI INFO_NULL, &fh)
MPI File seek (fh, rank*file size per proc, MPI SEEK SET)
MPI File read (fh, buffer, count, MPI INT, status)
MPI File close (&fh)
```

3

Parallel Read using Explicit Offset

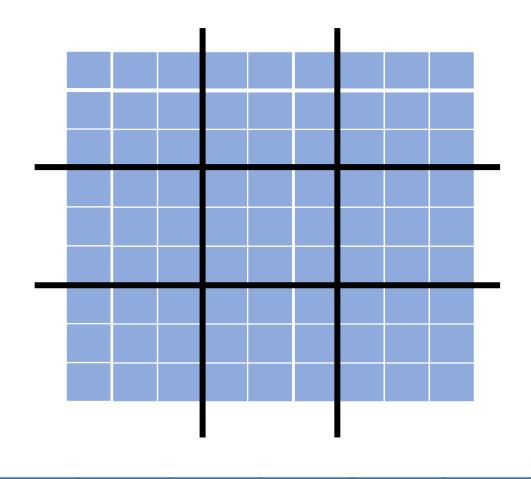
```
MPI_Offset offset = (MPI_Offset) rank*file_size_per_proc*sizeof(int)
MPI_File_open (MPI_COMM_WORLD, "/scratch/largefile",
MPI_MODE_RDONLY, MPI_INFO_NULL, &fh)
MPI_File_read_at (fh, offset, buffer, count, MPI_INT, status)
MPI_File_close (&fh)
```

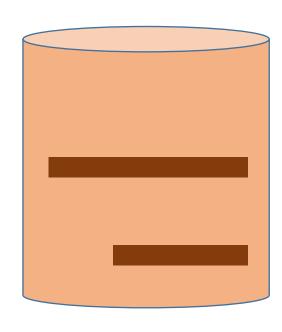
Every process reads a contiguous chunk

0 1 2 3 4 5

```
MPI_File fh; // FILE
MPI Init(&argc, &argv);
MPI Comm rank(MPI COMM WORLD, &myrank);
MPI Comm size(MPI COMM WORLD, &nprocs);
for (int i=0; i<BUFSIZE ; i++)</pre>
 buf[i]=i;
strcpy(filename, "testfileIO");
// File open, fh: individual file pointer
MPI File open (MPI COMM WORLD, filename, MPI MODE CREATE | MPI MODE RDWR, MPI INFO NULL, &fh);
MPI_Offset fo = (MPI_Offset) myrank*BUFSIZE*sizeof(int);
// File write using explicit offset (independent I/O)
MPI File write at (fh, fo, buf, BUFSIZE, MPI INT, MPI STATUS IGNORE); //fwrite
// File read using explicit offset (independent I/O)
MPI File read at (fh, fo, rbuf, BUFSIZE, MPI INT, &status); //fread
for (i=0; i<BUFSIZE ; i++)</pre>
 if (buf[i] != rbuf[i]) printf ("Mismatch [%d] %d %d\n", i, buf[i], rbuf[i]);
```

Large Domain





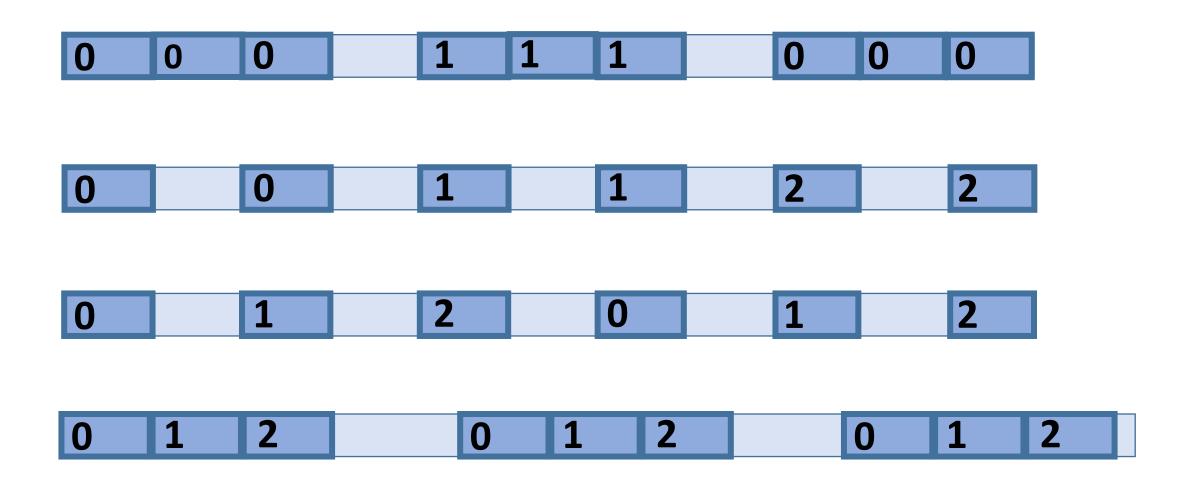
Access pattern



012345678

Every process in this example owns a 3x3 sub domain which may be stored as a 1D array as shown here. The first row elements of P0 will be followed by the first row elements of P1 and so on in order to maintain the correct row-wise information of the entire domain in a file.

Non-contiguous Access Patterns



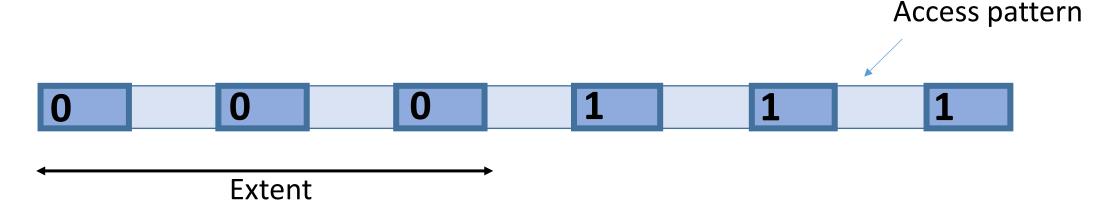
Multi-variable Dataset

Two ways to store multiple fields/variables

- Var1 for the entire domain, followed by Var2 for the entire domain, followed by Var3 for the entire domain and so on
- Var1, Var2, Var3, ... for grid point 1, Var1, Var2, Var3, ... for grid point 2 and so on

Every process analytically computes the offsets in both cases HW: Write the code to write 4 variables of a MxN domain from PxQ processes using the above two approaches.

Multiple Short Accesses



MPI_File_read_at (fh, offset1, buffer1, count1, MPI_INT, status)

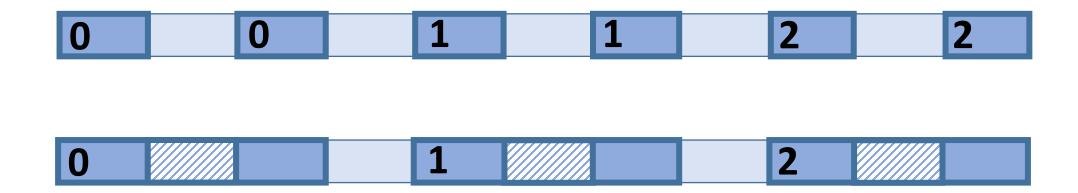
MPI_File_read_at (fh, offset2, buffer2, count2, MPI_INT, status)

MPI_File_read_at (fh, offset3, buffer3, count3, MPI_INT, status)

What is the problem with non-contiguous accesses?

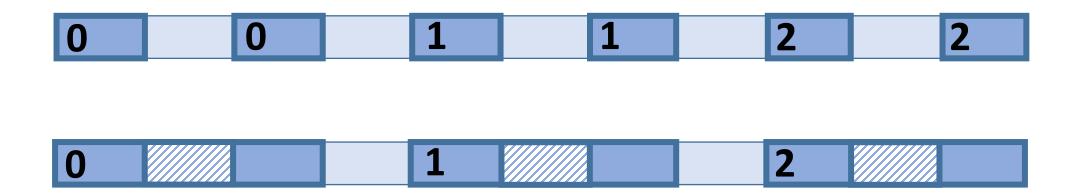
Can we instead use one read call?

Optimization – Data Sieving



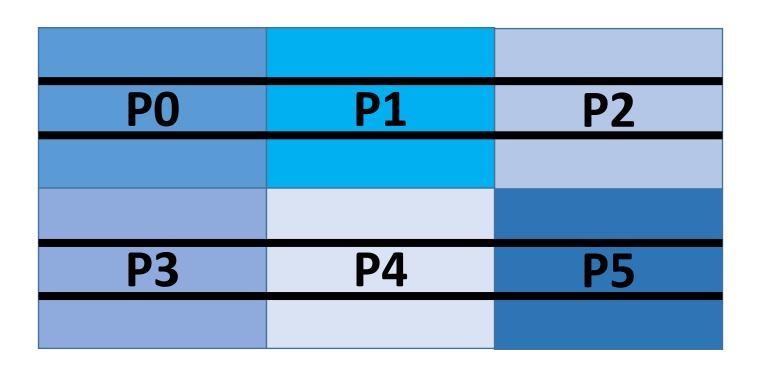
- Make large I/O requests and extract the data that is really needed
- Huge benefit of reading large, contiguous chunks

Data Sieving for Writes



- Copy only the user-modified data into the write buffer
- Write only the data that was modified read-modify-write

Multiple Non-contiguous Accesses

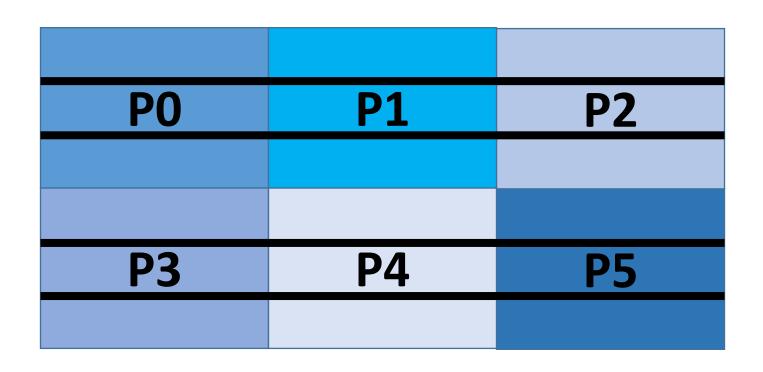


Can some of these requests be merged?

What is the access pattern?

PO P1 P2 P0 P1 P2 P0 P1 P2 P3 P4 P5 P3 P4 P5 P3 P4 P5

Create Sub-groups for Actual I/O



Can some of these requests be merged?

PO P1 P2 P0 P1 P2 P0 P1 P2 P3 P4 P5 P3 P4 P5 P3 P4 P5

P0 P3

Create Sub-groups for Actual I/O

P0 P1 P2 P0 P1 P2 P0 P1 P2 P3 P4 P5 P3 P4 P5 P3 P4 P5

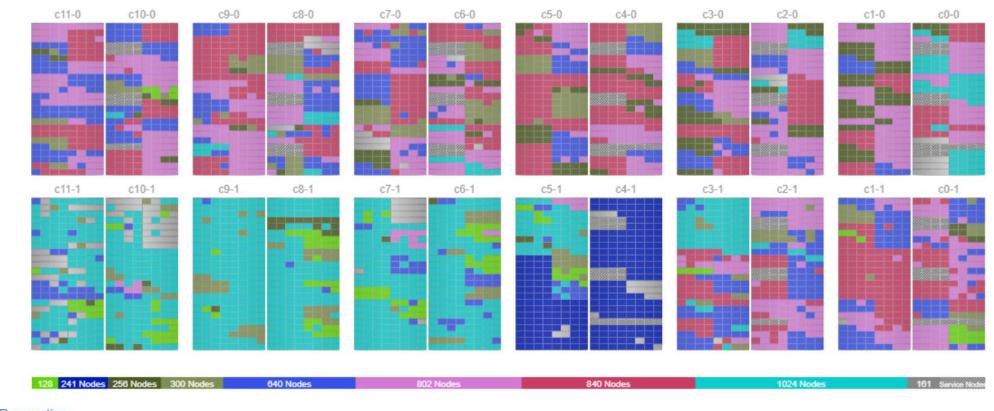
Two leaders created

Data per process = 1 MB

P0 P1 P2 P0 P1 P2 P0 P1 P2 P3 P4 P5 P3 P4 P5 P3 P4 P5 Assign more leaders

Data per process = 1 GB

Supercomputer Job Allocation



Running Starting Queued Reservations

Total Running Jobs: 8											
Job Id 🗘	Project ♦	Nodes v	Start Time ♦	Run Time ♦	Walltime 0	Queue ♦	Mode ♦				
512304	EstopSim_2	1024	9:13:30 AM	00:12:13	16:00:00	default	script				
512623	TurbShockWalls	840	7:57:42 AM	01:28:01	1d 00:00:00	default	script				
498557	TurbShockWalls	802	9:43:57 PM	11:41:46	1d 00:00:00	default	script				
513358	PSFMat_2	640	8:29:27 AM	00:56:16	12:00:00	default	script				
511830	ReconDepth	300	7:50:53 AM	01:34:50	06:00:00	default	script				
514000	HighLumin	256	8:50:22 AM	00:35:21	06:00:00	default	script				
514114	CVD_CityCOVID	241	1:28:47 AM	07:56:56	1d 12:00:00	CVD_Research	script				
514178	FDTD_Cancer_2a	128	8:00:51 AM	01:24:52	03:00:00	default	script				

Resources Required

- Number of nodes
- Wall-clock time
- Users are charged for node-hours

Should there be any constraints on the above requirements?

User Jobs

- Different types of applications
- Interactive vs. batch jobs
 - Debug in interactive mode
- Exclusive vs. shared access
- Charged based on total resource usage
 - Job is killed when requested wall-clock time is over
 - Need to plan resource usage apriori

Batch Queueing Systems

- Schedules jobs based on queues
- Has full knowledge of queued, running jobs
- Has full knowledge of the resource usage
- Often combination of best fit, fair share, priority-based
- Designed to be generic, can be customized
- Suited to meet demands of the scheduling goals of the centre
- Typically FIFO/FCFS with backfilling

Workload managers/Schedulers

- Portable Batch System (PBS)
- LoadLeveler
- Application Level Placement Scheduler (ALPS)
- Moab/Torque
- Simple Linux Utility for Resource Management (SLURM)

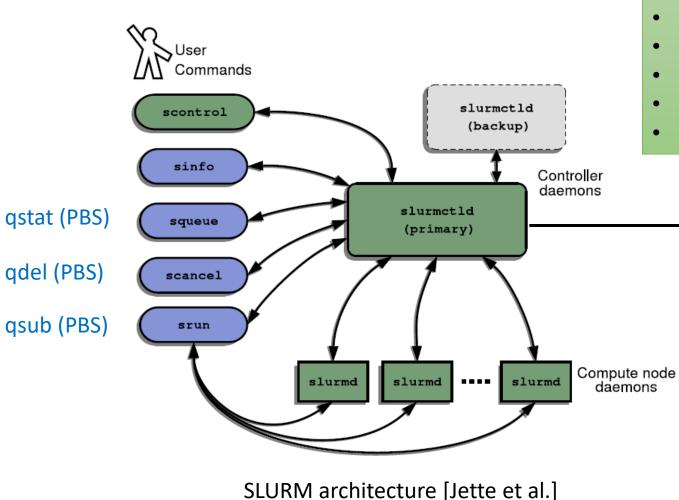
Example Batch Scheduler

- Network Queueing System developed at NASA
- Supported multiple queues of several types
- Disable/enable each queue
- Tune the #jobs running in each queue

Portable Batch Scheduler

- Genesis of PBS in NASA (from NQS)
- Client commands for submission, modification, and monitoring jobs
- Daemons running on service nodes, compute nodes, and servers

SLURM



- Monitors states of nodes
- Accepts job requests
- Maintains queue of requests
- Schedules jobs
- Initiates job execution and cleanup
- Polls slurmd periodically
- Maintains complete state information

- Responds to controller requests
- Maintains job state
- Initiate, manage, cleanup processes
- I/O handling

PARAM Rudra C-DAC (IUAC Delhi)

- Thanks to C-DAC
- Based on Intel Xeon
- 100 Gbps Mellanox Infiniband interconnect (fat-tree topology)
- Use a maximum of 2 nodes and 48 cores for a maximum wall-clock time of 10 minutes (for now)
- SLURM scheduler

SLURM Commands

```
#SBATCH -N 2
#SBATCH --ntasks-per-node=2
#SBATCH --error=job.%J.err
#SBATCH --output=job.%J.out
#SBATCH --time=00:10:00
#SBATCH --partition=standard
mpirun –np 4 ./exe <args>
```

sbatch <jobscript>
squeue
scancel <jobid>

Job Script

squeue

squeue

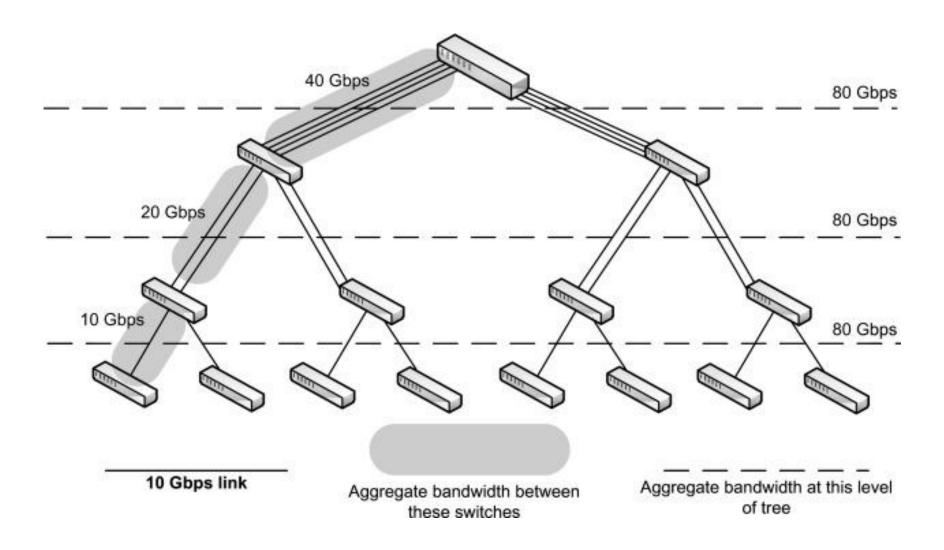
JOBID PARTITION NAME USER ST TIME NODES NODELIST(REASON)

12181 cpu QE FC abc R 1:21:59 16 rdcn[17-32]

squeue --me

JOBID PARTITION NAME USER ST TIME NODES NODELIST(REASON)

Fat-tree Topology



Job Allocation

Assume #nodes per rack = 20

Job 1: cn[17-32]
Spills from Rack 1 to
Rack 2

Job 2: cn[1-2],cn[33-40] Fragmentation

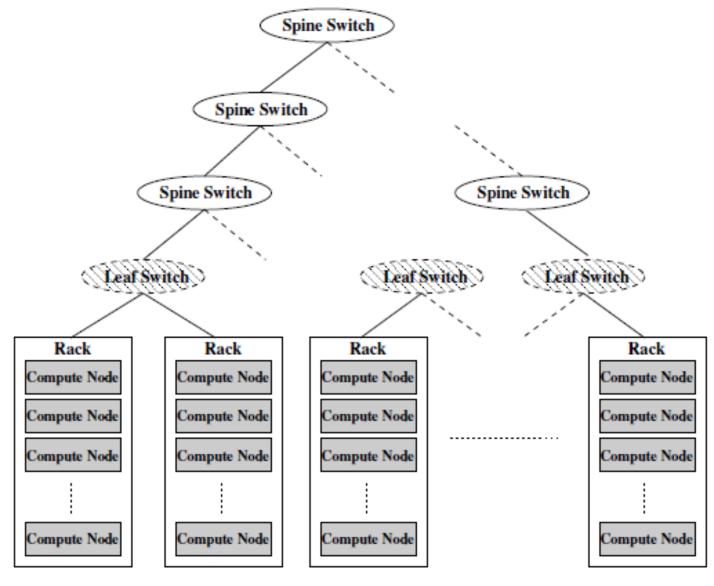
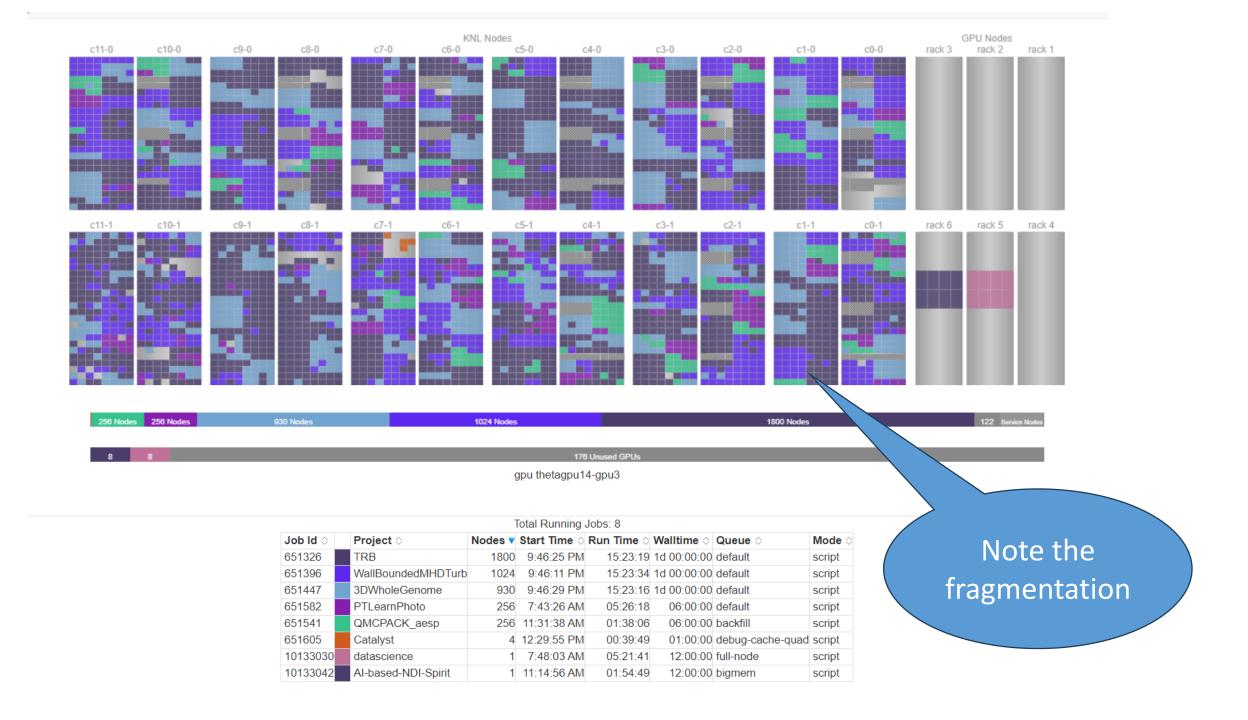


Figure 1. A Typical Topology



Important Metrics

User

- Job wait time = Job start time Job submit time
- Job turnaround time = Job end time Job Submit time

System

- Throughput = Number of jobs completed in a time unit
- Idle nodes = Number of idle nodes in a time unit

PARAM Sanganak (IITK) Partitions (Queues)

Partition Name	Minimum #CPU cores (equivalent nodes)	Maximum #CPU cores (equivalent nodes)	Maximum Time [Days- HH:MM:SS]	Default Time [HH:MM:SS]	Nodes allocated to each partition (some nodes are shared in more than one partition)	Total Nodes
serial	1	24	02-00:00:00	02:00:00	hm[001-002]	2(hm)
small	48 (1 node)	96 (2 nodes)	02-00:00:00	02:00:00	cn[001-050], hm[003-029]	50(cn)+27(hm)
medium	96 (2 nodes)	192 (4 nodes)	02-00:00:00	02:00:00	cn[051-110], hm[030-054]	60(cn)+25(hm)
large	192 (4 nodes)	480 (10 nodes)	03-00:00:00	02:00:00	cn[111-187], hm[055-078]	76(cn)+24(hm)
fat	480 (10 nodes)		02-00:00:00	02:00:00	cn[171-217], hm[055-078]	47(cn)+24(hm)
hm	48 (1 node)	288 (6 nodes)	02-00:00:00	02:00:00	hm[003-078]	76(hm)
gpu	cpu=1,gres/gpu=1	cpu=160,gres/gpu=8	02-00:00:00	02:00:00	gpu[001-020]	20(gpu)

^{*} Maximum #CPU Cores has not been set explicitly in the FAT partition, but it can be dictated by the maximum number of nodes in the partition.