

The Kernel and Range of a LT :-

Let $T: V \rightarrow W$ be a linear transformation. The kernel of T , denoted $\ker(T)$, is the set of all vectors in V that are mapped by T to 0 in W . That is, $\ker(T) = \{v \in V : T(v) = 0\}$

The range of T , denoted by $\text{range}(T)$, is the set of all vectors in W that are images of vectors in V under T . That is

$$\begin{aligned} \text{range}(T) &= \{T(v) : v \in V\} \\ &= \{w \in W : w = T(v) \text{ for some } v \in V\} \end{aligned}$$

Ex. Find the kernel and range of the differential operator

$D: P_3 \rightarrow P_3$ defined by $D(p(x)) = p'(x)$.

Soln:- Since $D(a+bx+cx^2+dx^3) = b+2cx+3dx^2$

$$\begin{aligned} \ker(D) &= \{a+bx+cx^2+dx^3 : D(a+bx+cx^2+dx^3) = 0\} \\ &\Rightarrow b+2cx+3dx^2 = 0 \\ &\Rightarrow b=0, c=0, d=0 \end{aligned}$$

$\therefore \ker(D) = \{a : a \in \mathbb{R}\}$ i.e. \ker of D is the set of constant poly.

$$\begin{aligned} \text{Now, range}(D) &= \{D(p(x)) : p(x) \in P_3\} \\ &= \{p'(x) : p(x) \in P_3\} \\ &= \{b+2cx+3dx^2 : b, c, d \in \mathbb{R}\} \end{aligned}$$

$$\text{or range}(D) = \{q(x) \in P_3 : q(x) = D(p(x)) \text{ for some } p(x) \in P_3\}$$

$$\begin{aligned} &= \{a+bx+cx^2+dx^3 : a+bx+cx^2+dx^3 = D(f+gx+hx^2+ix^3) \\ &\Rightarrow a+bx+cx^2+dx^3 = g+2hx+3ix^2 \end{aligned}$$

$$\Rightarrow a=g, b=2h, c=3i, d=0.$$

$$\begin{aligned} \therefore p(x) &= f+ax+\frac{b}{2}x^2+\frac{c}{3}x^3 \\ &= \{a+bx+cx^2 : a+bx+cx^2 = D(f+ax+\frac{b}{2}x^2+\frac{c}{3}x^3)\} \end{aligned}$$

Thm:- Let $T: V \rightarrow W$ be a linear transformation. Then:

(a) The Kernel of T is a subspace of V .

(b) The range of T is a subspace of W .

Pf:- (a) Since $T(0) = 0$, the zero vector of V is in $\text{Ker}(T)$, so $\text{Ker}(T)$ is nonempty. Let u and v be in $\text{Ker}(T)$ and let c be a scalar. Then $T(u) = T(v) = 0$, so

$$T(u+v) = T(u) + T(v) = 0 + 0 = 0$$

$$T(cu) = cT(u) = c \cdot 0 = 0$$

$\therefore u+v$ and $c u$ are in $\text{Ker}(T)$, and $\text{Ker}(T)$ is a subspace of V .

(b) Since $0 = T(0)$, the zero vector of W is in $\text{range}(T)$, so $\text{range}(T)$ is nonempty.

Let $T(u)$ and $T(v)$ be in the range of T and let c be a scalar. Then, $T(u) + T(v) = T(u+v)$ & $cT(u) = T(cu)$.

$T(u+v)$ is the image of $u+v$. Since u and v are in V , so $u+v$ is in V and hence $T(u+v)$ is in $\text{range}(T)$.

Similarly, $T(cu)$ is the image of $c u$. Since u is in V , so $c u$ is in V and hence $cT(u)$ is in $\text{range}(T)$.

$\therefore T(u) + T(v)$ and $cT(u)$ are in $\text{range}(T)$, and $\text{range}(T)$ is a subspace of W .

Def:- Let $T: V \rightarrow W$ be a linear transformation. The rank of T is the dimension of the range of T and is denoted by $\text{rank}(T)$. The nullity of T is the dimension of the kernel of T and is denoted by $\text{nullity}(T)$.