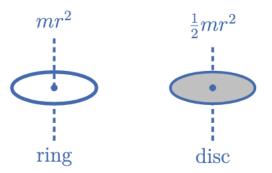
## <u>Dynamics of Rigid body</u> <u>Definitions</u>

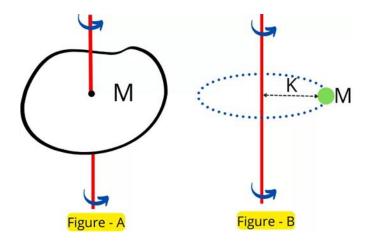
Moment of inertia: Moment of inertia is a quantity expressing a body's tendency to resist <u>angular acceleration</u>, which is the sum of the products of the mass of each particle in the body with the square of its distance from the axis of rotation.

$$I = \Sigma m_i r_i^2$$



<u>Radius of gyration:</u> Radius of gyration is defined as the radial distance to a point which would have a <u>moment of inertia</u> the same as the body's actual distribution of mass, if the total mass of the body were concentrated there.





Angular Momentum: The quantity of rotation of a body, which is the product of its moment of inertia and its angular velocity.

$$L = I\omega$$

<u>Torque</u>: Torque is the measure of the force that can cause an object to rotate about an axis

$$au = rF\sin\theta$$

