Chapter 8: Deadlocks



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- System Model
- Deadlock Characterization

- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock



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Chapter Objectives

• Illustrate how deadlock can occur when mutex locks areused • Define the four

necessary conditions that characterize deadlock Identify a deadlock situation in a resource allocation graph. Evaluate the four different approaches for preventing deadlocks. Apply the banker's algorithm for deadlock avoidance. Apply the deadlock detection algorithm. Evaluate approaches for recovering from deadlock.



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SystemModel

System consists of resources

- Resource types $R_1, R_2, ..., R_m$
- *CPU cycles, memory space, I/O devices* Each resource type *R*_i has *W*_i instances.
- Each process utilizes a resource as follows:
 - request
 - use
 - release



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Deadlock with Semaphores

- Data:
 - A semaphore s1 initialized to 1
 - A semaphore s2 initialized to 1
- Two processes P1 and P2

```
P1:
    wait(s1)
    wait(s2)
P2:
    wait(s2)
wait(s1)
```





Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can usearesource
- Hold and wait: a process holding at least one resourceiswaiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarilyby the process holding it, after that process has completeditstask
- Circular wait: there exists a set $\{P_0, P_1, ..., P_n^{}\}$ of waiting processes such that P_0 is waiting for a resource that isheldby P_1, P_1 is waiting for a resource that is held by $P_2, ..., P_{n-1}$ is waiting for a resource that is held

by P_n , and P_n is waitingfor a resource that is held by P_0 .





Resource-AllocationGraph

A set of vertices V and a set of edges E.

- V is partitioned into two types:
- $P = \{P_1, P_2, ..., P_n^{}\}$, the set consisting of all the processes in the system
- $R = \{R_1, R_2, ..., R_m^{}\}$, the set consisting of all resource types in the system
 - request edge directed edge P_i → R_j
 - assignment edge directed edge R_j → P_i





Resource AllocationGraphExample

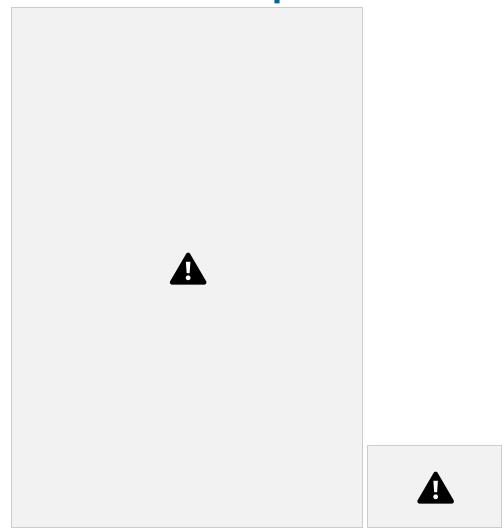
- One instance of R1
- Two instances of R2
- One instance of R3
- Three instance of R4
- T1 holds one instance of R2 and is waiting for an instance of R1
- T2 holds one instance of R1, one instance of R2, and is waiting for an instance of R3
- T3 is holds one instance of R3





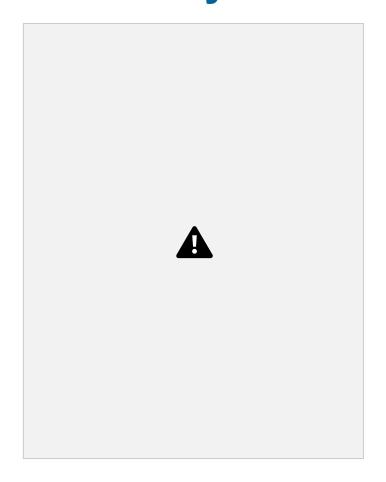


Resource Allocation GraphwithaDeadlock





Graph with a CycleBut noDeadlock







Basic Facts

- If graph contains no cycles ⇒ no deadlock If graph contains a cycle ⇒
 - If only one instance per resource type,

then deadlock

 If several instances per resource type, possibility of deadlock





Methods for HandlingDeadlocks

- Ensure that the system will never enter a deadlock state: Deadlock prevention
 - Deadlock avoidance
- Allow the system to enter a deadlock state and then recover Ignore the problem and pretend that deadlocks never occur inthesystem.





Deadlock Prevention

Invalidate one of the four necessary conditions for deadlock:

- Mutual Exclusion not required for sharable resources(e.g., read-only files); must hold for non-sharable resources
 Hold and Wait must guarantee that whenever a processrequests a resource, it does not hold any other resources
 - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
 Low resource utilization; starvation possible





Deadlock Prevention(Cont.)- No

Preemption: (stealing resources mid-way)

- If a process that is holding some resources requests another resourcethatcannot be immediately allocated to it, then all resources currentlybeingheld are released.
- Preempted resources are added to the list of resources for whichtheprocess is waiting. Process will be restarted only whenit canregainitsoldresources, as well as the new ones that it is requesting
- ☐ Eg1: P1 preempts CD ROM and Hard drive if printer is unavailable.☐ Eg2: If P2 has printer and is waiting for Hard Disk drive, it cbepreemptedand Printer can be given to P1.
- ☐ When aprocess (P1) request resources, we check whether theyareavailable or not. If they are available we allocate themelsewecheckthatwhether they are allocated to some other waiting processr (P2). If sowepreempt the resources from the waiting process(P2) and allocate them to the requesting process (PI). If resource is not available with P2, PI has to wait.



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Circular Wait - Circular Wait:

- Impose a total ordering of all resource types, and requirethat eachprocessrequests resources in an increasing order of enumeration
- Invalidating the circular wait condition is most common.
 Simply assign each resource (i.e., mutex locks) a unique number.
 Resources must be acquired in order.
- If: CD ROM drive = 1, Hard disk drive = 5, Printer=12•A
 process holding 'disk drive'

, cannot requestforCDROM drive, but it can request for printer. • Eg: semaphore

P1: P2:



wait(s1) wait(s2) s1 = 1wait(s2) wait(s1) s2 = 5

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Circular Wait - Deadlock can be prevented by using the

following protocol for circularwait: Each process can request the resource in increasing order. Aprocesscan

request any number of instances of resource type say Ri initially and the nitcan request instances of resource type Rj oniy if F(Rj) > F(Ri). • Alternatively, a process can request for an instance of resource of lower number by releasing all the higher number resources.



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Deadlock Avoidance

Requires that the system has some additional *a priori* informationavailable

 Simplest and most useful model requires that eachprocess declare the *maximum number* of resources of eachtypethat it may need

- The deadlock-avoidance algorithm dynamically examinesthe resource-allocation state to ensure that there cannever be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes



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Safe State

■ When a process requests an available resource, systemmust decide if immediate allocation leaves the systemin a safestate System is in **safe state** if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by

currently available resources + resources held by all the P_j , with j < l • That is:

• If P_i resource needs are not immediately available, then P_i wait until all P_j have finished • When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate • When P_i terminates, P_{i+1} can obtain its needed resources, and so on



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Basic Facts • If a system is in safe state ⇒ no deadlocks

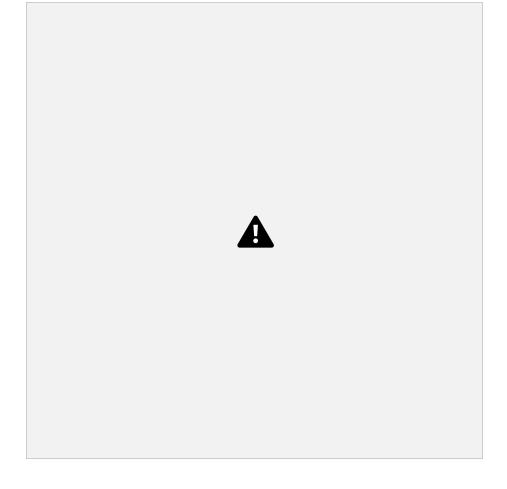
If a system is in unsafe state ⇒ possibility of deadlock = Avoidance ⇒
 ensure that a system will never enter anunsafestate.



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Safe, Unsafe, DeadlockState







Avoidance Algorithms

- Single instance of a resource type
 - Use a modified resource-allocation graph
- Multiple instances of a resource type
 - Use the Banker

's Algorithm



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Modified Resource-AllocationGraphScheme

- Claim edge P_i --> R_j indicates that process P_i may request resource R_j
- Request edge P_i → R_j indicates that process P_i requests resource R_j
 Claim edge converts to request edge when a processrequests a resource

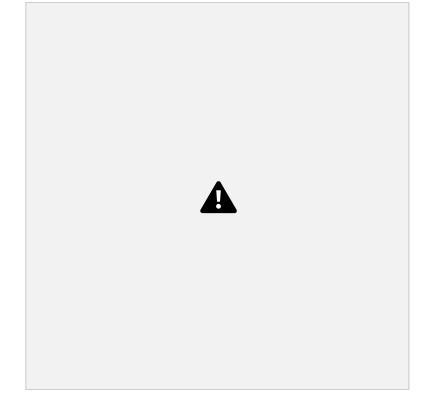
- Assignment edge $R_j \rightarrow P_i$ indicates that resource R_j^{Was} allocated to process P_i Request edge converts to an assignment edge whentheresource is allocated to the process
- When a resource is released by a process, assignment edgereconverts to a claim edge
- Resources must be claimed a priori in the system



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Resource-AllocationGraph



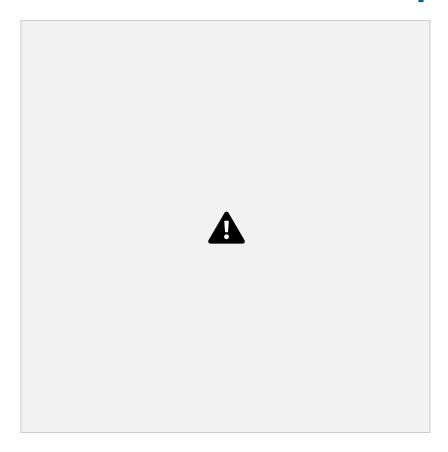


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Unsafe State In

Resource-AllocationGraph







Resource-AllocationGraphAlgorithm

• Suppose that process P_i requests a resource R_j • The request can be granted only if converting the request edgetoanassignment edge does not result in the formation of a cycleintheresource allocation graph





Banker's Algorithm

- Multiple instances of resources
- Each process must a priori claim maximumuse
 When a process requests a resource it may have to wait
 When a process gets all its resources it must return themin a finite amount of time





Data Structures for the Banker's Algorithm Let

n = number of processes, and m = number of resourcestypes.

- Available: Vector of length m. If available [j] = k, therearekinstances of resource type R_j available
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i mayrequest at most k instances of resource type R_j Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i iscurrently allocated k instances of R_j Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may needkmore instances of R_j to complete its task Need[i,j] = k

Max[i,j] – Allocation [i,j]





Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m*and *n*, respectively. Initialize:

Finish [i] = false for
$$i = 0, 1, ..., n-1$$

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) *Need_i* ≤ *Work*If no such *i* exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
 - 4. If *Finish* [*i*] == *true* for all *i*, then the systemis in a safestate





Resource-Request

AlgorithmforProcess P_i Request_i = request vector for process P_i . If

Request_i [j] = kthen process P_i wants k instances of resource type R_j 1. If $Request_i \le Need_i$ go to step 2. Otherwise, raiseerror condition, since process has exceeded its maximum claim

2. If Request_i ≤ Available, go to step 3. Otherwise P_i must wait, since resources are not available 3. Pretend to allocate requested resources to P_i by modifyingthe state as follows: Available = Available - Request_i; Allocation_i = Allocation_i + Request_i; Need_i = Need_i - Request_i;

• If safe \Rightarrow the resources are allocated to P_i • If unsafe \Rightarrow P_i must wait, and the old resource-allocation tate is restored





Example of Banker 'sAlgorithm

5 processes P₀through P₄;
 3 resource types:

A (10 instances), B (5 instances), and C (7 instances) • Snapshot at time T_0 :

Allocation Max Available

ABCABCABC

P₀010753332

 $P_1 2 0 0 3 2 2$

P₂302902

P₃211222

P₄002433





Example (Cont.) - The content of the matrix *Need* is

defined to be **Max – Allocation**

<u>Need</u>

ABC

 $P_0 7 4 3$

P₁ 1 2 2

 P_2600

 $P_3 0 1 1$

P₄431





Example(Cont.) - Snapshot at time T_0 :

Allocation Max Available Need

ABCABCABCABC

 P_0 0 1 0 7 5 3 3 3 2 7 4 3 P_1 2 0 0 3 2 2 1 22 P_2 3 0 2 9 0 2 6 00 P_3 2 1 1 2 2 2 0 11 P_4 0 0 2 4 3 3 4 31

• The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria





Example: P₁ Request (1,0,2) - Check that

Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true <u>Allocation Need Available</u> A B C A B C

P₀ 0 1 0 7 4 3 2 3 0 P₁ 3 0 2 0 2 0

 P_2 3 0 2 6 0 0 P_3 2 1 1 0 1 1 P_4 0 0 2 4 3 1

- Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement Can request for (3,3,0) by P_4 be granted?
- Can request for (0,2,0) by **P**₀ be granted?





Deadlock Detection- Allow system to enter deadlock state

- Detection algorithm
- Recovery scheme





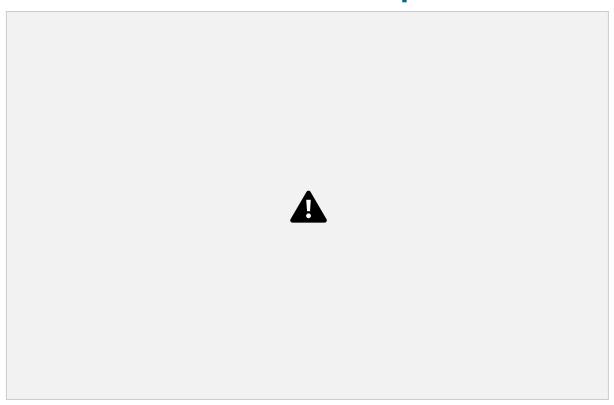
Single Instance of EachResourceType

- Maintain wait-for graph
 - Nodes are processes
 - $P_i \rightarrow P_j$ if P_i is waiting for P_j
- Periodically invoke an algorithm that searches for a cycleinthegraph. If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of n^2 operations, where n is the number of vertices in the graph





Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph Corresponding wait-for graph





Several Instances of a Resource Type

- Available: A vector of length m indicates the number of availableresources of each type
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process
- Request: An n x m matrix indicates the current request of eachprocess.
- If Request[i][j] = k, then process P_i is requesting k more instances of resource type R_j .





DetectionAlgorithm

- 1. Let *Work* and *Finish* be vectors of length *m*and *n*, respectivelyInitialize:
 - a) Work = Available
 - b) For *i* = 1,2, ..., *n*, if *Allocation*_i ≠ 0, then *Finish*[i] = *false*; otherwise, *Finish*[i] = *true*
- 2. Find an index *i* such that both:
 - a) Finish[i] == false
 - b) Request_i≤ Work

If no such *i* exists, go to step 4





Detection Algorithm(Cont.)

- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the systemisindeadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked

Algorithm requires an order of $O(m \times n^2)$ operations to detect whether the system is in deadlocked state



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Example of DetectionAlgorithm

- Five processes P₀through P₄; three resource types A (7 instances), B (2 instances), and C (6 instances)
- Snapshot at time T₀:

Allocation Request Available

ABCABCABC

 P_0 01000000 P_1 200202 P_2 303000 P_3 211100 Sequence <P₀, P₂, P₃, P₁, P₄> will result in Finish[i] =true for all i



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Example (Cont.)

• P₂requests an additional instance of type C <u>Request</u>

ABC

 $P_0 0 0 0$

 $P_1 2 0 2$

 $P_2 0 0 1$

 $P_3 1 0 0$

 $P_4 0 0 2$

State of system?

• Can reclaim resources held by process P_0 , but insufficient resources to fulfill other processes; requests



Deadlock exists, consisting of processes P₁, P₂, P₃, and P₄

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Detection-AlgorithmUsage

- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 How many processes will need to be rolled back?
 4 One for each disjoint cycle
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be abletotell which of the many deadlocked processes

"caused" the

deadlock.



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Recovery from Deadlock: ProcessTermination

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated. In which order should we choose to abort?
 Priority of the process
 - How long process has computed, and howmuch longer tocompletion
 - Resources the process has used
 - Resources process needs to complete
 - How many processes will need to be terminated
 Is process interactive

or batch?



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Recovery from Deadlock: ResourcePreemption

- Selecting a victim minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor



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Endof Chapter8



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Example (Cont.) - The content of the matrix Need is

defined to be **Max - Allocation**

<u>Need</u>

ABC

 $P_0 7 4 3$

• The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria





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Example of Banker 'sAlgorithm

5 processes P₀through P₄;

3 resource types:

A (10 instances), B (5 instances), and C (7 instances) • Snapshot at time T_0 :

Allocation Max Available Need

ABCABCABCABC

 P_0 0 1 0 7 5 3 3 3 2 7 4 3 P_1 2 0 0 3 2 2 1 22 P_2 3 0 2 9 0 2 6 00 P_3 2 1 1 2 2 2 0 11 P_4 0 0 2 4 3 3 4 31



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Resource-AllocationGraphScheme-

Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request

resource R_j 'represented by a dashed line • Claim edge converts to request edge when a process requests are source

- Request edge converted to an assignment edge when theresourceisallocated to the process
- When a resource is released by a process, assignment edgereconverts to a claim edge

• Resources must be claimed a priori in the system



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