

# NIOS II EMULATOR

## SOFTWARE DESIGN DOCUMENT

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## INTRODUCTION

### PURPOSE

Current environment software for the NIOS II processor has become outdated and received little maintenance throughout its life. Unreliable software accompanied by high costs of boards and chips requires a new solution to be created.

Creating an emulation of the chip and creating an environment for development brings life back to an aging system. Our system is designed to be a one and done solution for testing assembly code for the NIOS II processor without needing a separate board or micro controller. The associated GUI will provide a more efficient and user-friendly interaction.

### DESIGN GOALS

The NIOS II Emulator simply has to replicate the results of the NIOS II system, not the way things are calculated. This allows for the design of the system to remain simple, relative to the actual implementation of the original NIOS II FPGA. Along with simplicity, the other design goals revolve around replicating the behavior of the NIOS II without actually using the same methods.

#### List of Design Goals

1. Full functionality of NIOS II Emulator
  - a. System will be able to select a text file of assembly code from the user's file system.
  - b. System will run assembly code according to NIOS II architecture, in which there is a 32 bit, little endian processor environment with 16 bit memory addresses and 32 general purpose registers.
2. Simplicity
  - a. The implementation of the system architecture will be far simpler simpler than the original NIOS II, using advances made in the field and the use of high-level programming languages.

- b. Simplicity will be gauged by the ease in which instructions are implemented, as well as how memory is managed throughout execution.
  - c. The implementation language, javascript, comes with more packages than most high-level languages. Although packages can make things more complex in some situations, the use of packages for the emulator will make many operations (e.g. parsing) much more readable. It will also allow for less complex functions and fewer lines of code.
- 3. Maintainability
  - a. Maintaining the code may seem unnecessary due to the fact the NIOS II has been around and unchanging for some time, but it is very possible additional features will be added later on.
  - b. Future features would likely consist of additional capabilities that the NIOS II does not have, such as more advanced debugging or additional instructions not included in the original set.
- 4. User-Friendly
  - a. This NIOS II should have an appealing user interface that is easy to interact with and intuitive to use.
  - b. By updating the software user interface to something more comparable to what most people use on a daily basis today, the system will be much quicker to learn and use.

#### DESIGN TRADE-OFFS

1. Although emulation of the NIOS II output is possible, working with specific parts of a processor may not be. If a student were trying to learn how the inner parts of a processor work, an emulation may not be the best method.
2. Possible race condition if functions are not synchronized.
3. User-friendliness applies only to those familiar with the NIOS II Architecture. If someone unfamiliar with NIOS II attempted to use the system, they would encounter significant difficulties in understanding the system.

#### DEFINITIONS, ACRONYMS, AND ABBREVIATIONS

<u>Assembly Code</u>	low-level programming language designed for specific processor implementation
<u>Debugging</u>	using troubleshooting steps to find errors in programs
<u>Environment</u>	conditions in which the system operates
<u>Processor</u>	a computer chip capable of doing operations of 1s and 0s very quickly
<u>Register</u>	an information holder inside a processor
<u>G.U.I.</u>	Graphical User Interface

#### REFERENCES

- 1) <https://www.intel.com/content/www/us/en/programmable/documentation/iga1420498949526.html>
- 2) <https://www.draw.io/>
- 3) [http://robotics.ee.uwa.edu.au/courses/design/examples/example\\_design.pdf](http://robotics.ee.uwa.edu.au/courses/design/examples/example_design.pdf)

#### OVERVIEW

The current software design, namely the architecture, is the tool that will be used to guide development once coding has started. There will undoubtedly be changes to the software design when problems not previously thought of are encountered, which may require a redesign of a subsystem.

## CURRENT SOFTWARE ARCHITECTURE

No current system architecture exists, this is the initial design document.

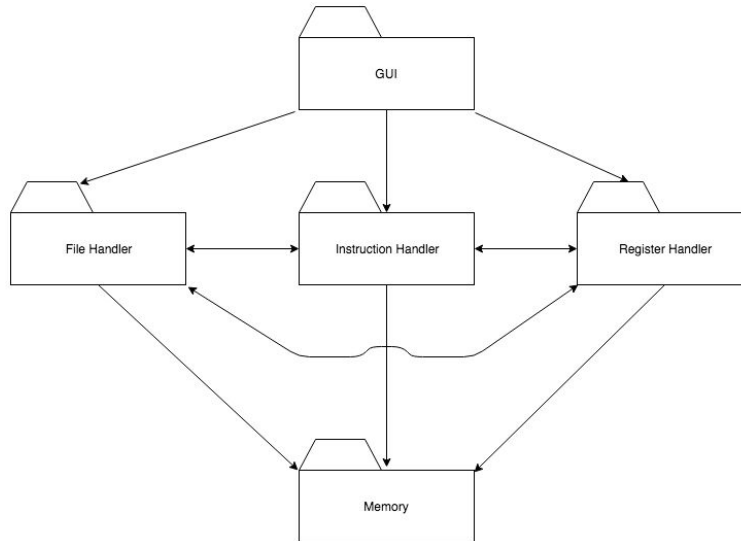
## PROPOSED SOFTWARE ARCHITECTURE

### OVERVIEW

The architectural style used in the NIOS II Emulator is a 3 layer webpage. The presentation layer is the first layer, consisting of the GUI its related components. The application layer is the second layer, where most of the logic and handling happens. It consists of the File Reader, Instruction Handler, and Register Handler. The third and final layer is the Database. It consists solely of the Memory subsystem.

### SUBSYSTEM DECOMPOSITION

1. GUI
  - a. Presentation Layer
  - b. The GUI gets register values for displaying to the user
  - c. Give user access to restart, start, and pause functionality
  - d. Initialized first with the rest of the presentation layer
2. File Reader
  - a. Application Layer
  - b. The File reader subsystem handles the access to the user's file system, uploading the file, and parses instructions.
  - c. Validates file type, instructions, and legality of memory allocation.
3. Instruction Handler
  - a. Application layer
  - b. Determining what instruction is being run, and using current register values retrieved from the register handler
4. Register Handler
  - a. Application layer
  - b. Responsible for updating register values
  - c. Getting values for instruction handler, used to perform operations for given instructions
5. Memory
  - a. Database Layer: non-persistent type
  - b. Holds input file
  - c. Holds instruction information
  - d. Holds register values



#### HARDWARE/SOFTWARE MAPPING

NONE

#### NON-PERSISTENT DATA MANAGEMENT

The non-persistent data will consist of hard coded memory, that only holds data during runtime. The memory is non-persistent, meaning no database holds the data once runtime is over. Rather than a database that stores information when the system is not running, the memory of this system will hold things like the input file and register values. Memory will be represented in an array. The inputted file, instructions, registers, etc, will be stored as indices in an array. The system will do basic CRUD operation to the array values. This will inturn emulate the NIOS II memory.

#### ACCESS CONTROL AND SECURITY

No access control or security is necessary for the current planned software architecture of the NIOS II emulator.

#### GLOBAL SOFTWARE CONTROL

Synchronization will be implemented sequentially by the code. Other means of synchronization and concurrency are unnecessary as long as the code is executed in a correct sequential order.

#### BOUNDARY CONDITIONS

1. File verification- before any file is run, each line of the file (as well as the file itself) will be validated to check for the following:
  - a. Make sure file is a .txt
  - b. Make sure all instructions are valid NIOS II instructions
  - c. Make sure file does not use numbers that are out of range of the NIOS II memory

2. Instruction Error Handling
  - a. In the event of an instruction failing due to any reason, execution of the file will stop at the line of failure
3. Shutdown Behavior
  - a. Shutdown behavior is minimal, the system will simply discard the file.
  - b. If the system were to shutdown unexpectedly, the user would only have to re-input their assembly file and run it again.
4. Startup Behavior
  - a. The system will initialize in a webpage, and await user input file
  - b. The system will initialize memory

## SUBSYSTEM SERVICES

1. GUI
  - a. Provides user with control of the system (Play, Pause, Restart), displays the register contents, and the pointer value.
2. File Reader
  - a. Validates file and stores instructions in memory.
3. Instruction Handler
  - a. Performs all instructions on the specified registers and returns the updated values.
4. Register Handler
  - a. Obtains the current value of each register from memory after each instruction is performed.
5. Memory
  - a. Contains the register values in a 65,536 byte array memory management system.

## PACKAGES

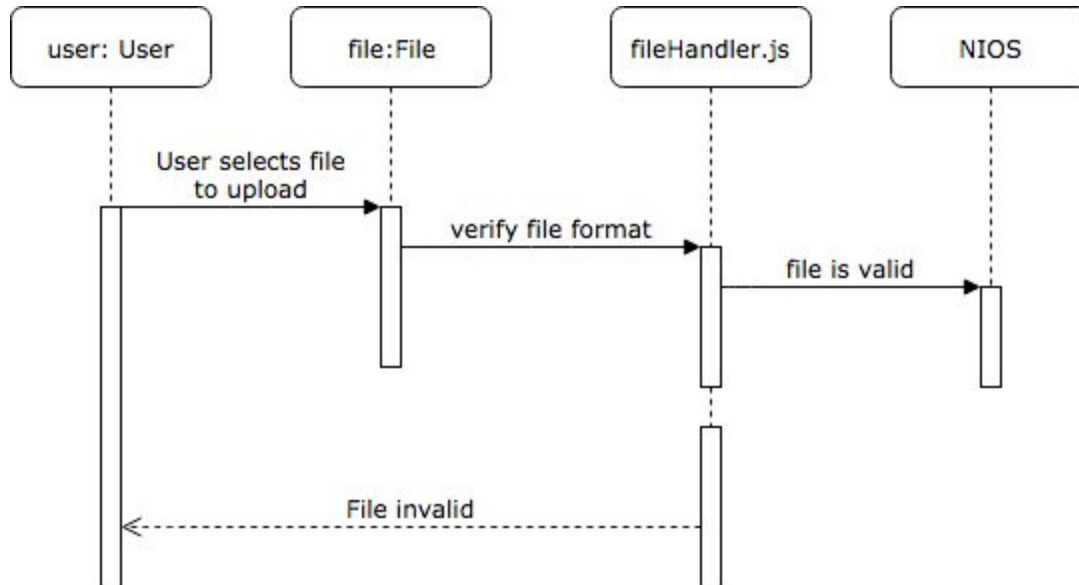
It is currently unknown what packages will be added once coding begins. This section will be updated with all packages used, as well as their dependencies, once it becomes clear what needs to be added.

## CLASS INTERFACES

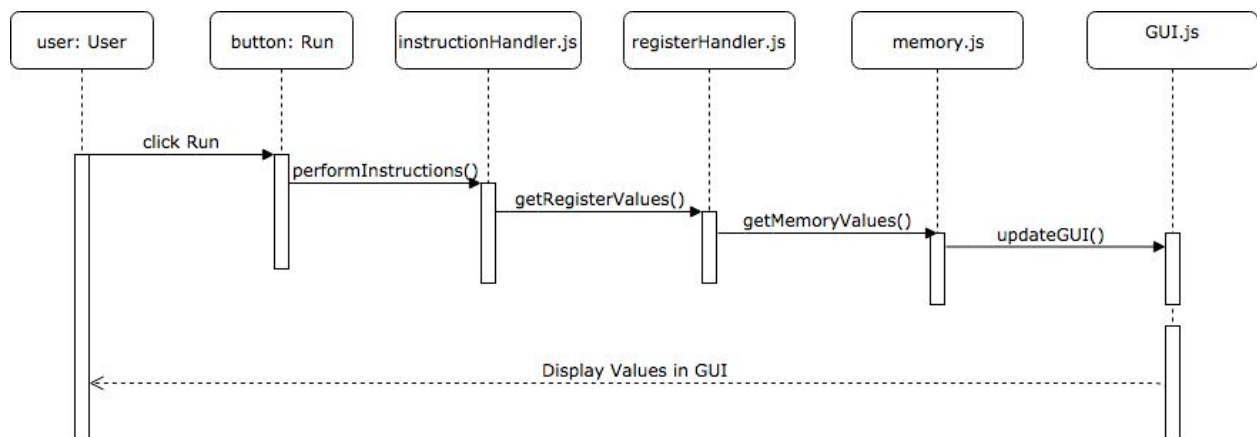
1. GUI Class: The gui class is the highest level class, and governs all the activity of the other classes through interactions with the html webpage.
2. Instruction Handler: The instruction Handler is handles the verification and execution of individual assembly instructions. It is triggered when the user decides to run a command or multiple commands. It interacts with the register handler and file handler based on the result of an instruction. It will throw an exception if an instruction does not conform to the NIOS II architecture.
3. Register Handler: The register handles deals with the interactions between registers, as well as holding the values of the registers throughout execution of the program. It interacts with the instruction handler when a register is needed or updated. It loads the initial register values from the file handler.
4. File Handler: The file handler is responsible for fetching and uploading the assembly text file from the user's file system. It then stores that data in the memory component. It will send instructions to memory and the instruction handler.
5. Memory: The memory component is responsible for all interactions with the virtual data that will be created to simulate to NIOS II memory.

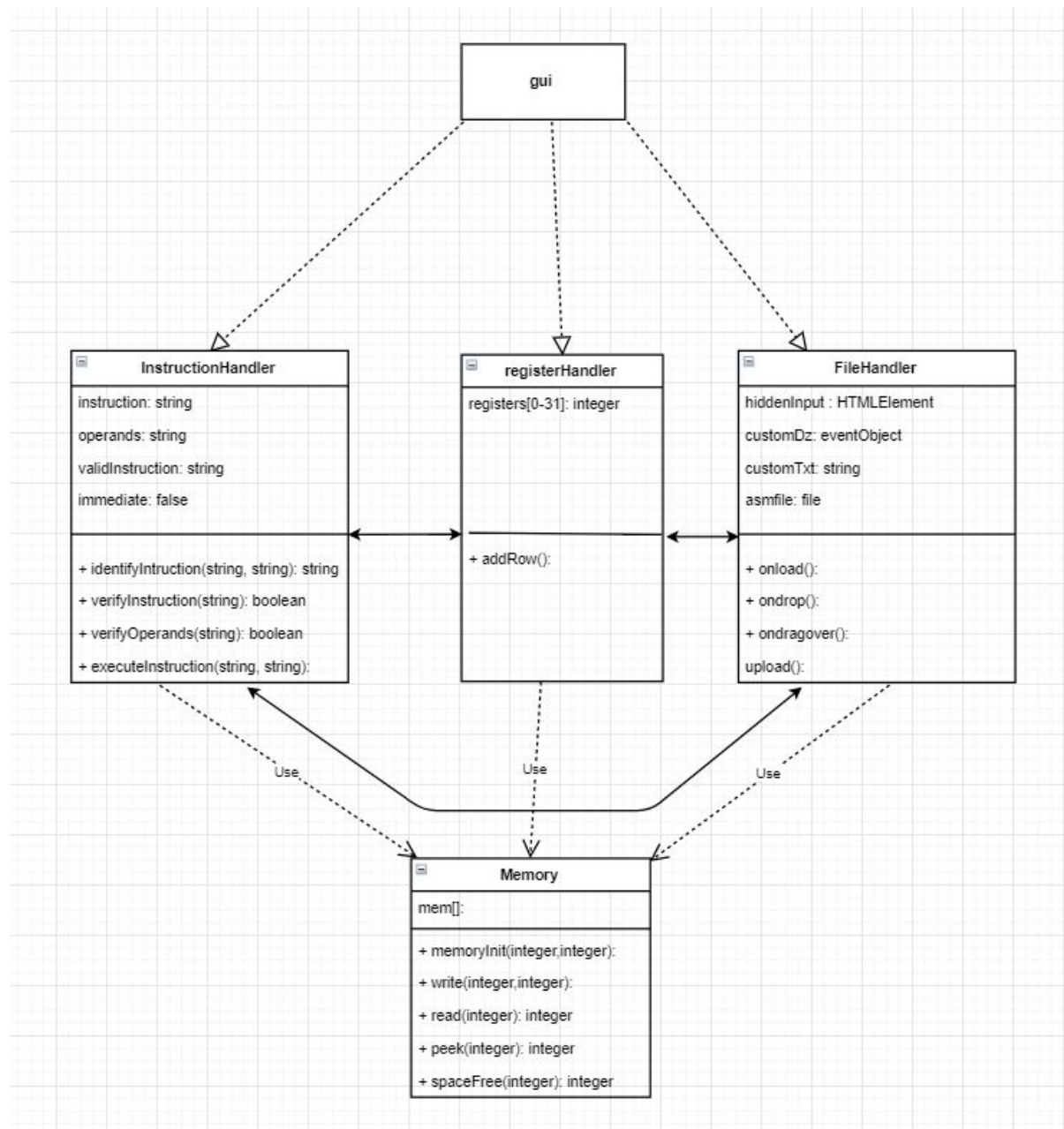
## DETAILED DESIGN

Sequence diagram of the user uploading a file to the web app:



Sequence diagram of the design level instruction processing to display values in GUI:





## GLOSSARY

**Race condition:** A race condition is the behavior of an electronics, software, or other system where the output is dependent on the sequence or timing of other uncontrollable events. It becomes a bug when events do not happen in the order the programmer intended.