	B-DACM-F-0.1 scoring sheet																							
Big to	wel [bt]		Small too	vel [st]																				
Lengti Widti	50		Length Width		planned gras	ping points				Indicate n	lanned graspi	na points				Indic	cate plan	ned graspin	ng points					
				marcate p	Junica grad	ping points				maicate p	annea graspi	ing points				maic	Julie piun	nea graspin	ig points					
Object			Firs	t fold					Secon	nd fold				[bt] o		i fold								
Starting config.	Success [GR1] (1   0)	Success [GR2] (1   0)	Success	Area Area before after	Quality function fold	Time in sec	Success [GR1]	Success [GR2] (1   0)	Success [MAN] (1   0)	Area Area before after	Quality function fold	Time in sec	Success [GR1]	Success [GR2] (1   0)	Success		Area after	Quality function fold	Time in sec	Assumptions	Used (YES   NO)	Assumptions	Used (YES   NO)	New assumptions
	(-1-)	(-1-)	(114)		-		(*1-7	(-1-)	(-1-)		-		(112)	(-1-)	(-1-)			-		Towel color Table position known	()	Illumination changes	(125   1115)	
[pg2]					-						-							-		Object position known Tablecloth color Towel dimensions				
Summary:			0.00%		-	avg: - var: -	0.00%	0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%				avg: - var: -	Assumptions	0/6	New assur	nptions	NO
Object						vui.						,		[bt] o	r [st]									
			Success	t fold	Quality				Secon Success [MAN]	nd fold	Quality				Thir	fold	Т	Quality						
Starting config.	Success [GR1] (1   0)	Success [GR2] (1   0)	[MAN] (1   0)	Area Area before after	Quality function fold	Time in sec	Success [GR1] (1   0)	Success [GR2] (1   0)	[MAN] (1   0)	Area Area before after	Quality function fold	Time in sec	Success [GR1] (1   0)	Success [GR2] (1   0)	[MAN] (1   0)	Area A	Area after	Quality function fold	Time in sec	Assumptions Towel color	Used (YES   NO)	Assumptions Illumination changes	Used (YES   NO)	New assumptions
[pg1]					-						-							-		Table position known Object position known				
					-						-							-		Tablecloth color Towel dimensions				
Summary:		0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%			-	avg: - var: -	Assumptions	0/6	New assur	nptions	NO
Object				t fold					Secon				1	[bt] o		l fold						I		
Starting config.	Success [GR1]	Success [GR2] (1   0)	Success	Area Area before after	Quality function fold	Time in sec	Success [GR1]	Success [GR2] (1   0)	Success [MAN] (1   0)	Area Area before after	Quality function fold	Time in sec	Success [GR1]	Success [GR2]	Success		Area after	Quality function fold	Time in sec		Used (YES   NO)		Used (YES   NO)	
config.	(1   0)	(1   0)	(1   0)	before after	r fold	in sec	(1   0)	(1   0)	(1   0)	before after	r fold	in sec	(1   0)	(1   0)	(1   0)	before	after	fold -	in sec	Assumptions Towel color	(YES   NO)	Assumptions  Top layer of folded towel contains grasp point	(YES   NO)	New assumptions
[ft]					-						-							-		Table position known Object position known Tablecloth color		Illumination changes		
					-						-							-		Towel dimensions				
Summary:	0.00%	0.00%	0.00%			avg: - var: -	0.00%	0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%			-	avg: - var: -	Assumptions	0/7	New assur	nptions	NO
Object			Fi	t fold					Secon	-1 5-1-1				[bt] o		l fold								
Starting	Success [GR1]	Success [GR2]	Success [MAN]	Area Area before after	Quality	Time	Success [GR1]	Success [GR2]	Success	Area Area	Quality function fold	Time	Success [GR1]	Success [GR2]	Success [MAN]		Area after	Quality function fold	Time		Used		Used (YES   NO)	
config.	(1   0)	(1   0)	(1   0)	before after	r fold	in sec	(1   0)	(1   0)	(1   0)	before after	fold -	in sec	(1   0)	(1   0)	(1   0)	before	after	fold -	in sec	Assumptions Towel color Table position known	(YES   NO)	Assumptions Grasp points visible on table Illumination changes	(YES   NO)	New assumptions
[cr]					-						-							-		Object position known Tablecloth color				
					-	ava: -					-	ava: -						-	ava: -	Towel dimensions				
Summary:	0.00%	0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%		-	avg: - var: -	0.00%	0.00%	0.00%			-	avg: - var: -	Assumptions	0/7	New assur	nptions	NO
Note: Fo	the secor	nd and thi	rd folds	, report on	ly one	of the rows	S.																	
				t fold					Secon		ry results				Thir	I fold			ı					
Start config.	Success [GR1] (1   0)	Success [GR2] (1   0)	Success [MAN] (1   0)		Quality function fold	Time in sec	Success [GR1] (1   0)	Success [GR2] (1   0)	Success [MAN] (1   0)		Quality function fold	Time in sec	Success [GR1] (1   0)	Success [GR2] (1   0)	Success [MAN] (1   0)			Quality function fold	Time in sec	Assumptions	New assumptions:			
[pg2]			0.00%			avg: -	0.00%	0.00%	0.00%		-	avg: -	0.00%	0.00%	0.00%			-	avg: -	0/6	NO			
[pg1]		0.00%	0.00%		-	avg: - var: - avg: -	0.00%	0.00%	0.00%		-	avg: - var: - avg: -	0.00%	0.00%	0.00%			-	avg: - var: - avg: -	0/6	NO			
[ft]	0.00%	0.00%	0.00%		-	var: - avg: -	0.00%	0.00%	0.00%		-	var: - avg: -	0.00%	0.00%	0.00%			-	var: - avg: -	0/7	NO			
13	0.00%	0.00%	0.00%		-	var: -	0.00%	0.00%	0.00%		-	var: -	0.00%	0.00%	0.00%			-	var: -	0/7	NO			

Comments							
What makes the system successful?							
What makes the system fail?							
What makes the system successful? What makes the system fail? What was improved compared to other methods?							
Chosen grasping points and/or grasping strategy.							