RAL-SI-2020-B19-0832_2-V1.0 Scoring Sheet

Big towel [bt]	
Length	100
Width	50

Small towel [st]	
Length	50
Width	30

Indicate planned grasping points   **Indicate planned grasping points**   **Indicate planned grasping points**

Object — [bt] or [st]

Starting config.	First fold							Second fold							Third fold							Assumptions	Used (YES | NO)	Assumptions	Used (YES | NO)	New assumptions
	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec					
[pg2]						-																Table color		Illumination changes		
						-																Table position				
						-																Towel color				
						-																Towel position				
						-																Towel dimensions				
Summary:			0,00%			-	avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	Assumptions	0/6	New assumptions		NO

Object — [bt] or [st]

Starting config.	First fold							Second fold							Third fold							Assumptions	Used (YES | NO)	Assumptions	Used (YES | NO)	New assumptions
	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec					
[pg1]						-																Table color		Illumination changes		
						-																Table position				
						-																Towel color				
						-																Towel position				
						-																Towel dimensions				
Summary:		0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	Assumptions	0/6	New assumptions		NO

Object — [bt] or [st]

Starting config.	First fold							Second fold							Third fold							Assumptions	Used (YES | NO)	Assumptions	Used (YES | NO)	New assumptions
	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec					
[ft]						-																Table color		Illumination changes		
						-																Table position				
						-																Towel color				
						-																Towel position				
						-																Towel dimensions				
Summary:	0,00%	0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	Assumptions	0/6	New assumptions		NO

Object — [bt] or [st]

Starting config.	First fold							Second fold							Third fold							Assumptions	Used (YES | NO)	Assumptions	Used (YES | NO)	New assumptions
	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)	Area before	Area after	Quality function fold	Time in sec					
[cr]						-																Table color		Illumination changes		
						-																Table position				
						-																Towel color				
						-																Towel position				
						-																Towel dimensions				
Summary:	0,00%	0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	0,00%	0,00%	0,00%				avg: - var: -	Assumptions	0/6	New assumptions		NO

Note: For the second and third folds, report only one of the rows.

Summary results

Start config.	First fold						Second fold						Third fold						Assumptions	New assumptions:
	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)		Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)		Quality function fold	Time in sec	Success [GR1] (1|0)	Success [GR2] (1|0)	Success [MAN] (1|0)		Quality function fold	Time in sec		
[pg2]			0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0/6	NO
[pg1]		0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0/6	NO
[ft]	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0/6	NO
[cr]	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0,00%	0,00%	0,00%		-	avg: - var: -	0/6	NO

Comments
- What makes the system successful?   - What makes the system fail?   - What was improved compared to other methods?   - Chosen grasping points and/or grasping strategy.