RAL-SI-2020-B19-0832_2-V1.0 Scoring Sheet

Big to Length Width	100		Small tow Length Width	50																						
Indicate planned grasping points					g points	Indicate planned grasping points								Indicate planned grasping points												
Object																[bt] o										
				t fold	0	uality				Secon	d fold		Quality				Success	d fold		Quality						
Starting config.	Success [GR1] (1 0)	Success [GR2] (1 0)	Success [MAN] (1 0)	Area before	Area fur	nction fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
						-																Table color		Illumination changes		
[pg2]						-									-							Table position Towel color				
						-																Towel position Towel dimensions				
						_																,		1		
Summary:			0,00%				vg: -	0,00%	0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%			-	avg: - var: -	Assumptions	0/6	New assur	mptions	NO
						1**	u	1	1	1	_		-	· · ·							1441.					
Object			Firm	t fold				1		Secon					1	[bt] o		d fold						1		
			Success		Q	uality							Quality				Success [MAN]			Quality						
Starting config.	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area fur after	nction fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	Success [MAN] (1 0)	Area before	Area after	function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
						-																Table color Table position		Illumination changes		
[pg1]						-																Towel color				
						-																Towel position Towel dimensions				
				_											-											
Summary:		0,00%	0,00%				vg: -	0,00%	0,00%	0,00%				avg: -	0,00%	0,00%	0,00%			-	avg: -	Assumptions	0/6	New assur	nptions	NO
																						'		•	•	
Object			Fire	t fold				Second fold						[bt] or [st] Third fold												
			Success			uality	_			Success			Quality	_			Success			Quality						
Starting config.	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area fur after	fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
						-					_	-						+				Table color Table position		Illumination changes		
[ft]						-																Towel color				
						-							1		1							Towel position Towel dimensions				
																										,
Summary:	0,00%	0,00%	0,00%				vg: - ar: -	0,00%	0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%			-	avg: - var: -	Assumptions	0/6	New assur	nptions	NO
Object			Fire	t fold						Secon	d fold					[bt] o		d fold								
			Success		. 0	uality	_	l		Success			Quality	_			Success			Quality	_					
Starting config.	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area fur after	nction fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	[MAN] (1 0)	Area before	Area after	function fold	Time in sec	Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
						-					-		-		-							Table color Table position		Illumination changes		
[cr]						-																Towel color				
						-									-							Towel position Towel dimensions				
						\Rightarrow				1											1			+		
Summary:	0,00%	0,00%	0,00%			- av	vg: - ar: -	0,00%	0,00%	0,00%			-	avg: - var: -	0,00%	0,00%	0,00%			-	avg: -	Assumptions	0/6	New assur	nptions	NO
-		•	-			- 1		•	•	•					•					•	•			•		

Note: For the second and third folds, report only one of the rows.

Summary results																			
			Firs	t fold			Second fold												
Start config.	Success [GR1] (1 0)	Success [GR2] (1 0)	Success [MAN] (1 0)		Quality function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	Success [MAN] (1 0)		Quality function fold	Time in sec	Success [GR1] (1 0)	Success [GR2] (1 0)	Success [MAN] (1 0)	Quality function fold	Time in sec	Assumptions	New assumptions:
[pg2]			0,00%			avg: - var: -	0,00%	0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%		avg: - var: -	0/6	NO
[pg1]		0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%		avg: - var: -	0/6	NO
[ft]	0,00%	0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%		avg: -	0/6	NO
[cr]	0,00%	0,00%	0,00%			avg: - var: -	0,00%	0,00%	0,00%		_	avg: - var: -	0,00%	0,00%	0,00%		avg: - var: -	0/6	NO

Comments

- What makes the system successful?
- What makes the system fail?
- What was improved compared to other methods?
- Chosen grasping points and/or grasping strategy.