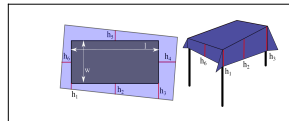


RAL-SI-2020-B19-0832_1-V1.0 Scoring Sheet

Table dimensions	
Length	120
Width	70

Tablecloth dimensions	
Length	240
Width	145



Indicate planned grasping points
<div style="border: 1px solid black; width: 100px; height: 100px; margin: 0 auto;"></div>

Starting config.	Success [MAN] (1 0)	Success [GR2] (1 0)	Success [GR1] (1 0)	h1	h2	h3	h4	h5	h6	Quality function rotation	Quality function in length	Quality function in width	Time in sec	Force measures (norm in N)			Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
														min	avg	max					
[pg2]										0,00%	0,00%	0,00%					Table color		Illumination changes		
										0,00%	0,00%	0,00%					Table position				
										0,00%	0,00%	0,00%					Tablecloth color				
										0,00%	0,00%	0,00%					Tablecloth position				
										0,00%	0,00%	0,00%					Tablecloth dimensions				

Summary:	0,00%									-	-	-	avg: - var: -	avg: - var: -	avg: - var: -	avg: - var: -	Assumptions:	0/6	New assumptions:		NO
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Starting config.	Success [MAN] (1 0)	Success [GR2] (1 0)	Success [GR1] (1 0)	h1	h2	h3	h4	h5	h6	Quality function rotation	Quality function in length	Quality function in width	Time in sec	Force measures (norm in N)			Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
														min	avg	max					
[pg1]										0,00%	0,00%	0,00%					Table color		Illumination changes		
										0,00%	0,00%	0,00%					Table position				
										0,00%	0,00%	0,00%					Tablecloth color				
										0,00%	0,00%	0,00%					Tablecloth position				
										0,00%	0,00%	0,00%					Tablecloth dimensions				

Summary:	0,00%	0,00%								-	-	-	avg: - var: -	avg: - var: -	avg: - var: -	avg: - var: -	Assumptions:	0/6	New assumptions:		NO
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Starting config.	Success [MAN] (1 0)	Success [GR2] (1 0)	Success [GR1] (1 0)	h1	h2	h3	h4	h5	h6	Quality function rotation	Quality function in length	Quality function in width	Time in sec	Force measures (norm in N)			Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
														min	avg	max					
[cr]										0,00%	0,00%	0,00%					Table color		Illumination changes		
										0,00%	0,00%	0,00%					Table position				
										0,00%	0,00%	0,00%					Tablecloth color				
										0,00%	0,00%	0,00%					Tablecloth position				
										0,00%	0,00%	0,00%					Tablecloth dimensions				

Summary:	0,00%	0,00%	0,00%							-	-	-	avg: - var: -	avg: - var: -	avg: - var: -	avg: - var: -	Assumptions:	0/6	New assumptions:		NO
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Starting config.	Success [MAN] (1 0)	Success [GR2] (1 0)	Success [GR1] (1 0)	h1	h2	h3	h4	h5	h6	Quality function rotation	Quality function in length	Quality function in width	Time in sec	Force measures (norm in N)			Assumptions	Used (YES NO)	Assumptions	Used (YES NO)	New assumptions
														min	avg	max					
[fd]										0,00%	0,00%	0,00%					Table color		Illumination changes		
										0,00%	0,00%	0,00%					Table position				
										0,00%	0,00%	0,00%					Tablecloth color				
										0,00%	0,00%	0,00%					Tablecloth position				
										0,00%	0,00%	0,00%					Tablecloth dimensions				

Summary:	0,00%	0,00%	0,00%							-	-	-	avg: - var: -	avg: - var: -	avg: - var: -	avg: - var: -	Assumptions:	0/6	New assumptions:		NO
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Starting config.	Success [MAN] (1 0)	Success [GR2] (1 0)	Success [GR1] (1 0)		Quality function rotation	Quality function in length	Quality function in width	Time in sec	Force measures (norm in N)			Assumptions:	New assumptions:
									<i>min</i>	<i>avg</i>	<i>max</i>		
[pg2]	0,00%				-	-	-	avg: -	avg: -	avg: -	avg: -	0/6	NO
								var: -	var: -	var: -	var: -		
[pg1]	0,00%	0,00%			-	-	-	avg: -	avg: -	avg: -	avg: -	0/6	NO
								var: -	var: -	var: -	var: -		
[cr]	0,00%	0,00%	0,00%		-	-	-	avg: -	avg: -	avg: -	avg: -	0/6	NO
								var: -	var: -	var: -	var: -		
[fd]	0,00%	0,00%	0,00%		-	-	-	avg: -	avg: -	avg: -	avg: -	0/6	NO
								var: -	var: -	var: -	var: -		

Comments

- What makes the system successful?
- What makes the system fail?
- What was improved compared to other methods?
- Chosen grasping points and/or grasping strategy.