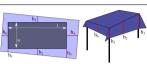
## B-DACM-T-0.1 scoring sheet

Table dime	nsions
Lenght	120
Width	70

ĺ	Tablec	loth dimensions
ı	Lenght	240
İ	Width	145





Starting	Success [MAN]		Success [GR1]	b4	h2	h2	b4	h5	h6	Quality function	Quality function in	Quality function in	Time	Force	measures (norn	n in N)	Assumptions	Used	Assumptions	Used	New assumptions
config.	(1   0)	(1   0)	(1   0)		2			113	110	rotation	lenght	width	in sec	min	avg	max	Assumptions	(YES   NO)	Assumptions	(YES   NO)	New assumptions
	1			42	38.5	35	63	37	55	1.52%	6.67%	2.00%	18.7				Table color	NO	Illumination changes	NO	
	0									0.00%	0.00%	0.00%					Table position known	YES			
[pg2]	1			48.5	47	45.5	66.5	29	51	1.33%	12.92%	24.00%	18.1				Object position known	NO			
	1			51	46.5	44	61.5	29	58	1.52%	2.92%	23.33%	18				Tablecloth color	NO			
	1			48	46	44	48	30	60.5	1.41%	10.42%	21.33%	18.3				Tablecloth dimensions	YES			

	Summary:	80.00%		
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4 449/	8.23%	17.67%	avg: 18.28	avg: -	avg: -	avg: -	Assumptions:	2/6	New assumptions:	NO
1.44%	0.23/6	17.07/0	var: 0.10	var: -	var: -	var: -	Assumptions.	2/6	New assumptions.	NO

Starting			Success [GR1]	h1	h2	h3	h4	h5		Quality function	Quality function in	Quality function in	Time	Force	measures (norm	n in N)	Assumptions	Used	Assumptions	Used (YES   NO)	New assumptions
config.	(1   0)	(1   0)	(1   0)							rotation	lenght	width	in sec	min	avg	max		(YES   NO)		(YES   NO)	
	1	1		31	17	4	59.5	62	64	1.63%	3.75%	60.00%	72.7				Table color	NO	Folded to make robot grasp short edge of tablecloth	YES	
	0	1								0.00%	0.00%	0.00%	72.46				Table position known	YES	Illumination changes	NO	
[pg1]	0	0								0.00%	0.00%	0.00%					Object position known	NO			
	1	1		22.5	13.5	5.5	57	62.5	62	1.60%	4.17%	65.33%	71.96				Tablecloth color	NO			
	1	1		38	33	24	68	42.5	50.5	1.59%	14.58%	12.67%	71.85				Tablecloth dimensions	YES			

Summ	ary:	60.00%	80.00%	
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1.61%	7.50%		avg: 72.24	avg: -	avg: -	avg: -	Assumptions:	2/7	Now assumptions:	NO
1.01/6	7.50 /6	46.00%	var: 0.16	var: -	var: -	var: -	Assumptions.	3//	New assumptions.	NO

Starting	Success [MAN]			h1	h2	h3	h4	h5	h6	Quality function	Quality function in	Quality function in	Time	Force	measures (norm	n in N)	Assumptions	Used	Assumptions	Used	New assumptions
config.	(1   0)	(1   0)	(1   0)							rotation	lenght	width	in sec	min	avg	max	Accumptions	(YES   NO)	Accumptions	(YES   NO)	non assamptions
	0	0	1														Table color	NO	Grasp points visible on table	YES	
	0	0	0														Table position known	YES	Illumination changes	NO	
[cr]	0	0	1														Object position known	NO	Cloth placed to make robot grasp the short edge of tablecloth	YES	Grasp point is the closest point of the cloth to the robot
	0	0	1														Tablecloth color	NO			
	0	0	1														Tablecloth dimensions	YES			
•	•	•										•						•			

Summary:	0.00%	0.00%	80.00%				avg: -	avg: -	avg: -	avg: -	Assumptions:	4/8	New accumptions:	VEC
Summary.	0.00 /6	0.00 /6	80.00%	-	-	-	var: -	var: -	var: -	var: -	Assumptions.	4/0	New assumptions.	123

Starting	Success [MAN]	Success [GR2]	Success [GR1]	h1	h2	h3	h4	h5	h6	Quality function	Quality function in	Quality function in	Time	Force	measures (norm	in N)	Assumptions	Used	Assumptions	Used	New assumptions
config.	(1   0)	(1   0)	(1   0)							rotation	lenght	width	in sec	min	avg	max		(YES   NO)		(YES   NO)	
	0	0	0							0	0	0					Table color	NO	Top layer of folded tablecloth contains grasp point	YES	
	0	0	0							0	0	0					Table position known	YES	Illumination changes	NO	
[fd]	0	0	1							0	0	0					Object position known	NO	Folded to make robot grasp short edge of tablecloth	YES	Grasp point is the closest point of the cloth to the robot
	0	0	1							0	0	0					Tablecloth color	NO			
	0	0	1							0	0	0					Tablecloth dimensions	YES			
		•										•						•			

				Summar	y results							
Starting config.	Success [MAN]	Success [GR2]		Quality function	Quality function in	Quality function in	Time	Force	measures (norm	n in N)	Assumptions:	New
	(1   0)	(1   0)	(1   0)	rotation	lenght	width	in sec	min	avg	max		assumptions:
[pg2]	80.00%			1.44%	8.23%	17.67%	avg: 18.28	avg: -	avg: -	avg: -	2/6	NO
[P92]	80.00 /6			1.44/0	0.23/6	17.07/6	var: 0.10	var: -	var: -	var: -	2/0	NO
[pg1]	60.00%	80.00%		1.61%	7.50%	46.00%	avg: 72.24	avg: -	avg: -	avg: -	3/7	NO
[hā1]	60.00 /6	80.00%		1.01/6	7.50 /6	46.00 /6	var: 0.16	var: -	var: -	var: -	3//	NO
[cr]	0.00%	0.00%	80.00%	_			avg: -	avg: -	avg: -	avg: -	4/8	YES
[CI]	0.00 /6	0.00 /6	80.00%	-	-	-	var: -	var: -	var: -	var: -	4/0	123
[fd]	0.00%	0.00%	60.00%	_			avg: -	avg: -	avg: -	avg: -	4/8	YES
[iu]	0.00 /6	0.00 /6	60.00%	-	-	-	var: -	var: -	var: -	var: -	4/0	123