

TD – Semantics and Verification

VII– Büchi Automata and ω -Regular Properties

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In the rest of the exercises, we will discuss properties of ω -regular expressions and Büchi automata. Given $U \subseteq \Sigma^*$ and $A \subseteq \Sigma^\omega$, recall that

- A is ω -regular iff there are regular languages $E_1, \dots, E_n, F_1, \dots, F_n \subseteq \Sigma^*$ such that for all i , $\epsilon \notin F_i$ and

$$A = E_1 \cdot F_1^\omega + \dots + E_n \cdot F_n^\omega$$

- $U \cdot A = \{\hat{\sigma} \cdot \sigma \in \Sigma^\omega \mid \hat{\sigma} \in U \text{ and } \sigma \in A\}$
- If $\epsilon \notin U$, $U^\omega = \{\sigma \in \Sigma^\omega \mid \exists (u_k \in U)_{k \in \mathbb{N}}. \sigma = u_0 \cdot u_1 \cdot u_2 \cdots\}$

Exercise 1.

Let φ, ψ with parameters ρ and let $\theta(X) := \psi \vee (\varphi \wedge \bigcirc X)$. Let further $P := \llbracket (\varphi \cup \psi) \vee \Box \varphi \rrbracket_\rho$. Show that P is a fixpoint of $\llbracket \theta \rrbracket_\rho(X)$.

Exercise 2.

Let $A = \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$. For the following subsets $P_i \subseteq A^\omega$: is P_i open? closed? dense?, ω -regular?

1. $P_1 = \{\sigma \in A^\omega \mid \exists^\infty i, \sigma(i) = \mathbf{a} \text{ and there are arbitrarily large consecutive sequences of bs}\}$
2. $P_2 = \{\sigma \in A^\omega \mid \exists^\infty i, \sigma(i) = \mathbf{a} \wedge \exists k > i, \sigma(k) = \mathbf{b}\}$

Büchi Automata

Exercise 3.

1. Let $\text{AP} = \{a, b\}$. Give an non-deterministic Büchi automaton (NBA) that accepts “b holds for a finite time until a holds forever and b never holds again”. You may use propositional formulas as labels.
2. Depict an NBA for the language described by the ω -regular expression $(AB+)^*((AA+B)C)^\omega + (A^*C)^\omega$.

Constructions on Büchi Automata

Exercise 4.

Let \mathcal{A}_1 and \mathcal{A}_2 be Büchi automata, and \mathcal{A} an NFA.

1. Show that there is a Büchi automaton $\mathcal{A}_1 + \mathcal{A}_2$ with $\mathcal{L}_\omega(\mathcal{A}_1 + \mathcal{A}_2) = \mathcal{L}_\omega(\mathcal{A}_1) \cup \mathcal{L}_\omega(\mathcal{A}_2)$.
2. Show that there is a Büchi automaton $\mathcal{A} \odot \mathcal{A}_1$ with $\mathcal{L}_\omega(\mathcal{A} \odot \mathcal{A}_1) = \mathcal{L}(\mathcal{A}) \cdot \mathcal{L}(\mathcal{A}_1)$.
3. Show that if $\epsilon \notin \mathcal{L}(\mathcal{A})$, there is a Büchi automaton \mathcal{A}_ω such that $\mathcal{L}_\omega(\mathcal{A}_\omega) = \mathcal{L}(\mathcal{A})^\omega$.
4. Show that there is a Büchi automaton $\mathcal{A}_1 \sqcap \mathcal{A}_2$ with $\mathcal{L}_\omega(\mathcal{A}_1 \sqcap \mathcal{A}_2) = \mathcal{L}_\omega(\mathcal{A}_1) \cap \mathcal{L}_\omega(\mathcal{A}_2)$.

Decomposition of ω -regular Linear Time Properties

Exercise 5.

Let $U \subseteq \Sigma^*$ and $A, B \subseteq \Sigma^\omega$.

1. Show that $\text{pref}(A \cup B) = \text{pref}(A) \cup \text{pref}(B)$.
2. Show that $\text{pref}(U \cdot A) = \text{pref}(U) \cup U \cdot \text{pref}(A)$.
3. Show that $\text{pref}(U^\omega) = \text{pref}(U^*)$.

Exercise 6.

We want to show the decomposition theorem for ω -regular properties.

1. Show that if $A \subseteq \Sigma^\omega$ is ω -regular, then $\text{pref}(A) \subseteq \Sigma^*$ is regular. (You may use that $\text{pref}(U)$ is regular if $U \subseteq \Sigma^*$ is regular.)
2. Show that $\text{cl}(U)$ is a safety property induced by $P_{\text{bad}} = U^c$.
3. Deduce that if $P \subseteq \mathcal{P}(\text{AP})^\omega$ is an ω -regular safety property, then P is a *regular* safety property.
4. Let P_{bad} be a set of bad prefix of $\text{cl}(U)$ and \mathcal{A} be a complete deterministic automaton recognizing P_{bad} such that for all final state q_F of \mathcal{A} and all $a \in \Sigma$, $\delta(q_F, a) = q_F$. Show that $\mathcal{L}_\omega(\mathcal{A}) = (2^{\text{AP}})^\omega \setminus \text{cl}(U)$.
5. Show that if U is regular then $\text{cl}(U)$ is ω -regular (*we recall that if $\text{cl}(U)$ is a regular safety property, we can always find P_{bad} and \mathcal{A} satisfying the properties of the previous question*).
6. Show that for every ω -regular linear time property P , there is a ω -regular safety property P_{safe} and a ω -regular liveness property P_{live} such that $P = P_{\text{safe}} \cap P_{\text{live}}$.