

TD – Semantics and Verification  
**IX– Bisimulations and HML**  
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## Bisimulations

Recall that for two  $TS_0$  and  $TS_1$  such that  $TS_i = (S_i, \text{Act}, \rightarrow_i, I_i, \text{AP}, L_i)$ , the relation  $\mathcal{R} \subseteq S_0 \times S_1$  is said to be a bisimulation iff for all  $(s_0, s_1) \in \mathcal{R}$ , we have:

- $L_0(s_0) = L_1(s_1)$ , and
- for each  $i \in \{0, 1\}$  and each  $\alpha \in \text{Act}$  if  $s_i \xrightarrow{\alpha} s'_i$ , then there is  $s'_{1-i} \in S_{1-i}$  such that  $s_{1-i} \xrightarrow{\alpha} s'_{1-i}$  and  $(s'_0, s'_1) \in \mathcal{R}$ .

We write  $TS_0 \approx TS_1$  if there is bisimulation  $\mathcal{R}$  such that for all  $s_i \in S_i$ , there is  $s_{1-i} \in S_{1-i}$  satisfying  $(s_0, s_1) \in \mathcal{R}$ . The bisimilarity relation  $\sim$  between two systems is defined by  $s_0 \sim s_1$  iff there is a bisimulation  $\mathcal{R}$  such that  $(s_0, s_1) \in \mathcal{R}$ .

### Exercise 1.

Given two transition systems  $TS_0$  and  $TS_1$ , show that:

1. for all  $s \in S_0$ ,  $s \sim s$ .
2. if  $\mathcal{R}$  is a bisimulation, then  $\mathcal{R}^{-1} = \{(s_1, s_0) \in S_1 \times S_0 \mid (s_0, s_1) \in \mathcal{R}\}$  is also a bisimulation.
3. Given a third transition system  $TS_2$ , if  $\mathcal{R}$  is a bisimulation between  $TS_0$  and  $TS_1$  and  $\mathcal{T}$  is a bisimulation between  $TS_1$  and  $TS_2$  then

$$\mathcal{T} \circ \mathcal{R} = \{(s_0, s_2) \in S_0 \times S_2 \mid \exists s_1 \in S_1, (s_0, s_1) \in \mathcal{R} \text{ and } (s_1, s_2) \in \mathcal{T}\}$$

is also a bisimulation.

4. The bisimilarity relation between  $TS_0$  and  $TS_1$  is a bisimulation.
5. If  $\mathcal{R}$  is a bisimulation between  $TS_0$  and  $TS_1$ , then  $\mathcal{R} \subseteq \sim$ .
6. The bisimilarity between  $TS_0$  and itself is an equivalence relation.

### Exercise 2.

Given a transition system  $TS = (S, \text{Act}, \rightarrow, I, \text{AP}, L)$  and  $\sim$  its bisimilarity relation with itself, we define  $TS_{\sim} = (S_{\sim}, \text{Act}, \rightarrow_{\sim}, I_{\sim}, \text{AP}, L_{\sim})$  as follows:

- the states  $S_{\sim}$  of  $TS_{\sim}$  are the equivalence classes of  $\sim$ , i.e.  $S_{\sim} = \{[s]_{\sim} \mid [s]_{\sim} = \{a \in S \mid s \sim a\}\}$
- $I_{\sim} = \{[i]_{\sim} \mid i \in I\}$
- $[s]_{\sim} \xrightarrow{\alpha}_{\sim} [s']_{\sim}$  if  $s \xrightarrow{\alpha} s'$
- $L_{\sim}([s]_{\sim}) = L(s)$

Show that  $TS \approx TS_{\sim}$ .

## HML

We recall that for two sets AP and Act,

- A Kripke frame over Act is given by a set of states  $S$  together with a relation  $\rightarrow \subseteq S \times \text{Act} \times S$ .

- A Kripke model over Act and AP is given by a Kripke frame  $(S, \text{Act}, \rightarrow)$  together with a state labelling  $L : S \rightarrow 2^{\text{AP}}$ .
- The formulae of HML are defined by  $\varphi, \psi := \top \mid \perp \mid a \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \neg\varphi \mid [\alpha]\varphi \mid \langle\alpha\rangle\varphi$  with  $\alpha \in \text{Act}$  and  $a \in \text{AP}$ .

Moreover, given a Kripke model  $M = (S, \text{Act}, \rightarrow, \text{AP}, L)$ , we define the interpretation of an HML-formula inductively (note that  $M$  is not explicit in the notation of the interpretation, but the interpretation depends on  $M$ ):

- $\llbracket a \rrbracket = \{s \in S \mid a \in L(s)\}$
- $\llbracket \top \rrbracket = S$
- $\llbracket \perp \rrbracket = \emptyset$
- $\llbracket \varphi \wedge \psi \rrbracket = \llbracket \varphi \rrbracket \cap \llbracket \psi \rrbracket$
- $\llbracket \varphi \vee \psi \rrbracket = \llbracket \varphi \rrbracket \cup \llbracket \psi \rrbracket$
- $\llbracket \neg\varphi \rrbracket = S \setminus \llbracket \varphi \rrbracket$
- $\llbracket [\alpha]\varphi \rrbracket = \{s \in S \mid \forall s', \text{ if } s \xrightarrow{\alpha} s' \text{ then } s' \in \llbracket \varphi \rrbracket\}$
- $\llbracket \langle\alpha\rangle\varphi \rrbracket = \{s \in S \mid \exists s', s \xrightarrow{\alpha} s' \text{ and } s' \in \llbracket \varphi \rrbracket\}$

We say that a state  $s$  of  $M$  satisfies  $\varphi$ , and denote it  $s \models \varphi$ , iff  $s \in \llbracket \varphi \rrbracket$ . We say that  $M$  satisfies  $\varphi$ , and denote it  $M \models \varphi$ , if  $s \models \varphi$  for all  $s \in S$ . We say that  $\varphi$  is valid, and denote it  $\models \varphi$  if  $M \models \varphi$  for every Kripke model  $M$  (over Act and AP). Finally we say that  $\varphi$  and  $\psi$  are logically equivalent, and denote it  $\varphi \equiv \psi$ , if  $\models \varphi \leftrightarrow \psi$  (with the usual definition of  $\leftrightarrow$ ). Equivalently,  $\varphi \equiv \psi$  if and only if  $\llbracket \varphi \rrbracket = \llbracket \psi \rrbracket$  for every Kripke model.

#### Exercise 3.

Let AP be a set. We fix  $\text{Act} = \{\bullet\}$ . We define the Kripke model  $M((2^{\text{AP}})^\omega) = ((2^{\text{AP}})^\omega, \text{Act}, \rightarrow, \text{AP}, L)$  on streams where

- $\alpha \xrightarrow{\bullet} \beta$  iff  $\beta = \alpha \upharpoonright 1$
  - $L(\alpha) = \alpha(0)$
1. Show that  $\llbracket \langle\bullet\rangle\varphi \rrbracket = \llbracket [\bullet]\varphi \rrbracket = \{\sigma \mid \sigma \upharpoonright 1 \in \llbracket \varphi \rrbracket\}$
  2. Show that for all  $P \subseteq (2^{\text{AP}})^\omega$ , the following are equivalent:
    - There is a HML-formula  $\varphi$  such that  $P = \llbracket \varphi \rrbracket$
    - There is a LML-formula  $\varphi$  such that  $P = \llbracket \varphi \rrbracket$
  3. Show that for all  $\alpha, \beta \in (2^{\text{AP}})^\omega$ ,  $\alpha = \beta$  iff  $\alpha \sim \beta$ .

#### Exercise 4.

Show the following equivalences:

1.  $\langle\alpha\rangle\varphi \equiv \neg[\alpha]\neg\varphi$
2.  $[\alpha]\varphi \equiv \neg\langle\alpha\rangle\neg\varphi$
3.  $\langle\alpha\rangle(\varphi \vee \psi) \equiv (\langle\alpha\rangle\varphi) \vee (\langle\alpha\rangle\psi)$
4.  $[\alpha](\varphi \wedge \psi) \equiv ([\alpha]\varphi) \wedge ([\alpha]\psi)$
5.  $\langle\alpha\rangle\perp \equiv \perp$
6.  $[\alpha]\top \equiv \top$

## Characterization of DBAs

#### Exercise 5.

1. Let  $\text{AP} = \{a, b\}$ . Show that  $\{\sigma \mid \exists^\infty t, a \in \sigma(t)\} \subseteq (2^{\text{AP}})^\omega$  is not closed.
2. Show that there is a DBA  $\mathcal{A}$  such that  $\mathcal{L}_\omega(\mathcal{A})$  is not a safety property.
3. Show that for every regular safety property  $P$ , there is a DBA  $\mathcal{A}$  such that  $P = \mathcal{L}_\omega(\mathcal{A})$ .