Ram Padmanabhan

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EDUCATION

University of Illinois Urbana-Champaign — Urbana, IL, USA
Ph.D. Electrical and Computer Engineering — *August 2023 — Present*
Advisor: Prof. Melkior Ornik

University of Michigan — Ann Arbor, MI, USA
M.S. Electrical and Computer Engineering — *August 2021 — April 2023*
Advisor: Prof. Peter Seiler

PES University — Bengaluru, India
B. Tech Electronics and Communication Engineering — *August 2017 — June 2021*
Advisors: Prof. Rajini Makam and Prof. Koshy George
Capstone Project: *Adaptive Iterative Learning Control*

PUBLICATIONS

Preprints and Submitted Material:

[1] G. Puthumanaillam, **R. Padmanabhan**, J. Fuentes, N. Cruz, P. Padrao, R. Hernandez, H. Jiang, W. Schafer, L. Bobadilla, and M. Ornik, "Online Learning of Deceptive Policies under Intermittent Observation," *arXiv:2509.14453* [cs.RO], Sep. 2025.

[2] **R. Padmanabhan** and M. Ornik, "Ignore Drift, Embrace Simplicity: Constrained Nonlinear Control through Driftless Approximation," *arXiv:2509.06188* [math.OC], Sep. 2025.

[3] **R. Padmanabhan** and M. Ornik, "Approximate Energetic Resilience of Nonlinear Systems under Partial Loss of Control Authority," *arXiv:2502.07603* [math.OC], Feb. 2025.

Journal Articles:

[4] **R. Padmanabhan**, A. Aspeel, N. Ozay, and M. Ornik, "Mode-Prefix-Based Control of Switched Linear Systems with Applications to Fault Tolerance," *IEEE Control Systems Letters*, 9, pp. 1784–1789, Jul. 2025 (presented at *64th IEEE Conference on Decision and Control (CDC)*, Dec. 2025).

[5] **R. Padmanabhan** and P. Seiler, "Analysis of Gradient Descent with Varying Step Sizes using Integral Quadratic Constraints," *IEEE Transactions on Automatic Control*, 70(1), pp. 587–594, Jan. 2025.

[6] **R. Padmanabhan**, R. Makam, and K. George, "Multiple Estimation Models for Discrete-time Adaptive Iterative Learning Control," *International Journal of Systems Science*, 55(10), pp. 2154–2171, Apr. 2024.

[7] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "Discrete Robust Control of Robot Manipulators using an Uncertainty and Disturbance Estimator," *Journal of Dynamic Systems, Measurement and Control*, 145(5): 051022, May 2023.

[8] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator," *International Journal of Robust and Nonlinear Control*, 31(10), pp. 4994–5015, Jul. 2021.

Conference Papers:

[9] S. A. Dinkar, **R. Padmanabhan**, A. Clarke, P.-O. Gutman, and M. Ornik, "Analysis of the Unscented Transform Controller for Systems with Bounded Nonlinearities," in *5th Modeling, Estimation and Control Conference (MECC)*, Pittsburgh, PA, USA, Oct. 2025.

[10] **R. Padmanabhan** and M. Ornik, "Energetic Resilience of Linear Driftless Systems," in *11th IFAC Symposium on Robust Control Design (ROCOND)*, Porto, Portugal, Jul. 2025.
(Selected as Finalist, IFAC Young Author Award.)

[11] **R. Padmanabhan**, C. Bakker, S. A. Dinkar, and M. Ornik, "How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances," in *63rd IEEE Conference on Decision and Control (CDC)*, Milan, Italy, Dec. 2024.

[12] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "Second-Level Adaptation and Optimization for Multiple Model Adaptive Iterative Learning Control," in *Seventh Indian Control Conference (ICC)*, Mumbai, India, Dec. 2021, pp. 289–294.

[13] S. Damodaran, **R. Padmanabhan**, R. Maahin, and S. Gurugopinath, "A Copula-Driven Unsupervised Learning Framework for Anomaly Detection with Multivariate Heterogeneous Data," in *IEEE 31st International Workshop on Machine Learning for Signal Processing (MLSP)*, Gold Coast, Queensland, Australia, Oct. 2021.

[14] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "A Novel Strategy with Multiple Models to Improve Performance of Adaptive Iterative Learning Control," in *IEEE International Conference on Electronics, Computing and Communication Technologies (CONECCT)*, Bengaluru, India, Jul. 2021.

[15] **R. Padmanabhan**, S. Damodaran, V. N. Batra, and S. Gurugopinath, "A Convolutional Neural Network Architecture for Camera Model Identification with Small Datasets," in *IEEE International Conference on Electronics, Computing and Communication Technologies (CONECCT)*, Bengaluru, India, Jul. 2020.

AWARDS AND FELLOWSHIPS

Joan and Lalit Bahl Fellowship	*August 2025 — May 2026*
Finalist, IFAC Young Author Award	*July 2025*
Graduate College Mentoring Certificate	*May 2025*
Joan and Lalit Bahl Fellowship	*August 2024 — May 2025*
Prof. CNR Rao Merit Scholarship	*August 2017 — May 2020*
Prof. MRD Merit Scholarship	*August 2017 — May 2020*

MENTORING

Undergraduate Research Apprenticeship Program (URAP) *August 2024 — May 2025*
Mentored an undergraduate student at UIUC on the use of the particle filter for three-dimensional robot localization.

Promoting Undergraduate Research in Engineering (PURE) *August — December 2023*
Mentored a group of three undergraduates at UIUC in investigating the performance of different nonlinear Kalman filters on the problem of battery state-of-charge estimation.
(One student subsequently joined our primary research group.)

TEACHING

Graduate Student Instructor, University of Michigan Ann Arbor, MI, USA
EECS 460 — Control System Analysis and Design *January — April 2023*
Held two discussion sessions each week, with teaching evaluations among the University's highest.

Graduate Student Instructor, University of Michigan Ann Arbor, MI, USA
EECS 301 — Probabilistic Methods in Engineering *August — December 2022*
Held two discussion sessions each week, with teaching evaluations among the University's highest.

EXPERIENCE

Research Intern, Indian Institute of Technology, Bombay   Mumbai, India
Systems and Control Engineering   *December 2020 — May 2021*
Used feedback linearization to achieve an upwind climb in gliding unmanned aerial vehicles with various wind gradient models, avoiding heavy computations from optimal control formulations.

Research Intern, Indian Space Research Organization   Bengaluru, India
Control and Digital Electronics Group   *June — July 2019*
Studied the properties of the Linear and Ensemble Kalman Filter, applied to a one– and three-dimensional motion estimation problem.

PEER REVIEWER

Automatica, IEEE Control Systems Letters, IEEE Transactions on Industrial Electronics, IEEE Transactions on Systems, Man and Cybernetics.
American Control Conference (2025), *IEEE Conference on Decision and Control* (2024, 2025), *IFAC Symposium on Robust Control Design* (2025), *Modeling, Estimation and Control Conference* (2025).

OTHER PRESENTATIONS & POSTERS

Posters:

11th Midwest Workshop on Control and Game Theory
University of Illinois Urbana-Champaign   Urbana, IL, USA
Mode-Prefix-Based Control of Switched Linear Systems with Applications to Fault Tolerance   *April 2025*

10th Midwest Workshop on Control and Game Theory
Northwestern University   Evanston, IL, USA
How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances   *April 2024*

Presentations:

University of California, Berkeley   Berkeley, CA, USA
Analysis of Gradient Descent with Varying Step Sizes using IQCs [Online]   *February 2023*

Research at ECE (R@ECE) Colloquium
PES University   Bengaluru, India
Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator   *April 2021*

MEMBERSHIPS

Graduate Student Member: IEEE; IEEE Control Systems Society; IEEE Signal Processing Society