Machine Learning I

KNN y Naives Bayes

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- 0.1 Definición del proyecto
- 0.2 KNN
- 0.2.1 Distancias
- 0.2.2 KNN Classifier
- 0.2.2.1 R Base

```
library(ISLR)
library(class)
library(caret)
```

```
set.seed(42)
Default$student = as.numeric(Default$student) - 1
default_idx = sample(nrow(Default), 5000)
default_trn = Default[default_idx, ]
default_tst = Default[-default_idx, ]
# training data
X_default_trn = default_trn[, -1]
y_default_trn = default_trn$default
# testing data
X_default_tst = default_tst[, -1]
y_default_tst = default_tst$default
prediccion <- knn(train = X_default_trn, test = X_default_tst,</pre>
                  cl = y_default_trn, k = 3)
head(prediccion)
calc_class_err = function(actual, predicted) {
 mean(actual != predicted)
}
calc_class_err(actual = y_default_tst,
               predicted = knn(train = X_default_trn,
                              test = X_default_tst,
                               cl = y_default_trn,
                               k = 5))
calc_class_err(actual = y_default_tst,
               predicted = knn(train = scale(X_default_trn),
                               test = scale(X_default_tst),
                               cl = y_default_trn,
                                    = 5))
set.seed(42)
k_{to} = 1:100
err_k = rep(x = 0, times = length(k_to_try))
for (i in seq_along(k_to_try)) {
 pred = knn(train = scale(X_default_trn),
            test = scale(X_default_tst),
```

```
cl = y_default_trn,
             k = k_{to_{try}[i]},
             prob = T)
 err_k[i] = calc_class_err(y_default_tst, pred)
}
# plot error vs choice of k
plot(err_k, type = "b", col = "dodgerblue", cex = 1, pch = 20,
     xlab = "k, number of neighbors", ylab = "classification error",
     main = "(Test) Error Rate vs Neighbors")
# add line for min error seen
abline(h = min(err_k), col = "darkorange", lty = 3)
# add line for minority prevalence in test set
abline(h = mean(y_default_tst == "Yes"), col = "grey", lty = 2)
min(err_k)
which(err_k == min(err_k))
max(which(err_k == min(err_k)))
0.2.2.2 packages Caret
set.seed(430)
default_idx = createDataPartition(Default$default, p = 0.75, list = FALSE)
default_trn = Default[default_idx, ]
default_tst = Default[-default_idx, ]
modelLookup("knn")
sim_knn_mod = train(
  default ~ .,
  data = default_trn,
 method = "knn",
```

trControl = trainControl(method = "cv", number = 5),

tuneGrid = expand.grid(k = seq(1, 31, by = 2)))

preProcess = c("center", "scale"),

sim_knn_mod

```
sim_knn_mod$modelType
get_best_result = function(caret_fit) {
  best = which(rownames(caret_fit$results) == rownames(caret_fit$bestTune))
  best_result = caret_fit$results[best, ]
  rownames(best_result) = NULL
  best_result
head(sim_knn_mod$results, 5)
get_best_result(sim_knn_mod)
plot(sim_knn_mod)
sim_knn_mod$finalModel
head(predict(sim_knn_mod, newdata = default_tst, type = "prob"))
caret::confusionMatrix(predict(sim_knn_mod), dp_entr_NUM$CLS_PRO_pro13)
0.2.3 KNN Regresor
library(FNN)
library(MASS)
data(Boston)
set.seed(42)
boston_idx = sample(1:nrow(Boston), size = 250)
trn_boston = Boston[boston_idx, ]
```

```
trn_boston = Boston[boston_idx, ]
tst_boston = Boston[-boston_idx, ]

X_trn_boston = trn_boston[-ncol(trn_boston)]
X_tst_boston = tst_boston[-ncol(trn_boston)]
y_trn_boston = trn_boston["medv"]
y_tst_boston = tst_boston["medv"]
```

```
pred_001 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 1)
pred_005 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 5)
pred_010 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 10)
pred_050 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 50)
pred_100 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 100)
pred_250 = knn.reg(train = X_trn_boston, test = X_tst_boston, y = y_trn_boston, k = 250)
rmse = function(actual, predicted) {
sqrt(mean((actual - predicted) ^ 2))
}
# define helper function for getting knn.reg predictions
# note: this function is highly specific to this situation and dataset
make_knn_pred = function(k = 1, training, predicting) {
  pred = FNN::knn.reg(train = training["lstat"],
                      test = predicting["lstat"],
                      y = training$medv, k = k)$pred
 act = predicting$medv
 rmse(predicted = pred, actual = act)
}
# define values of k to evaluate
k = c(1, 5, 10, 25, 50, 250)
# get requested train RMSEs
knn_trn_rmse = sapply(k, make_knn_pred,
                      training = trn_boston,
                      predicting = trn_boston)
# get requested test RMSEs
knn_tst_rmse = sapply(k, make_knn_pred,
                      training = trn_boston,
                      predicting = tst_boston)
# determine "best" k
best_k = k[which.min(knn_tst_rmse)]
# find overfitting, underfitting, and "best"" k
fit_status = ifelse(k < best_k, "Over", ifelse(k == best_k, "Best", "Under"))</pre>
```

```
# summarize results
knn_results = data.frame(
    k,
    round(knn_trn_rmse, 2),
    round(knn_tst_rmse, 2),
    fit_status
)
colnames(knn_results) = c("k", "Train RMSE", "Test RMSE", "Fit?")

# display results
knitr::kable(knn_results, escape = FALSE, booktabs = TRUE)
```

0.2.3.1 packages Caret

```
caret::modelLookup("knn")
library("CDR")
library("class")
library("caret")
library("reshape")
library("ggplot2")
data(dp_entr_NUM)
head(dp_entr_NUM)
# Definimos un método de remuestreo
cv <- trainControl(</pre>
  method = "repeatedcv",
 number = 10,
 repeats = 5,
  classProbs = TRUE,
  preProcOptions = list("center"),
  summaryFunction = twoClassSummary
```

```
# Definimos la red de posibles valores del hiperparámetro
hyper_grid <- expand.grid(k = c(1:10,15,20,30,50,75,100))</pre>
```

```
set.seed(101)
# Se entrena el modelo ajustando el hiperparámetro óptimo
model <- train(</pre>
  CLS_PRO_pro13 ~ .,
  data = dp_entr_NUM,
  method = "knn",
 trControl = cv,
  tuneGrid = hyper_grid,
  metric = "ROC"
ggplot(model) +
  geom_vline(xintercept = unlist(model$bestTune),col="red",linetype="dashed") +
  theme_light()
ggplot(melt(model\$resample[,-4]), aes(x = variable, y = value, fill=variable)) +
   geom_boxplot(show.legend=FALSE) +
  xlab(NULL) + ylab(NULL)
set.seed(101)
confusionMatrix(predict(model), dp_entr_NUM$CLS_PRO_pro13)
```

0.3 Naives Bayes

0.3.1 NB Classifier

```
set.seed(430)
iris_obs = nrow(iris)
iris_idx = sample(iris_obs, size = trunc(0.50 * iris_obs))
# iris_index = sample(iris_obs, size = trunc(0.10 * iris_obs))
iris_trn = iris[iris_idx, ]
iris_tst = iris[-iris_idx, ]
library(e1071)
```

```
library(e1071)
iris_nb = naiveBayes(Species ~ ., data = iris_trn)
iris_nb
```

```
head(predict(iris_nb, iris_trn))
head(predict(iris_nb, iris_trn, type = "class"))
head(predict(iris_nb, iris_trn, type = "raw"))

iris_nb_trn_pred = predict(iris_nb, iris_trn)
iris_nb_tst_pred = predict(iris_nb, iris_tst)

calc_class_err(predicted = iris_nb_trn_pred, actual = iris_trn$Species)

calc_class_err(predicted = iris_nb_tst_pred, actual = iris_tst$Species)

table(predicted = iris_nb_tst_pred, actual = iris_tst$Species)
```

0.3.2 Packages caret

```
library("caret")
library("naivebayes")
library("reshape")
library("ggplot2")
library("CDR")

data("dp_entr")
```

```
# se muestra la salida del modelo
model
```

```
confusionMatrix(model)
```

```
ggplot(melt(model$resample[,-4]), aes(x = variable, y = value, fill=variable)) +
  geom_boxplot(show.legend=FALSE) +
  xlab(NULL) + ylab(NULL)
```

0.4 Bibliografia

 $\bullet \ \ https://daviddalpiaz.github.io/r$

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