

# Practical Machine Learning - Project

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This document details the Project for the course Practical Machine Learning under Data Science specialization.

## Background

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website here: '<http://groupware.les.inf.puc-rio.br/har>' (<http://groupware.les.inf.puc-rio.br/har>)' (see the section on the Weight Lifting Exercise Dataset).

## Data

The training data for this project are available here:

<https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv>  
(<https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv>)

The test data are available here:

<https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv>  
(<https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv>)

The data for this project come from this source: <http://groupware.les.inf.puc-rio.br/har> (<http://groupware.les.inf.puc-rio.br/har>). If you use the document you create for this class for any purpose please cite them as they have been very generous in allowing their data to be used for this kind of assignment.

## What you should submit

The goal of your project is to predict the manner in which they did the exercise. This is the “classe” variable in the training set. You may use any of the other variables to predict with. You should create a report describing how you built your model, how you used cross validation, what you think the expected out of sample error is, and why you made the choices you did. You will also use your prediction model to predict 20 different test cases.

- 1. Your submission should consist of a link to a Github repo with your R markdown and compiled HTML file describing your analysis. Please constrain the text of the writeup to < 2000 words and the number of figures to be less than 5. It will make it easier for the graders if you submit a repo with a gh-pages branch so the HTML page can be viewed online (and you always want to make it easy on graders :-).
- 2. You should also apply your machine learning algorithm to the 20 test cases available in the test data above. Please submit your predictions in appropriate format to the programming assignment for automated grading. See the programming assignment for additional details.

## Modeling Details

The following sections detail about the prediction modeling, cross-validation and testing.

### ***Pre-requisites***

The following libraries are need to be loaded if installed, otherwise need to be downloaded.

- caret package
- libraries for working with Decision trees and Randomforest
- libraries for representing decision trees.

```
setwd("C:/Rama Mohan D/Learning/GitRepo/Practical_ML_Proj/Data/DataInputFiles")
```

```
library(caret)
```

```
## Loading required package: lattice
```

```
## Loading required package: ggplot2
```

```
library(rpart)
```

```
library(rpart.plot)
```

```
library(rattle)
```

```
## Rattle: A free graphical interface for data mining with R.
```

```
## Version 3.3.0 Copyright (c) 2006-2014 Togaware Pty Ltd.
```

```
## Type 'rattle()' to shake, rattle, and roll your data.
```

```
library(randomForest)
```

```
## randomForest 4.6-10
```

```
## Type rfNews() to see new features/changes/bug fixes.
```

## Data Preparation

### ***Loading and Cleaning Data***

```
set.seed(7315)
```

```
# Loading the training data set - replacing all missing with "NA"
```

```
trainingset <- read.csv("C:/Rama Mohan D/Learning/GitRepo/Practical_ML_Proj/Data/DataInputFiles/pml-training.csv", na.strings=c("NA", "#DIV/0!", ""))
```

```
# Loading the testing data set
```

```
testingset <- read.csv("C:/Rama Mohan D/Learning/GitRepo/Practical_ML_Proj/Data/DataInputFiles/pml-testing.csv", na.strings=c("NA", "#DIV/0!", ""))
```

```
dim(trainingset)
```

```
## [1] 19622 160
```

```
dim(testingset)
```

```
## [1] 20 160
```

## ***Data Cleaning***

```
# Delete columns with all missing values
```

```
trainingset<-trainingset[,colSums(is.na(trainingset)) == 0]
```

```
testingset <-testingset[,colSums(is.na(testingset)) == 0]
```

```
# ignoring irrelevant data
```

```
trainingset <-trainingset[,-c(1:7)]
```

```
testingset <-testingset[,-c(1:7)]
```

```
# new datasets:
```

```
dim(trainingset)
```

```
## [1] 19622 53
```

```
dim(testingset)
```

```
## [1] 20 53
```

```
head(trainingset,2)
```

```

##  roll_belt pitch_belt yaw_belt total_accel_belt gyros_belt_x gyros_belt_y
## 1      1.41      8.07    -94.4              3      0.00      0
## 2      1.41      8.07    -94.4              3      0.02      0
##  gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 1      -0.02      -21          4          22          -3
## 2      -0.02      -22          4          22          -7
##  magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
## 1          599      -313    -128      22.5    -161          34
## 2          608      -311    -128      22.5    -161          34
##  gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
## 1          0.00      0.00    -0.02    -288      109      -123
## 2          0.02    -0.02    -0.02    -290      110      -125
##  magnet_arm_x magnet_arm_y magnet_arm_z roll_dumbbell pitch_dumbbell
## 1      -368          337          516      13.05217    -70.49400
## 2      -369          337          513      13.13074    -70.63751
##  yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y
## 1    -84.87394              37              0      -0.02
## 2    -84.71065              37              0      -0.02
##  gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_y accel_dumbbell_z
## 1              0          -234              47      -271
## 2              0          -233              47      -269
##  magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## 1          -559          293              -65      28.4
## 2          -555          296              -64      28.3
##  pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## 1          -63.9      -153              36      0.03
## 2          -63.9      -153              36      0.02
##  gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## 1              0          -0.02              192      203
## 2              0          -0.02              192      203
##  accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 1          -215          -17              654      476
## 2          -216          -18              661      473
##  classe
## 1      A
## 2      A

```

```
head(testingset,2)
```

```

##  roll_belt pitch_belt yaw_belt total_accel_belt gyros_belt_x gyros_belt_y
## 1    123.00    27.00   -4.75             20      -0.50      -0.02
## 2     1.02     4.87  -88.90             4       -0.06      -0.02
##  gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 1     -0.46     -38       69      -179       -13
## 2     -0.07     -13       11       39       43
##  magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
## 1       581     -382    40.7    -27.8    178       10
## 2       636     -309     0.0     0.0     0       38
##  gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
## 1     -1.65     0.48    -0.18     16     38     93
## 2     -1.17     0.85    -0.43    -290    215    -90
##  magnet_arm_x magnet_arm_y magnet_arm_z roll_dumbbell pitch_dumbbell
## 1     -326     385     481    -17.73748    24.96085
## 2     -325     447     434    54.47761    -53.69758
##  yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y
## 1    126.2360             9         0.64         0.06
## 2   -75.5148             31         0.34         0.05
##  gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_y accel_dumbbell_z
## 1     -0.61             21        -15         81
## 2     -0.71          -153         155        -205
##  magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## 1       523          -528         -56        141
## 2      -502           388         -36        109
##  pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## 1       49.3         156             33         0.74
## 2      -17.6         106             39         1.12
##  gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## 1     -3.34          -0.59        -110         267
## 2     -2.78          -0.18         212         297
##  accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 1     -149          -714         419         617
## 2     -118          -237         791         873
##  problem_id
## 1          1
## 2          2

```

## **sampling - Cross-validation**

Splitting training data into training and Cross-validation sets using datapartition function.

- Cross-validation is performed by sampling training data set randomly without replacement into 2 subsamples:
- subTraining data (75% of the original Training data set)
- subTesting data (25%).
- Models are fitted on the subTraining data set, and tested on the subTesting data. Most accurate model is chosen, and tested on the original Testing data set.

```
samples <- createDataPartition(y=trainingset$classe, p=0.75, list=FALSE)
subTraining <- trainingset[samples, ]
subTesting <- trainingset[-samples, ]
dim(subTraining)
```

```
## [1] 14718    53
```

```
dim(subTesting)
```

```
## [1] 4904    53
```

```
head(subTraining,2)
```

```

##  roll_belt pitch_belt yaw_belt total_accel_belt gyros_belt_x gyros_belt_y
## 1      1.41      8.07    -94.4              3      0.00              0
## 2      1.41      8.07    -94.4              3      0.02              0
##  gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 1      -0.02      -21          4          22          -3
## 2      -0.02      -22          4          22          -7
##  magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
## 1          599      -313    -128      22.5    -161          34
## 2          608      -311    -128      22.5    -161          34
##  gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
## 1          0.00          0.00    -0.02    -288      109      -123
## 2          0.02    -0.02    -0.02    -290      110      -125
##  magnet_arm_x magnet_arm_y magnet_arm_z roll_dumbbell pitch_dumbbell
## 1      -368          337          516      13.05217    -70.49400
## 2      -369          337          513      13.13074    -70.63751
##  yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y
## 1    -84.87394              37              0      -0.02
## 2    -84.71065              37              0      -0.02
##  gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_y accel_dumbbell_z
## 1              0          -234              47      -271
## 2              0          -233              47      -269
##  magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## 1      -559              293              -65      28.4
## 2      -555              296              -64      28.3
##  pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## 1      -63.9          -153              36      0.03
## 2      -63.9          -153              36      0.02
##  gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## 1              0          -0.02              192      203
## 2              0          -0.02              192      203
##  accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 1      -215              -17              654      476
## 2      -216              -18              661      473
##  classe
## 1      A
## 2      A

```

```
head(subTesting,2)
```

```

##  roll_belt pitch_belt yaw_belt total_accel_belt gyros_belt_x gyros_belt_y
## 3      1.42      8.07    -94.4              3      0.00      0
## 7      1.42      8.09    -94.4              3      0.02      0
##  gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 3      -0.02      -20        5        23        -2
## 7      -0.02      -22        3        21        -4
##  magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
## 3          600      -305    -128     22.5    -161        34
## 7          599      -311    -128     21.9    -161        34
##  gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
## 3          0.02     -0.02     -0.02     -289     110     -126
## 7          0.00     -0.03      0.00     -289     111     -125
##  magnet_arm_x magnet_arm_y magnet_arm_z roll_dumbbell pitch_dumbbell
## 3         -368        344        513     12.85075    -70.27812
## 7         -373        336        509     13.12695    -70.24757
##  yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y
## 3    -85.14078              37              0      -0.02
## 7    -85.09961              37              0      -0.02
##  gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_y accel_dumbbell_z
## 3              0          -232              46      -270
## 7              0          -232              47      -270
##  magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## 3          -561              298              -63      28.3
## 7          -551              295              -70      27.9
##  pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## 3          -63.9          -152              36      0.03
## 7          -63.9          -152              36      0.02
##  gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## 3          -0.02              0.00              196      204
## 7          0.00          -0.02              195      205
##  accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 3          -213              -18              658      469
## 7          -215              -18              659      470
##  classe
## 3      A
## 7      A

```

## Exploratory Analysis of Data

All the levels of classes with frequency

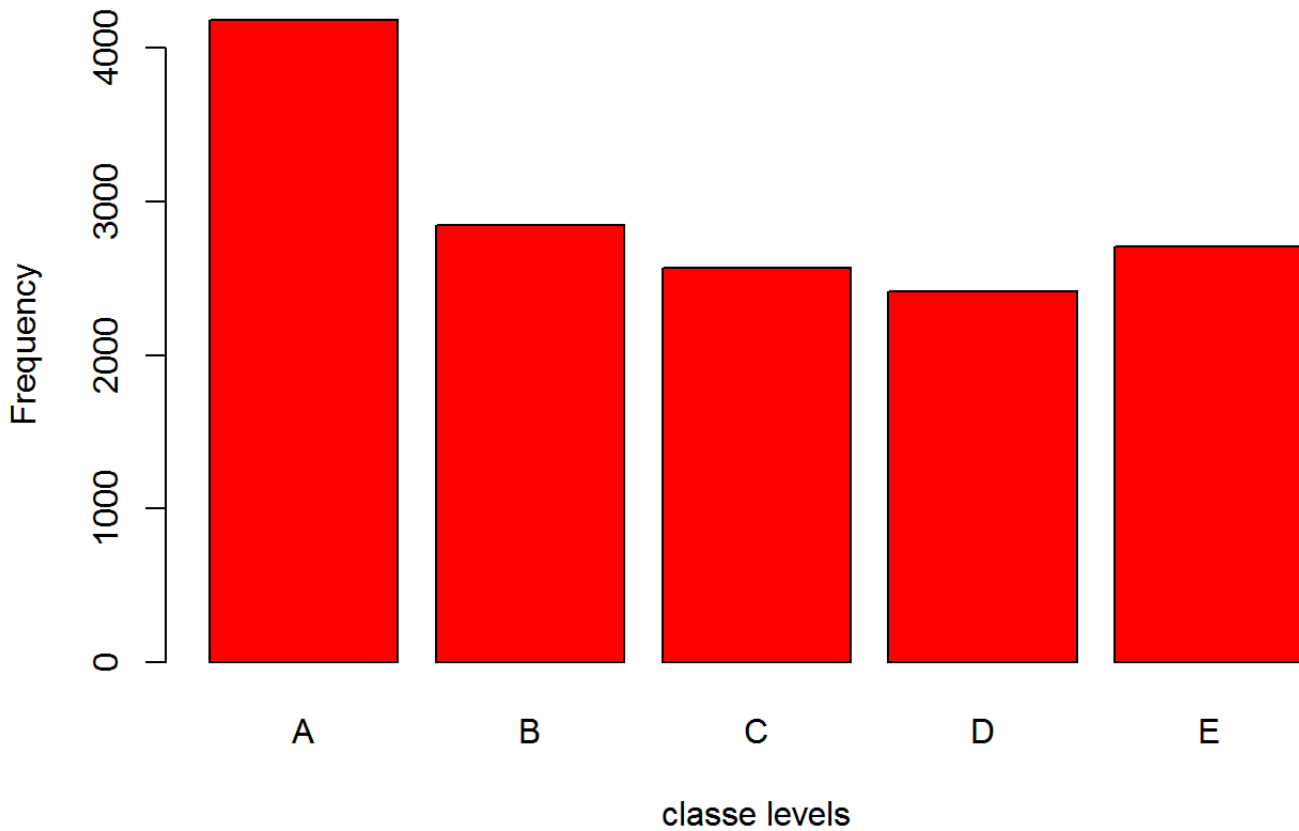
```

plot(subTraining$classe, col="red", main="Plot of levels of the variable classe within the subTraining data set", xlab="classe levels", ylab="Frequency")

```



## Plot of levels of the variable classe within the subTraining data set



### Modeling

Here two prediction (classification) models are tried

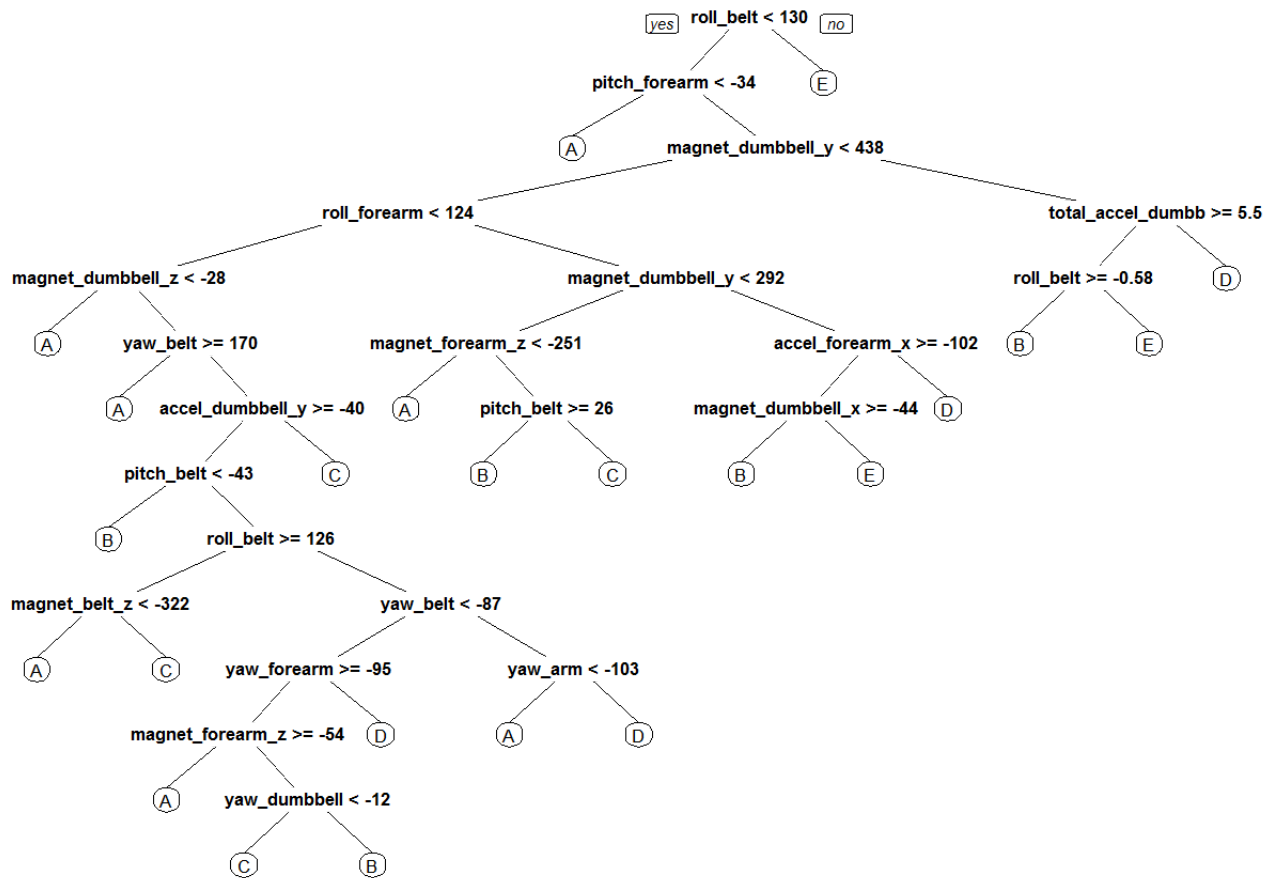
- Decision Tree modeling
- Random Forest modeling

### Using Decision Tree Approach

```
modell1 <- rpart(classe ~ ., data=subTraining, method="class")  
  
# Prediction for subtesting data:  
prediction1 <- predict(modell1, subTesting, type = "class")
```

to view the decision tree run this command

```
# Plot of the Decision Tree  
rpart.plot(modell1)
```



```
#fancyRpartPlot(model1)
```

***prediction statistics***

```
# Test results on subTesting data set:
confusionMatrix(prediction1, subTesting$classe)
```

```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction   A    B    C    D    E
##           A 1290  185   11   79   50
##           B   40  520   41   31   70
##           C   28   83  693  133  112
##           D   15   82   55  529   92
##           E   22   79   55   32  577
##
## Overall Statistics
##
##           Accuracy : 0.7359
##           95% CI : (0.7234, 0.7482)
##   No Information Rate : 0.2845
##   P-Value [Acc > NIR] : < 2.2e-16
##
##           Kappa : 0.6644
##   McNemar's Test P-Value : < 2.2e-16
##
## Statistics by Class:
##
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity           0.9247   0.5479   0.8105   0.6580   0.6404
## Specificity           0.9074   0.9540   0.9121   0.9405   0.9530
## Pos Pred Value        0.7988   0.7407   0.6606   0.6843   0.7542
## Neg Pred Value        0.9681   0.8979   0.9580   0.9334   0.9217
## Prevalence            0.2845   0.1935   0.1743   0.1639   0.1837
## Detection Rate        0.2631   0.1060   0.1413   0.1079   0.1177
## Detection Prevalence  0.3293   0.1431   0.2139   0.1576   0.1560
## Balanced Accuracy      0.9161   0.7510   0.8613   0.7992   0.7967
```

## Using Random Forest Approach

```
#Using Random forest
model2 <- randomForest(classe ~. , data=subTraining, method="class")

# Predicting:
prediction2 <- predict(model2, subTesting, type = "class")
```

The `getTree` method from `randomForest` returns a structure. The output is shown below, with terminal nodes indicated by status code (-1).

```
# Plot of the Random Forest
rfmodeldetails <- getTree(model2, 1, labelVar=TRUE)
head(rfmodeldetails,3)
```

```
## left daughter right daughter split var split point status
## 1 2 3 total_accel_belt 20.5 1
## 2 4 5 accel_dumbbell_y -38.5 1
## 3 6 7 roll_belt 129.5 1
## prediction
## 1 <NA>
## 2 <NA>
## 3 <NA>
```

## ***prediction statistics***

```
# Test results on subTesting data set:
confusionMatrix(prediction2, subTesting$classe)
```

```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction  A    B    C    D    E
##           A 1394    1    0    0    0
##           B    0  947    7    0    0
##           C    0    1  848    6    0
##           D    0    0    0  798    2
##           E    1    0    0    0  899
##
## Overall Statistics
##
##           Accuracy : 0.9963
##           95% CI : (0.9942, 0.9978)
##           No Information Rate : 0.2845
##           P-Value [Acc > NIR] : < 2.2e-16
##
##           Kappa : 0.9954
##           McNemar's Test P-Value : NA
##
## Statistics by Class:
##
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity      0.9993  0.9979  0.9918  0.9925  0.9978
## Specificity      0.9997  0.9982  0.9983  0.9995  0.9998
## Pos Pred Value   0.9993  0.9927  0.9918  0.9975  0.9989
## Neg Pred Value   0.9997  0.9995  0.9983  0.9985  0.9995
## Prevalence       0.2845  0.1935  0.1743  0.1639  0.1837
## Detection Rate   0.2843  0.1931  0.1729  0.1627  0.1833
## Detection Prevalence 0.2845  0.1945  0.1743  0.1631  0.1835
## Balanced Accuracy 0.9995  0.9981  0.9950  0.9960  0.9988
```

## Out-of-sample error

. The expected out-of-sample error - accuracy in the cross-validation data. . Accuracy is the proportion of correct classified observation . Expected accuracy is the expected accuracy in the out-of-sample data set (i.e. original testing data set).

Random Forest Approach prediction accuracy is better compared to decision tree

## Prediction on TESTING Data

Prediction on testing data is done using both the modeling approaches but Random Forest Approach predictions are used for generating files.

```
# predict outcome levels on the original Testing data set using Decision Tree algorithm and Random Forest Approach
predictfinal1 <- predict(model1, testingset, type="class")
predictfinal2 <- predict(model2, testingset, type="class")
```

## Writing to Files

```
# Write files for submission
pml_write_files = function(x){
  n = length(x)
  for(i in 1:n){
    filename = paste0("problem_id_",i,".txt")
    write.table(x[i],file=filename,quote=FALSE,row.names=FALSE,col.names=FALSE)
  }
}
pml_write_files(predictfinal2)
```