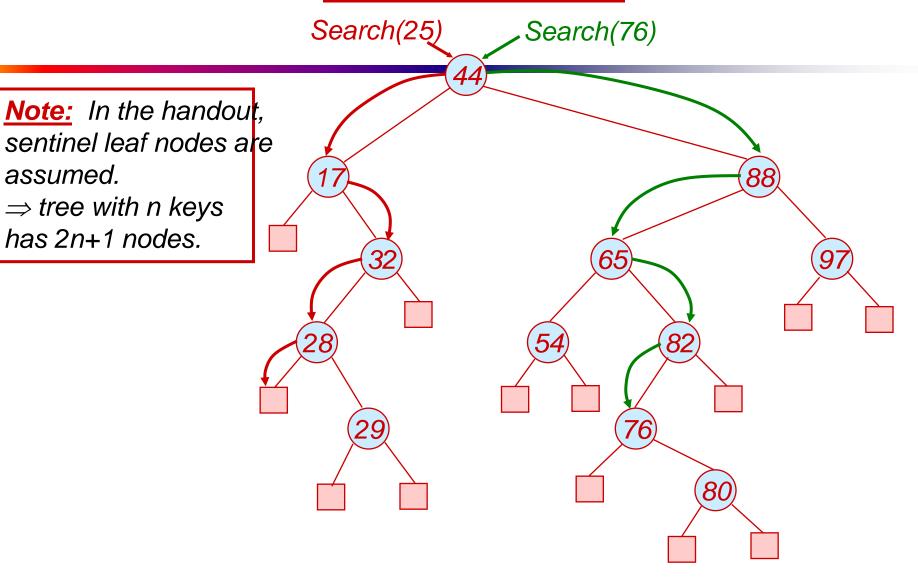
Algorithms

Splay Trees

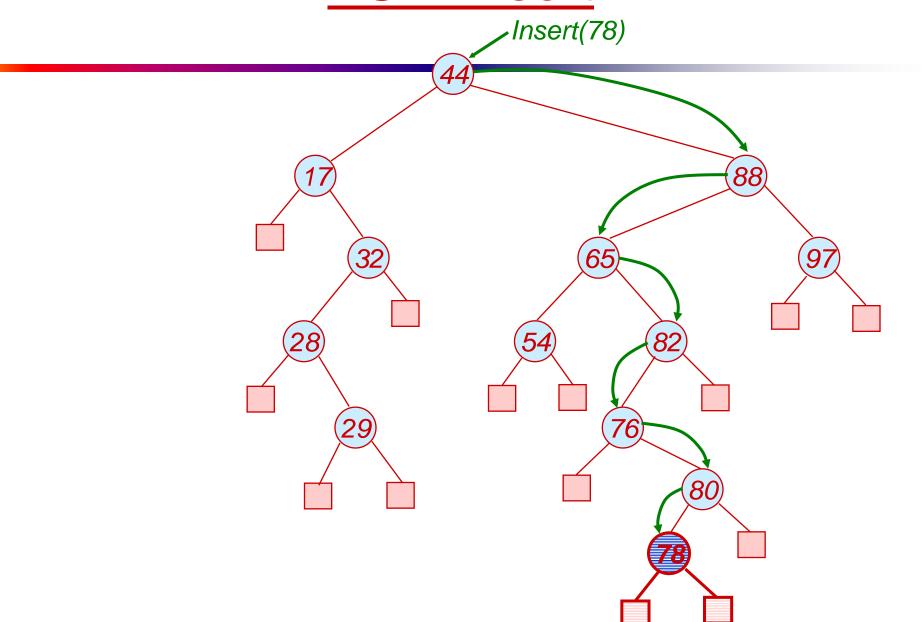
Splay Trees

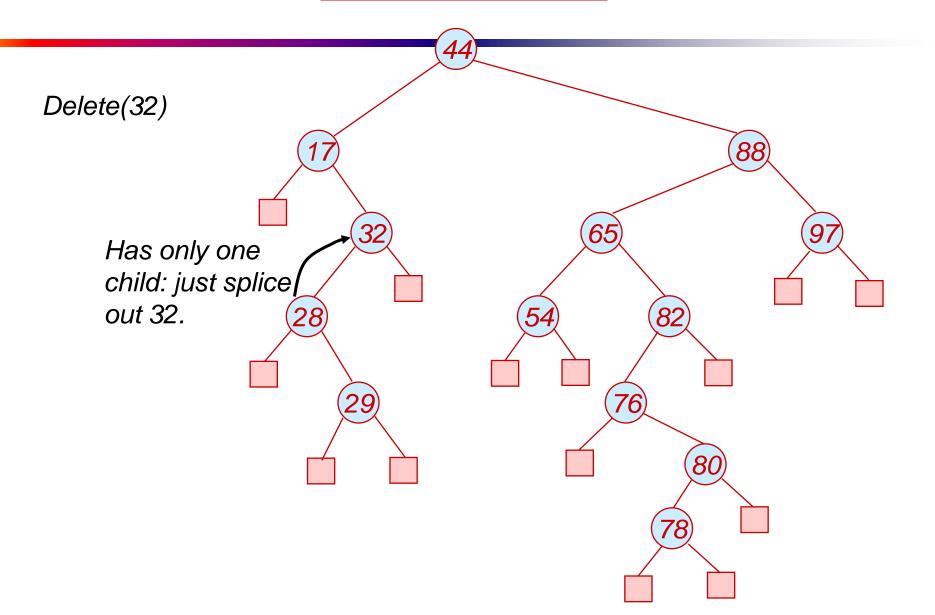
- In balanced tree schemes, explicit rules are followed to ensure balance.
- In splay trees, there are no such rules.
- Search, insert, and delete operations are like in binary search trees, except at the end of each operation a special step called **splaying** is done.
- Splaying ensures that all operations take O(lg n) amortized time.
- First, a quick review of BST operations...

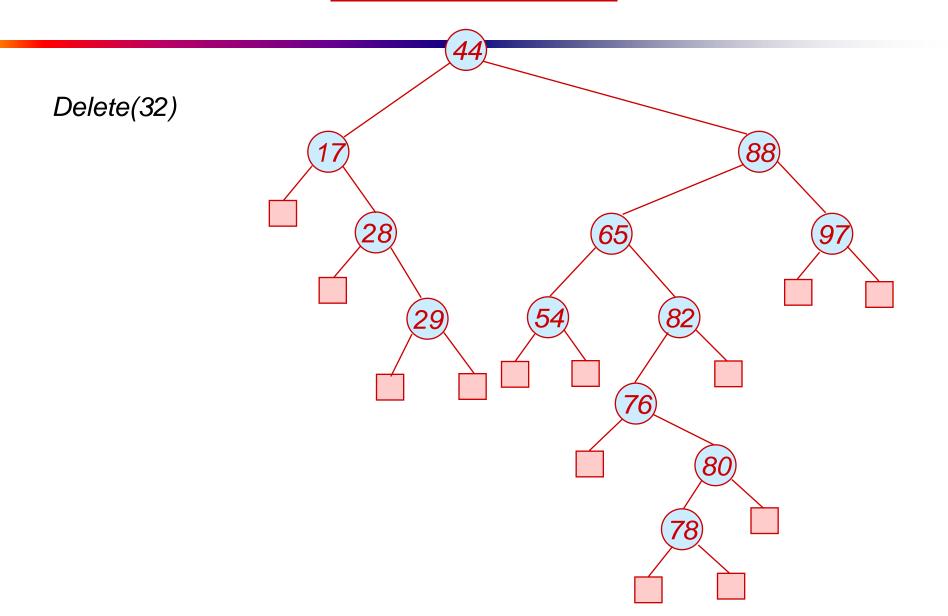
BST: Search

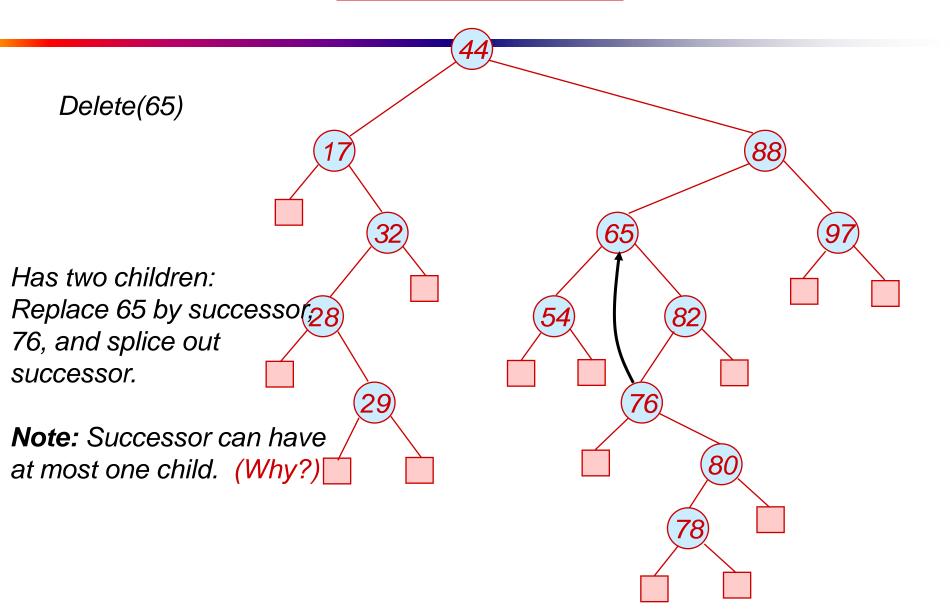


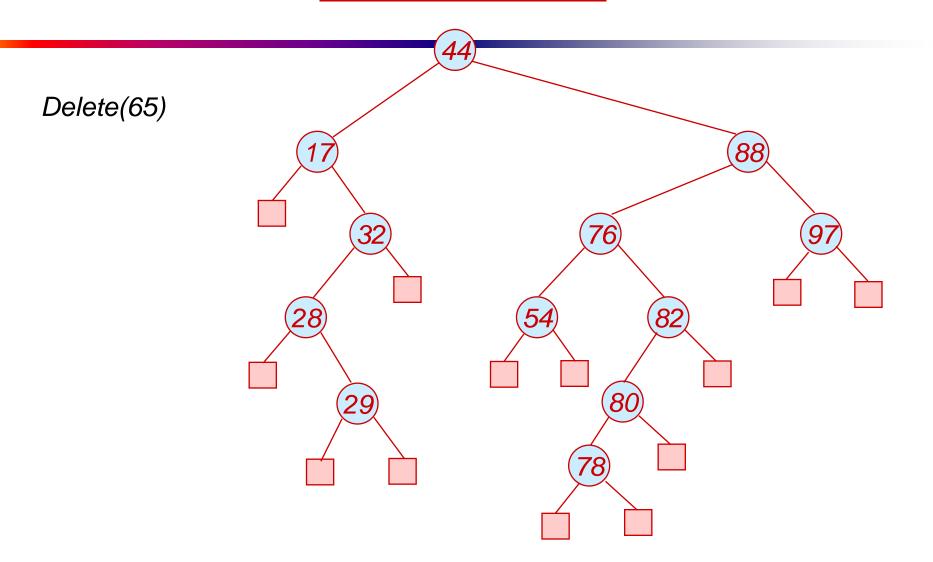
BST: Insert







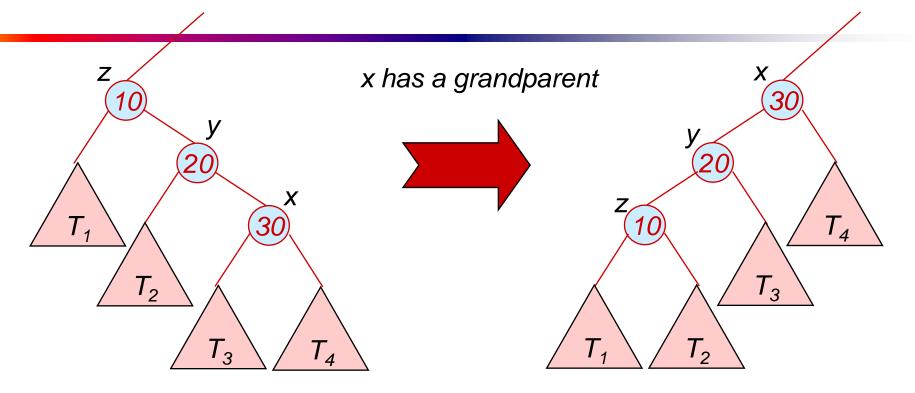




Splaying

- In splay trees, after performing an ordinary BST Search, Insert, or Delete, a splay operation is performed on some node x (as described later).
- The splay operation moves x to the root of the tree.
- The splay operation consists of sub-operations called zig-zig, zig-zag, and zig.

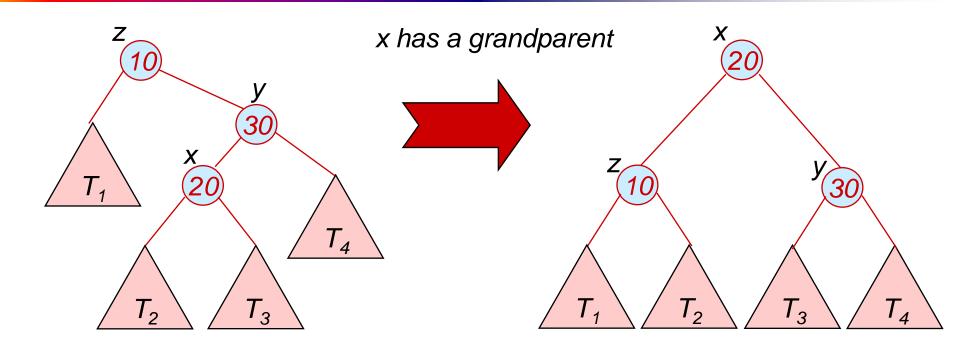
Zig-Zig



(Symmetric case too)

Note: x's depth decreases by two.

Zig-Zag

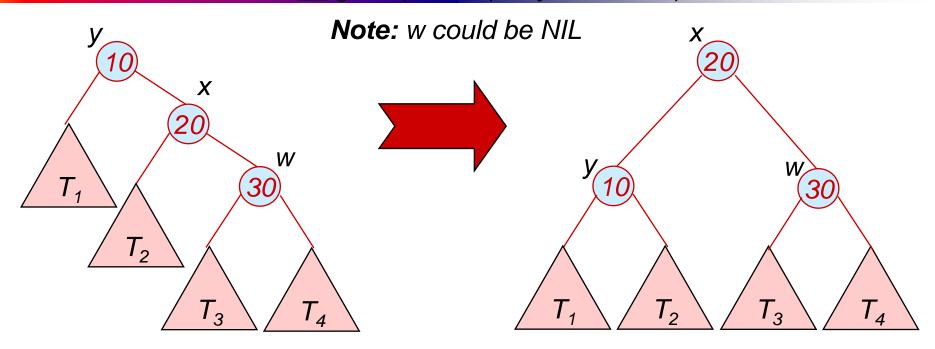


(Symmetric case too)

Note: x's depth decreases by two.



x has no grandparent (so, y is the root)



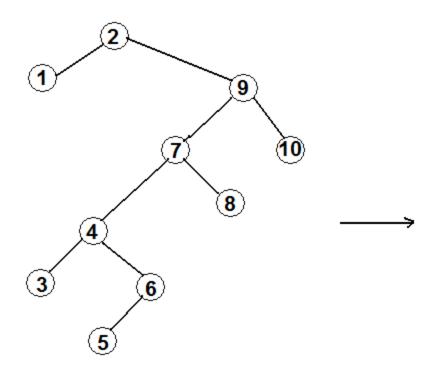
(Symmetric case too)

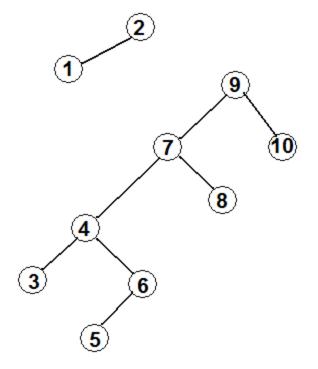
Note: x's depth decreases by one.

Top Down Splay Trees

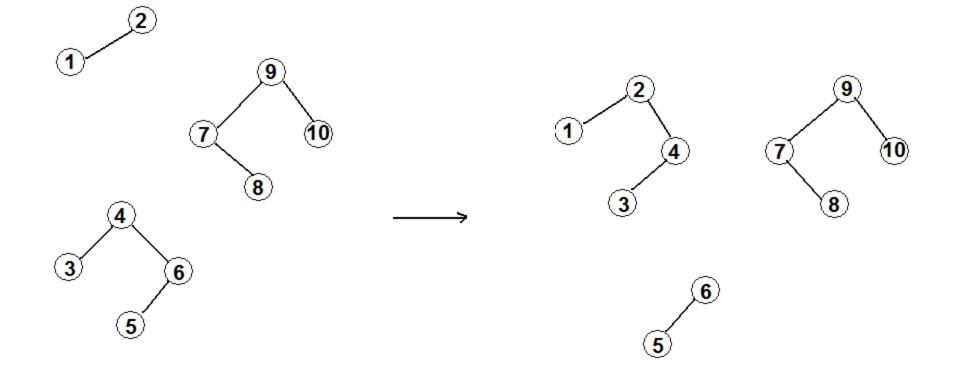
- Works by starting at the top and working down to produce a similar result.
- All of the nodes lower than the target are put into one tree and all of the nodes greater than the target are put into another tree then it is recombined.

Top Down Splaying

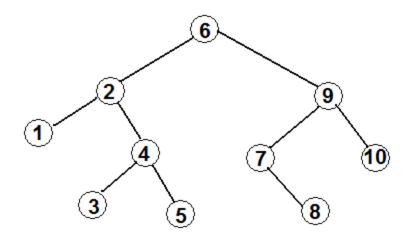


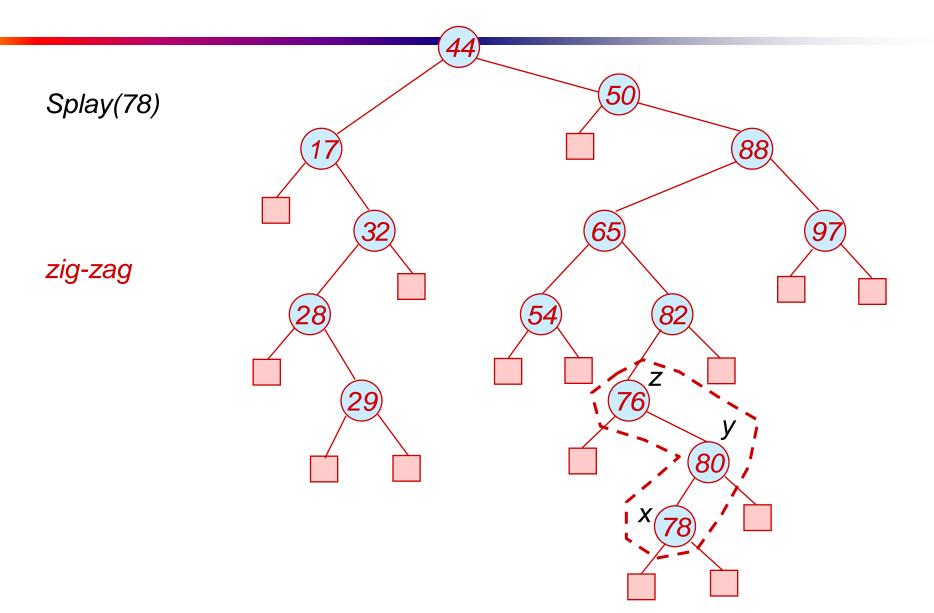


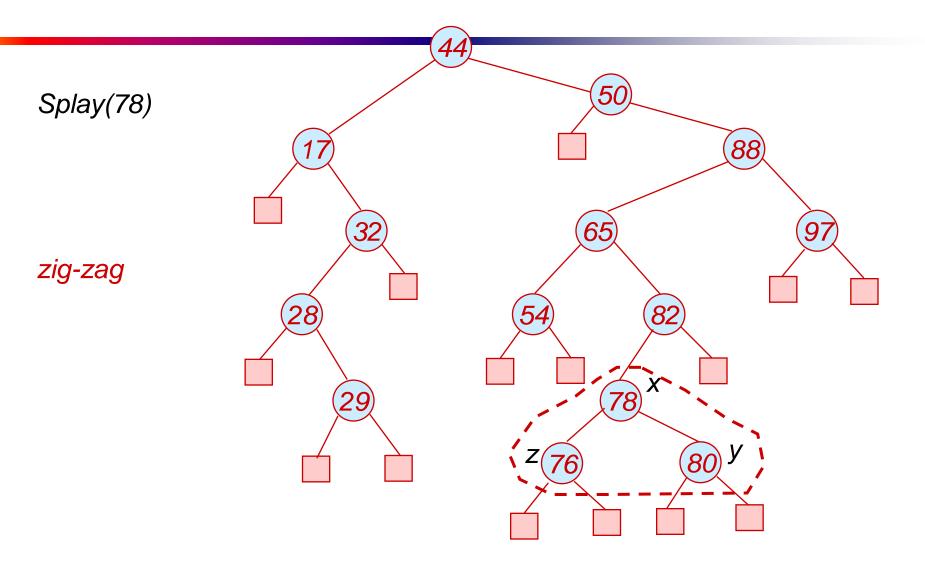
Top Down Splaying

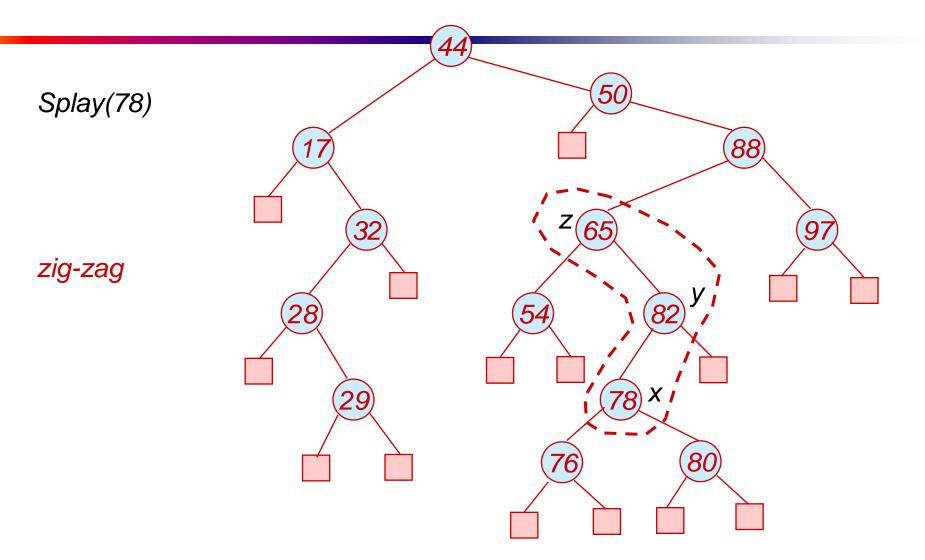


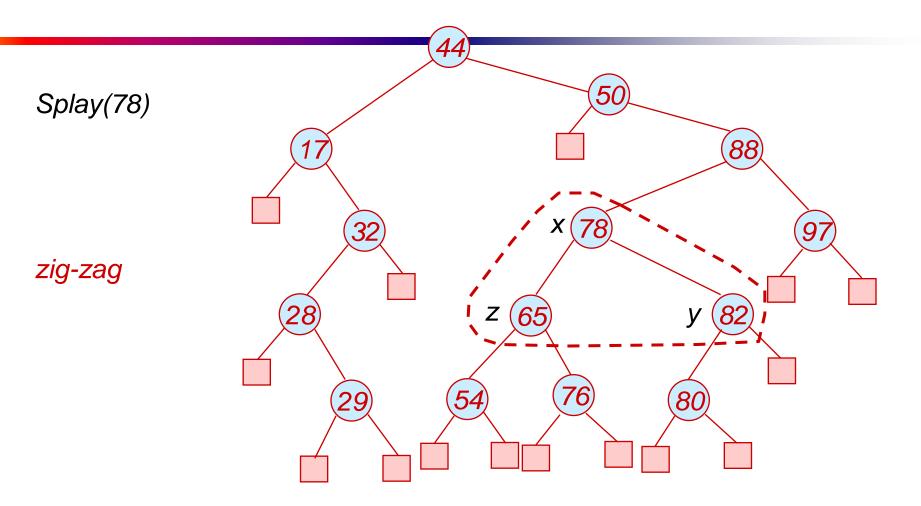
Top Down Splaying

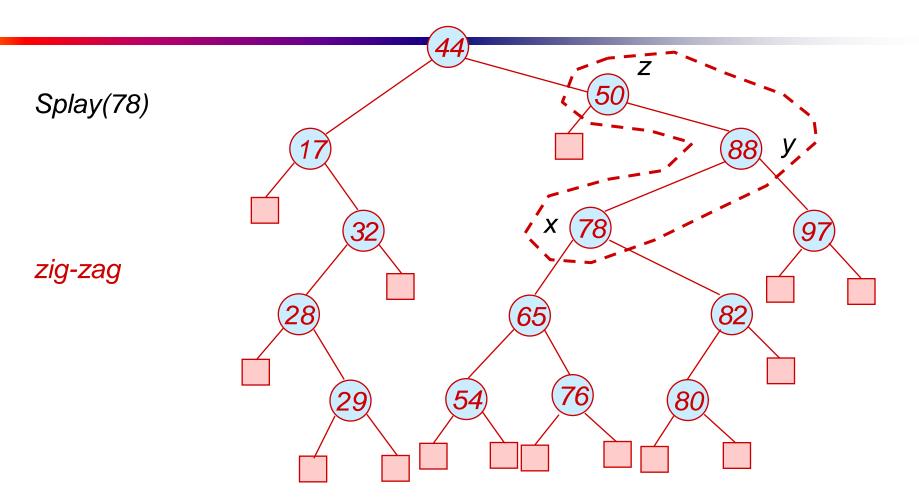


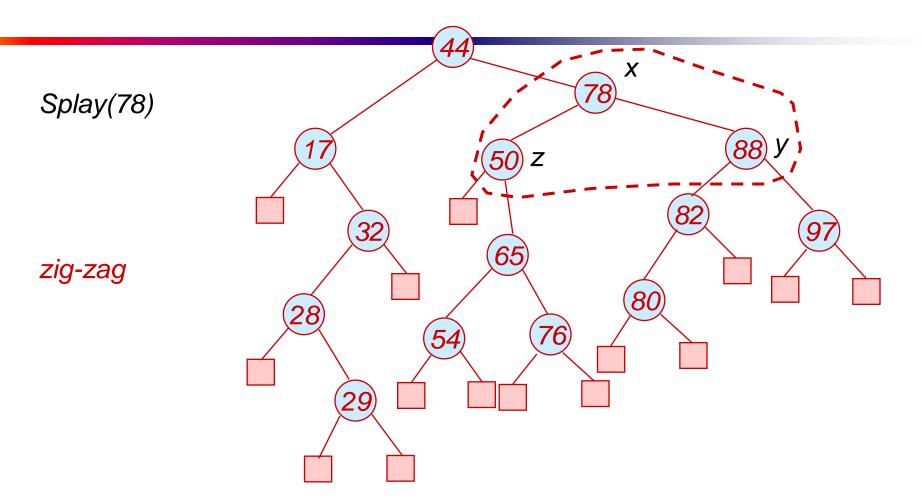


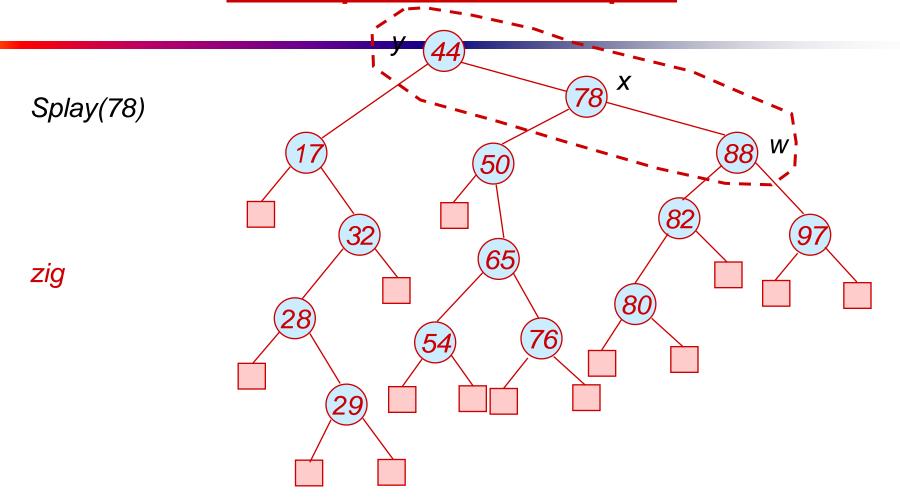


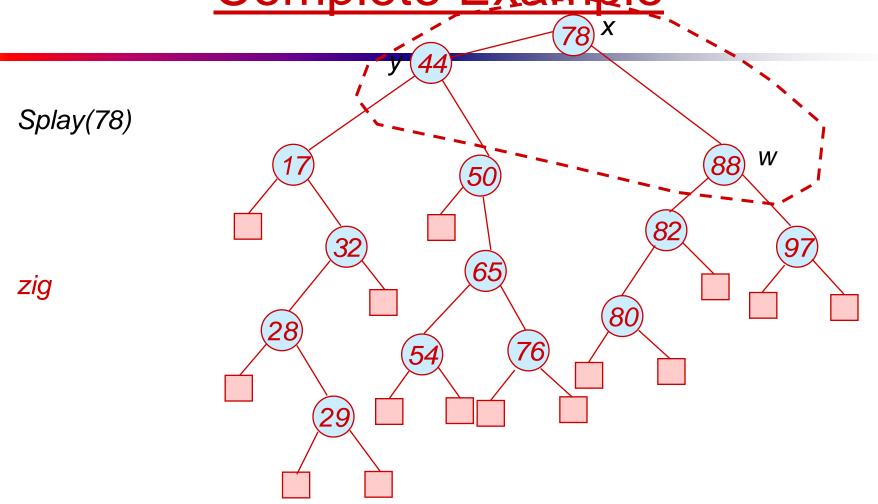












Result of splaying

- The result is a binary tree, with the left subtree having all keys less than the root, and the right subtree having keys greater than the root.
- Also, the final tree is "more balanced" than the original.
- However, if an operation near the root is done, the tree can become less balanced.

When to Splay

• Search:

- Successful: Splay node where key was found.
- Unsuccessful: Splay last-visited internal node (i.e., last node with a key).

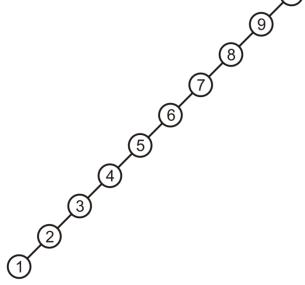
• Insert:

Splay newly added node.

• Delete:

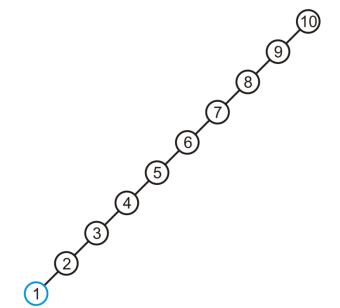
- Splay parent of removed node (which is either the node with the deleted key or its successor).
- Note: All operations run in O(h) time, for a tree of height h.

With a little consideration, it becomes obvious that inserting 1 through 10, in that order, will produce the splay tree (10)

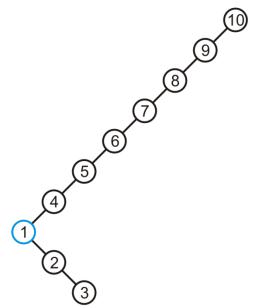


We will repeatedly access the deepest node in the tree

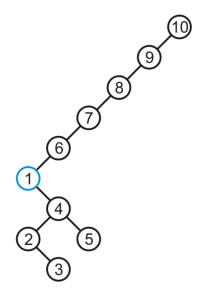
- With each operation, this node will be splayed to the root
- We begin with a zig-zig rotation



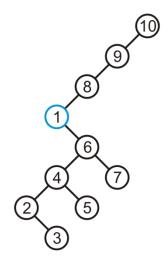
This is followed by another zig-zig operation...



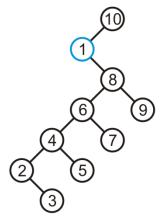
...and another



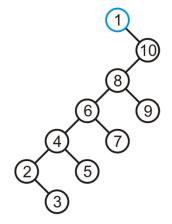
...and another



At this point, this requires a single zig operation to bring 1 to the root

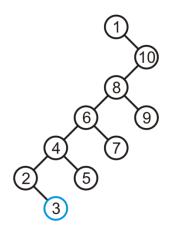


The height of this tree is now 6 and no longer 9



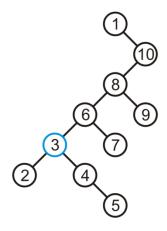
The deepest node is now 3:

This node must be splayed to the root beginning with a zig-zag operation

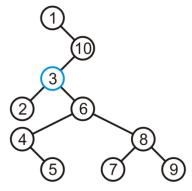


The node 3 is rotated up

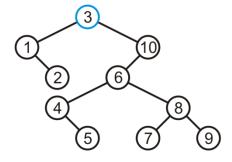
Next we require a zig-zig operation



Finally, to bring 3 to the root, we need a zig-zag operation

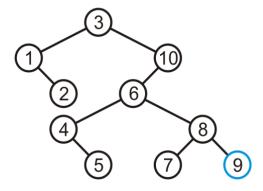


The height of this tree is only 4



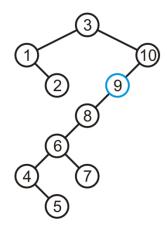
Of the three deepest nodes, 9 requires a zig-zig operation, so will access it next

The zig-zig operation will push 6 and its left sub-tree down

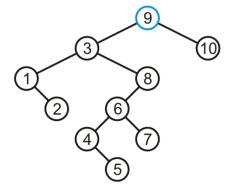


This is closer to a linked list; however, we're not finished

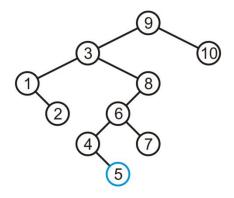
A zig-zag operation will move 9 to the root



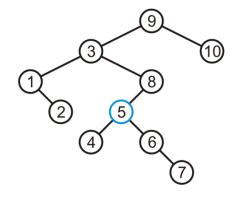
In this case, the height of the tree is now greater: 5



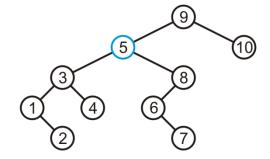
Accessing the deepest node, 5, we must begin with a zig-zag operation



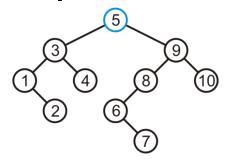
Next, we require a zig-zag operation to move 5 to the location of 3



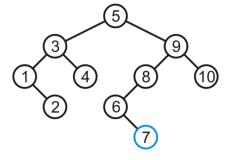
Finally, we require a single zig operation to move 5 to the root



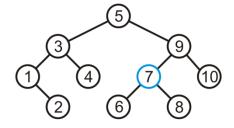
The height of the tree is 4; however, 7 of the nodes form a perfect tree at the root



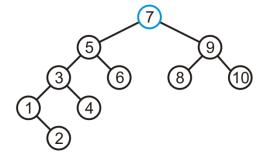
Accessing 7 will require two zig-zag operations



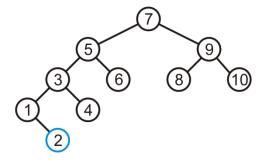
The first zig-zag moves it to depth 2



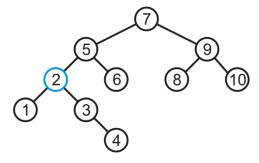
7 is promoted to the root through a zig-zag operation



Finally, accessing 2, we first require a zigzag operation

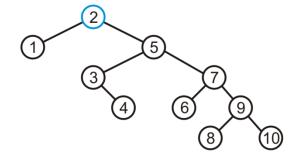


This now requires a zig-zig operation to promote 2 to the root



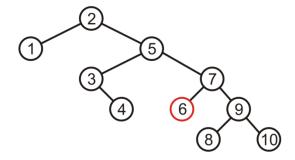
In this case, with 2 at the root, 3-10 must be in the right sub-tree

The right sub-tree happens to be AVL balanced

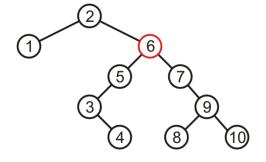


To remove a node, for example, 6, splay it to the root

First we require a zig-zag operation

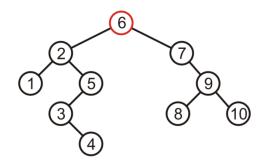


At this point, we need a zig operation to move 6 to the root

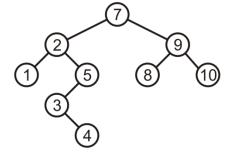


We will now copy the minimum element from the right sub-tree

In this case, the node with 7 has a single subtree, we will simply move it up



Thus, we have removed 6 and the resulting tree is, again, reasonably balanced



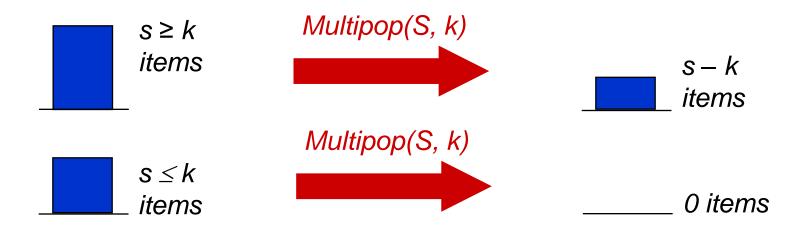
Amortized Analysis

- Based on the <u>Accounting Method</u>
 - <u>Idea:</u> When an operation's amortized cost exceeds it actual cost, the difference is assigned to certain tree nodes as **credit**.
 - Credit is used to pay for subsequent operations
 whose amortized cost is less than their actual cost.
- Most of our analysis will focus on splaying.
 - The BST operations will be easily dealt with at the end.

Review: Accounting Method

Stack Example:

- Operations:
 - Push(S, x).Pop(S).Can implement in O(1) time.
 - Multipop(S, k): if stack has s items, pop off min(s, k) items.



Accounting Method (Continued)

- We charge each operation an amortized cost.
- Charge may be more or less than actual cost.
- If more, then we have **credit**.
- This credit can be used to pay for future operations whose amortized cost is less than their actual cost.
- Require: For any sequence of operations, amortized cost upper bounds worst-case cost.
 - That is, we always have nonnegative credit.

Accounting Method (Continued)

Stack Example:

Actual Costs:

Push:

Pop: 1

Multipop: min(s, k)

Amortized Costs:

Push:

Pop:

Multipop:

 $\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$ All O(1).

For a sequence of n operations, does total amortized cost upper bound total worst-case cost, as required?

What is the total worstcase cost of the sequence

Pays for the push and a future pop.

<u>Ranks</u>

- T is a splay tree with n keys.
- **Definition:** The <u>size</u> of node v in T, denoted n(v), is the number of nodes in the subtree rooted at v.
 - **Note:** The root is of size 2n+1.
- **Definition:** The **rank** of v, denoted r(v), is lg(n(v)).
 - **Note:** The root has rank lg(2n+1).
- **Definition:** $r(T) = \sum_{v \in T} r(v)$.

Meaning of Ranks

- The rank of a tree is a measure of how well balanced it is.
- A well balanced tree has a low rank.
- A badly balanced tree has a high rank.
- The splaying operations tend to make the rank smaller, which balances the tree and makes other operations faster.
- Some operations near the root may make the rank larger and slightly unbalance the tree.
- Amortized analysis is used on splay trees, with the rank of the tree being the potential

Credit Invariant

 We will define amortized costs so that the following invariant is maintained.

Each node v of T has r(v) credits in its account.

- So, each operation's **amortized cost** = its real cost + the total change in r(T) it causes (positive or negative).
- Let R_i = op. i's real cost and Δ_i = change in r(T) it causes. Total am. cost = $\sum_{i=1,...,n} (R_i + \Delta_i)$. Initial tree has rank 0 & final tree has non-neg. rank. So, $\sum_{i=1,...n} \Delta_i \geq 0$, which implies total am. cost \geq total real cost.

What's Left?

- We want to show that the per-operation amortized cost is *logarithmic*.
- To do this, we need to look at how BST operations and splay operations affect r(T).
 - We spend most of our time on splaying, and consider the specific BST operations later.
- To analyze splaying, we first look at how r(T) changes as a result of a single substep, i.e., zig, zig-zig, or zig-zag.
 - Notation: Ranks before and after a substep are denoted r(v) and r'(v), respectively.

Proposition

Proposition: Let δ be the change in r(T) caused by a single substep. Let x be the "x" in our descriptions of these substeps. Then,

- $\delta \le 3(r'(x) r(x)) 2$ if the substep is a zig-zig or a zig-zag;
- $\delta \leq 3(r'(x) r(x))$ if the substep is a zig.

Proof:

Three cases, one for each kind of substep...

Case 1: zig-zig

Only the ranks of x, y, and z change. Also, r'(x) = r(z), T_1 $r'(y) \le r'(x)$, and $r(y) \ge r(x)$. Thus.

$$T_1$$
 T_2
 T_3
 T_4
 T_4
 T_5
 T_4
 T_5
 T_5
 T_4
 T_5
 T_7
 T_7
 T_7
 T_7
 T_7
 T_7

$$\delta = r'(x) + r'(y) + r'(z) - r(x) - r(y) - r(z)$$

$$= r'(y) + r'(z) - r(x) - r(y)$$

$$\leq r'(x) + r'(z) - 2r(x).$$
 (1)

Also, $n(x) + n'(z) \le n'(x)$, which (by property of lg), implies

$$r(x) + r'(z) \le 2r'(x) - 2$$
, i.e.,

$$r'(z) \le 2r'(x) - r(x) - 2$$
. (2)

If
$$a > 0$$
, $b > 0$, and $c \ge a + b$, then $\lg a + \lg b \le 2 \lg c - 2$.

By (1) and (2),
$$\delta \le r'(x) + (2r'(x) - r(x) - 2) - 2r(x) = 3(r'(x) - r(x)) - 2$$
.

Case 2: zig-zag

Only the ranks of x, y, and T_1 z change. Also, r'(x) = r(z)and $r(x) \le r(y)$. Thus,

$$\delta = r'(x) + r'(y) + r'(z) - r(x) - r(y) - r(z)$$

$$= r'(y) + r'(z) - r(x) - r(y)$$

$$\leq r'(y) + r'(z) - 2r(x).$$
 (1)

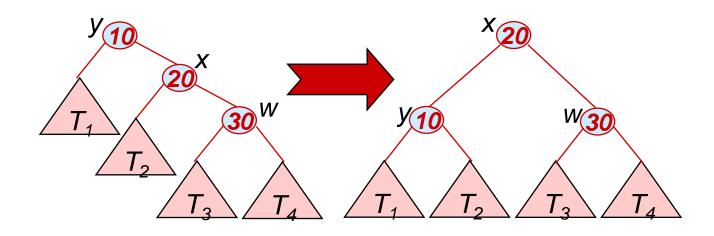
Also, $n'(y) + n'(z) \le n'(x)$, which (by property of lg), implies

$$r'(y) + r'(z) \le 2r'(x) - 2$$
. (2)

By (1) and (2),
$$\delta \le 2r'(x) - 2 - 2r(x)$$

 $\le 3(r'(x) - r(x)) - 2$.

Case 3: zig



Only the ranks of x and y change. Also, $r'(y) \le r(y)$ and $r'(x) \ge r(x)$. Thus,

$$\delta = r'(x) + r'(y) - r(x) - r(y)$$

$$\leq r'(x) - r(x)$$

$$\leq 3(r'(x) - r(x)).$$

Proposition

Proposition: Let T be a splay tree with root t, and let Δ be the total variation of r(T) caused by splaying a node x at depth d. The $\Delta \leq 3(r(t) - r(x)) - d + 2$.

Proof:

Splay(x) consists of $p = \lceil d/2 \rceil$ substeps, each of which is a zigzig or

zig-zag, except possibly the last one, which is a zig if d is odd.

Let $r_0(x) = x$'s initial rank, $r_i(x) = x$'s rank after the i^{th} substep, and $\delta_i = the$ variation of r(T) caused by the i^{th} substep, where $1 \le i \le p$.

By Proposition

$$\Delta = \sum_{i=1}^{p} \delta_{i} \le \sum_{i=1}^{p} (3(r_{i}(x) - r_{i-1}(x)) - 2) + 2$$

$$= 3(r_{p}(x) - r_{0}(x)) - 2p + 2$$

$$\le 3(r(t) - r(x)) - d + 2$$

Meaning of Proposition

- If d is small (less than 3(r(t) r(x)) + 2) then the splay operation can increase r(t) and thus make the tree less balanced.
- If d is larger than this, then the splay operation decreases r(t) and thus makes the tree better balanced.
- Note that $r(t) \le 3\lg(2n+1)$

Comparisons

Advantages:

- The amortized run times are similar to that of AVL trees and red-black trees
- The implementation is easier
- No additional information (height/colour) is required

Disadvantages:

The tree will change with read-only operations

DICTIONARIES Search Trees Lists Multi-Way Search Trees Multi-Lists Binary Search Trees Linear Lists **B-trees** Move-to-Front Splay Trees Red-Black Trees 2-3-4 Trees Hash Tables competitive competitive? **SELF ADJUSTING WORST-CASE EFFICIENT**