

Raman Kumar

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ABOUT

I am a Research Associate at IIT Delhi, working with [Prof. Aaditeshwar Seth](#) on applying machine learning to geospatial datasets. Previously, I collaborated with [Prof. Prem Kalra](#) on computer vision applications for medical datasets. Additionally, I have five and half years of industry experience as a Machine Learning Engineer.

EDUCATION

IIT Delhi, India

B.Tech, Computer Science and Engineering (2014)

PUBLICATIONS

1. **R. Kumar**, R. R. Dhanakshirur, R. Singh, C. Arora, P. Kalra, A. Suri, *A deep learning approach for objective evaluation of microscopic neuro-drilling craniotomy skills*, accepted for publication at Computers in Biology and Medicine [Code](#)
2. **R. Kumar**, A. Seth, *Multi-resolution UAV and satellite data processing for contextually relevant Land use Land Cover*, manuscript in preparation [Code](#)
3. C. Bansal et al. Beyond Flat Classifiers: Practical Methodologies for Regionally Accurate and Relevant Land Use and Land Cover Classification Using Landsat and Sentinel Data under review at Remote Sensing [Code](#)

RESEARCH PROJECTS

Multi-resolution UAV and satellite data processing for contextually relevant LULC (Current)

- Developed a novel methodology for accurate differentiation and delineation of scrublands, plantations and farmlands using high-resolution UAV as well as sentinel imagery
- Leveraged weak supervision on entropy, Hough transforms, size etc to train model that outperforms Google's Dynamic World LULC
- Containerized the entire workflow using Docker to streamline deployment and reproducibility
- Developed a hybrid pipeline utilizing local compute (NVIDIA RTX A5500 GPU) and Google Earth Engine to process 2,200 sq. km in under 3 hours; actively used by [Core-Stack](#) and [Well Labs](#)
- Currently authoring a **first-author** manuscript

Automatic assessment of microscopic neuro-drilling craniotomy skills (Finished in Apr '24)

- Developed a computer vision-based system to grade training for the critical neurosurgical procedure of microscopic craniotomy
- Collaborated with neurosurgeons to curate a high-quality annotated dataset of micro-drilling procedures on ovine skulls and scapulae
- Developed a geometry-constrained training strategy for Transformer and CNN models on limited data, surpassing human-level accuracy
- Integrated the best performing model with surgical micro-drills in [NETS lab](#) at AIIMS
- **First-author** paper currently under review at *Computers in Biology and Medicine*

- This project was a part of **NeuroMentor** which received [Prix Galien India](#) award 2024

Identifying Ecotypes(Current)

- Developed a methodology to automatically identify ecotypes (e.g., Orans of Rajasthan, barren hilltops of Sahyadris) requiring ecological restoration
- Developed a bottom-up methodology which uses pixels identified by environmental rules on reference sites and use Simple Non-Iterative Clustering (SNIC) on NDVI time-series to generate superpixels patches for ecotypes
- Currently exploring symbolic regression to automatically derive rule sets from multiple data layers (LULC, terrain, rainfall, elevation, tree canopy, land degradation, etc.)

Large-Scale Cropping Intensity Classification Using Unsupervised Learning (Current)

- Developed an unsupervised method to classify annual cropping intensity at 10-meter resolution across India using time-series vegetation indices from optical satellite data
- Designed a systematic sampling strategy and collaborated with grassroot NGO to validate our methodology

Forecasting Forest Fire using Climate and Human variables(Current)

- Worked on classifying small and large forest fires using Landsat dataset and curated a dataset of historical forest fires clusters over the past 9 years on 6 eastern states of India
- Modeled forecasting of forest fire using climate forecast variables CFSV2: NCEP Climate Forecast System Version 2
- Currently in the process to adding human variables like human settlements and infrastructure development

Surgical Tool tracking (Finished in Jan '24)

- Developed a library to simultaneously capture 6D tool position and RGB frames from optical and infrared camera on [Polaris Vega](#): a tool tracking system used in neuro-surgery
- Developed a pipeline on gstreamer to extract RGB frames from network packets and overlay the 2D projection of tool position on the frames
- The library is currently in use to collect data for **SLAM** based endoscopic tracking

INDUSTRY EXPERIENCE

Euler Systems Inc., Mumbai, IN
Tech Lead

July '18 – Apr '22

Complaint Classification System: (Gojek)

- Designed and implemented an end-to-end system to classify customer complaints into 100+ categories, aiding customer service representatives in resolving issues more efficiently
- Developed an ML pipeline inspired from a paper titled [COTA](#) which uses a pointwise ranking algorithm resulting in higher accuracy compared to a standard multi-class classifier.
- Designed and Implemented a [distributed architecture](#) consisting of a training cluster and inference cluster, and a ten stage data pipeline to preprocess incoming data, train, and deploy the model across API serving containers.
- Serialized distributed ML model using mlearn to deploy on lightweight API servers, achieving

millisecond response time.

Data Plan Optimization: (Kore Wireless)

- Developed a product that predicts optimal data plans to decrease data overage and cost for an American SIM card provider
- Developed an heuristic based dynamic bin packing algorithm to find optimal plan
- Saved \$600K per year with optimal predictions

Doctor Recommendation System: (Dhani)

- Lead a team to build recommendation system which recommends doctors based on patient's history
- Developed a software to allocate doctors in real-time for video calling from a pool of doctors
- Reduced the waiting time for patients from 65 secs to 12 secs with efficient allocation

Backend Development: (Nykaa)

- Implemented e-commerce search, product recommendations and price and inventory management system for Nykaa
- Migrated Nykaa's monolith architecture to microservice architecture

Ikarus, Gurgaon, IN
Software Engineer

Nov '16 – Jul '18

Robotic Process Automation(RPA):

- Worked on Named-entity Recognition(NER) to extract entities like items, prices from unstructured text documents
- Developed an algorithm to detect tables in scanned documents by identifying lines using Hough Transforms
- Worked on auto orientation correction of scanned documents to increase OCR accuracy
- Implemented scalable and distributed data pipeline on pyspark to process millions of documents in batches

TECHNICAL SKILLS

Languages	Python, Java, C#, C/C++, scala
Libraries	PyTorch, Keras, mxnet, Scikit-Learn, Numpy, Pandas, NLTK, matplotlib, spacy, OpenCV
GIS	Google Earth Engine, GDAL, QGIS, Rasterio
Frameworks and Tools	Pyspark, Git, Docker, AWS Lambda, AWS EC2, Elastic Search, mLeap, redis, bash

HOBBIES

Drumming, hiking and reading fiction

REFERENCES

[Prof. Aaditeshwar Seth](#) (IIT Delhi), [Prof. Prem Kalra](#) (IIT Delhi), [Sandeep Kadam](#) (CTO, Kissht)