# Multilayer Neural Networks

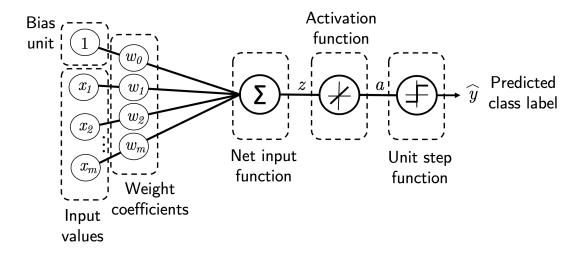
January 1, 2025

- 1 Multi-layer Neural Network
- 2 Modeling complex functions with artificial neural networks

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- 2.1 Single-layer neural network recap
- [3]: Image(filename='images/12\_01.png', width=600)

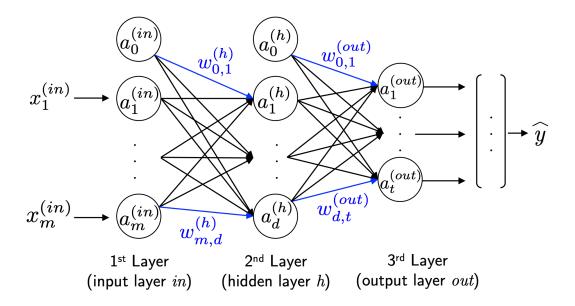
[3]:



2.2 Introducing the multi-layer neural network architecture

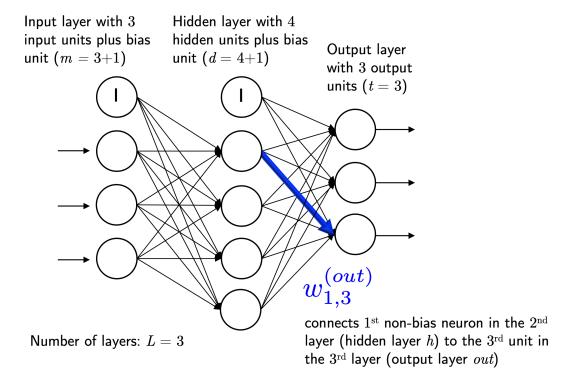
```
[4]: Image(filename='images/12_02.png', width=600)
```

[4]:



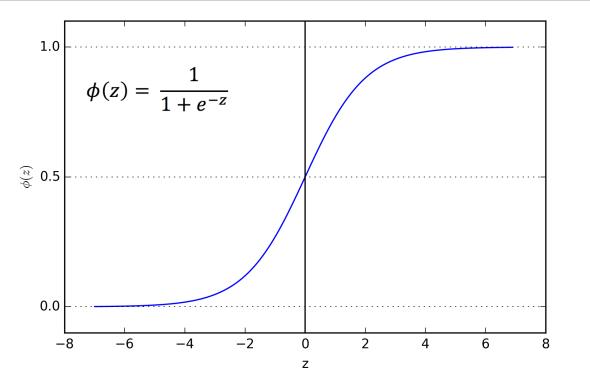
[5]: Image(filename='images/12\_03.png', width=500)

[5]:



#### 2.3 Activating a neural network via forward propagation

[6]:



To use the scikit-learn API for loading MNIST, please uncomment the following code below.

[7]: "\nfrom sklearn.datasets import fetch\_openml\nfrom sklearn.model\_selection
 import train\_test\_split\n\n\nX, y = fetch\_openml('mnist\_784', version=1,
 return\_X\_y=True)\ny = y.astype(int)\nX = ((X / 255.) - .5) \* 2\nX\_train, X\_test,
 y\_train, y\_test = train\_test\_split(\n X, y, test\_size=10000,
 random\_state=123, stratify=y)\n"

### 3 Classifying handwritten digits

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#### 3.1 Obtaining and preparing the MNIST dataset

The MNIST dataset is publicly available at http://yann.lecun.com/exdb/mnist/ and consists of the following four parts:

- Training set images: train-images-idx3-ubyte.gz (9.9 MB, 47 MB unzipped, 60,000 examples)
- Training set labels: train-labels-idx1-ubyte.gz (29 KB, 60 KB unzipped, 60,000 labels)
- Test set images: t10k-images-idx3-ubyte.gz (1.6 MB, 7.8 MB, 10,000 examples)
- Test set labels: t10k-labels-idx1-ubyte.gz (5 KB, 10 KB unzipped, 10,000 labels)

In this section, we will only be working with a subset of MNIST, thus, we only need to download the training set images and training set labels.

After downloading the files, simply run the next code cell to unzip the files.

```
[8]: # this code cell unzips mnist

import sys
import gzip
import shutil
import os

if (sys.version_info > (3, 0)):
    writemode = 'wb'
else:
    writemode = 'w'

zipped_mnist = [f for f in os.listdir() if f.endswith('ubyte.gz')]
for z in zipped_mnist:
    with gzip.GzipFile(z, mode='rb') as decompressed, open(z[:-3], writemode)_u

as outfile:
    outfile.write(decompressed.read())
```

#### IGNORE IF THE CODE CELL ABOVE EXECUTED WITHOUT PROBLEMS:

If you have issues with the code cell above, I recommend unzipping the files using the Unix/Linux gzip tool from the terminal for efficiency, e.g., using the command

```
gzip *ubyte.gz -d
```

in your local MNIST download directory, or, using your favorite unzipping tool if you are working with a machine running on Microsoft Windows. The images are stored in byte form, and using the following function, we will read them into NumPy arrays that we will use to train our MLP.

Please note that if you are **not** using gzip, please make sure that he files are named

• train-images-idx3-ubyte

- train-labels-idx1-ubyte
- t10k-images-idx3-ubyte
- t10k-labels-idx1-ubyte

If a file is e.g., named train-images.idx3-ubyte after unzipping (this is due to the fact that certain tools try to guess a file suffix), please rename it to train-images-idx3-ubyte before proceeding.

```
[9]: import os
      import struct
      import numpy as np
      def load mnist(path, kind='train'):
          """Load MNIST data from `path`"""
          labels_path = os.path.join(path,
                                      '%s-labels-idx1-ubyte' % kind)
          images_path = os.path.join(path,
                                      '%s-images-idx3-ubyte' % kind)
          with open(labels_path, 'rb') as lbpath:
              magic, n = struct.unpack('>II',
                                        lbpath.read(8))
              labels = np.fromfile(lbpath,
                                   dtype=np.uint8)
          with open(images path, 'rb') as imgpath:
              magic, num, rows, cols = struct.unpack(">IIII",
                                                      imgpath.read(16))
              images = np.fromfile(imgpath,
                                   dtype=np.uint8).reshape(len(labels), 784)
              images = ((images / 255.) - .5) * 2
          return images, labels
[10]: !ls
     README.md
                                 t10k-images-idx3-ubyte.gz
     ch12.ipynb
                                 t10k-labels-idx1-ubyte
     ch12.py
                                 t10k-labels-idx1-ubyte.gz
     images
                                 train-images-idx3-ubyte
     mnist_scaled.npz
                                 train-images-idx3-ubyte.gz
                                 train-labels-idx1-ubyte
     neuralnet.py
```

Rows: 60000, columns: 784

[11]: X\_train, y\_train = load\_mnist('', kind='train')

t10k-images-idx3-ubyte

train-labels-idx1-ubyte.gz

print('Rows: %d, columns: %d' % (X\_train.shape[0], X\_train.shape[1]))

```
[12]: X_test, y_test = load_mnist('', kind='t10k')
print('Rows: %d, columns: %d' % (X_test.shape[0], X_test.shape[1]))
```

Rows: 10000, columns: 784

Visualize the first digit of each class:

```
[13]: import matplotlib.pyplot as plt

fig, ax = plt.subplots(nrows=2, ncols=5, sharex=True, sharey=True)
ax = ax.flatten()
for i in range(10):
    img = X_train[y_train == i][0].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys')

ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('images/12_5.png', dpi=300)
plt.show()
```





Visualize 25 different versions of "7":

```
[14]: fig, ax = plt.subplots(nrows=5, ncols=5, sharex=True, sharey=True,)
ax = ax.flatten()
for i in range(25):
   img = X_train[y_train == 7][i].reshape(28, 28)
   ax[i].imshow(img, cmap='Greys')

ax[0].set_xticks([])
```

```
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('images/12_6.png', dpi=300)
plt.show()
```

```
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```

```
X_train.shape
```

[17]: (60000, 784)

#### 3.2 Implementing a multi-layer perceptron

```
[18]: import numpy as np
      import sys
      class NeuralNetMLP(object):
          """ Feedforward neural network / Multi-layer perceptron classifier.
          Parameters
          _____
          n_hidden : int (default: 30)
             Number of hidden units.
          12 : float (default: 0.)
             Lambda value for L2-regularization.
              No regularization if l2=0. (default)
          epochs: int (default: 100)
              Number of passes over the training set.
          eta : float (default: 0.001)
             Learning rate.
          shuffle : bool (default: True)
              Shuffles training data every epoch if True to prevent circles.
          minibatch_size : int (default: 1)
              Number of training examples per minibatch.
          seed : int (default: None)
             Random seed for initializing weights and shuffling.
          Attributes
          _____
          eval_{-}: dict
           Dictionary collecting the cost, training accuracy,
            and validation accuracy for each epoch during training.
          def __init__(self, n_hidden=30,
                       12=0., epochs=100, eta=0.001,
                       shuffle=True, minibatch_size=1, seed=None):
              self.random = np.random.RandomState(seed)
             self.n_hidden = n_hidden
             self.12 = 12
             self.epochs = epochs
              self.eta = eta
```

```
self.shuffle = shuffle
    self.minibatch_size = minibatch_size
def _onehot(self, y, n_classes):
    """Encode labels into one-hot representation
    Parameters
    y : array, shape = [n_examples]
        Target values.
    n classes : int
        Number of classes
    Returns
    onehot : array, shape = (n_examples, n_labels)
    11 11 11
    onehot = np.zeros((n_classes, y.shape[0]))
    for idx, val in enumerate(y.astype(int)):
        onehot[val, idx] = 1.
    return onehot.T
def _sigmoid(self, z):
    """Compute logistic function (sigmoid)"""
    return 1. / (1. + np.exp(-np.clip(z, -250, 250)))
def _forward(self, X):
    """Compute forward propagation step"""
    # step 1: net input of hidden layer
    # [n_examples, n_features] dot [n_features, n_hidden]
    # -> [n_examples, n_hidden]
    z_h = np.dot(X, self.w_h) + self.b_h
    # step 2: activation of hidden layer
    a_h = self._sigmoid(z_h)
    # step 3: net input of output layer
    \# [n_examples, n_hidden] dot [n_hidden, n_classlabels]
    \# \rightarrow [n_{examples}, n_{classlabels}]
    z_out = np.dot(a_h, self.w_out) + self.b_out
    # step 4: activation output layer
    a_out = self._sigmoid(z_out)
```

```
return z_h, a_h, z_out, a_out
def _compute_cost(self, y_enc, output):
    """Compute cost function.
    Parameters
    y_{enc} : array, shape = (n_{examples}, n_{labels})
        one-hot encoded class labels.
    output : array, shape = [n_examples, n_output_units]
        Activation of the output layer (forward propagation)
    Returns
    cost : float
        Regularized cost
    n n n
    L2_{term} = (self.12 *
               (np.sum(self.w_h ** 2.) +
                np.sum(self.w_out ** 2.)))
    term1 = -y_enc * (np.log(output))
    term2 = (1. - y_enc) * np.log(1. - output)
    cost = np.sum(term1 - term2) + L2_term
    # If you are applying this cost function to other
    # datasets where activation
    # values maybe become more extreme (closer to zero or 1)
    # you may encounter "ZeroDivisionError"s due to numerical
    # instabilities in Python & NumPy for the current implementation.
    # I.e., the code tries to evaluate log(0), which is undefined.
    # To address this issue, you could add a small constant to the
    # activation values that are passed to the log function.
    # For example:
    \# term1 = -y_enc * (np.log(output + 1e-5))
    # term2 = (1. - y_enc) * np.log(1. - output + 1e-5)
    return cost
def predict(self, X):
    """Predict class labels
    Parameters
```

```
X : array, shape = [n_examples, n_features]
        Input layer with original features.
    Returns:
    _____
    y_pred : array, shape = [n_examples]
        Predicted class labels.
    z_h, a_h, z_out, a_out = self._forward(X)
    y_pred = np.argmax(z_out, axis=1)
    return y_pred
def fit(self, X_train, y_train, X_valid, y_valid):
    """ Learn weights from training data.
    Parameters
    _____
    X_{train} : array, shape = [n_{examples}, n_{features}]
        Input layer with original features.
    y_train : array, shape = [n_examples]
        Target class labels.
    X_valid : array, shape = [n_examples, n_features]
        Sample features for validation during training
    y_valid : array, shape = [n_examples]
        Sample labels for validation during training
    Returns:
    self
    HHHH
    n_output = np.unique(y_train).shape[0] # number of class labels
    n_features = X_train.shape[1]
    #############################
    # Weight initialization
    #############################
    # weights for input -> hidden
    self.b h = np.zeros(self.n hidden)
    self.w_h = self.random.normal(loc=0.0, scale=0.1,
                                  size=(n_features, self.n_hidden))
    # weights for hidden -> output
    self.b_out = np.zeros(n_output)
    self.w_out = self.random.normal(loc=0.0, scale=0.1,
```

```
size=(self.n_hidden, n_output))
epoch_strlen = len(str(self.epochs)) # for progress formatting
self.eval_ = {'cost': [], 'train_acc': [], 'valid_acc': []}
y_train_enc = self._onehot(y_train, n_output)
# iterate over training epochs
for i in range(self.epochs):
    # iterate over minibatches
    indices = np.arange(X_train.shape[0])
    if self.shuffle:
        self.random.shuffle(indices)
    for start_idx in range(0, indices.shape[0] - self.minibatch_size +
                           1, self.minibatch_size):
        batch_idx = indices[start_idx:start_idx + self.minibatch_size]
        # forward propagation
        z_h, a_h, z_out, a_out = self._forward(X_train[batch_idx])
        ##################
        # Backpropagation
        ##################
        # [n examples, n classlabels]
        delta_out = a_out - y_train_enc[batch_idx]
        # [n_examples, n_hidden]
        sigmoid_derivative_h = a_h * (1. - a_h)
        \# [n_examples, n_classlabels] dot [n_classlabels, n_hidden]
        # -> [n_examples, n_hidden]
        delta_h = (np.dot(delta_out, self.w_out.T) *
                   sigmoid_derivative_h)
        # [n_features, n_examples] dot [n_examples, n_hidden]
        # -> [n_features, n_hidden]
        grad_w_h = np.dot(X_train[batch_idx].T, delta_h)
        grad_b_h = np.sum(delta_h, axis=0)
        # [n_hidden, n_examples] dot [n_examples, n_classlabels]
        # -> [n_hidden, n_classlabels]
        grad_w_out = np.dot(a_h.T, delta_out)
        grad_b_out = np.sum(delta_out, axis=0)
```

```
# Regularization and weight updates
        delta_w_h = (grad_w_h + self.12*self.w_h)
        delta_b_h = grad_b_h # bias is not regularized
        self.w_h -= self.eta * delta_w_h
        self.b_h -= self.eta * delta_b_h
        delta_w_out = (grad_w_out + self.12*self.w_out)
        delta_b_out = grad_b_out # bias is not regularized
        self.w_out -= self.eta * delta_w_out
        self.b_out -= self.eta * delta_b_out
    #############
    # Evaluation
    ############
    # Evaluation after each epoch during training
   z_h, a_h, z_out, a_out = self._forward(X_train)
    cost = self._compute_cost(y_enc=y_train_enc,
                              output=a_out)
   y_train_pred = self.predict(X_train)
   y_valid_pred = self.predict(X_valid)
   train_acc = ((np.sum(y_train == y_train_pred)).astype(np.float) /
                 X_train.shape[0])
    valid_acc = ((np.sum(y_valid == y_valid_pred)).astype(np.float) /
                 X_valid.shape[0])
    sys.stderr.write('\r%0*d/%d | Cost: %.2f '
                     '| Train/Valid Acc.: %.2f%%/%.2f%% ' %
                     (epoch_strlen, i+1, self.epochs, cost,
                      train_acc*100, valid_acc*100))
    sys.stderr.flush()
    self.eval_['cost'].append(cost)
    self.eval_['train_acc'].append(train_acc)
    self.eval_['valid_acc'].append(valid_acc)
return self
```

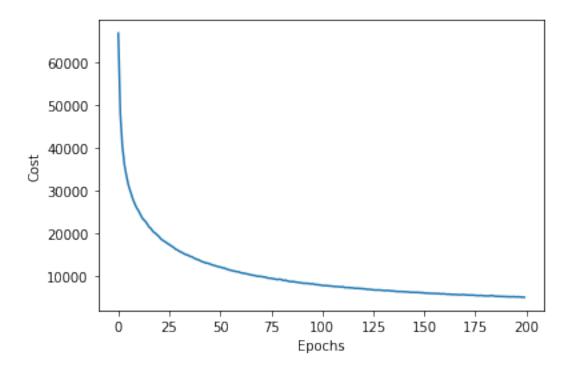
```
[19]: n_epochs = 200

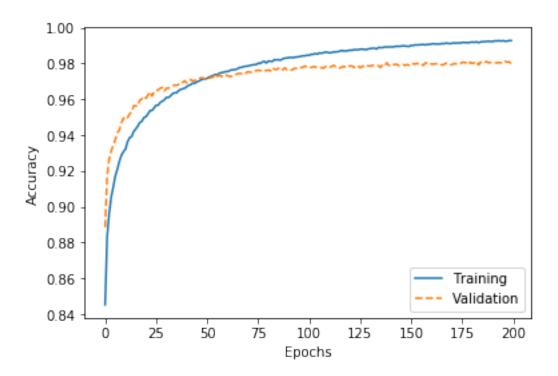
## @Readers: PLEASE IGNORE IF-STATEMENT BELOW

##

## This cell is meant to run fewer epochs when
```

```
## the notebook is run on the Travis Continuous Integration
      ## platform to test the code on a smaller dataset
      ## to prevent timeout errors; it just serves a debugging tool
      if 'TRAVIS' in os.environ:
          n_{epochs} = 20
[20]: nn = NeuralNetMLP(n_hidden=100,
                        12=0.01,
                        epochs=n_epochs,
                        eta=0.0005,
                        minibatch_size=100,
                        shuffle=True,
                        seed=1)
      nn.fit(X_train=X_train[:55000],
             y_train=y_train[:55000],
             X_valid=X_train[55000:],
             y_valid=y_train[55000:])
     200/200 | Cost: 5065.78 | Train/Valid Acc.: 99.28%/97.98%
[20]: <__main__.NeuralNetMLP at 0x7fdfc8463518>
[21]: import matplotlib.pyplot as plt
      plt.plot(range(nn.epochs), nn.eval_['cost'])
      plt.ylabel('Cost')
      plt.xlabel('Epochs')
      #plt.savefig('images/12_07.png', dpi=300)
      plt.show()
```



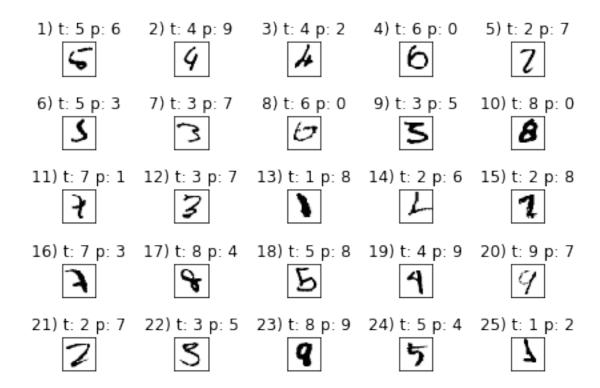


Test accuracy: 97.54%

```
miscl_img = X_test[y_test != y_test_pred][:25]
correct_lab = y_test[y_test != y_test_pred][:25]
miscl_lab = y_test_pred[y_test != y_test_pred][:25]

fig, ax = plt.subplots(nrows=5, ncols=5, sharex=True, sharey=True)
ax = ax.flatten()
for i in range(25):
    img = miscl_img[i].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys', interpolation='nearest')
    ax[i].set_title('%d) t: %d p: %d' % (i+1, correct_lab[i], miscl_lab[i]))

ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
#plt.savefig('images/12_09.png', dpi=300)
plt.show()
```



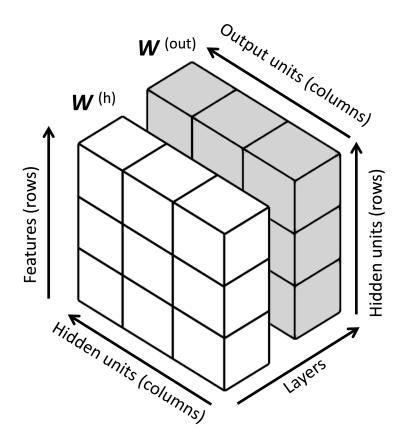
## 4 Training an artificial neural network

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## 4.1 Computing the logistic cost function

```
[25]: Image(filename='images/12_10.png', width=300)
```

[25]:



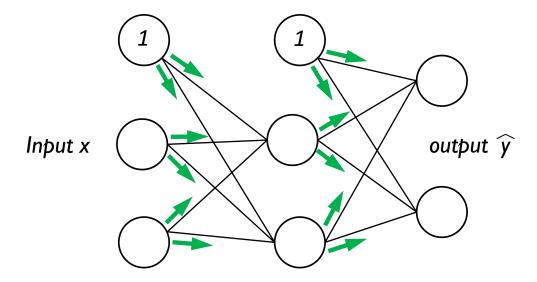
4.2 Developing your intuition for backpropagation

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4.3 Training neural networks via backpropagation

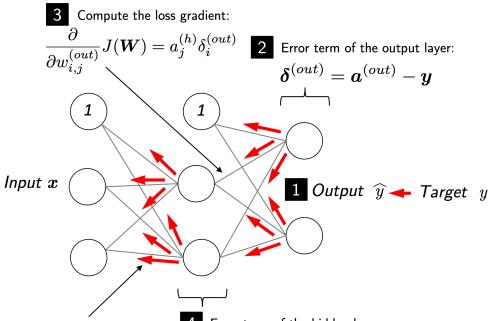
[26]: Image(filename='./images/12\_11.png', width=400)

[26]:



[27]: Image(filename='images/12\_12.png', width=500)

[27]:



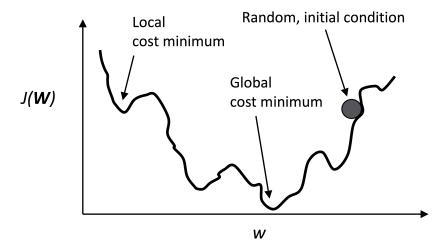
5 Compute the loss gradient:

$$rac{\partial}{\partial w_{i,j}^{(h)}}J(oldsymbol{W})=a_{j}^{(in)}\delta_{i}^{(h)}$$

Compute the loss gradient:  $\frac{\partial}{\partial w_{i,j}^{(h)}} J(\boldsymbol{W}) = a_j^{(in)} \delta_i^{(h)} \qquad \boldsymbol{\delta}^{(h)} = \boldsymbol{\delta}^{(out)} \left( \boldsymbol{W}^{(out)} \right)^\top \odot \frac{\partial \phi \left( \boldsymbol{a}^{(h)} \right)}{\partial \boldsymbol{a}^{(h)}}$ 

## 5 Convergence in neural networks

```
[28]: Image(filename='images/12_13.png', width=500)
[28]:
```



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## 6 Summary

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Readers may ignore the next cell.

[29]: ! python ../.convert\_notebook\_to\_script.py --input ch12.ipynb --output ch12.py

[NbConvertApp] Converting notebook ch12.ipynb to script [NbConvertApp] Writing 19664 bytes to ch12.py