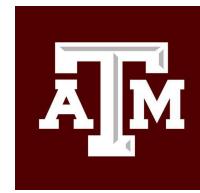
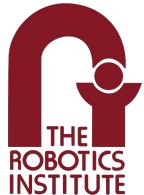


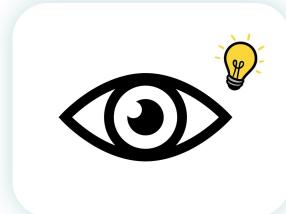


# Learning with an Evolving Class Ontology

Zhiqiu Lin, Deepak Pathak, Yu-Xiong Wang, Deva Ramanan\*, Shu Kong\*



Visual perception systems need to cope with **evolving class ontology..**



Lifelong learning  
perception system



Recognize as: Bus?

Types of bus?



Articulated?



School Bus?



Recognize as: Pedestrian?

Types of pedestrian?



A child?



A police officer?

Contemporary industry-made datasets, such as Mapillary[1] and Argoverse[2], continually refined the ontology from version 1.0 to 2.0.

Mapillary v1.2 (2017)



Mapillary v2.0 (2021)



Argoverse v1.0 (2019)



Argoverse v2.0 (2021)



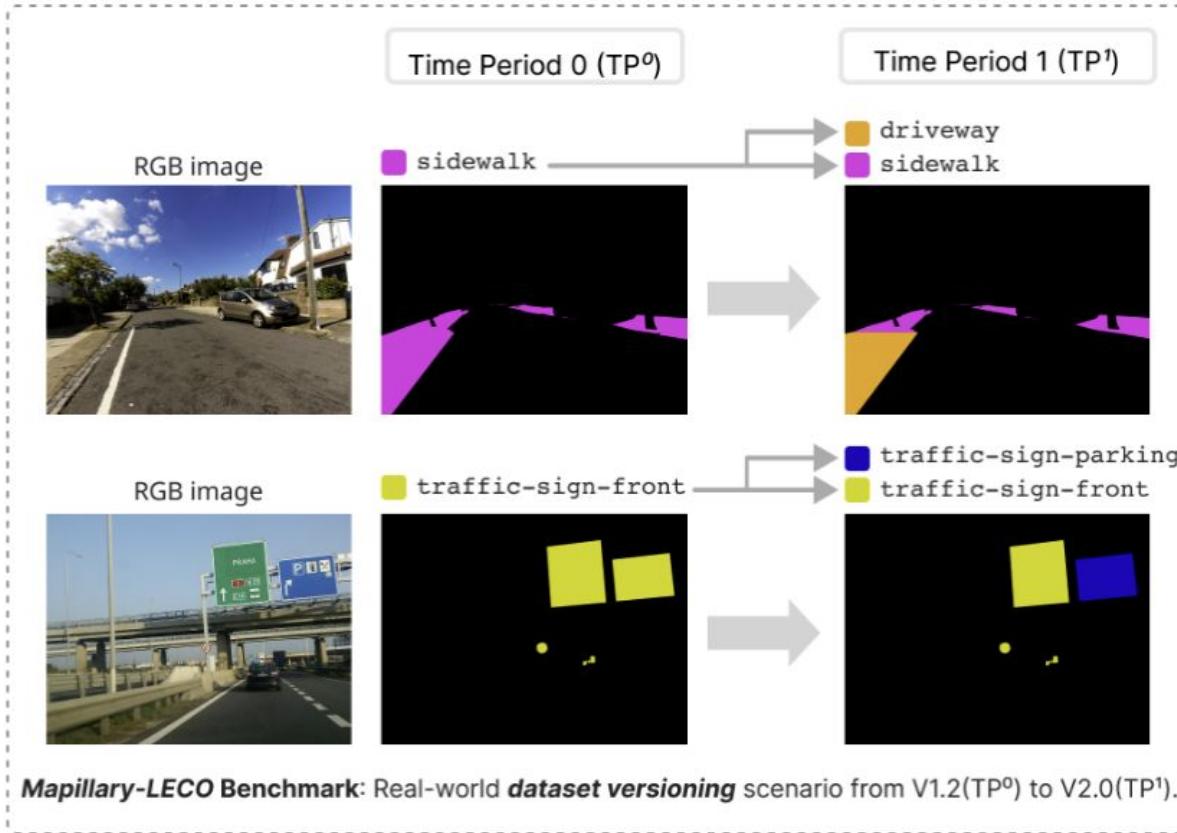
2016

2018

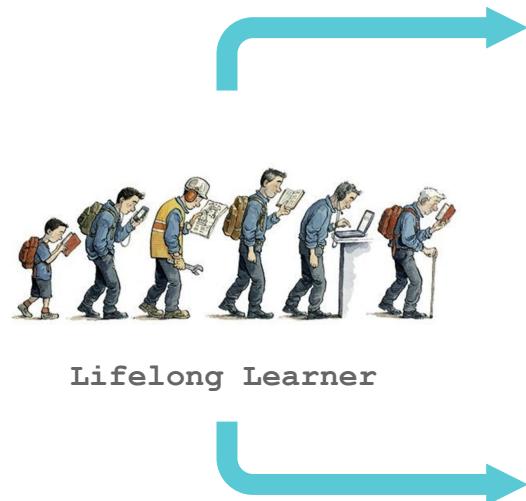
2020

2022

We study the problem of **LECO**: Learning with an Evolving Class Ontology.  
Each time period (TP) of a LECO problem refines the class ontology:



Humans, as **lifelong learners**, are also good at solving LECO problems.



Dog

Types of dog?



Husky



Corgi



Bear

Types of bear?



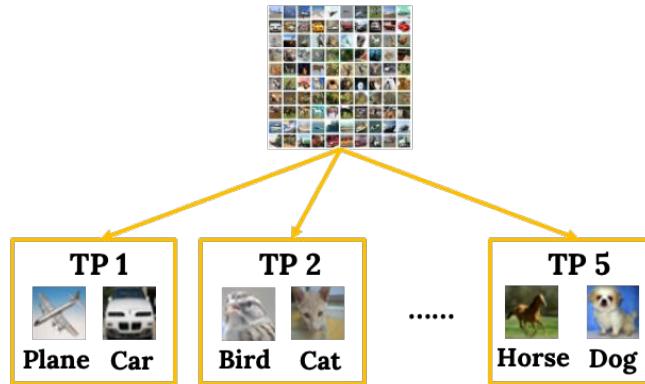
Polar bear



Brown bear

# Class-Incremental Learning (CIL) v.s. LECO

Split-CIFAR10



In CIL, classes are disjoint across TPs, i.e., having no relationship with each other.

LECO



In LECO, the newly added classes are always refined ones from last TP.

# Class-Incremental Learning (CIL) v.s. LECO

TP 1



Others



Dog



Bear

TP 2



Others



Horse



Zebra



Husky



Corgi



Brown



Polar

Note: This **Others** class is sometimes called “**Unlabeled**” or “**Void**” in many datasets [1, 2].



LECO is a more general form of CIL (class-incremental learning) problem by assuming a catch-all **Others** class.

[1] The Mapillary Vistas Dataset for Semantic Understanding of Street Scenes. In ICCV 2017.

[2] The Cityscapes Dataset for Semantic Urban Scene Understanding. In CVPR 2016.

## Class-Incremental Learning (CIL) v.s. LECO

In **CIL**:

- Training data from previous TPs will be **discarded**.
- Overall performance measured by **testsets of previous + current TPs**.

In **LECO**:

- **Keeping all history data** because storage is cheaper than annotation.
- Overall performance measured by the **testset of current TP only**.



LECO targets at practical applications by preserving all data (without setting an artificial small replay buffer).

# **L**earning with an **E**volving **C**lass **O**ntology

→ “LECO” benchmark for lifelong vision

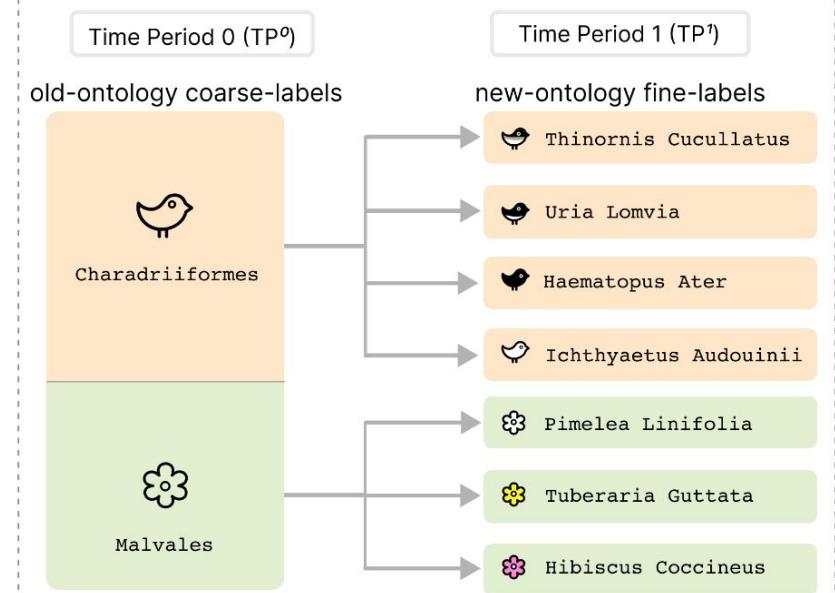
# Benchmark Construction

## LECO-segmentation (Mapillary V1.2 -> V2.0)



**Mapillary-LECO Benchmark:** Real-world **dataset versioning** scenario from V1.2(TP<sup>0</sup>) to V2.0(TP<sup>1</sup>).

## LECO-classification (iNaturalist/CIFAR)



**iNat-LECO Benchmark:** Long-tailed class ontology **evolves from coarse to fine**.

# Question 1: Should one label new data, or relabel old data?

Mapillary v1.2 (2017)



Mapillary v2.0 (2021)



Same images, but relabeled!  
(RelabelOld)

Argoverse v1.0 (2019)



Argoverse v2.0 (2021)



Collect new data to label!  
(LabelNew)

2016

2018

2020

2022



# Question 1: Should one label new data, or relabel old data?

Time Period 0 ( $TP^0$ )

$TP^0$  data  
with old ontology



Time Period 1 ( $TP^1$ )

What samples do we annotate with new ontology?  
Relabel the old, or label the new?

**RelabelOld:** Reannotate  $TP^0$  samples with new ontology.



**LabelNew:** Collect **new samples** to annotate.



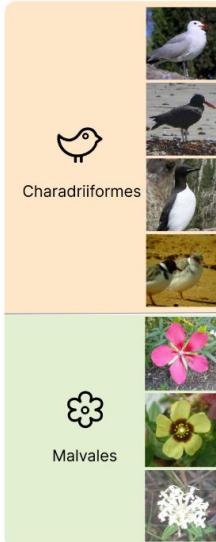
Key insight:

LabelNew will produce more data for training (though with inconsistent labels)

# Question 1: Should one label new data, or relabel old data?

Time Period 0 ( $TP^0$ )

$TP^0$  data  
with old ontology



Time Period 1 ( $TP^1$ )

What samples do we annotate with new ontology?  
Relabel the old, or label the new?

**RelabelOld:** Reannotate  $TP^0$  samples with new ontology.



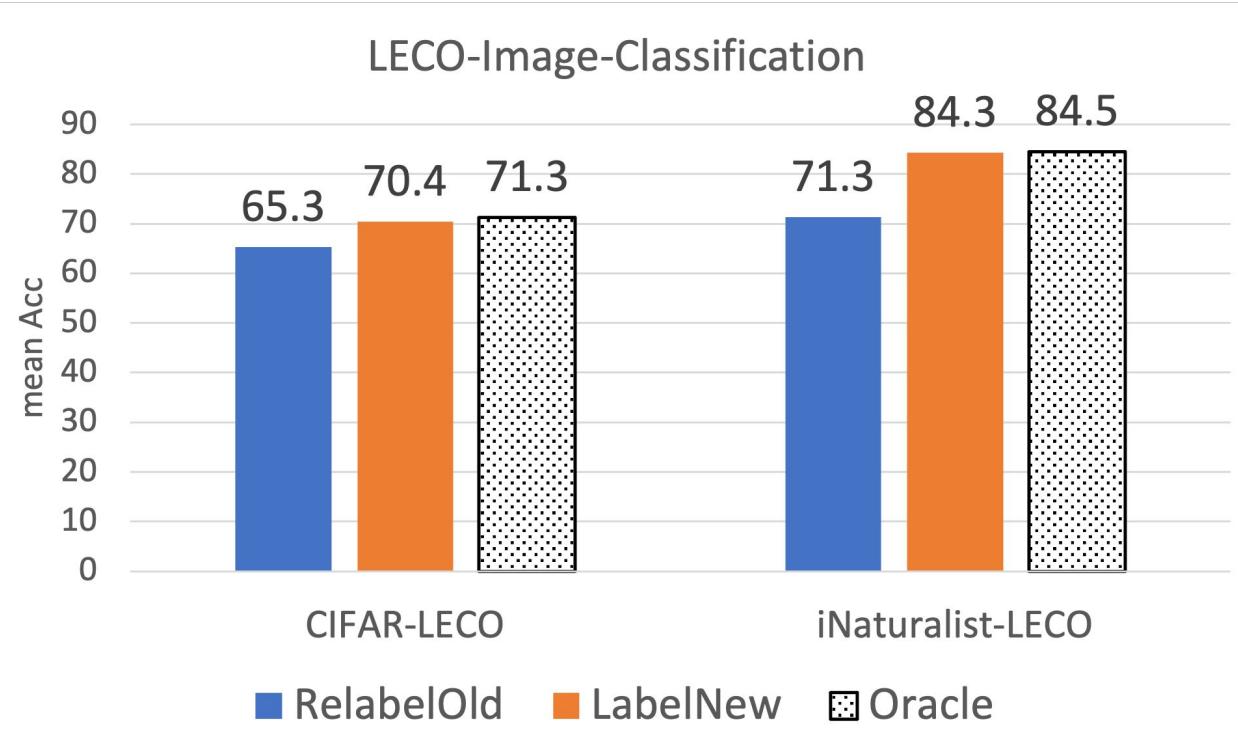
VS.

**LabelNew:** Collect **new samples** to annotate.



Key insight:  
**LabelNew produces more data for training!**

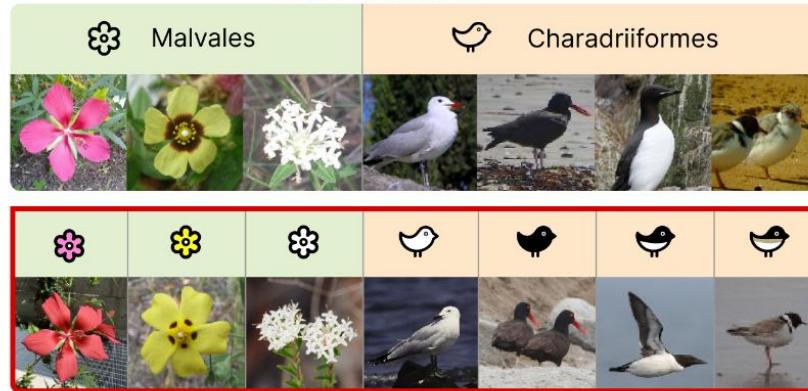
# Question 1: Should one label new data, or relabel old data?



Takeaway: LabelNew produces a better classifier for training on more overall data.

## Question 2: How to train on data with both coarse- and fine-grained labels?

**LabelNew:** Collect **new samples** to annotate.



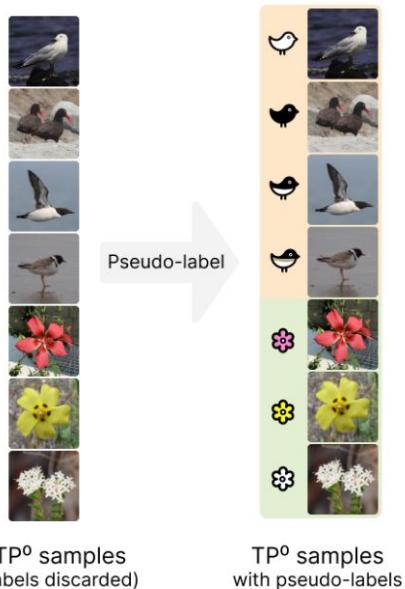
Our proposals:

1. Discard old-ontology labels and only use data.
2. Train on both coarse- and fine-grained labeled data.
3. Exploit the coarse-to-fine label hierarchy.

## Question 2: How to train on data with both coarse- and fine-grained labels?

Proposal 1: Discard old-ontology labels and only use data.  
⇒ Semi-supervised learning (SSL)

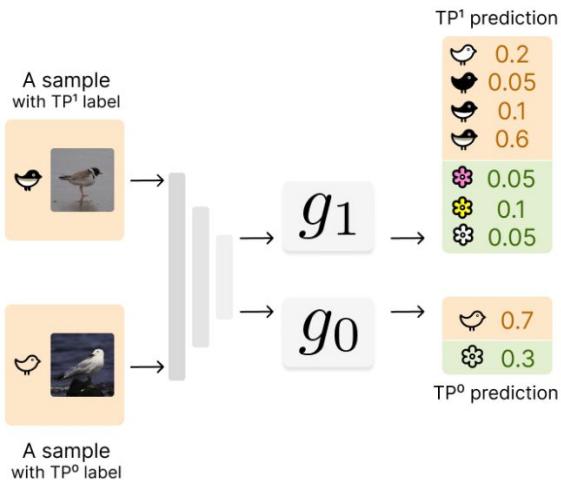
$\mathcal{L}_{SSL}$ : Utilize  $TP^0$  samples



## Question 2: How to train on data with both coarse- and fine-grained labels?

**Proposal 2: Train on both coarse- and fine-grained labeled data.  
⇒ Joint Training**

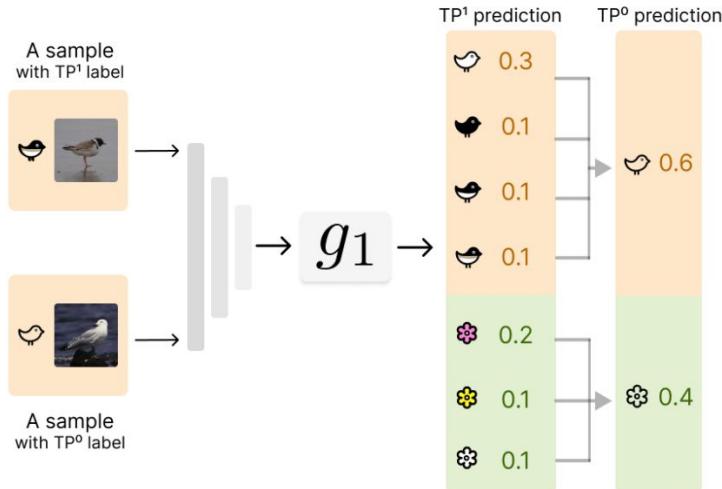
$\mathcal{L}_{Joint}$ : Utilize both TP<sup>0</sup> samples and labels



## Question 2: How to train on data with both coarse- and fine-grained labels?

Proposal 3: Exploiting coarse-to-fine label hierarchy.  
⇒ Learning-with-Partial-Labels (LPL)

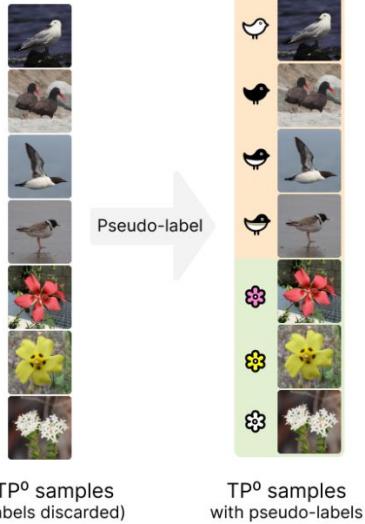
$\mathcal{L}_{LPL}$  : Utilize TP<sup>1</sup> samples, labels, and taxonomic hierarchy



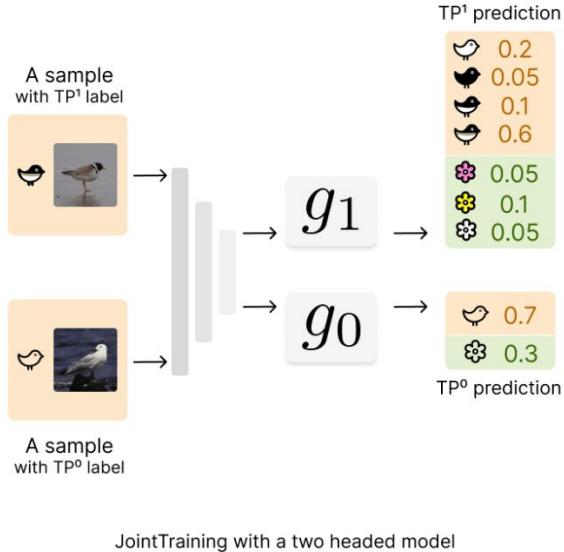
Learning-with-Partial-Labels (LPL) marginalizes leaf node's probabilities for parent classes, then performs training with old-ontology labels

## Question 2: How to train on data with both coarse- and fine-grained labels?

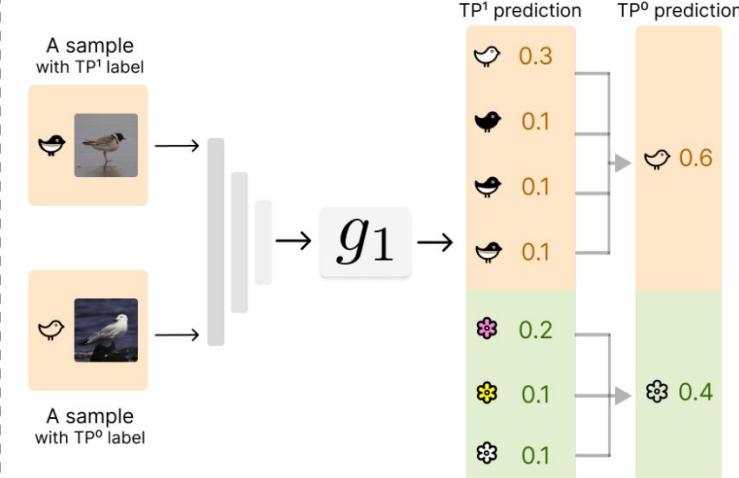
$\mathcal{L}_{SSL}$ : Utilize TP<sup>0</sup> samples



$\mathcal{L}_{Joint}$ : Utilize both TP<sup>0</sup> samples and labels

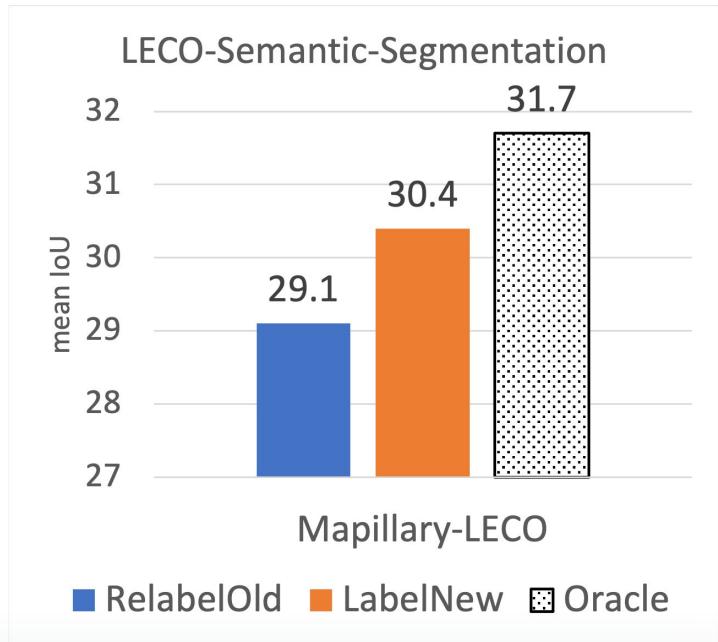


$\mathcal{L}_{LPL}$ : Utilize TP<sup>0</sup> samples, labels, and taxonomic hierarchy

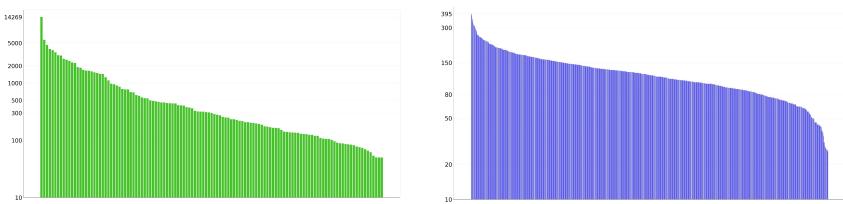


Check out the paper for comprehensive ablation results!

## Question 3: Do our proposals generalize to real-world scenarios?



Our solutions generalize to real-world LECO scenario (Mapillary) without given the label hierarchy.



We show consistent improvements under:

- Long-tailed distribution (Mapillary/iNaturalist)
- More than 2 TPs (iNaturalist)

# Thank You!



Scan for our site!