```
C =


  Kp + Kd * s


  with Kp = 300, Kd = 10

Continuous-time PD controller in parallel form.
Model Properties

T =

     10 s + 300
  ----------------
  s^2 + 20 s + 320

Continuous-time transfer function.
Model Properties

C =

             1
  Kp + Ki * --- + Kd * s
             s

  with Kp = 350, Ki = 300, Kd = 50

Continuous-time PID controller in parallel form.
Model Properties

C =

             1
  Kp + Ki * --- + Kd * s
             s

  with Kp = 320, Ki = 796, Kd = 32.2

Continuous-time PID controller in parallel form.
Model Properties

info =

  struct with fields:

                Stable: 1
    CrossoverFrequency: 32
           PhaseMargin: 90

>>
```