

P_motor =

$$\frac{0.01}{0.005 s^2 + 0.06 s + 0.1001}$$

Continuous-time transfer function.

Model Properties

sys_cl =

$$\frac{1}{0.005 s^2 + 0.06 s + 1.1}$$

Continuous-time transfer function.

Model Properties

sys_cl =

$$\frac{0.01 s^2 + 0.75 s + 0.01}{0.005 s^3 + 0.07 s^2 + 0.8501 s + 0.01}$$

Continuous-time transfer function.

Model Properties

sys_cl =

$$\frac{0.01 s^2 + s + 2}{0.005 s^3 + 0.07 s^2 + 1.1 s + 2}$$

Continuous-time transfer function.

Model Properties

sys_cl =

$$\frac{0.1 s^2 + s + 2}{0.005 s^3 + 0.16 s^2 + 1.1 s + 2}$$

Continuous-time transfer function.

Model Properties

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