

C =

$$\frac{s^2 + s + 1}{s}$$

Continuous-time transfer function.

Model Properties

C =

$$K_p + K_i * \frac{1}{s} + K_d * s$$

with  $K_p = 1$ ,  $K_i = 1$ ,  $K_d = 1$

Continuous-time PID controller in parallel form.

Model Properties

Unrecognized function or variable 'P'.

Error in codecruisecontrol (line 19)

step(P);

>>

>> codecruisecontrol

C =

$$\frac{s^2 + s + 1}{s}$$

Continuous-time transfer function.

Model Properties

T =

$$\frac{100}{1000 s + 150}$$

Continuous-time transfer function.

Model Properties

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