# SUDHARSHAN RAMESH

Boulder, CO | \$\frac{3720-655-0515}{ Sudharshan.ramesh@colorado.edu} | in https://www.linkedin.com/in/sudharshanr99/

## **EDUCATION:**

Master of Science, Mechanical Engineering | University of Colorado Boulder

**Expected May 2025** 

<u>Courses:</u> Advanced Product Design, Mechatronics and Robotics, Advanced Robotics, Feedback Control, Advanced Linear Systems, Robust Multivariate Control, Micro-Electro-Mechanical Systems, Practical Electronics Systems

• Master of Science, Computational Analytics | Georgia Institute of Technology

Expected May 2025

<u>Courses:</u> Intro to Analytical Modelling, Computing for Data analysis, Deterministic Optimization, Computational Data Analytics, Deep Learning, Reinforcement Learning and Decision Making, Data & Visual Analytics, High Dimensional Data Analytics

• Bachelor of Technology, Mechanical Engineering | National Institute of Technology, Warangal

May 2021

<u>Courses:</u> Basic Electronic Engineering, Mechatronics, Engineering Mechanics, Kinematics and Dynamics of Machinery, Design of Machine Elements, Computer Aided Manufacturing, Production Planning and Control

#### SKILLS

- Software & Tools: SolidWorks, ANSYS, Python, MATLAB, Arduino, Raspberry Pi, ROS2, AWS, LabVIEW, Ignition SCADA HMI Development & OPC UA Integration, CODESYS, OpenPLC, Siemens PLC SIM, Allen-Bradley PLCs, TwinCAT, SPI, I2C
- · Concepts: Machine Learning, Control Systems, PCB Design, Mechanical Design, Data Analysis, IoT, Model Predictive Control
- Skills: Creative thinking, Innovative, Time Management, Analytical, Collaboration, Adaptability, Detail-oriented

### **WORK EXPERIENCE:**

**IDFC First Bank Oct 2022 – Jul 2023** 

Data Scientist, Credit Cards

Mumbai, India

- Developed an ARIMA-based forecasting model in Python, achieving a <1% average deviation in predicting monthly credit card expenditure and balances, significantly supporting strategic growth initiatives.
- Implemented an XGBoost Classifier to categorize credit card accounts into optimal APR tiers, improving revenue by 25% through enhanced risk analysis.

Axis Bank Aug 2021 – Oct 2022

Data Analyst, Liabilities Acquisition

Mumbai, India

Engineered a projection framework with a 0.3% average deviation, accurately forecasting month-end savings account balances and
driving strategic financial planning through deep trend analysis, contributing to revenue growth in savings account acquisition by
30%.

Wheels India Pvt. Ltd Jun 2019 – Jul 2019

Intern – Research and Development, Air Suspension Division

Chennai, India

- Engineered and optimized air suspension system for heavy-duty trucks, focusing on load distribution dynamics and system reliability, for an OEM, achieving a 20% improvement in load-bearing performance.
- Monitored and analyzed structural testing procedures and production line operations, gaining insights into advanced manufacturing processes, robotics automation, and stringent quality control standards.

## **PROJECTS:**

- Autonomous Battle Bots Robot | Arduino, C++, SOLIDWORKS, 3D Printing
  - Developed a winning autonomous combat robot using Arduino and PIXY vision sensor for target detection, high-torque actuators for mobility, and real-time motor control, achieving 90% shooting accuracy.
- Autonomous Pet Bot | Raspberry Pi, Arduino, ROS2, Python, SOLIDWORKS, 3D Printing
  - Engineered a robotic pet with sensor-driven navigation, multi-actuator mobility, and ROS2-based integration, utilizing LiDAR and RealSense camera for sensor fusion and Kalman filtering to enhance localization (SLAM), gesture recognition, and autonomous mapping.
- SAE India Efficycle | SOLIDWORKS, ANSYS, Finite Element Analysis
  - Engineered the steering mechanism and system for a hybrid vehicle, collaborating within a team of 8 to ensure seamless integration of components and working using prototyping and engineering principles to design and FEA to validate integrity.
- UR5 robotic arm manipulation | MATLAB, Inverse Kinematics
  - Automated the testing process for pneumatic actuator performance using a 6-axis UR5 robotic arm, equipped with a load cell to measure force at various actuator positions by implementing inverse kinematics algorithms to control the UR5 arm's movements and optimize the precision of force measurements.
- Quad Rotor Dynamics with Wind Gusts | MATLAB, PID control systems
  - Designed and a PID and Model Predictive Control based trajectory control system for a quadrotor drone, enhancing trajectory tracking under wind disturbances and achieving a 40% boost in stability metrics using MATLAB Simulink.
- Raspberry Pi-based Conveyor Belt Automation | Python, Modbus, SCADA
  - Designed a PLC-style control system using a Raspberry Pi to automate a conveyor belt for object sorting, integrating Modbus communication with a SCADA dashboard for real-time monitoring and control.
- Lunar Lander RL Control System | Python, OpenAl Gym, DQN, DDPG
  - Developed RL-based control for lunar landing, optimizing stability and fuel efficiency using DQN & DDPG and achieved a 215.49 average reward over 100 episodes, adapting to wind and turbulence conditions.
- Pneumonia Detection with Deep Learning | Python, PyTorch, CNNs
  - Built an ensemble of ResNet-18, DenseNet-121, and GoogLeNet for pneumonia classification, achieving 85% accuracy.