Rafael Delwart

Robotics Engineer

About Me

I am a Robotics Engineering graduate from UCSC, born and raised in San Francisco, with hands-on experience in microelectronics, programming microcontrollers, and automating complex systems. I am proficient in Kicad, C, and SolidWorks, capable of simulating and developing real-world applications. I am a fast learner with practical expertise in coding, electrical systems, and 3D modeling.

Major Projects

Wet-Dry Cycler for RNA Production

Recruited and led a team to design and build an automated system to simulate early Earth conditions for non-enzymatic RNA synthesis, supporting origins-of-life research in collaboration with Dr. David Deamer.

3D Tracking Using an IMU for Rock Climbing

Developed an inertial measurement unit (IMU)-based tracking system for analyzing climber movement, improving performance insights, and real-time motion visualization.

Mechatronics Competition (2nd Place)

Led the development of a high-performance autonomous robotic system, integrating microcontrollers, sensors, and real-time feedback for competitive mechatronics tasks.

Detailed descriptions and documentation available at:

ramfi-d.github.io/Website/

Most Relevant Courses

Comp	uter	Scie	ence:

CSE 100/L: Logic Design (A-) CSE 101: Data Structures (B) CSE 107: Prob. & Stats (B-) CSE 12: Assembly (A) CSE 16: Discrete Math (B) CSE 20: Python (B)

CSE 30: Prog. Abstractions (B) ECE 13: C Programming (A-)

Electrical & Mech. Engineering:

ECE 129A/B/C: Project for Professor Deamer (A)

ECE 242: Applied Feedback Control (A) ECE 141: Feedback Control Systems (A) ECE 171/L: Analog Elec. (A-) ECE 167/L: Sensors (B+) Lab (A+)

ECE 121/L: Embedded Systems (A) ECE 118: Mechatronics (A) ECE 103/L: Signals & Systems (A+)

ECE 103/L: Signals & Systems (A-ECE 101/L: Circuits (B+)

Math & Physics:

ECE 9: Statics & Mechanics (B)
MATH 19A: Calc I (B+)
MATH 19B: Calc II (B)
MATH 21: Linear Algebra (A)
MATH 23A: Vector Calc (B)
PHYS 5A/L: Physics I (B+) Lab (A)
PHYS 5C/N: Physics III (B+) Lab (A)

AM 20: Math Methods II (A-) ECE 10: Kinematics (A+)

Work Experience

UCSC, Santa Cruz, CA

Undergraduate Tutor — ECE167: Sensors and Sensing

Supervisor: Professor Collen Josephson (cjosephson@ucsc.edu)

Winter Quarter 2025

Led tri-weekly lab sessions on sensor technologies and data processing. Covered sensing principles, calibration, signal filtering, ADC, and data acquisition. Guided students in practical lab applications using C programming.

Skills

Programming: Python, Kicad, C, C++, Verilog, MATLAB, Assembly, HTML, CSS, Latex.

Math & Physics: Strong background in advanced concepts. Systems Modeling: Kinematics, dynamics, SolidWorks, OnShape. Electronics: Circuit design, analysis, analog/digital systems.

Projects: Microcontrollers, sensors, 3D prototyping, technical documentation.

Languages: Fluent in French.

Education

University of California, Santa Cruz (UCSC)

Robotics Engineering, Minor in Electrical Engineering

Sept 2020 - June 2025

References

Prof. David Deamer (deamer@soe.ucsc.edu) • Prof. Collen Josephson (cjosephson@ucsc.edu) • Prof. Zouheir Rezki (zrezki@ucsc.edu)

Contact

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