view\_frames Result Recorded at time: 1539102398.223 world Broadcaster: /robot\_state\_publisher Average rate: 50.194 Hz Most recent transform: 1539102398.711 ( -0.487 sec old) Buffer length: 4.981 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.194 Hz Average rate: 40.164 Hz Most recent transform: 1539102398.711 ( -0.487 sec old) Most recent transform: 1539102398.210 ( 0.013 sec old) Buffer length: 4.981 sec Buffer length: 4.980 sec shoulder link Broadcaster: /ur\_driver Broadcaster: /robot\_state\_publisher Average rate: 120.091 Hz Average rate: 40.164 Hz Most recent transform: 1539102398.218 ( 0.005 sec old) Most recent transform: 1539102398.210 ( 0.013 sec old) Buffer length: 4.988 sec Buffer length: 4.980 sec tool0\_controller upper\_arm\_link Broadcaster: /robot\_state\_publisher Average rate: 40.164 Hz Most recent transform: 1539102398.210 ( 0.013 sec old) Buffer length: 4.980 sec forearm link Broadcaster: /robot\_state\_publisher Average rate: 40.164 Hz Most recent transform: 1539102398.210 ( 0.013 sec old)

base

Buffer length: 4.980 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 40.164 Hz Most recent transform: 1539102398.210 ( 0.013 sec old) Buffer length: 4.980 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 40.164 Hz Most recent transform: 1539102398.210 ( 0.013 sec old) Buffer length: 4.980 sec wrist\_3\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher

tool0

Average rate: 50.194 Hz Most recent transform: 1539102398.711 ( -0.487 sec old) Buffer length: 4.981 sec

ee\_link

Average rate: 50.194 Hz Most recent transform: 1539102398.711 ( -0.487 sec old) Buffer length: 4.981 sec