## ECE4110: Random Signals in Communications and Signal Processing

# Spectral Analysis and Linear Filtering of Random Processes

Qing Zhao
School of Electrical and Computer Engineering
Cornell University, Ithaca, NY 14850
qz16@cornell.edu

## **Outline**

- Autocorrelation function and power spectrum density.
- Joint WSS, crosscorrelation function, and cross power spectrum density.
- White noise.
- Linear filtering of random processes.
- Optimal linear filtering and Wiener filter.

## **WSS** and Correlation Functions

## Wide Sense Stationarity (WSS):

A random process is wide sense stationary (WSS) if

$$(i) \quad \mathbb{E}[X(t_i)] = m$$

(ii) 
$$R_X(t_1, t_2) \stackrel{\Delta}{=} \mathbb{E}[X(t_1)X(t_2)]$$
  
 $= R_X(t_1 - t_2)$   
 $= R_X(\tau)$ , where  $\tau = t_1 - t_2$ 

## Properties of the Autocorrelation function $R_X(\tau)$ :

Let  $R_X(\tau)$  be the autocorrelation function of a zero-mean WSS random process. Then

- 1.  $R_X(0) = \mathbb{E}[X^2(t)]$  is the average power of X(t).
- 2.  $R_X(\tau)$  is even:  $R_X(-\tau) = R_X(\tau)$ .
- 3.  $R_X(0) \ge |R_X(\tau)|$ .

#### Joint WSS:

Two random processes  $\{X(t)\}_{t=-\infty}^{\infty}$  and  $\{Y(t)\}_{t=-\infty}^{\infty}$  are jointly wide sense stationary (WSS) if

$$(i) \quad \text{both } \{X(t)\}_{t=-\infty}^{\infty} \text{ and } \{Y(t)\}_{t=-\infty}^{\infty} \text{ are WSS;}$$

(ii) 
$$R_{X,Y}(t_1, t_2) \stackrel{\Delta}{=} \mathbb{E}[X(t_1)Y(t_2)]$$
  
=  $R_{X,Y}(t_1 - t_2)$   
=  $R_{X,Y}(\tau)$ , where  $\tau = t_1 - t_2$ 

## **Power Spectrum Density**

## **Power Spectrum Density:**

□ The power spectrum density  $S_X(f)$  of a discrete-time WSS random process  $\{X_n\}_{n=-\infty}^{\infty}$  is the discrete-time Fourier transform of the autocorrelation function  $R_X(k)$ :

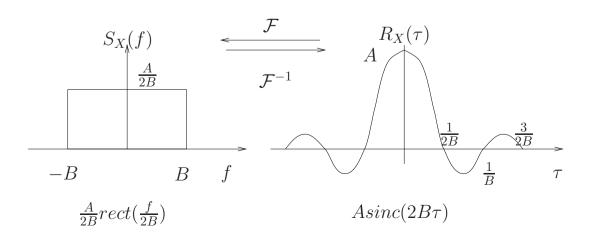
$$S_X(f) \stackrel{\Delta}{=} \sum_{k=-\infty}^{\infty} R_X(k) e^{-j2\pi fk} \qquad (-\frac{1}{2} < f \le \frac{1}{2})$$

$$R_X(k) = \int_{-\frac{1}{2}}^{\frac{1}{2}} S_X(f) e^{j2\pi fk} df$$

□ The power spectrum density  $S_X(f)$  of a continuous-time WSS random process  $\{X(t)\}_{t=-\infty}^{\infty}$  is the Fourier transform of the autocorrelation function  $R_X(\tau)$ :

$$S_X(f) \stackrel{\Delta}{=} \int_{-\infty}^{\infty} R_X(\tau) e^{-j2\pi f \tau} d\tau$$

$$R_X(\tau) = \int_{-\infty}^{\infty} S_X(f) e^{j2\pi f \tau} df$$



## **Power Spectrum Density**

## **Properties of Power Spectrum Density:**

For a real-valued random process  $\{X(t)\}_{t=-\infty}^{\infty}$ ,

- 1.  $S_X(f) \geq 0$  for all f;
- 2.  $S_X(f)$  is real and even;
- 3. Average power:

$$R_X(0) = \int_{-\frac{1}{2}}^{\frac{1}{2}} S_X(f) df$$
 (discrete time) 
$$R_X(0) = \int_{-\infty}^{\infty} S_X(f) df$$
 (continuous time)

## **Cross Power Spectrum Density:**

For jointly WSS random processes  $\{X(t)\}_{t=-\infty}^{\infty}$  and  $\{Y(t)\}_{t=-\infty}^{\infty}$ , the cross power spectrum density  $S_{X,Y}(f)$  is the Fourier transform of the crosscorrelation function  $R_{X,Y}(\tau)$ .

## **Linear Filtering of Random Processes**

#### **Discrete Time:**

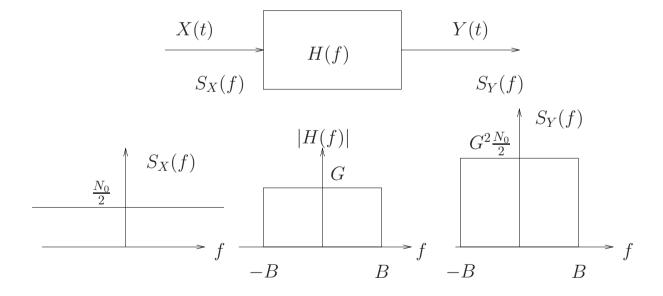
$$Y_n = \sum_{l=-\infty}^{\infty} h_l X_{n-l}$$

$$S_Y(f) = |H(f)|^2 S_X(f) \quad (-\frac{1}{2} < f \le \frac{1}{2})$$
(1)

## **Continuous Time:**

$$Y(t) = \int_{-\infty}^{\infty} h(s)X(t-s)ds$$
  

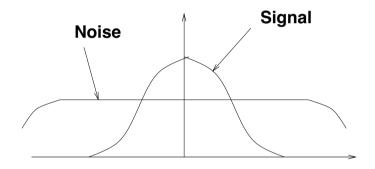
$$S_Y(f) = |H(f)|^2 S_X(f)$$
(2)



## White Noise and Gaussian Processes

#### White Noise:

- ullet Continuous-time white noise  $\{X(t)\}$ : a WSS process with zero mean and PSD  $S_X(f)=N_0/2$  within the frequency range of interest  $f\in [-W,W]$ .
- Discrete-time white noise  $\{X_n\}$ : a sequence of zero-mean and uncorrelated random variables each with variance  $\text{Var}(X_n) = \sigma^2$ , i.e.,  $R_X(k) = \sigma^2 \delta_k$  and  $S_X(f) = \sigma^2 \left(-\frac{1}{2} < f \leq \frac{1}{2}\right)$ .



#### **Gaussian Processes**

- Definition: A random process X(t) is Gaussian if for all n and  $t_1, \dots, t_n$ , random variables  $X(t_1), \dots, X(t_n)$  are jointly Gaussian.
- Properties:
  - The output of a linear filter driven by a Gaussian process is Gaussian.
  - Wide sense stationarity implies strict stationarity.

## **Optimal Filtering of Random Processes**

### **Optimal Filtering:**

 $\{X_n\}_{n=-\infty}^{\infty}$  and  $\{Z_n\}_{n=-\infty}^{\infty}$  are zero-mean jointly WSS random processes.

Estimate  $Z_n$  using a linear function of  $\{X_{n-a}, \ldots, X_{n+b}\}$ :

$$\hat{Z}_n = \sum_{j=-b}^a h_j X_{n-j}$$

Choose the linear filter response  $\{h_n\}_{n=-b}^a$  to minimize MSE  $\mathbb{E}[(Z_n-\hat{Z}_n)^2].$ 

## The Optimality Equations:

Based on the orthogonality principle, the optimal linear filter  $\{h_n\}_{n=-b}^a$  satisfies

$$R_{Z,X}(m) = \sum_{j=-b}^{a} h_j R_X(m-j), \quad \forall m = -b, \dots, a.$$

The MMSE is given by

$$R_Z(0) - \sum_{j=-b}^{a} h_j R_{Z,X}(j)$$

#### Wiener Filter:

For infinite smoothing with  $a=\infty$  and  $b=\infty$ , we have

$$R_{Z,X}(m) = \sum_{j=-\infty}^{\infty} h_j R_X(m-j) = h(m) * R_X(m)$$

Taking Fourier transform leads to

$$H(f) = \frac{S_{Z,X}(f)}{S_X(f)}$$