

Recall

Started conditional stuff for continuous rvs.

Given continuous rv X , event A , conditional pdf of X given A is defined as the function $f_{X|A}(x)$ satisfying

$$P(X \in J | A) = \int_J f_{X|A}(x) dx \quad \forall J \subset \mathbb{R}$$

Special Case: If A is an event of the form $\{X \in W\}$ for some $W \subset \mathbb{R}$,

$$f_{X|A}(x) = \begin{cases} \frac{f_X(x)}{P(\{X \in W\})}, & x \in W \\ 0, & x \notin W \end{cases}$$

Example - "Light Bulb"

Suppose T is exponential(λ) rv

$$f_T(t) = \begin{cases} \lambda e^{-\lambda t}, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

Pick $t_0 > 0$; let

$$\begin{aligned} X &= T - t_0, \\ A &= \{T > t_0\}; \end{aligned}$$

find $f_{X|A}(x)$.

Note: $A = \{T > t_0\} = \{X > 0\}$!

Hence,

$$f_{X|A}(x) = \begin{cases} \frac{f_x(x)}{P(\{T > t_0\})}, & x > 0 \\ 0, & x \leq 0 \end{cases}$$

where

$$P(\{T > t_0\}) = \int_{t_0}^{\infty} f_T(t) dt = e^{-\lambda t_0}$$

and

$$f_x(x) = \begin{cases} \lambda e^{-\lambda(t_0+x)}, & x > -t_0 \\ 0, & x \leq -t_0 \end{cases}$$

How'd we get this? First find $F_X(x)$.

$$\begin{aligned} F_X(x) &= P(X \leq x) = P(\{T \leq t_0 + x\}) \\ &= \int_{-\infty}^{t_0+x} f_T(t) dt \end{aligned}$$

Now take $\frac{d}{dx}$

$$f_X(x) = \frac{d}{dx} \left(\int_{-\infty}^{t_0+x} f_T(t) dt \right) = f_T(t_0+x)$$

where

$$f_T(t_0+x) = \begin{cases} \lambda e^{-\lambda(t_0+x)}, & x > -t_0 \\ 0, & x \leq -t_0 \end{cases}$$

Therefore,

$$f_{X|A}(x) = \begin{cases} \frac{\lambda e^{-\lambda(t_0+x)}}{e^{-\lambda t_0}} & , x \geq 0 \\ 0 & , x < 0 \end{cases} = \begin{cases} \lambda e^{-\lambda x} & , x \geq 0 \\ 0 & , x < 0 \end{cases}$$

In light-bulb terms, "find bulb still on at time t_0 , remaining bulb lifetime is still exponential (x), as 'brand-new' lifetime"



This is the "resetting"/"regeneration" property of exponential pdfs - similar to geometric "resetting" in discrete world

Total Probability Theorem in context of $f_{X|A}$:

If X is a continuous rv and A_1, \dots, A_n are events of positive probability that partition Ω , then

$$f_X(x) = \sum_{k=1}^n f_{X|A_k}(x) P(A_k)$$

To see this: go via cdfs.

$$F_{X|A_k} = \frac{P(\{X \leq x\} \cap A_k)}{P(A_k)}$$

$$\frac{d}{dx} F_{X|A_k} = f_{X|A_k}(x)$$

By Total Probability Theorem,

$$F_x(x) = P(\{X \leq x\}) = \sum_{k=1}^n F_{x|A_k} P(A_k) \xrightarrow{\frac{d}{dx}} \sum_{k=1}^n f_{x|A_k} P(A_k) = f_x(x)$$

Comment: this holds when A_k aren't of the special form $\{X \in W_k\}$!

Example - Walking To Class

Before leaving for campus, spin wheel; w/ prob $2/3$ I walk via the gorge, $1/3$ via collegetown.

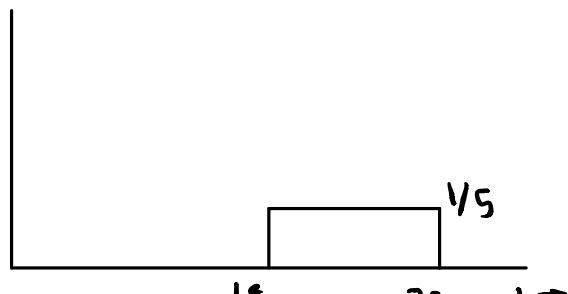
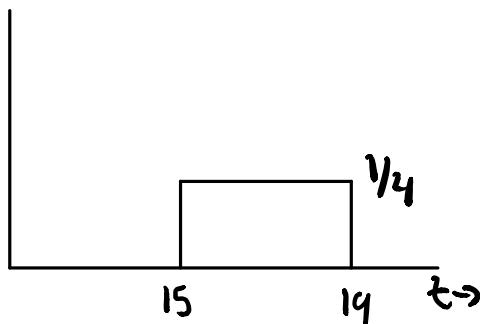
- Walking via gorge, travel time uniform on $[15, 19]$ minutes
- Walking via ctown, travel time uniform on $[18, 23]$ minutes

Let X = travel time.

$f_x(x)$?

Let $A = \text{walk via gorge} \Rightarrow A^c = \text{walk via ctown}$

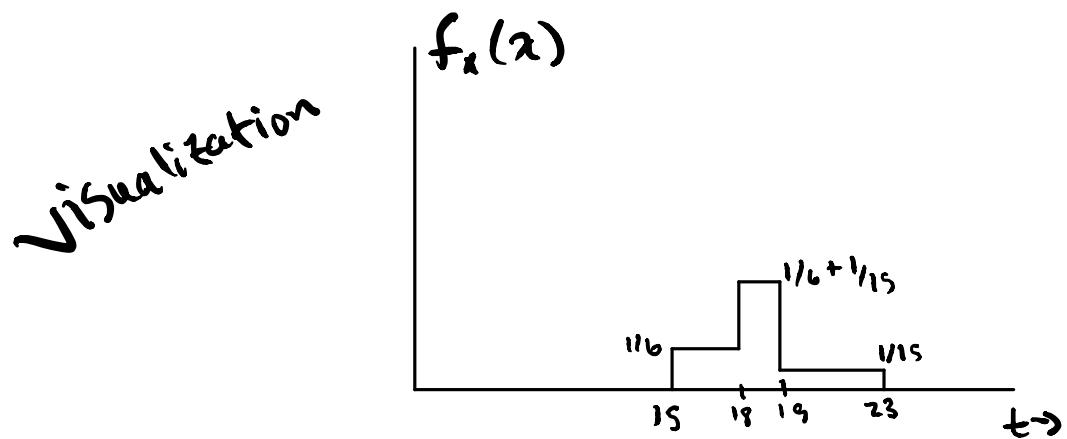
$f_{x|A}(x)$



Thus

$$f_X(x) = f_{X|A}(x) \cdot \left(\frac{2}{3}\right) + f_{X|A^c}(x) \cdot \left(\frac{1}{3}\right)$$

$$f_X(x) = \begin{cases} 0 & , x < 15 \\ \frac{1}{6} & , 15 \leq x < 18 \\ \frac{1}{6} + \frac{1}{15} & , 18 \leq x < 19 \\ \frac{1}{15} & , 19 \leq x < 23 \\ 0 & , x > 23 \end{cases}$$



Next, discuss conditional pdf of a continuous rv X given $Y=y$ for some other continuous rv Y

Naive approach: Let $A = \{Y=y\}$. But Y is continuous!
So $P(\{Y=y\})=0 \Rightarrow$ it is NOT a suitable A
for $f_{X|A}(x)$

Instead we proceed as follows:

- 1) Given V , look at $P(\{X \in V\} | \{Y \in [y-\delta, y+\delta]\})$
- 2) Take $\lim \delta \rightarrow 0$
- 3) Find that it equals

$$\int_V (\quad) dx \quad \text{this is our goal}$$

$$P(\{X \in V\} | \{Y \in [y-\delta, y+\delta]\}) = \frac{P(\{X \in V\} \cap \{Y \in [y-\delta, y+\delta]\})}{P(\{Y \in [y-\delta, y+\delta]\})}$$

$$= \frac{\int_V dx \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t)}{\int_V f_Y(t) dt} = \frac{\int_V dx \left(\frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t) \right)}{\left(\frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_Y(t) \right)}$$

Multiply by $1 = \frac{1/2\delta}{1/2\delta}$

$$\frac{\int_V dx \left(\frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t) \right)}{\left(\frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_Y(t) \right)} \xrightarrow{\lim \delta \rightarrow 0} \frac{\int_V f_{x,y}(x,y) dx}{f_Y(y)}$$

$$\frac{\int_V f_{x,y}(x,y) dx}{f_Y(y)} = \int_V \left(\frac{f_{x,y}(x,y)}{f_Y(y)} \right) dx$$

Bottom line: conditional pdf of X given $Y=y$ is

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

What you integrate over
for any $x \in \mathcal{X}$ to get
 $P(\{X \in \mathcal{X}\} | Y=y)$

Note: for fixed y , this as a function of x is a legit pdf

$$\int_{-\infty}^{+\infty} f_{X|Y}(x|y) dx = \int_{-\infty}^{+\infty} \frac{f_{X,Y}(x,y)}{f_Y(y)} dx = \frac{1}{f_Y(y)} \int_{-\infty}^{+\infty} f_{X,Y}(x,y) dx = \frac{f_Y(y)}{f_Y(y)} = 1 \checkmark$$

As for conditional pmfs in discrete-world, can use conditional pdfs to compute joints, marginals, etc, in situations most naturally expressed in conditional terms.

e.g.

$$f_{X,Y}(x,y) = f_{X|Y}(x|y) f_Y(y)$$

Integrate over x or y to get

$$f_X(x) = \int_{-\infty}^{+\infty} f_{X|Y}(x|y) dy \quad \text{OR} \quad f_Y(y) = \int_{-\infty}^{+\infty} f_{Y|X}(y|x) f_X(x) dx$$

This generalizes "obviously" to > 2 rvs.

"What mathematicians say when they know something that isn't entirely obvious to anybody else"
- Some kid in a math class

- Rami Pellumbi

Take X, Y, Z for example.

$$f_{x,y,z}(x,y,z) = \frac{f_{x,y,z}(x,y,z)}{f_z(z)} \quad \text{OR} \quad f_{x|y,z}(x|y,z) = \frac{f_{x,y,z}(x,y,z)}{f_{y,z}(y,z)}$$

etc., etc., etc

And we have chain rules such as

Need not memorize

$$f_x(x) = f_{x|y,z}(x|y,z) f_{y,z}(y,z)$$

Example - Radar Gun

Speed of passenger vehicle $- X$ - exponential w/ $\lambda = 50$.

Y = radar gun measurement of X , given $X=x$, is Gaussian; mean x , variance $\sigma^2 = x/10$

$$f_x(x) = \begin{cases} 50e^{-50x}, & x > 0 \\ 0, & x < 0 \end{cases}$$

$$f_{y|x}(y|x) = \frac{1}{\sqrt{2\pi(\frac{x^2}{100})}} e^{-\frac{(y-x)^2}{(x^2/50)}}$$

Hence $f_{x,y}(x,y) = f_{y|x}(y|x) f_{x|x}(x)$ and $f_y(y) = \int_{-\infty}^{+\infty} (\quad) dx$

One loose end:

Expected value rule for joints.

$$\mathbb{E}(g(x,y)) = \int_{-\infty}^{+\infty} dx \int_{-\infty}^{+\infty} dy g(x,y) f_{x,y}(x,y)$$