

Similar Matrices

Situation

$$T: V \rightarrow V \quad (T \in \mathcal{L}(V))$$

Suppose

$$\dim V = n < \infty$$

and

α, β two bases of V

from HW:

$$[T]_{\beta} = [id]_{\beta \leftarrow \alpha} [T]_{\alpha \leftarrow \alpha} [id]_{\alpha \leftarrow \beta}$$

Let

$$[T]_{\alpha} = A$$

$$[T]_{\beta} = B$$

$$[id]_{\beta \leftarrow \alpha} = Q^{-1}$$

$$[id]_{\alpha \leftarrow \beta} = Q$$

Then

$$B = Q^{-1} A Q$$

Definition: We say A is similar to B ($A \sim B$) if \exists invertible $n \times n$ matrix Q st. $B = Q^{-1} A Q$

Proposition: \sim is an equivalence relation on the set of $n \times n$ matrices

Aside

\sim is an equivalence relation if $\forall x, y, z \in S$

① $x \sim x$

② $x \sim y \rightarrow y \sim x$

③ $x \sim y, y \sim z \rightarrow x \sim z$

Proof (of Proposition)

Let A, B, C be $n \times n$ matrices.

① $A \sim A \rightarrow$ choose $Q = I$

② $A \sim B, B = Q^{-1} A Q$

then $B \sim A, Q B Q^{-1} = A$

③ $A \sim B, B = Q^{-1} A Q, Q, S$ invertible

$B \sim C, C = S^{-1} B S$

then $A \sim C$

$$C = S^{-1} Q^{-1} A Q S$$
$$= (QS)^{-1} A (QS)$$
$$A \sim C$$

Problem: Find a nice form for $T \in \mathcal{L}(V)$, or $A_{n \times n}$ ← assuming $\dim V = n$

2 versions of problem

① find a basis β of V s.t. $[T]_{\beta}$ is "totally nice"

② find a matrix $\underbrace{B = Q^{-1} A Q}_{B \text{ similar to } A}$ s.t. B is "totally nice"

Definition: ① A matrix $A \in \mathbb{F}^{n \times n}$ is called diagonalizable if $\exists Q$
 s.t. $B = Q^{-1} A Q$ is diagonal
 i.e.

$$B = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \lambda_n \end{pmatrix}$$

② $T: V \rightarrow V$ LT

is called diagonalizable if \exists basis \mathcal{B} of V s.t.
 $[T]_{\mathcal{B}}$ is diagonalizable

Example

Suppose $B = Q^{-1} A Q$ is diagonal

$$\begin{pmatrix} \lambda_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n \end{pmatrix}$$

So Note: $QB = AQ$

Let $Q = [\vec{v}_1 \dots \vec{v}_n]$, $\vec{v}_i \in \mathbb{F}^n \neq 0$

Note: $[\vec{v}_1 \dots \vec{v}_n]$ a basis of V which is \mathbb{F}^n here

$\Leftrightarrow Q = [\vec{v}_1 \dots \vec{v}_n]$ is invertible

$$[\vec{v}_1 \dots \vec{v}_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} = A [\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n]$$

$$[\lambda_1 \vec{v}_1 \ \lambda_2 \vec{v}_2 \ \dots \ \lambda_n \vec{v}_n] = [A\vec{v}_1 \ A\vec{v}_2 \ \dots \ A\vec{v}_n]$$

i.e.

$$A\vec{v}_1 = \lambda_1 \vec{v}_1$$

$$A\vec{v}_2 = \lambda_2 \vec{v}_2$$

\vdots

$$A\vec{v}_n = \lambda_n \vec{v}_n$$

Example (Part 2):

If T is diagonalizable, then what?

i.e. $\beta = [\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n]$ basis of V $[T]_\beta = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \lambda_n \end{pmatrix}$

$$[T]_\beta = \begin{matrix} & \begin{matrix} T(\vec{v}_1) & T(\vec{v}_2) & \dots & T(\vec{v}_n) \end{matrix} \\ \begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vdots \\ \vec{v}_n \end{matrix} & \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix} \end{matrix}$$

$$T(\vec{v}_1) = \lambda_1 \vec{v}_1$$

$$T(\vec{v}_2) = \lambda_2 \vec{v}_2$$

\vdots

$$T(\vec{v}_n) = \lambda_n \vec{v}_n$$

Definition: Let $T: V \rightarrow V$ be a LT ($T \in \mathcal{L}(V)$).

A vector $\vec{v} \in V$ is an eigenvector of T if

Ⓐ $\vec{v} \neq 0$

Ⓑ $T(\vec{v}) = \lambda \vec{v}$ for some $\lambda \in \mathbb{F}$

This λ is called the eigenvalue associated to \vec{v} .

$\lambda \in \mathbb{F}$ is an eigenvalue of T if \exists eigenvector \vec{v} of T w/ eigenvalue λ

Situation

Do NOT assume V finite dimensional
until we say so

$$T \in \mathcal{L}(V)$$

Proposition: Suppose $\lambda_1, \lambda_2, \dots, \lambda_m$ are **distinct** eigenvalues of T
and $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m \in V$ are corresponding
corresponding eigenvectors (\Rightarrow nonzero), then the
set $(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m)$ are linearly **INDEPENDENT**

Proof

Suppose $(\vec{v}_1, \dots, \vec{v}_m)$ is LD.

$$a_1 \vec{v}_1 + \dots + a_m \vec{v}_m = \vec{0}$$

$$T(a_1 \vec{v}_1 + \dots + a_m \vec{v}_m) = T(\vec{0})$$

$$a_1 \lambda_1 \vec{v}_1 + \dots + a_m \lambda_m \vec{v}_m = \vec{0}$$

Let k be the smallest integer s.t. $\vec{v}_k \in \text{span}(\vec{v}_1, \dots, \vec{v}_{k-1})$

i.e. $\vec{v}_k = c_1 \vec{v}_1 + \dots + c_{k-1} \vec{v}_{k-1}$

then $T(\vec{v}_k) = \lambda_k \vec{v}_k = c_1 \lambda_1 \vec{v}_1 + \dots + c_{k-1} \lambda_{k-1} \vec{v}_{k-1}$

Multiply by λ_k , subtract

$$\begin{aligned} \vec{0} &= (c_1 \lambda_1 - c_1 \lambda_k) \vec{v}_1 + \dots + c_{k-1} (\lambda_{k-1} - \lambda_k) \vec{v}_{k-1} \\ &= c_1 (\lambda_1 - \lambda_k) \vec{v}_1 + \dots + c_{k-1} (\lambda_{k-1} - \lambda_k) \vec{v}_{k-1} \end{aligned}$$

LI

$$\Rightarrow c_1 (\lambda_1 - \lambda_k) = 0 \dots c_{k-1} (\lambda_{k-1} - \lambda_k) = 0$$

Not all c_i can be zero b/c then $\vec{v}_k = \vec{0}$ but

it is an eigenvector so that can't be the case.

$$\Rightarrow \lambda_i = \lambda_k \quad i \in [1, k-1]$$

Contradiction, λ_i distinct.