

# Recap

(a) Linear maps/transformations

$$T: V \rightarrow W \quad T \in \mathcal{L}(V, W)$$

vector space

examples: differentiation, projections, rotations,

if  $A$  is an  $m \times n$  matrix over  $\mathbb{F}$  ( $L_A$ )

$$L_A: \mathbb{F}^n \rightarrow \mathbb{F}^m$$
$$\vec{x} \mapsto A\vec{x}$$

IMPORTANT

## Key facts

- If  $(v_1, \dots, v_n)$  is a basis of  $V$  and  $(w_1, \dots, w_n)$  are ANY elements of  $W$ , then  $\exists! T: V \rightarrow W$  s.t.  $T(v_i) = w_i$  (LT)

(b) Kernel + Images  $T: V \rightarrow W$

$$\ker T \text{ (nullspace)} \subseteq V \quad (\text{all vectors } \vec{v} \text{ in } V \text{ s.t. } T(\vec{v}) = 0)$$

$$\text{im } T \text{ (range/image)} \subseteq W$$

key facts: •  $\ker T \subseteq V$  is a subspace  $\Rightarrow$  is a vector space

$\text{im } T \subseteq W$  is a subspace  $\Rightarrow$  is a vector space

$$\bullet \dim V = \dim \ker T + \dim \text{im } T$$

(c) Matrix of  $T: V \rightarrow W$  (LT)

If  $A = (\vec{v}_1, \dots, \vec{v}_n)$  is a basis of  $V$

$B = (\vec{w}_1, \dots, \vec{w}_m)$  is a basis of  $W$

If  $\vec{v} \in V$ ,  $\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$  (unique,  $\vec{v}_i$  form a basis)

$$[\vec{v}]_A := \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \in \mathbb{F}^n$$

$\swarrow$   $m \times n$  matrix

Matrix of  $T$   $M(T) = [T]_{B \leftarrow A}$

example:  $V = [\mathbb{R}]_{\leq 3}$ , basis  $B = (1, x, x^2, x^3)$

$T: V \rightarrow V$  (differentiation)

find  $[T]_B = [T]_{B \leftarrow B}$

$$[T]_B = \left[ [T(1)]_B, [T(x)]_B, [T(x^2)]_B, [T(x^3)]_B \right]^{4 \times 4}$$

$$T(1) = 0$$

$$T(x) = 1$$

$$T(x^2) = 2x$$

$$T(x^3) = 3x^2$$

$$= \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

In general ( $A, B$  as above)

$$[T]_{B \leftarrow A} = \left[ [T(\vec{v}_1)]_B, \dots, [T(\vec{v}_n)]_B \right]^{m \times n \text{ matrix over } \mathbb{F}}$$

## Key Properties

$$\textcircled{1} [T(\vec{v})]_B = [T]_{B \leftarrow A} [\vec{v}]_A$$

$T: V \rightarrow W$   
 $\textcircled{2}$  If also  $S: W \rightarrow U$ ,  $C = (u_1, \dots, u_p)$  basis of  $U$

$$ST: V \rightarrow U$$

$$[ST]_{C \leftarrow A} = [S]_{C \leftarrow B} [T]_{B \leftarrow A}$$

(d) Invertible  $T$ , inverse  $T^{-1}$ , isomorphism

- $T: V \rightarrow W$  is invertible if  $\exists$  LT  $S: W \rightarrow V$  s.t.

$$TS = I_W, ST = I_V$$

- If  $T$  is invertible,  $S$  is unique, with  $S = T^{-1}$

- $T$  is an isomorphism if  $T$  is invertible

## Key Facts

- $T$  invertible  $\Leftrightarrow \begin{matrix} T \text{ is injective} \\ T \text{ is surjective} \end{matrix} \Rightarrow T \text{ is bijective}$

$$\Leftrightarrow \begin{matrix} \ker T = 0 \\ \text{and } \text{im } T = W \end{matrix}$$

- If  $V, W$  are both finite dimensional, then

$$I^f \dim V = \dim W \Leftrightarrow V \overset{\text{isomorphic}}{\cong} W$$

• If  $\dim V = n < \infty$

then  $T: V \rightarrow V$  is an isomorphism  $\Leftrightarrow T$  is injective

$\Leftrightarrow T$  is surjective

$\Leftrightarrow \exists S: V \rightarrow V^{(LT)} \text{ s.t. } TS = I_V$

$\Leftrightarrow S: V \rightarrow V^{(LT)} \text{ s.t. } ST = I_V$