Problem 4 mus

W 1:30-3:36

T 3-5

Th 1:36 - 3:30

(a), (b) -you should NOT need finite dimensional

(c), (d) - Let V be finite dimensional SiTe I(V)

Dual Vector Spaces

Recall: (1) a LT P: V->IF is called a linear function on V

example

V= Co(R) choose nET, NTO

Define  $Y_n: V \to IR$  by  $Y_n(f) = \int_{1}^{2\pi} f(x) \cos(n\pi x) dx$ 

3 v\* = L(V, IF) dual vector space to V

Proposition

If dim V=n

then dim V\* = n = dim V

V, V\* isomorphic ble same dimension

Proof

Krow dim L(V, W)= (dim V)(dim W)

:. L(V,F) has dim= (dim V)(dim IF) = dim V

Basis of V\*

Suppose  $a = (V_1, ..., V_n)$  is a basis of V.

To give a  $P: V \rightarrow F$  LT, it suffices to give a numbers  $a_1, ..., a_n \in F$  then  $\exists ! P: V \rightarrow F$  s.t.  $P(V_i) = q_i \forall V$ 

Let's get some elements of v\*

let 152n

tefine 9:17

v; H

v; H

v; H

$$\varphi_i(a_i v_i + \cdots + a_n v_n)$$

$$= a_i \varphi(\vec{v}_i) = a_i$$

We have P, ..., In EV\* as just defined

Is P,.... In a basis for V\*?

"easy" lemma: Suppose qev\*, then (4:U7IF)  $P = \sum_{i=1}^{n} \varphi(v_i) \, \psi_i \in V^*$ 

Proof: To show LHS (Q) = RHS it suffices to show that for each 
$$\vec{v}_{j}$$
 |  $(\vec{v}_{j}) = RHS(\vec{v}_{j}) = RHS(\vec{v}_{j})$ 

$$Q(\vec{v}_{j}) = \sum_{i=1}^{n} [Q(\vec{v}_{i}) \ Q(\vec{v}_{i})] = \begin{cases} 1 \cdot Q(\vec{v}_{j}), & j=j \\ 0, & j \neq j \end{cases}$$

$$= \sum_{i=1}^{n} Q(\vec{v}_{i}) \ Q(\vec{v}_{i}) = \begin{cases} 1 \cdot Q(\vec{v}_{j}), & j=j \\ 0, & j \neq j \end{cases}$$

Proposition: let  $a^* = (\ell_1, ..., \ell_n)$ Then  $a^*$  is a basis of  $V^*$  (assuming a is a basis of V)

One way: Prove l, ..., In is LI, than since it has same number of elements as dimension it must span

Another: Have already shown (P.,..., In) spans V\* since n=din V\*
it is also LI

Third: Show Ping In LI Show Ping In Spans V\*

Proof)  $a_1 P_1 + a_2 P_2 + \cdots + a_n P_n = 0$  as functions  $v \to V$ Show  $a_1 = a_2 - \cdots = a_n = 0$ 

Appry  $a_1 l_1 + a_2 l_2 + \dots + a_n l_n$  to  $\vec{v}_i$   $a_1 l_1 (\vec{v}_i) + \dots + a_n l_n (\vec{v}_i) = 0$   $a_1 l_2 l_3 l_4 l_5$ 

example: V=R2, V\*=(R2)\* ~1R2 isomorphic to

Definition: Let  $T: V \to W$  be a LT. Define the <u>transpose</u> of T  $T^{t}: W \to V^{*}$   $f \mapsto T^{t}(f)$   $V \xrightarrow{g} Uf$ 

T + (f) = g = fT

Basic Shopping List of Facts  $0.7^{t}$  is a linear transformation  $0.(TS)^{t}(f) = St.T^{t}$ 

7: N→ N 2: N→ N