

Recall that a **function**  $f$  is a rule that assigns to each element in a set  $A$  one **and only one** element in a set  $B$ . If  $f$  assigns the value  $b$  to the element  $a$  in  $A$ , we write

$$b = f(a)$$

and call  $b$  the **image** of  $a$  under  $f$ .

The set  $A$  is the **domain of definition** of  $f$  (even if  $A$  is not a domain in the sense of chapter 1), and the set of all images  $f(a)$  is the **range** of  $f$ .

We sometimes refer to  $f$  as a **mapping** of  $A$  into  $B$ .

We will concern ourselves with **complex-valued functions of a complex variable**, so that the **domains of definition** and the **ranges** are **subsets of the complex numbers**.

So let

$$f(z) = \frac{z^2 - 1}{z^2 + 1}$$

then, unless stated otherwise, we take the domain of  $f$  to be the set of all  $z$  for which the formula is well-defined.

If  $w$  denotes the value of the function  $f$  at the point  $z$ , we then write

$$w = f(z).$$

Just as  $z$  decomposes into

$$z = x + iy \quad (\text{real + imaginary part})$$

the real + imaginary parts of  $w$  are each (real-valued) functions of  $z$  or, equivalently, of  $x$  and  $y$ , and so we customarily write

$$w = u(x, y) + i v(x, y)$$

with  $u, v$  denoting the real + imaginary parts, respectively, of  $w$ .

Thus a complex-valued function of a complex variable is, in essence, a pair of real functions of two variables.

**Example 1:** Write  $w = f(z) = z^2 + 2z$  in the form  $w = u(x, y) + i v(x, y)$

Setting  $z = x + iy$ ,

$$w = f(z) = (x + iy)^2 + 2(x + iy)$$

$$w = x^2 - y^2 + i2xy + 2x + i2y$$

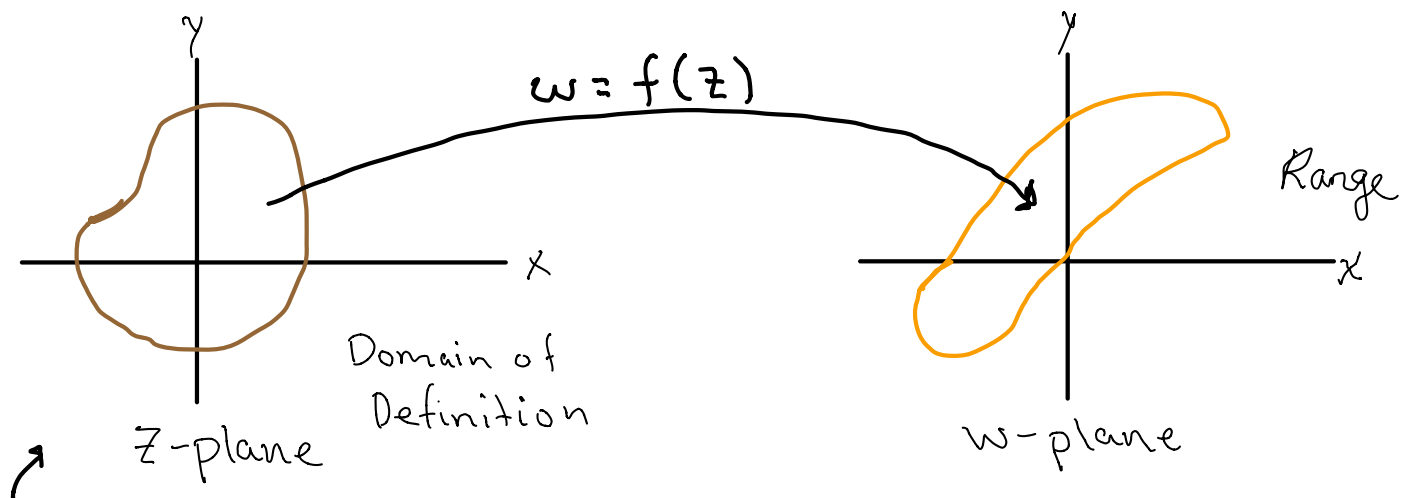
$$w = (x^2 - y^2 + 2x) + i(2xy + 2y)$$

Unfortunately, it is generally impossible to draw the graph of a complex function; to display two real functions of two real variables graphically would require four dimensions.

We can visualize some of the properties of a complex function

$$w = f(z)$$

by sketching its domain of definition in the  $z$ -plane and its range in the  $w$ -plane.



Representation of a complex function

**Example 2:** Describe the range of the function  $f(z) = z^2 + 2i$  defined on the closed unit disk  $|z| \leq 1$

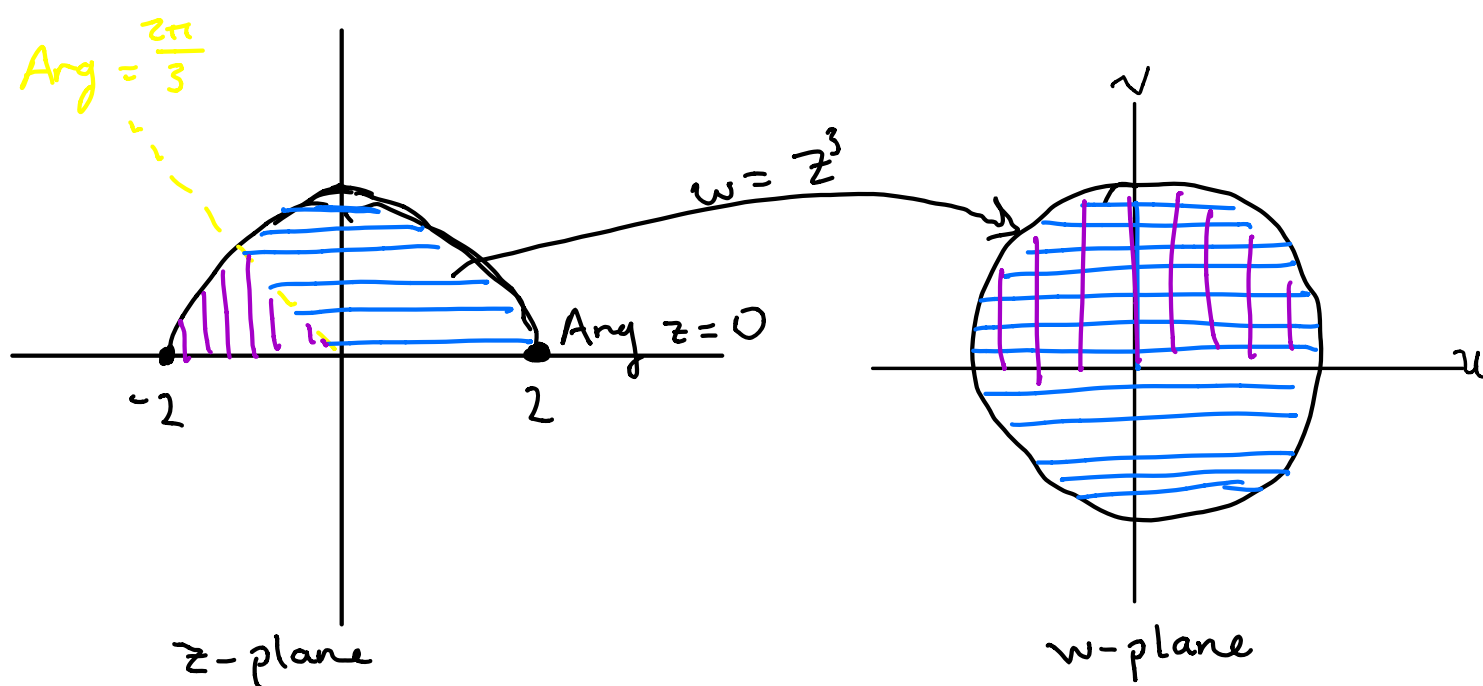
We have

$$u(x, y) = x^2 \quad v(x, y) = 2$$

Thus as  $z$  varies over the closed unit disk,  $u$  varies between 0 and 1, and  $v$  is constant.

The range is therefore the line segment from  $w = 0 + 2i$  to  $w = 1 + 2i$

**Example 3:** Describe the function  $f(z) = z^3$  for  $z$  in the semidisk given by  $|z| \leq 2$ ,  $\text{Im } z \geq 0$  (figure below)



The points  $z$  in the sector of the semidisk from  $\text{Arg } z = 0$  to  $\text{Arg } z = \frac{2\pi}{3}$ , when cubed, cover the entire disk  $|w| \leq 8$ . The cubes of the remaining  $z$ -points also fall on this disk, overlapping it in the upper half. Depicted above.

The function  $f(z) = 1/z$  is called the inversion mapping.

It is an example of a one-to-one function because it maps distinct points to distinct points.

i.e. if  $z_1 \neq z_2$ ,  $f(z_1) \neq f(z_2)$

**Example 4:** Show that the inversion mapping  $w = 1/z$  corresponds to a rotation of the Riemann sphere by  $180^\circ$  about the  $x_1$ -axis.

Let  $Z = (x_1, x_2, x_3)$  denote the stereographic projection of the point  $z$

Let  $W = (\hat{x}_1, \hat{x}_2, \hat{x}_3)$  denote the stereographic projection of  $1/z$

$$x_1 = \frac{2 \operatorname{Re}(z)}{|z|^2 + 1}, \quad x_2 = \frac{2 \operatorname{Im}(z)}{|z|^2 + 1}, \quad x_3 = \frac{|z|^2 - 1}{|z|^2 + 1}$$

$$\hat{x}_1 = \frac{2 \operatorname{Re}(1/z)}{|1/z|^2 + 1}, \quad \hat{x}_2 = \frac{2 \operatorname{Im}(1/z)}{|1/z|^2 + 1}, \quad \hat{x}_3 = \frac{|1/z|^2 - 1}{|1/z|^2 + 1}$$

Using  $\operatorname{Re}(1/z) = \operatorname{Re}(z)/|z|^2$   
 $\operatorname{Im}(1/z) = -\operatorname{Im}(z)/|z|^2$

We get after simplification that

$$\hat{x}_1 = \frac{2 \operatorname{Re}(z)}{1 + |z|^2}, \quad \hat{x}_2 = \frac{-2 \operatorname{Im}(z)}{1 + |z|^2}, \quad \hat{x}_3 = \frac{1 - |z|^2}{1 + |z|^2}$$

$$\hat{x}_1 = x_1, \quad \hat{x}_2 = -x_2, \quad \hat{x}_3 = -x_3$$

A rotation about  $x_1$ -axis preserves  $x_1$  and negates  $x_2, x_3$ ; so indeed  $W$  is the stated rotation of  $Z$ .

A consequence of this example is the fact that an inversion mapping preserves the class of circles and lines  
(Prob 17)