

## Recall

Started conditional stuff for continuous rvs.

Given continuous rv  $X$ , event  $A$ , conditional pdf of  $X$  given  $A$  is defined as the function  $f_{X|A}(x)$  satisfying

$$P(X \in J | A) = \int_J f_{X|A}(x) dx \quad \forall J \subset \mathbb{R}$$

Special Case: If  $A$  is an event of the form  $\{X \in W\}$  for some  $W \subset \mathbb{R}$ ,

$$f_{X|A}(x) = \begin{cases} \frac{f_X(x)}{P(\{X \in W\})}, & x \in W \\ 0, & x \notin W \end{cases}$$

## Example - "Light Bulb"

Suppose  $T$  is exponential( $\lambda$ ) rv

$$f_T(t) = \begin{cases} \lambda e^{-\lambda t}, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

Pick  $t_0 > 0$ ; let

$$\begin{aligned} X &= T - t_0, \\ A &= \{T > t_0\}; \end{aligned}$$

find  $f_{X|A}(x)$ .

Note:  $A = \{T > t_0\} = \{X > 0\}$ !

Hence,

$$f_{X|A}(x) = \begin{cases} \frac{f_x(x)}{P(\{T > t_0\})}, & x > 0 \\ 0, & x \leq 0 \end{cases}$$

where

$$P(\{T > t_0\}) = \int_{t_0}^{\infty} f_T(t) dt = e^{-\lambda t_0}$$

and

$$f_x(x) = \begin{cases} \lambda e^{-\lambda(t_0+x)}, & x > -t_0 \\ 0, & x \leq -t_0 \end{cases}$$

How'd we get this? First find  $F_X(x)$ .

$$\begin{aligned} F_X(x) &= P(X \leq x) = P(\{T \leq t_0 + x\}) \\ &= \int_{-\infty}^{t_0+x} f_T(t) dt \end{aligned}$$

Now take  $\frac{d}{dx}$

$$f_X(x) = \frac{d}{dx} \left( \int_{-\infty}^{t_0+x} f_T(t) dt \right) = f_T(t_0+x)$$

where

$$f_T(t_0+x) = \begin{cases} \lambda e^{-\lambda(t_0+x)}, & x > -t_0 \\ 0, & x \leq -t_0 \end{cases}$$

Therefore,

$$f_{X|A}(x) = \begin{cases} \frac{\lambda e^{-\lambda(t_0+x)}}{e^{-\lambda t_0}} & , x \geq 0 \\ 0 & , x < 0 \end{cases} = \begin{cases} \lambda e^{-\lambda x} & , x \geq 0 \\ 0 & , x < 0 \end{cases}$$

In light-bulb terms, "find bulb still on at time  $t_0$ , remaining bulb lifetime is still exponential ( $x$ ), as 'brand-new' lifetime"



This is the "resetting"/"regeneration" property of exponential pdfs - similar to geometric "resetting" in discrete world

**Total Probability Theorem** in context of  $f_{X|A}$ :

If  $X$  is a continuous rv and  $A_1, \dots, A_n$  are events of positive probability that partition  $\Omega$ , then

$$f_X(x) = \sum_{k=1}^n f_{X|A_k}(x) P(A_k)$$

To see this: go via cdfs.

$$F_{X|A_k} = \frac{P(\{X \leq x\} \cap A_k)}{P(A_k)}$$

$$\frac{d}{dx} F_{X|A_k} = f_{X|A_k}(x)$$

By Total Probability Theorem,

$$F_x(x) = P(\{X \leq x\}) = \sum_{k=1}^n F_{x|A_k} P(A_k) \xrightarrow{\frac{d}{dx}} \sum_{k=1}^n f_{x|A_k} P(A_k) = f_x(x)$$

Comment: this holds when  $A_k$  aren't of the special form  $\{X \in W_k\}$ !

### Example - Walking To Class

Before leaving for campus, spin wheel; w/ prob  $2/3$  I walk via the gorge,  $1/3$  via collegetown.

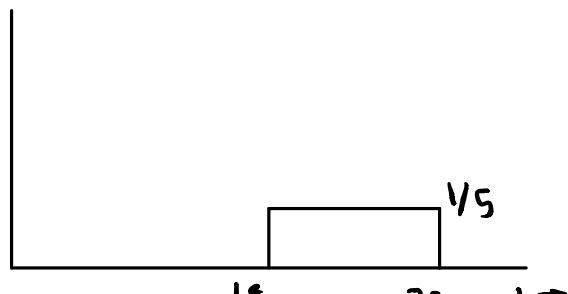
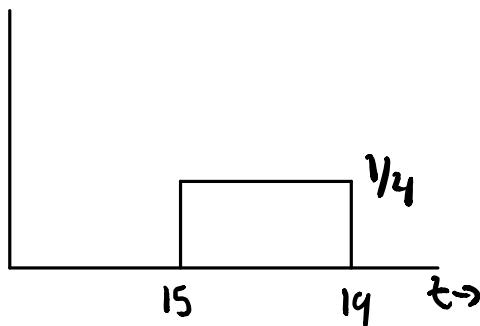
- Walking via gorge, travel time uniform on  $[15, 19]$  minutes
- Walking via ctown, travel time uniform on  $[18, 23]$  minutes

Let  $X$  = travel time.

$f_x(x)$ ?

Let  $A = \text{walk via gorge} \Rightarrow A^c = \text{walk via ctown}$

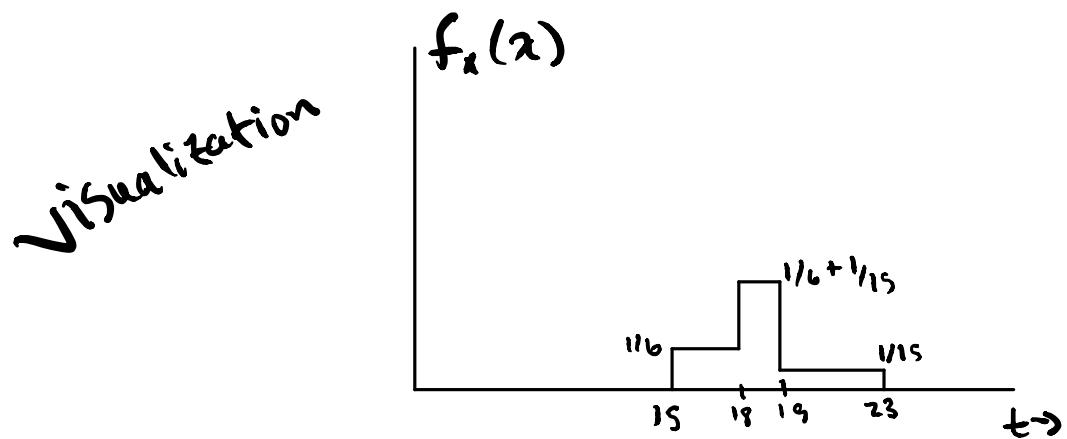
$f_{x|A}(x)$



Thus

$$f_X(x) = f_{X|A}(x) \cdot \left(\frac{2}{3}\right) + f_{X|A^c}(x) \cdot \left(\frac{1}{3}\right)$$

$$f_X(x) = \begin{cases} 0 & , x < 15 \\ \frac{1}{6} & , 15 \leq x < 18 \\ \frac{1}{6} + \frac{1}{15} & , 18 \leq x < 19 \\ \frac{1}{15} & , 19 \leq x < 23 \\ 0 & , x > 23 \end{cases}$$



Next, discuss conditional pdf of a continuous rv  $X$  given  $Y=y$  for some other continuous rv  $Y$

Naive approach: Let  $A = \{Y=y\}$ . But  $Y$  is continuous!  
So  $P(\{Y=y\})=0 \Rightarrow$  it is NOT a suitable  $A$  for  $f_{X|A}(x)$

Instead we proceed as follows:

- 1) Given  $V$ , look at  $P(\{X \in V\} | \{Y \in [y-\delta, y+\delta]\})$
- 2) Take  $\lim \delta \rightarrow 0$
- 3) Find that it equals

$$\int_V (\quad) dx \quad \text{this is our goal}$$

$$P(\{X \in V\} | \{Y \in [y-\delta, y+\delta]\}) = \frac{P(\{X \in V\} \cap \{Y \in [y-\delta, y+\delta]\})}{P(\{Y \in [y-\delta, y+\delta]\})}$$

$$= \frac{\int_V dx \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t)}{\int_V f_y(t) dt} = \frac{\int_V dx \left( \frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t) \right)}{\left( \frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_y(t) \right)}$$

Multiply by  $1 = \frac{1/2\delta}{1/2\delta}$

$$\frac{\int_V dx \left( \frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_{x,y}(x,t) \right)}{\left( \frac{1}{2\delta} \int_{y-\delta}^{y+\delta} dt f_y(t) \right)} \xrightarrow{\lim \delta \rightarrow 0} \frac{\int_V f_{x,y}(x,y) dx}{f_y(y)}$$

$$\frac{\int_V f_{x,y}(x,y) dx}{f_y(y)} = \int_V \left( \frac{f_{x,y}(x,y)}{f_y(y)} \right) dx$$

Bottom line: conditional pdf of  $X$  given  $Y=y$  is

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

What you integrate over  
for any  $x \in \mathcal{X}$  to get  
 $P(\{X \in \mathcal{X}\} | Y=y)$

Note: for fixed  $y$ , this as a function of  $x$  is a legit pdf

$$\int_{-\infty}^{+\infty} f_{X|Y}(x|y) dx = \int_{-\infty}^{+\infty} \frac{f_{X,Y}(x,y)}{f_Y(y)} dx = \frac{1}{f_Y(y)} \int_{-\infty}^{+\infty} f_{X,Y}(x,y) dx = \frac{f_Y(y)}{f_Y(y)} = 1 \checkmark$$

As for conditional pmfs in discrete-world, can use conditional pdfs to compute joints, marginals, etc, in situations most naturally expressed in conditional terms.

e.g.

$$f_{X,Y}(x,y) = f_{X|Y}(x|y) f_Y(y)$$

Integrate over  $x$  or  $y$  to get

$$f_X(x) = \int_{-\infty}^{+\infty} f_{X|Y}(x|y) dy \quad \text{OR} \quad f_Y(y) = \int_{-\infty}^{+\infty} f_{Y|X}(y|x) f_X(x) dx$$

This generalizes "obviously" to  $> 2$  rvs.

"What mathematicians say when they know something that isn't entirely obvious to anybody else"  
- Some kid in a math class

- Rami Pellumbi

Take  $X, Y, Z$  for example.

$$f_{x,y,z}(x,y,z) = \frac{f_{x,y,z}(x,y,z)}{f_z(z)} \quad \text{OR} \quad f_{x|y,z}(x|y,z) = \frac{f_{x,y,z}(x,y,z)}{f_{y,z}(y,z)}$$

etc., etc., etc

And we have chain rules such as

Need not memorize

$$f_x(x) = f_{x|y,z}(x|y,z) f_{y,z}(y,z)$$

### Example - Radar Gun

Speed of passenger vehicle  $- X$  - exponential w/  $\lambda = 50$ .

$Y$  = radar gun measurement of  $X$ , given  $X=x$ , is Gaussian; mean  $x$ , variance  $\sigma^2 = x/10$

$$f_x(x) = \begin{cases} 50e^{-50x}, & x > 0 \\ 0, & x < 0 \end{cases}$$

$$f_{y|x}(y|x) = \frac{1}{\sqrt{2\pi(\frac{x^2}{100})}} e^{-\frac{(y-x)^2}{(x^2/50)}}$$

Hence  $f_{x,y}(x,y) = f_{y|x}(y|x) f_{x|x}(x)$  and  $f_y(y) = \int_{-\infty}^{+\infty} (\quad) dx$

One loose end:

Expected value rule for joints.

$$\mathbb{E}(g(x,y)) = \int_{-\infty}^{+\infty} dx \int_{-\infty}^{+\infty} dy g(x,y) f_{x,y}(x,y)$$