

## Recall

Bayes rule stuff involving continuous rvs.

### Example - Bit Through Noisy Channel

Consider :  $\tilde{S} = \pm 1$ ;  $P(\{\tilde{S}=1\}) = p$ ,  $p \in (0, 1)$

- $N$  Gaussian, 0 mean, variance  $\sigma^2$
- $Y = S + N$      $S \rightarrow$  Noisy Channel  $\rightarrow Y$

Want :  $P(S=1 | Y=y)$

Have a grip on:  $P(S=1)$ ,  $P(S=-1)$ ,  $f_{Y|S}(y|1)$ ,  $f_{Y|S}(y|-1)$

$f_{Y|S}(y|1)$  = Gaussian, mean 1, var  $\sigma^2$

$f_{Y|S}(y|-1)$  = Gaussian, mean -1, var  $\sigma^2$

By Baye's Rule:

$$\begin{aligned}
 P(S=1 | Y=y) &= \frac{f_{Y|S}(y|1) P(\{\tilde{S}=1\})}{f_{Y|S}(y|1) P(\{\tilde{S}=1\}) + f_{Y|S}(y|-1) P(\{\tilde{S}=-1\})} \\
 &= \frac{P \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y-1)^2}{2\sigma^2}\right)}{P \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y-1)^2}{2\sigma^2}\right) + (1-p) \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y+1)^2}{2\sigma^2}\right)} \\
 &= \frac{pe^y}{pe^y + (1-p)e^{-y}} \quad \left. \begin{array}{l} \text{y} \rightarrow \infty \rightarrow 1 \\ \text{y} \rightarrow -\infty \rightarrow 0 \end{array} \right\}
 \end{aligned}$$

This example is inferring about a discrete event from a continuous observation.

The reverse situation also arises. Observe some event A; infer about conditional rv Y - specifically  $f_{Y|A}(y)$  - know  $f_Y(y)$  and  $P(A|Y=y)$ ,  $P(A^c|Y=y)$ .

Flip Baye's Rule.

$$P(A|Y=y) = \frac{f_{Y|A}(y) P(A)}{f_Y(y)} \rightarrow f_{Y|A}(y) = \frac{P(A|Y=y) f_Y(y)}{P(A)}$$

Rewriting  $P(A)$  using Total Probability Theorem yields

$$f_{Y|A}(y) = \frac{P(A|Y=y) f_Y(y)}{\int_{-\infty}^{+\infty} P(A|Y=y) f_Y(y) dy}$$

NEXT TOPIC

### Derived Distributions

Setup: X continuous rv; pdf  $f_X(x)$ ;  $Y=g(X)$ ; want  $f_Y(y)$ .

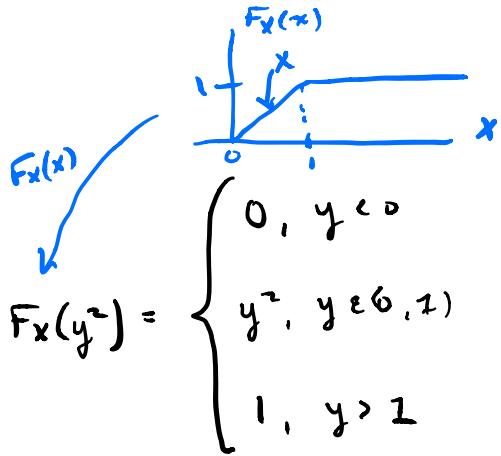
NOT easy in general - look at some special situations where it is.

In these situations, get  $f_Y(y)$  via

- find  $F_Y(y)$
- $f_Y(y) = dF_Y(y)/dy$

## Example

$X$  uniform on  $[0,1]$ .  $Y = g(X) = \sqrt{X}$ .



Thus

$$f_Y(y) = \frac{d}{dy} F_Y(y) = \begin{cases} 2y, & y \in [0,1] \\ 0, & \text{else} \end{cases}$$

## Example

$X$  has pdf  $f_X(x)$ , cdf  $F_X(x)$ ;  $Y = X^2$ .

$$F_Y(y) = P(Y \leq y) = P(X^2 \leq y) = \begin{cases} 0, & y < 0 \\ P(-\sqrt{y} \leq X \leq \sqrt{y}), & y \geq 0 \end{cases} = \begin{cases} 0, & y < 0 \\ F_X(\sqrt{y}) - F_X(-\sqrt{y}), & y \geq 0 \end{cases}$$

$$f_Y(y) = \frac{dF_Y(y)}{dy} = \begin{cases} 0, & y < 0 \\ \frac{1}{2\sqrt{y}} f_X(\sqrt{y}) + \frac{1}{2\sqrt{y}} f_X(-\sqrt{y}), & y \geq 0 \end{cases}$$

## Example - More General

$X$  has  $f_X(x)$ ,  $F_X(x)$ ;  $Y = \alpha X + b$ ,  $\alpha \neq 0$

$$F_Y(y) = P(\alpha X + b \leq y) = \begin{cases} P\left(X \leq \frac{y-b}{\alpha}\right), & \alpha > 0 \\ P\left(X \geq \frac{y-b}{\alpha}\right), & \alpha < 0 \end{cases}$$

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Thus when  $\alpha > 0$ ,

$$F_Y(y) = F_X\left(\frac{y-b}{\alpha}\right) \Rightarrow f_Y(y) = \frac{1}{\alpha} f_X\left(\frac{y-b}{\alpha}\right)$$

and when  $\alpha < 0$

$$F_Y(y) = 1 - F_X\left(\frac{y-b}{\alpha}\right) \Rightarrow f_Y(y) = -\frac{1}{\alpha} f_X\left(\frac{y-b}{\alpha}\right)$$

### Examples - Affine Situation

①  $X$  is exponential( $\lambda$ );  $Y = \alpha X + \beta$ .

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & x \geq 0 \\ 0, & x < 0 \end{cases} \rightarrow f_Y(y) = \frac{1}{|\alpha|} f_X\left(\frac{y-\beta}{\alpha}\right) = \begin{cases} \frac{\lambda}{|\alpha|} e^{-\lambda\left(\frac{y-\beta}{\alpha}\right)}, & \frac{y-\beta}{\alpha} \geq 0 \\ 0, & \frac{y-\beta}{\alpha} < 0 \end{cases}$$

Note: when  $\beta=0$ , and  $\alpha > 0$ ,  $Y$  is also exponential w/ rate parameter  $\lambda/\alpha$

②  $X$  is Gaussian  $\mu, \sigma^2$ ,  $Y = \alpha X + \beta$ .

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \rightarrow f_Y(y) = \frac{1}{\alpha\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\alpha\mu-\beta)^2}{2\alpha^2\sigma^2}}$$

$\frac{1}{\alpha} = \frac{1}{\sqrt{\alpha^2}}$  !

Note:  $Y$  also Gaussian! mean =  $\alpha\mu+\beta$ . Variance =  $\underline{\alpha^2\sigma^2}$

Comment:  $E(Y) = \alpha\mu+\beta$ ,  $Var(Y) = \alpha^2\sigma^2$ , but until we do the calculation, NOT obvious that  $Y$  is also Gaussian

All these examples have something in common!  $g$  is strictly monotonic and differentiable

Here's a careful-ish statement of a general result of which all examples so far are special cases.

- $X$  is a continuous rv whose density  $f_X(x)$  is concentrated on a single interval  $a < x < b$ .  $a = -\infty$  and/or  $b = +\infty$  allowed.
- $Y = g(X)$ ,  $g$  strictly monotonic and differentiable, implying that  $f_Y(y)$  is concentrated on  $(g(a), g(b))$   <sup>$g$  increasing</sup> or  $(g(b), g(a))$   <sup>$g$  decreasing</sup>
- Let  $h$  be the inverse function of  $g$  - defined only on  $(g(a), g(b))$  or  $(g(b), g(a))$  —  $h$  is also strictly monotonic and differentiable on its domain of definition

Then

$$f_Y(y) = \begin{cases} \left| \frac{dh(y)}{dy} \right| f_X(h(y)) & , \text{ increasing} \\ 0 & , \text{ decreasing} \end{cases}, \quad y \in (g(a), g(b)) \text{ OR } y \in (g(b), g(a))$$

Example -

$X$  has pdf  $f_X(x)$ ;  $Y = e^{3x}$

$$(a, b) = (-\infty, \infty)$$

$$(g(a), g(b)) = (0, \infty)$$

$$h(y) = \frac{1}{3} \ln(y) \text{ on } (0, \infty)$$

$$\Rightarrow f_Y(y) = \begin{cases} \frac{1}{3y} f_X(h(y)) & , y > 0 \\ 0 & , y \leq 0 \end{cases}$$

$f_X(\frac{1}{3} \ln(y))$

Example -  $g$  strictly decreasing

- Drive from NYC to Boston ( $\approx 180$  miles) at constant speed  $X$ .
- $X$  uniform on  $[30, 60] = [a, b]$
- $Y = \text{travel time in hours} = \frac{180}{X} = g(X)$

$(g(a), g(b)) = (6, 3) \rightarrow f_Y(y) \text{ concentrated on } 3 \leq y \leq 6$

$$h(y) = \frac{180}{y} \xrightarrow{\text{d/dy}} -\frac{180}{y^2}$$

$$f_Y(y) = \begin{cases} \frac{180}{y^2} f_X\left(\frac{180}{y}\right), & y \in [3, 6] \\ 0, & y \notin [3, 6] \end{cases}$$