

# Lab 13: Trees

## 1.1 Information

Topics: Trees

Turn in: This is another on-paper "lab". Turn in a text file, PDF file, scanned or photographed images.

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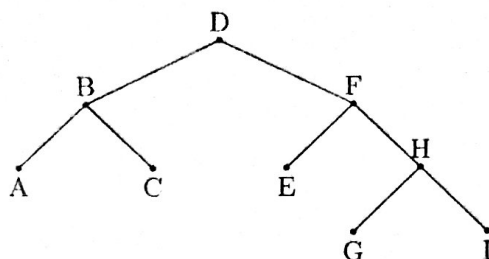
## 1.2 About: Efficiency

Every data structure has trade-offs. For example, it is faster to access items at some position in an array than it is to do so in a linked list. However, if the array is unsorted, there is not a good efficient way to search the array to find some specific data. If we were to build a sorted array, we would have to decide *when* to do the sorting...

- During Insert - Locate the proper place for the new data
- After Insert - Insert to the end, then re-sort the array

Either way, the act of inserting data into the array will slow down the process, since we would need to either shift  $n$  items over to make room for the new item, or perform a sorting algorithm; neither way is as efficient as simply putting data in the array at the end, but it might make *access time* more efficient.

When selecting a data structure to use, part of what we need to consider is what we're designing and how the data structure will be used - will we do a lot of inserts? Will we do a lot of accesses? If we're inserting data often but not reading that data very much, a structure like a Linked List or Unsorted Array might be fine, with  $O(1)$  time for the "push" function. If we don't do insertions very often, but need to read the data frequently, it would be better to keep our data sorted.



Smaller  $\longleftrightarrow$  Larger

Trees, especially Binary Search Trees (which we will talk about on its own), are a type of structure where we can make a compromise. Specifically for a **Binary Search Tree**, insert and access are both  $O(\log n)$  on average, because as we traverse through the tree, each step we're removing *half* of the search space.

We will return to Binary Search Trees later, but for now let's go over the terminology associated with Trees.

### 1.3 Intro to Trees

**Tree:** A collection of **Nodes** (or **vertices**) and **Edges**.

**Edge:** A path that connects two Nodes together. If we have  $N$  nodes, then there are  $N - 1$  edges.

**Nodes:** A vertex in the tree, usually associated with some data.

**Root Node:** The source Node of the tree; it has no parents. Each Tree has one Root Node, usually drawn at the top. All other Nodes descend from the Root Node.

**Leaf Node:** A Node with no children.

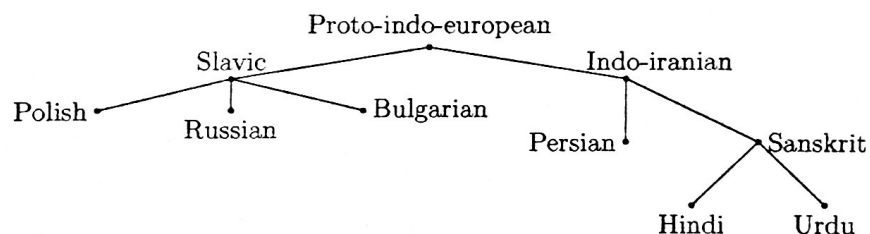
**Node Family:** We use family terminology to talk about how Nodes are related to each other.

- **Parent node:** Given some Node  $n$ ,  $n$ 's parent is the Node immediately above  $n$ , in the path between  $n$  and the root node. Each Node can have only 0 or 1 parent.
- **Ancestor node:** Given some Node  $n$ , an Ancestor of  $n$  is any Node along the path from  $n$  to the root node.
- **Child node:** Given some Node  $n$ ,  $n$ 's child is a Node that comes immediately below it in the tree. Node  $n$  lies in the path from its child to the root node. Each Node can have 0 or more children. With a Binary Search Tree, a Node can have 0, 1, or 2 children.
- **Descendant node:** Given some Node  $n$ , a Descendant is a Node that comes below it in the tree, where the Node  $n$  lies in the path from that descendant to the root node.
- **Sibling node:** Given some Node  $n$ , a Sibling of  $n$  is another Node where  $n$  and that Sibling share the same Parent node.

## Question 1

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For the given tree:



- a. What are all the (listed) ancestors of *Russian*?

Slavic - Proto-Indo-European

- b. What are all the (listed) descendants of *Indo-iranian*?

Sanskrit - Hindi - Urdu

- c. What are all the (listed) siblings of *Polish*?

Slavic - Indo-Iranian - Polish

- d. What are all the (listed) leaves of the tree?

Polish - Russian - Bulgarian - Persian - Hindi - Urdu

**Path:** A path between two nodes,  $n_a$  and  $n_b$ , is a series of connecting edges between these two nodes.

**Path Length:** The Length of a Path is the amount of edges in the path.

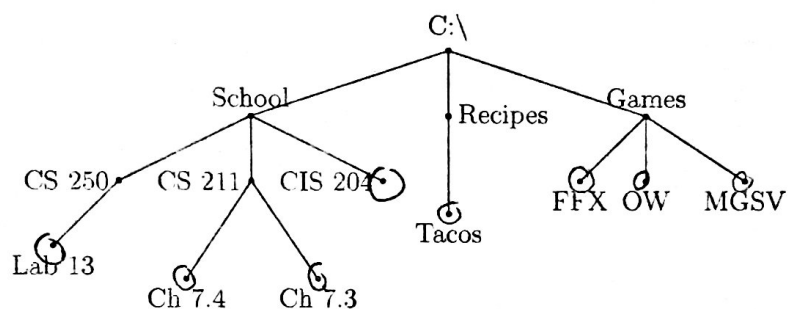
**Node Depth:** Given any node  $n$ , the Depth of  $n$  is the *length* of the path between  $n$  and the root.

**Node Height:** Given any node  $n$ , the Height of  $n$  is the longest path from  $n$  to a leaf. Leaves have a height of 0.

## Question 2

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For the given tree:



- a. Write out all the Nodes in the path from *Lab 13* to *C:\*.

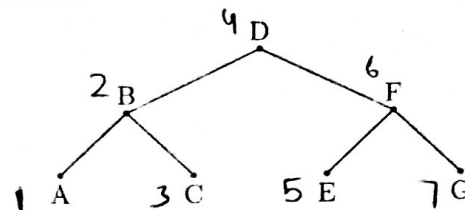
CS 250 - School - C:\

- b. What is the length of the path from *Lab 13* to *C:\*? 3

- c. Find the Depths and Heights for the following:

Node	Depth	Height
Lab 13	<u>3</u>	<u>0</u>
Ch 7.3	<u>3</u>	<u>0</u>
Tacos	<u>2</u>	<u>0</u>
MGSV	<u>2</u>	<u>0</u>
CS 211	<u>2</u>	<u>1</u>
School	<u>1</u>	<u>2</u>

### 1.3.1 Traversals



Since a Tree is not a linear structure, what order do you display its contents? There are three main methods you will see for traversing through a tree. Each of these are recursive, beginning at the root node. Once the end of a path is reached (by hitting a leaf), the recursion causes it to step back upwards through the tree.

**Pre-order traversal** Begin at the Root  $r$  node of some Tree/Subtree...

1. Process  $r$
2. Traverse left, if available
3. Traverse right, if available

With the above tree, we process nodes as such:

D - B - A - C - F - E - G  
4 2 1 3 6 5 7

**In-order traversal** Begin at the Root  $r$  node of some Tree/Subtree...

1. Traverse left, if available
2. Process  $r$
3. Traverse right, if available

With the above tree, we process nodes as such:

A - B - C - D - E - F - G  
1 2 3 4 5 6 7

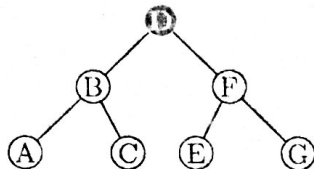
**Post-order traversal** Begin at the Root  $r$  node of some Tree/Subtree...

1. Traverse left, if available
2. Traverse right, if available
3. Process  $r$

With the above tree, we process nodes as such:

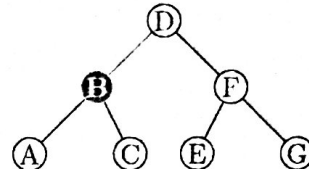
A - C - B - E - G - F - D  
1 3 2 5 7 6 4

## Step-by-step pre-order illustration:



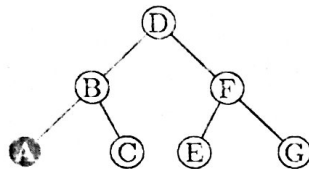
1. Begin at D. Process "D" then go left.

Output: D



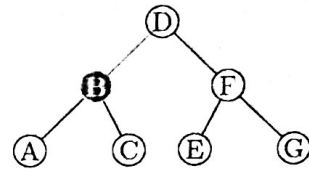
2. Process "B" then go left.

Output: D B



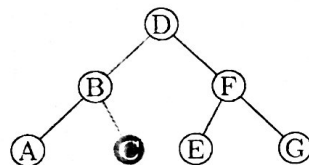
3. Process "A"; no more children, return (back to B).

Output: D B A



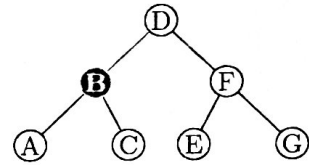
4. Go to right child.

Output: D B A



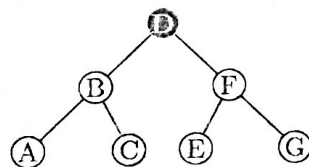
5. Process "C"; no more children, return (back to B).

Output: D B A C



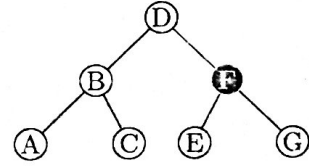
6. Done with left and right subtrees, return (back to D).

Output: D B A C



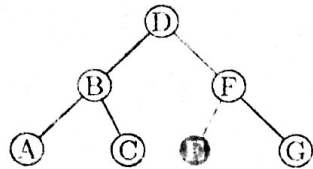
5. Go to right child.

Output: D B A C



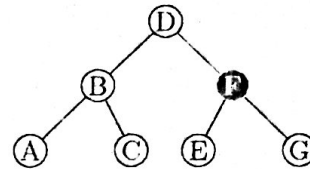
6. Process "F" then go left.

Output: D B A C F



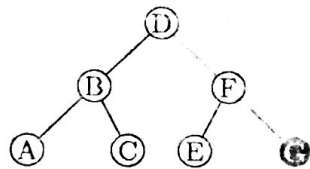
7. Process "E" then return (back to F).

Output: D B A C F E



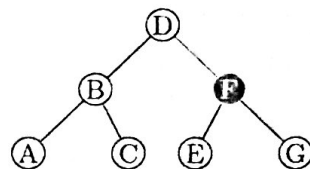
8. Go to right child.

Output: D B A C F E



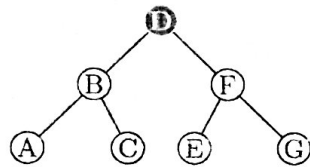
9. Process "G" then return (to F).

Output: D B A C F E G



10. Return (to D).

Output: D B A C F E G



11. Finished.

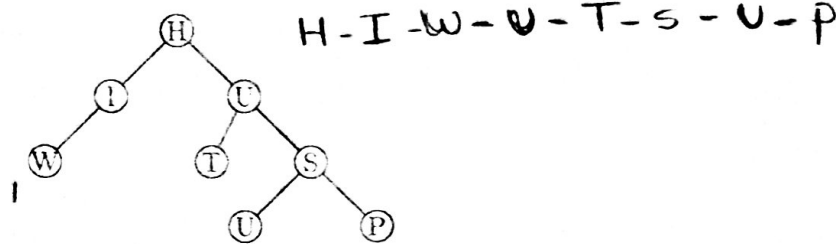
Output: D B A C F E G

Hopefully these steps help you better visualize the recursive nature of tree traversal.

## Question 3

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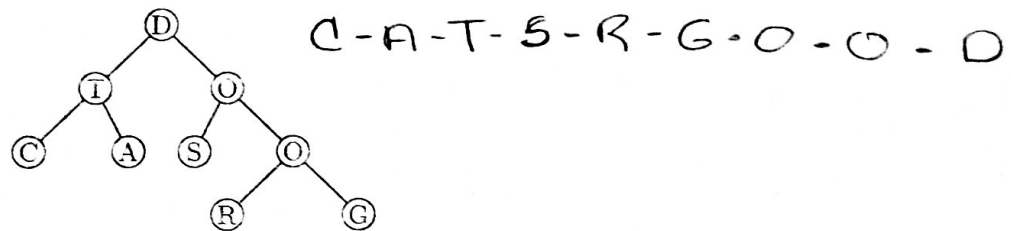
Traverse the following tree using **pre-order** traversal. Write out each Node as you "process" it.



## Question 4

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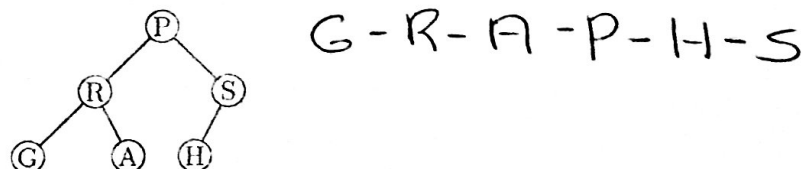
Traverse the following tree using **post-order** traversal. Write out each Node as you "process" it.



## Question 5

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Traverse the following tree using **in-order** traversal. Write out each Node as you "process" it.





## Question 6

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We have a Node class declared like this:

```
template <typename T>
struct Node
{
    T data;
    Node* ptrLeft;
    Node* ptrRight;
};
```

And we have nodes already declared, `nodeA`, `nodeB`, `nodeC`, `nodeD`. They store 'A', 'B', 'C', and 'D', respectively. Write some basic code to create a tree with these nodes. One will be a root. For each Node, the item to its *left* should be lower in value ( $A < B$ ), and the item to its *right* should be greater ( $C > B$ ).

```
Struct Node* root = newNode(B'B');
root root → ptrLeft = newNode('A')
root → ptrRight = newNode('C')
root → ptrRight → ptrRight = newNode('D')
```

