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In [1]: import numpy as np
import matplotlib.pyplot as plt from
sklearn import tree from
sklearn.datasets import load_iris
from itertools import combinations
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In [2]: iris = load_iris() X = iris.data
y = iris.target feature_names =
iris.feature_names target_names =
iris.target_names
```

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In [3]: print("Feature names:", feature_names)
print("Target names:", target_names)
print("\nFirst 5 samples:\n", X[:5])
print("\nFirst 5 labels:\n", y[:5])
```

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Feature names: ['sepal length (cm)', 'sepal width (cm)', 'petal length (cm)',  
'petal width (cm)']
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Target names: ['setosa' 'versicolor' 'virginica']
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```
First 5 samples:
[[5.1 3.5 1.4 0.2]
[4.9 3. 1.4 0.2]
[4.7 3.2 1.3 0.2]
[4.6 3.1 1.5 0.2]
[5. 3.6 1.4 0.2]]
```

```
First 5 labels:
[0 0 0 0 0]
```

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In [4]: plot_colors = "ryb"
plot_step = 0.02
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In [5]: plt.figure(figsize=(12, 10))
pair_index = 1
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<Figure size 1200x1000 with 0 Axes>
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In [8]: pair_index = 1
for pair in combinations(range(4), 2):
    X_pair = X[:, pair]
    clf = tree.DecisionTreeClassifier(criterion='entropy', max_depth=4,
        random_state=42)
    clf.fit(X_pair, y)

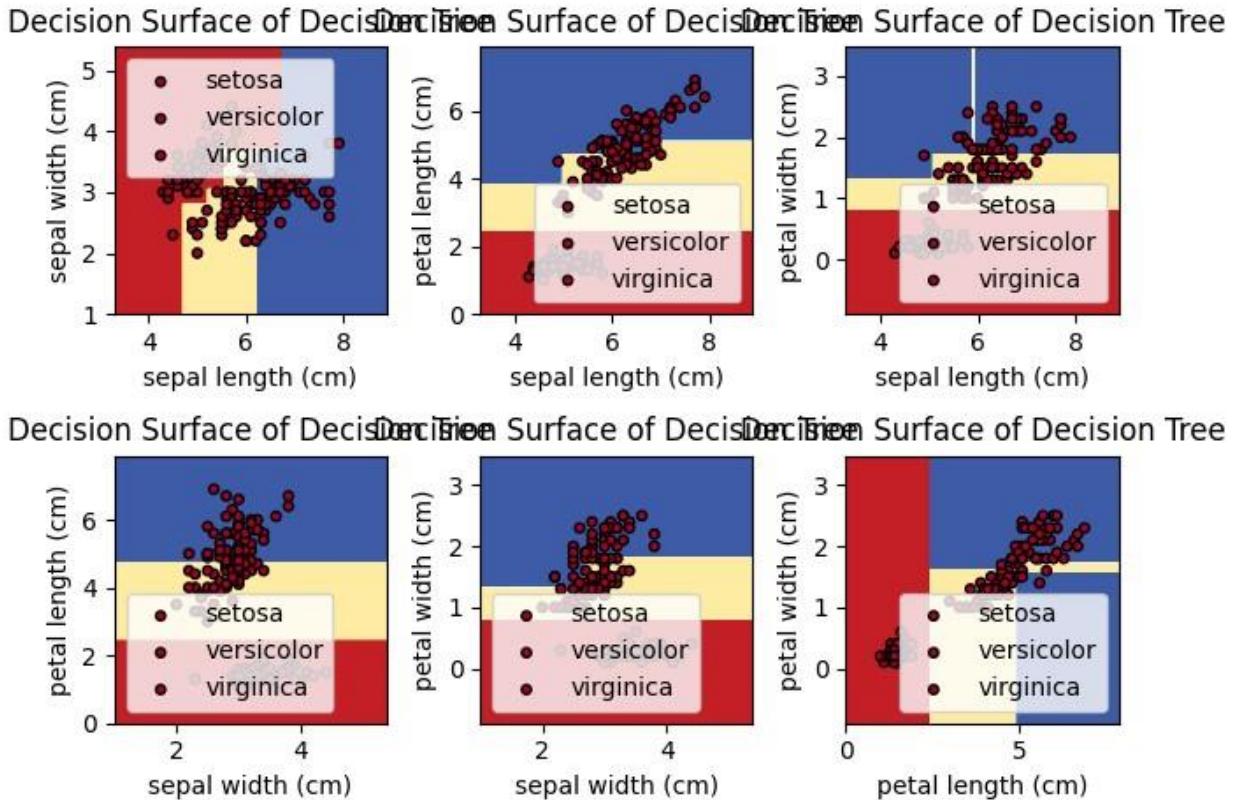
    x_min, x_max = X_pair[:, 0].min() - 1, X_pair[:, 0].max() + 1
    y_min, y_max = X_pair[:, 1].min() - 1, X_pair[:, 1].max() + 1
    xx, yy = np.meshgrid(np.arange(x_min, x_max, plot_step),
        np.arange(y_min, y_max, plot_step))

    plt.subplot(2, 3, pair_index)
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)
    cs = plt.contourf(xx, yy, Z, cmap=plt.cm.RdYlBu)

    plt.xlabel(feature_names[pair[0]])
    plt.ylabel(feature_names[pair[1]])

    for i, color in zip(range(len(target_names)), plot_colors):
        idx = np.where(y == i)
        plt.scatter(X_pair[idx, 0], X_pair[idx, 1], c=y[idx], label=target_names[i])

    plt.title('Decision Surface of Decision Tree')
    plt.legend()
plt.tight_layout()
pair_index += 1
plt.show()
```



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In [10]: x_min, x_max = X_pair[:, 0].min() - 1, X_pair[:, 0].max() + 1
y_min, y_max = X_pair[:, 1].min() - 1, X_pair[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, plot_step),
                     np.arange(y_min, y_max, plot_step))

In [11]: z = clf.predict(np.c_[xx.ravel(),
                         yy.ravel()])
          Z = z.reshape(xx.shape)

plt.figure(figsize=(12, 10))

for pair_index, pair in enumerate(combinations(range(4), 2), start=1):
    X_pair = X[:, pair]
    clf = tree.DecisionTreeClassifier(criterion='entropy', max_depth=4, random_state=42)
    clf.fit(X_pair, y)
```

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In [14]: clf.fit(X_pair, y)

[

    x_min, x_max = X_pair[:, 0].min() - 1, X_pair[:, 0].max() + 1
    y_min, y_max = X_pair[:, 1].min() - 1, X_pair[:, 1].max() + 1
    xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.02),
                          np.arange(y_min, y_max, 0.02))
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()]).reshape(xx.shape)

    plt.subplot(3, 2, pair_index)
    plt.contourf(xx, yy, Z, alpha=0.3, cmap=plt.cm.RdYlBu)

    plot_colors = "ryb" for i, color in
    zip(range(3), plot_colors):
        plt.scatter(X_pair[y == i, 0], X_pair[y == i, 1], c=color,
                    label=target_names[i], edgecolor='k', s=30)

    plt.xlabel(feature_names[pair[0]])
    plt.ylabel(feature_names[pair[1]])
    plt.title(f"Decision Boundary ({feature_names[pair[0]]} vs
              {feature_names[pair[1]]})")

plt.tight_layout()
plt.show()
```

