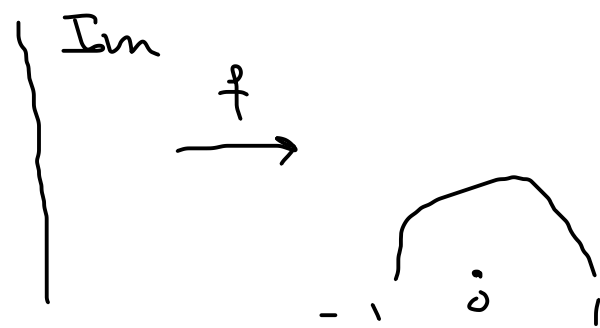


Teorema

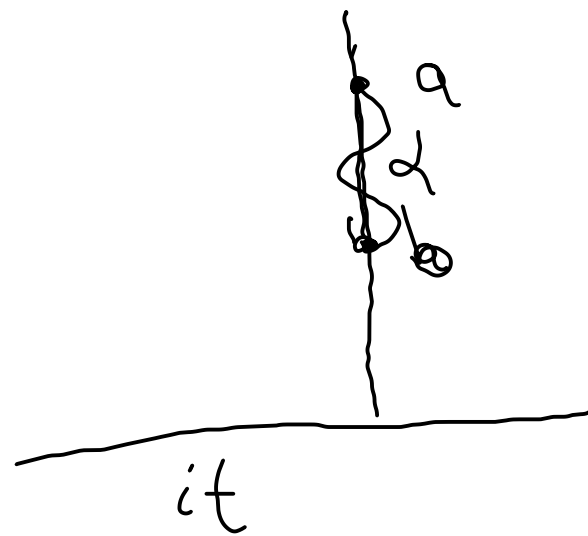
$$G_{H^+} \in \text{Iso}(H)$$

↖ métrica
hiperbólica



isometrías
traslaciones $a \in \mathbb{R}$
y homotecias

Teo Las rectas hiperbólicas son
geodesicas i.e. minimizan
la distancia entre sus puntos.



$$\alpha[0,1] \rightarrow H^+$$

$$\alpha(0) = a \quad \alpha(1) = b$$

$$l(\alpha) = \int_0^1 \|\alpha'(t)\|_H dt$$

$$\alpha(t) = (x(t), y(t))$$

$$\alpha'(t) = (x'(t), y'(t))$$

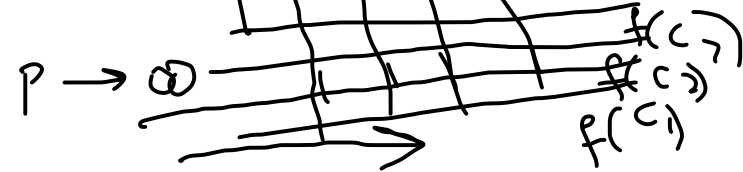
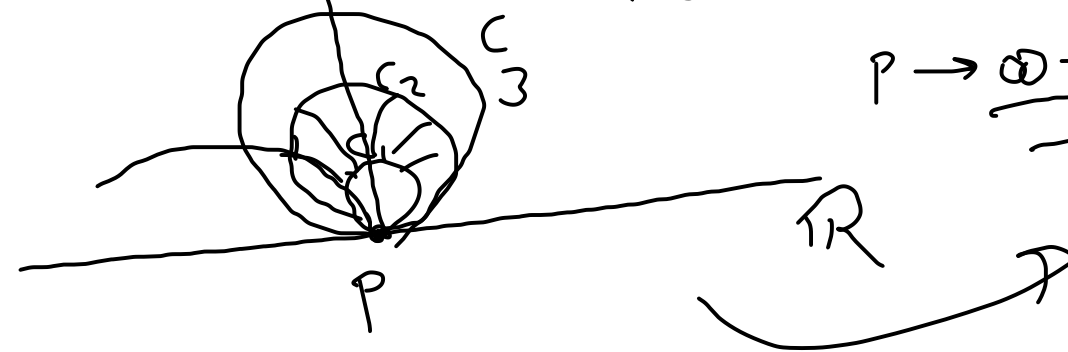
$$\|\alpha'(t)\|_H = \|(x'(t), y'(t))\|_H \geq \|(0, y'(t))\|_H$$

$$l(\alpha) \geq \int_0^1 \|(0, y'(t))\|_H dt = \int_b^a \frac{1}{t} dt$$

$$= \ln\left(\frac{a}{b}\right)$$

↖ minimiza

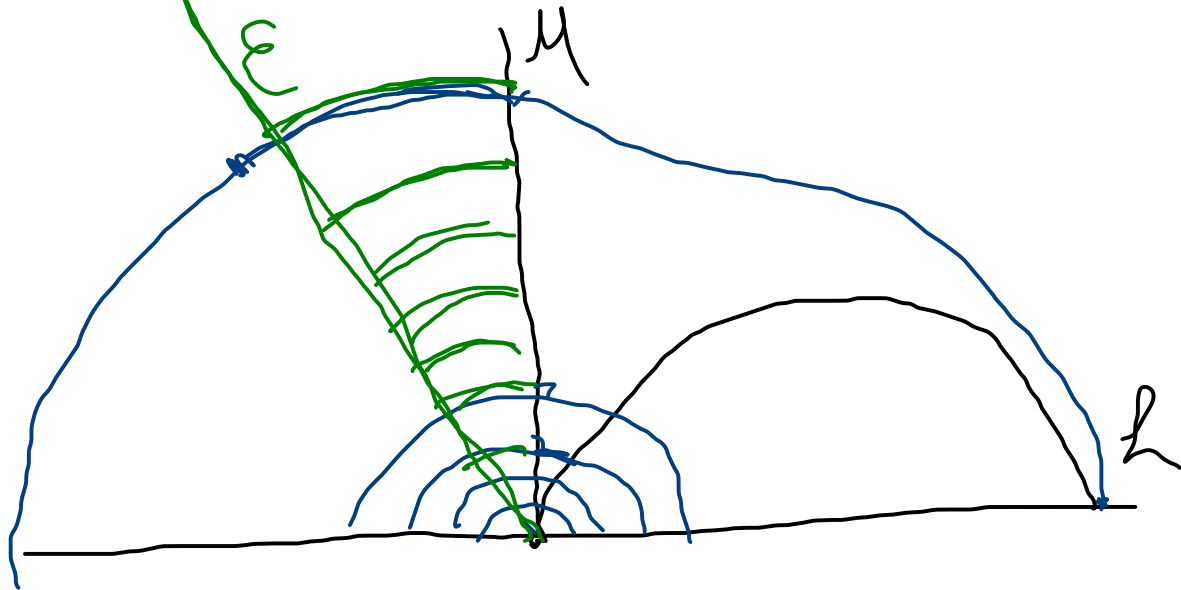
Proposición Los horociclos tangentes en un punto al infinito son equidistantes



$$\omega \in \mathbb{R}$$

Afirmación Rectas paralelas no son equidistantes
de hecho su distancia crece tanto como se quiera

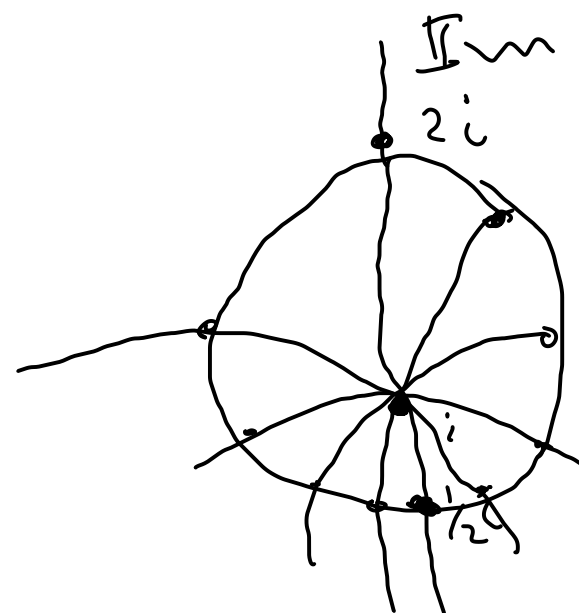
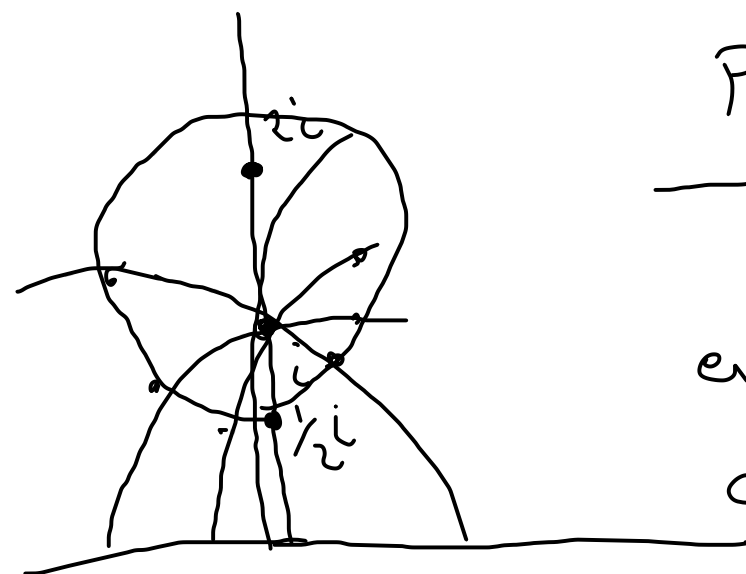
E es equidistante a M



Proposición

Una circunferencia hiperbólica
en una circunferencia euclidiana
con el centro desplazado
hacia Re

\mathbb{R}



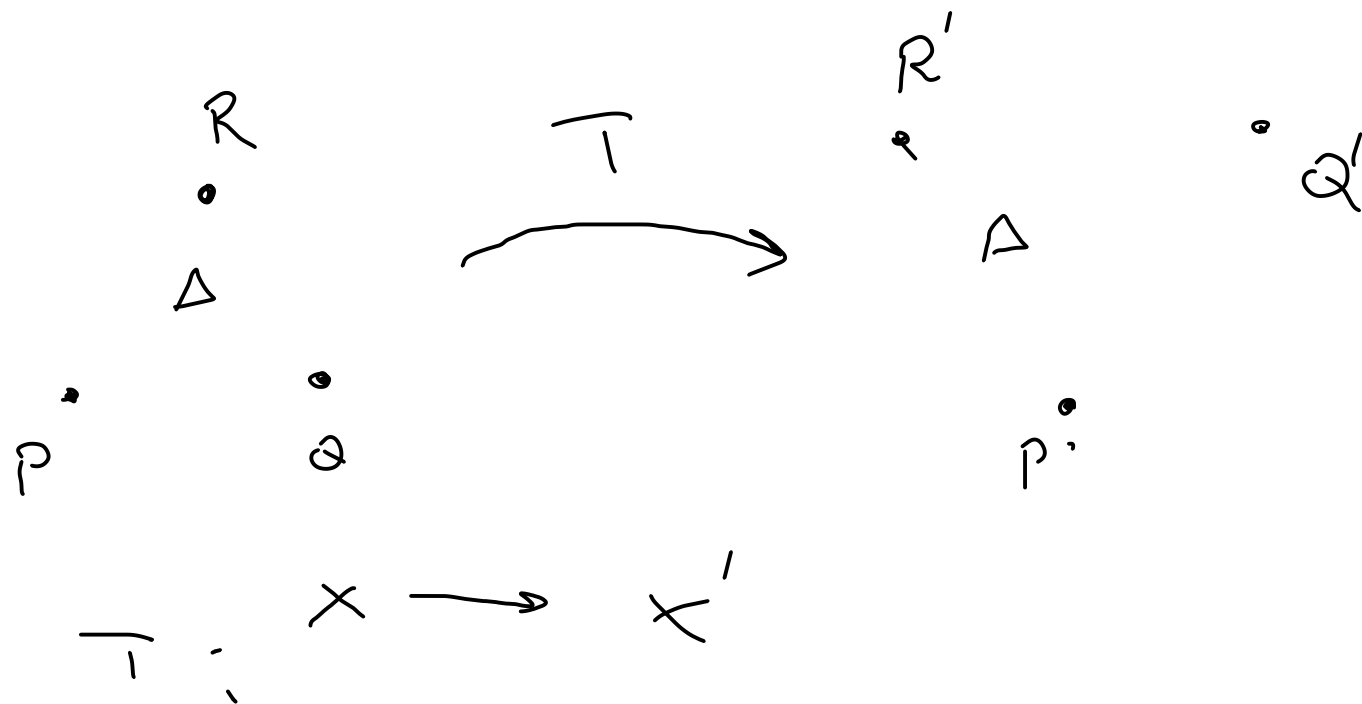
Teo $\text{Iso}^+(\mathbb{H}) = \text{PSL}(2, \mathbb{R})$

$S \in \mathbb{H}^+$

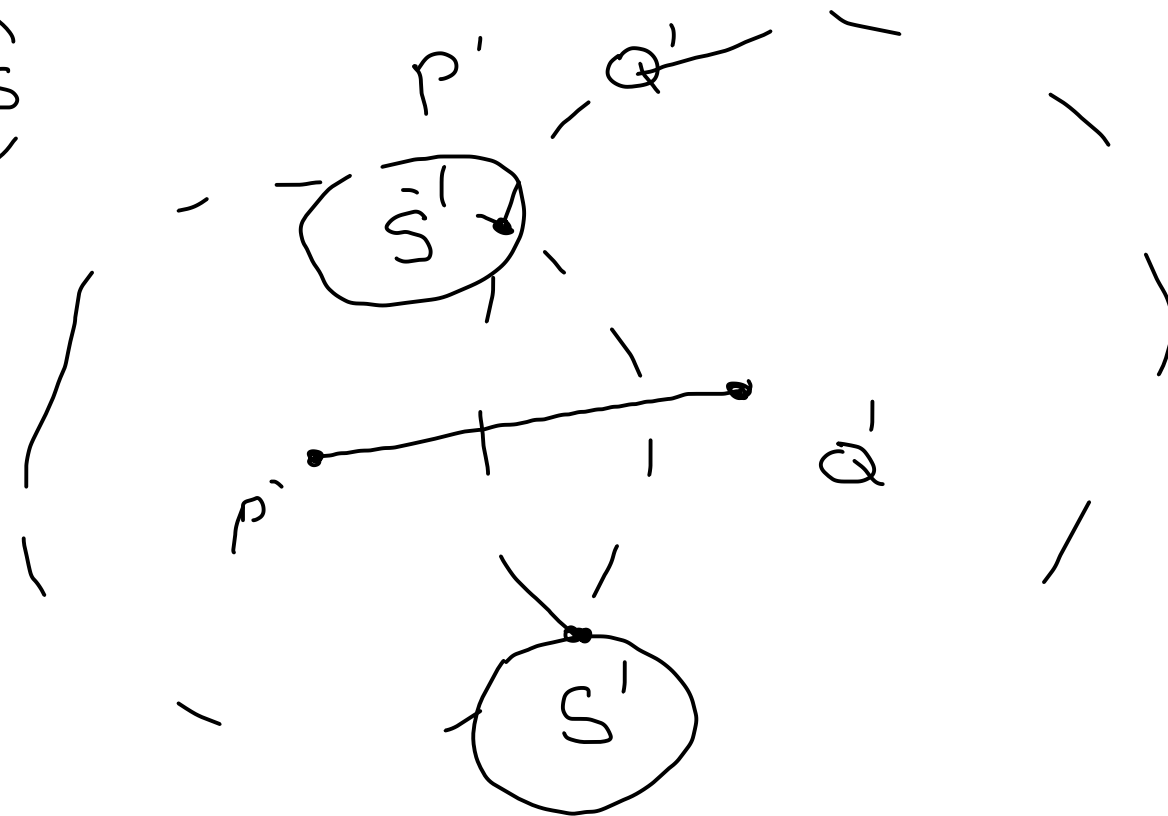
ya vimos \supset falta \subset

presene la orientacion

Sea T una isometria de \mathbb{H}^+



$\Delta(p, q, s)$



Tomamos s' tal que

$(p, q; r, s) = (p', q'; r', T(s))$

$f: \begin{matrix} p \\ q \\ r \end{matrix} \rightarrow \begin{matrix} p' \\ q' \\ s' \end{matrix}$

así $T = f \in \text{PSL}(2, \mathbb{R})$

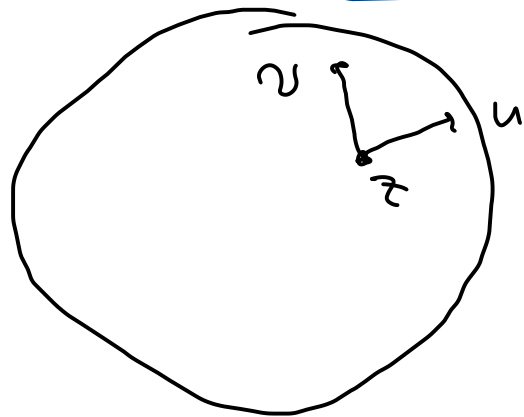
Como se ve la métrica en Δ

$$Q: H^+ \longrightarrow \Delta \quad \frac{z-i}{-iz+1} = f(z)$$

tenemos

$$u \cdot_{\Delta} v = 4 \frac{u \cdot v}{(1-r^2)^2}$$

$$u, v \in T_{\text{rcio}} \Delta$$



$$z = re^{i\theta}$$

$$Q: H^+ \rightarrow \Delta$$

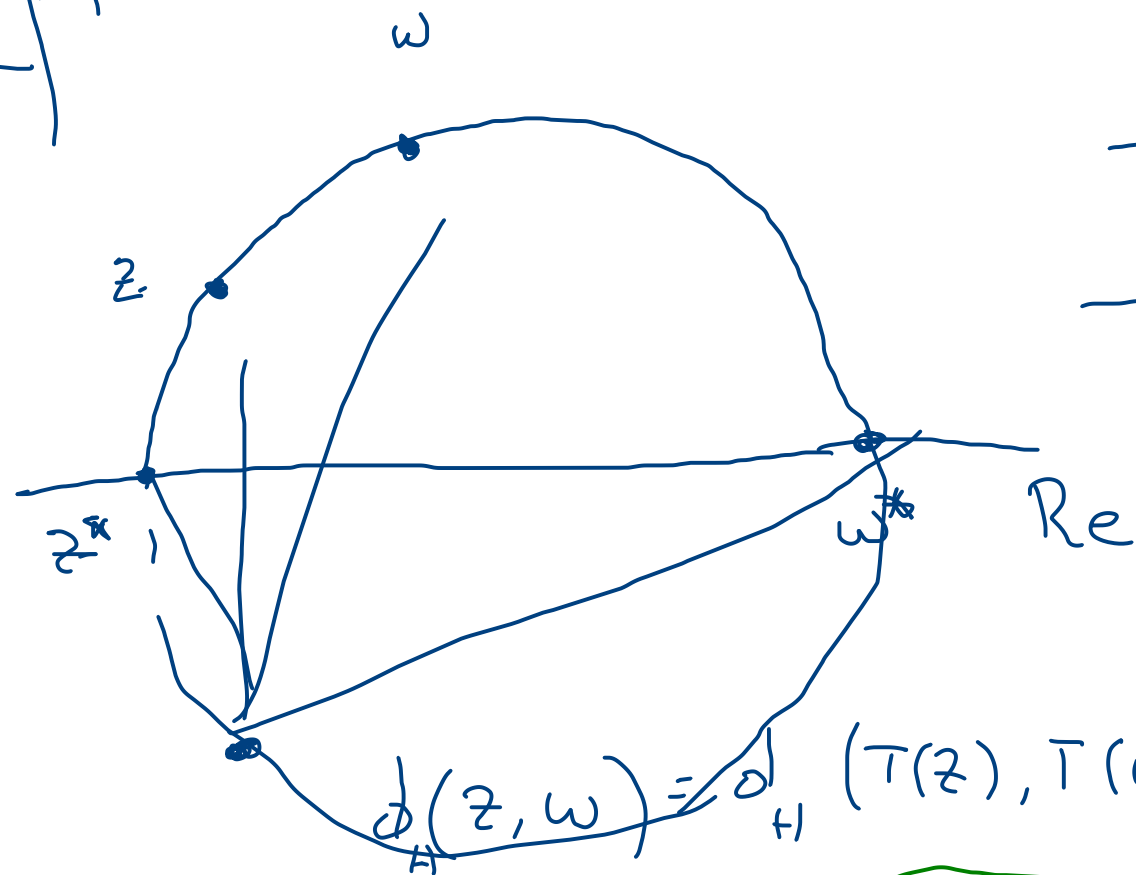
$$z_0 \longrightarrow z \quad u, v$$

$$\cdot_H \quad \overleftarrow{(JQ)^{-1}}$$

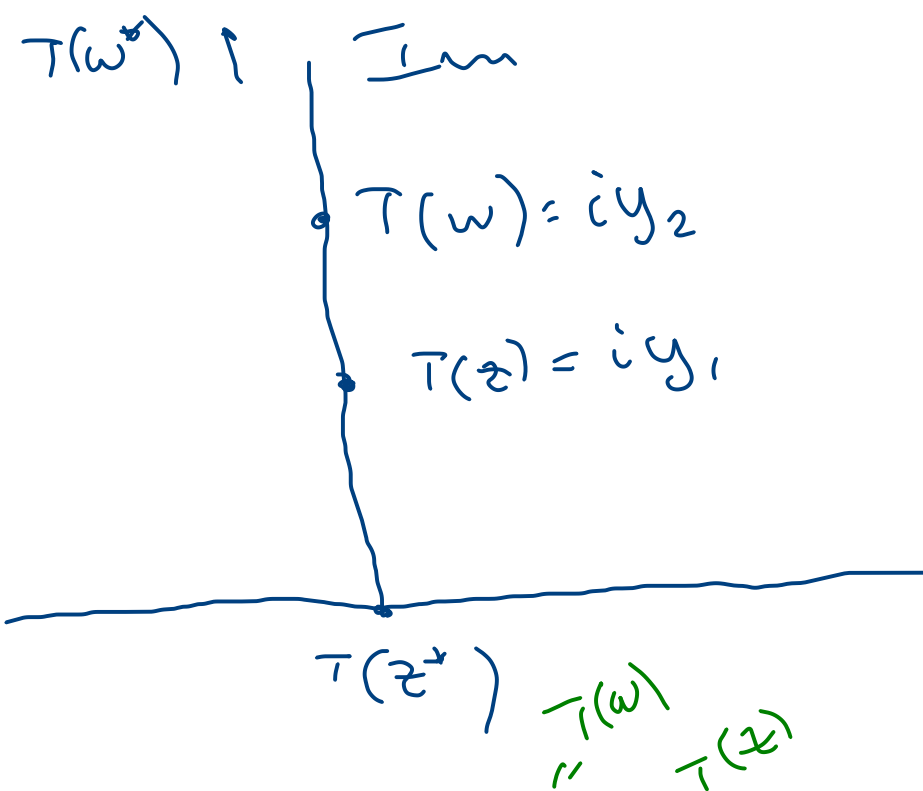
$$\text{rcio} \mid \text{Im} \quad f$$

$$\alpha'(t) \quad \overrightarrow{(Jf)} \quad \beta'(t)$$

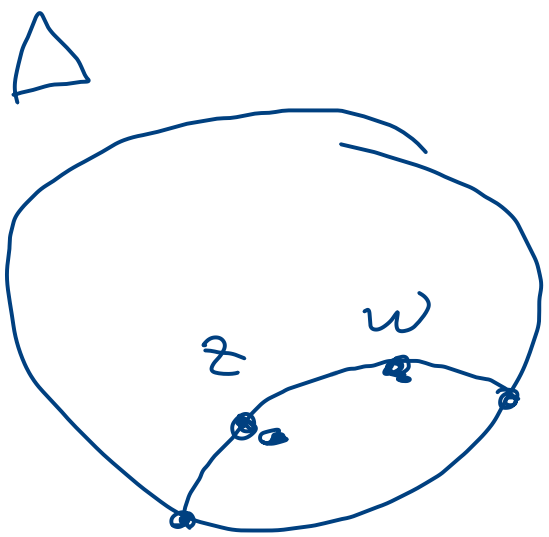
H



T
→



$$d_H(z, w) = d_H(T(z), T(w)) = \ln \left(\frac{T(w)}{T(z)} \right) = \ln (iy_1, iy_2 / 0, \infty)$$



$$d_H(z, w) = \ln (z, w, z^*, w^*)$$

quando ϕ
vale em Δ