

amici::SteadystateProblem
::workSteadyStateProblem

amici::SteadystateProblem
::createSteadystateSimSolver

getLinearSolver

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graph LR; A[amici::SteadystateProblem::workSteadyStateProblem] --> C[getLinearSolver]; B[amici::SteadystateProblem::createSteadystateSimSolver] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions, 'amici::SteadystateProblem::workSteadyStateProblem' and 'amici::SteadystateProblem::createSteadystateSimSolver', are shown in white boxes on the left. Blue arrows point from each of these boxes to a single target function, 'getLinearSolver', which is shown in a gray box on the right.