

MODULE 1.3

Orthogonal Projections in R^m

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Inner product and norm in R^m

- Let $x, y \in R^m$. The inner product is defined as

$$\langle x, y \rangle = x^T y = \sum_{i=1}^n x_i y_i = y^T x = \langle y, x \rangle \quad (1)$$

- Norm of a vector x is given by

$$\|x\| = \langle x, x \rangle^{\frac{1}{2}} = \left(\sum_{i=1}^m x_i^2 \right)^{\frac{1}{2}} \quad (2)$$

- Cauchy- Schwartz inequality: From

$$\langle x, y \rangle = \|x\| \|y\| \cos(\theta) \quad (3)$$

it follows that

$$|\cos \theta| = \frac{|\langle x, y \rangle|}{\|x\| \|y\|} \leq 1 \quad (4)$$

Projection of y along x - a geometric view

- Let $\hat{x} = \frac{x}{||x||}$ be the unit vector,

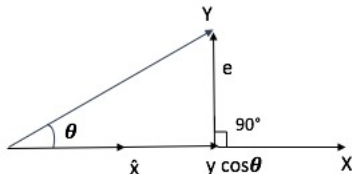
$$||\hat{x}|| = 1 \quad (5)$$

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$$\langle y, \hat{x} \rangle = y^T \hat{x} = ||y|| \cos(\theta) \quad (6)$$

which is the component of y in the direction \hat{x} .

- The vector $(y \cos \theta) \hat{x}$ is called the projection of y along \hat{x}



Orthogonality of this projection

- Let $e = y - (y\cos\theta)\hat{x}$ be the error in the projection
- Then,

$$\langle e, \hat{x} \rangle = e^T \hat{x} = y^T \hat{x} - (y\cos\theta)\hat{x}^T \hat{x} = 0 \quad (7)$$

- Hence the name orthogonal projection

Analytical expression for orthogonal projection

- Let $h \in R^m$ and $x \in R^m$ be any other vector
- Any vector along h can be expressed as a multiple $h\alpha$ for some real α
- Problem: Given x and h , find $\alpha \in R$ that minimizes the distance between x and $h\alpha$
- That is, find α that minimizes

$$\begin{aligned} Q(\alpha) &= \|x - h\alpha\|^2 = (x - h\alpha)^T (x - h\alpha) \\ &= x^T x - 2x^T h\alpha + \alpha^2 h^T h \end{aligned} \quad (8)$$

- Minimizer α^* is obtained by solving

$$0 = \frac{dQ}{d\alpha} = -2h^T x + 2\alpha h^T h \quad (9)$$

- That is,

$$\alpha^* = (h^T h)^{-1} h^T x = h^+ x \quad (10)$$

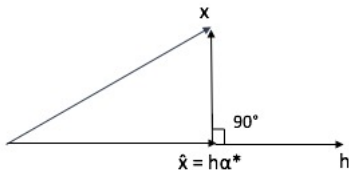
where

$$h^+ = (h^T h)^{-1} h^T \quad (11)$$

is called the generalized inverse of h

Expression for the projection

- The orthogonal projection of x along h is given by



$$\hat{x} = h\alpha^* = hh^+x = h(h^T h)^{-1}h^T x = P_h x \quad (12)$$

where

$$P_h = hh^+ = h(h^T h)^{-1}h^T \quad (13)$$

is called the orthogonal projection matrix

Orthogonality of projection

- Let

$$e = x - \hat{x} = (I - P_h)x \quad (14)$$

be the error in the projection

- Clearly:

$$h^T e = (h^T - h^T P_h)x = 0 \quad (15)$$

since $h^T P_h = (h^T h)(h^T h)^{-1}h^T = h^T$

- Hence, P_h is called the orthogonal projection operator

Properties of P_h

- Symmetry: $P_h^T = P_h$
- Idempotent: $P_h^2 = P_h$
- P_h is a rank one matrix
- $\det(P_h) = 0$, that is, P_h is singular
- 1 is the only non-zero eigenvalue of P_h
- P_h is not an orthogonal matrix: $P_h^T \neq P_h^{-1}$ since P_h^{-1} is not defined

A Generalization

- Let $H \in R^{m \times n}$ with $m > n$ and $\text{Rank}(H) = n$
- Then, $(H^T H) \in R^{n \times n}$ is SPD
- Let $x \in R^m$
- Problem: Find an $\alpha \in R^n$ such that $\hat{x} = H\alpha \in R$
and

$$\begin{aligned} Q(\alpha) &= (x - H\alpha)^T (x - H\alpha) = \|x - H\alpha\|^2 \\ &= x^T x - 2x^T H\alpha + \alpha^T (H^T H)\alpha \end{aligned} \quad (16)$$

is a minimum

- From

$$\nabla_{\alpha} Q(\alpha) = -2H^T x + 2(H^T H)\alpha = 0 \quad (17)$$

it follows that

$$\alpha^* = (H^T H)^{-1} H^T x = H^+ x \quad (18)$$

minimizes $Q(\alpha)$ since

$$\nabla_{\alpha}^2 Q(\alpha) = (H^T H) \text{ is } SPD \quad (19)$$

- $H^+ = (H^T H)^{-1} H^T \in R^{n \times m}$ is called the generalized inverse of H

Optimal projection

- Then

$$\hat{x} = H\alpha^* = H(H^T H)^{-1}H^T x = HH^+x = P_H x \quad (20)$$

where

$$P_H = H(H^T H)^{-1}H^T \in R^{m \times m} \quad (21)$$

is the projection operator in R^m onto the n-dimensional subspace spanned by the columns of H

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$$e = x - \hat{x} = (I - P_H)x \quad (22)$$

is the error in this projection

- Verify that

$$e^T H = 0 \quad (23)$$

and hence the name orthogonal projection

Properties of P_H

- Symmetry: $P_H^T = P_H$
- Idempotent: $P_H^2 = P_H$
- $RANK(P_H) = n$ since that of H is n
- P_H is singular
- There are exactly n non-zero eigenvalues of P_H
- P_H is not an orthogonal matrix

- Chapters 5 and 6 in J. Lewis, S. Lakshmivarahan and S.K. Dhall (2006) Dynamic Data Assimilation, Cambridge University Press.

- 1) Let $x \in R^m$ and $h = (1, 1, \dots, 1)^T \in R^m$ and $h = (1, 1, 1, \dots, 1)^T \in R^m$ be a vector all of whose components are 1. Compute an expression for α that minimizes the distance between x and $h\alpha$.

2) Let $H = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$

- Compute $H^T H$, HH^T , H^+ , P_H , HH^+ , H^+H , HH^+H , H^+HH^+
- Compute the eigenvalues of P_H

3) Verify the following:

a) $HH^+H = H$

b) $H^+HH^+ = H^+$

c) $(H^+H)^T = H^+H$

d) $(HH^+)^T = HH^+$

Note: Any H^+ satisfying the properties (a)-(d) is called the Moore-Penrose inverse.

4) Given P_H , define $P_H^\perp = I - P_H$

- Verify that P_H^\perp is symmetric and idempotent
- For the H in problem 2, Compute P_H^\perp and its rank