

1. First run ``python classifier.py``
it will pull up the camera and detect objects that are in front of the camera.
2. then run ``sudo python lora_sender.py``
Here I am using sudo because it will need sudo access to access the node of the raspberry pi. This script basically sends the labels that are detected from the objection model to the receiver Node.
3. then run ``sudo python lora_receiver.py`` on another pi (receiver node).
You will be able to see the labels that are being sent by the sender Node.

I also included all the steps in the README file. Please refer to that.