

Introduction to Robotics

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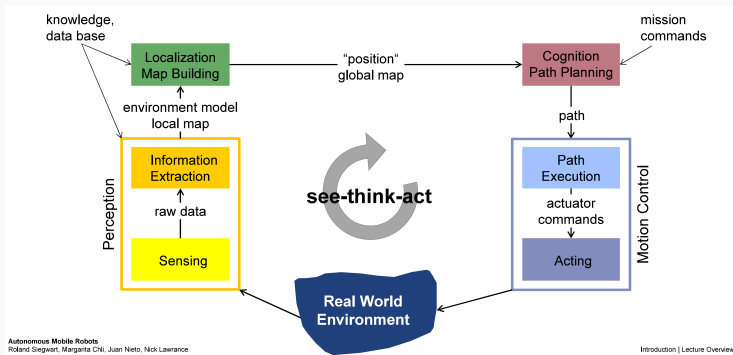
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A quick recap

Overview of Autonomous Robots

Sense-compute-move cycle



Brief history of Robotics

- Who coined the term "Robotics"?

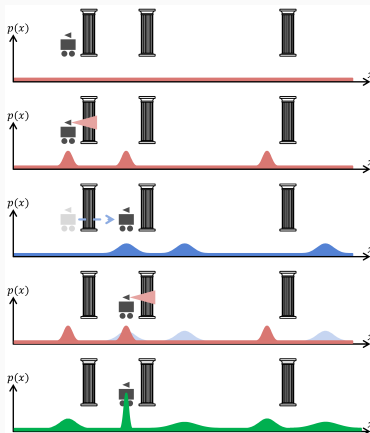
Brief history of Robotics

- Who coined the term "Robotics"?
- Which is the first general purpose mobile robot?

Probabilistic localization

Localize the robot in a given map dealing with uncertain data

Updates its belief state (fusing information from various sensors - laser scanner, wheel odometer, etc.)



See the (Lecture 2) attached slides from EdX

Robot Operating Systems (ROS)

See the attached slides for ROS

Wheeled robot kinematics

See the attached slides from EdX

For the next class

- ROS - installation, configuration, and setup
- Wheeled robot kinematics - continued