# Introduction to Robotics

## CSCI/ATRI 4530/6530

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# Announcements

- Course website is up: `http://cs.uga.edu/~csx530`
- Assignment 1 is out - Deadline: Monday 09/10 (12:20 PM)

# A quick recap

- What is Computer Vision?

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- What is an Omnidirectional camera model?
- What is Stereo Vision and its model?
- How do you calibrate a camera model?

# For today - ROS Practicals

- Publisher and Subscriber (Python)
- roslaunch
- Custom Messages - Creation and Usage