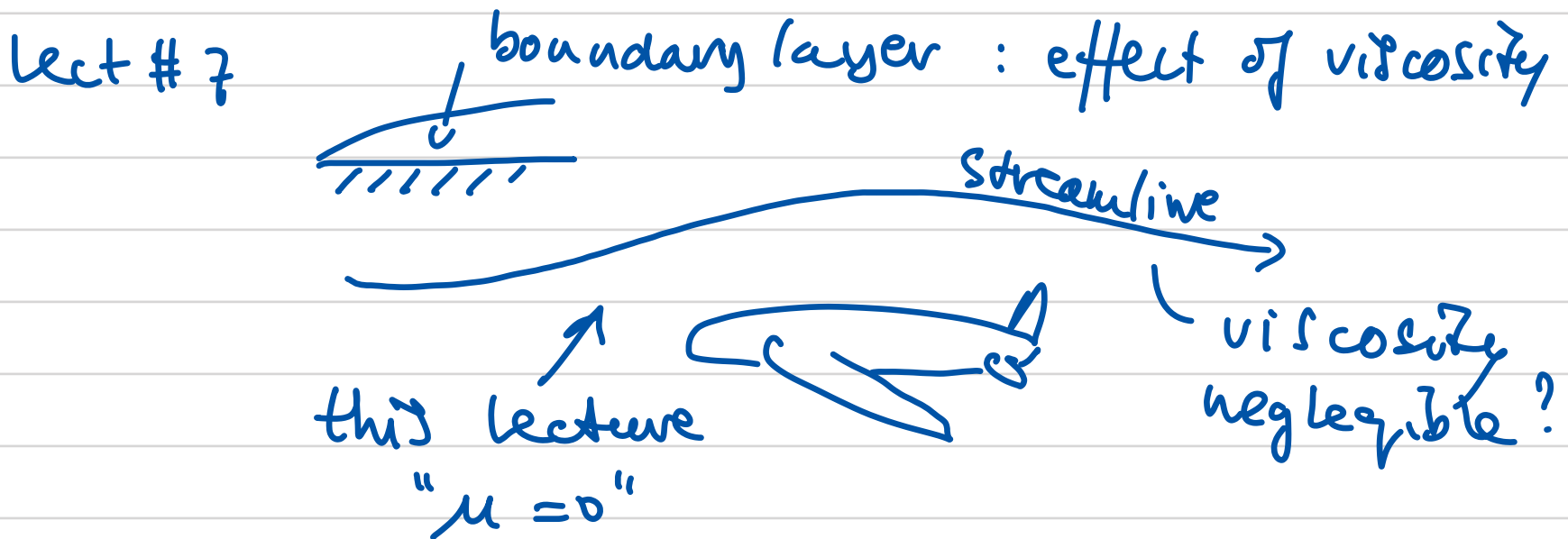


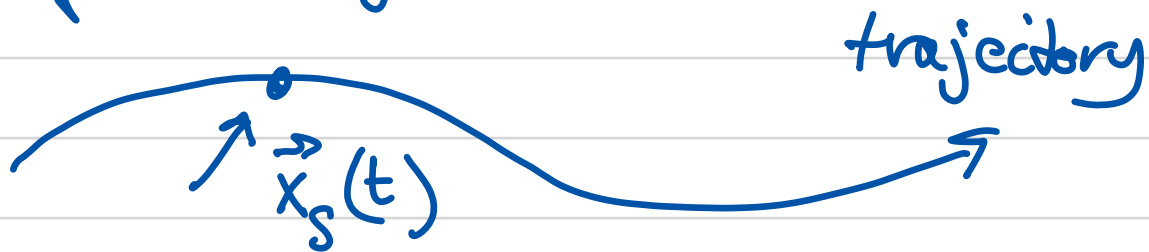
Fluid Mechanics I

Lecture #8 Euler & Bernoulli eqs.



First: Material Derivative.

Imagine micro-sensor for pressure following the fluid:



$$\frac{d}{dt} \vec{x}_s(t) = \vec{u}(\vec{x}_s(t), t)$$

Pressure measured by sensor:

$$p(\vec{x}_s(t), t)$$

measured
✓ pressure changes with time due to

- pressure field changes with time
- sensor position changes with time

$$\frac{d}{dt} p(\vec{x}_s(t), t) \stackrel{\text{chain rule}}{=}$$

$$= \frac{\partial p}{\partial x} \frac{dx_s}{dt} + \frac{\partial p}{\partial y} \frac{dy_s}{dt} + \frac{\partial p}{\partial z} \frac{dz_s}{dt} + \frac{\partial p}{\partial t} \frac{dt}{dt} \quad \begin{matrix} \text{=} \\ \text{=} \end{matrix}$$

$\left(\begin{matrix} \equiv u(\vec{x}_s, t) & \equiv v(\vec{x}_s, t) & \equiv w(\vec{x}_s, t) \end{matrix} \right)$

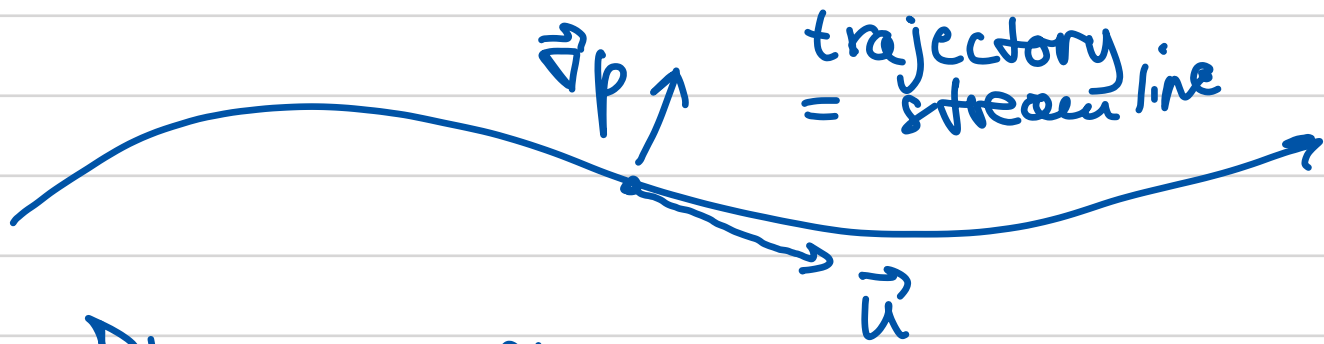
$$\Rightarrow \underbrace{\frac{d}{dt} p(\vec{x}_s(t), t)} = \frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z}$$

$$\equiv \frac{Dp}{Dt} : \text{material derivative}^*$$

$$\Leftrightarrow \frac{Dp}{Dt} = \frac{\partial p}{\partial t} + \underbrace{u_j \frac{\partial p}{\partial x_j}}_{\text{sum!}}$$

* time-derivative while traveling with the fluid.

Example: Steady flow



$$\Rightarrow \frac{Dp}{Dt} = u_j \frac{\partial p}{\partial x_j}$$

Suppose $\frac{Dp}{Dt} = 0 \Rightarrow p$ is constant along streamline

C.a.s.

$\Rightarrow \vec{\nabla} p$ does not have a component in the direction of the streamline $\Rightarrow \vec{\nabla} p \perp \vec{u} \Leftrightarrow \vec{\nabla} p \cdot \vec{u} = 0$

Euler's equation.

Momentum equation with $\mu = 0$

$$\frac{\partial}{\partial t}(\rho u_i) + \frac{\partial}{\partial x_j}(\rho u_i u_j + p \delta_{ij} - \cancel{\mu(\cdot)}) = \rho g_i$$

$$\begin{aligned} \frac{\partial}{\partial x_j}(\rho \delta_{ij}) &= \frac{\partial}{\partial x_1}(\rho \delta_{i1}) + \frac{\partial}{\partial x_2}(\rho \delta_{i2}) + \frac{\partial}{\partial x_3}(\rho \delta_{i3}) \\ &= \frac{\partial \rho}{\partial x_i} \end{aligned}$$

$$\Rightarrow \frac{\partial \rho u_i}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_j u_i) = - \underbrace{\frac{\partial p}{\partial x_i} + \rho g_i}_{=0 \text{ max const.}}$$

$$\underbrace{\frac{\partial \rho}{\partial t} u_i + \rho \frac{\partial u_i}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_j) u_i + \rho u_j \frac{\partial u_i}{\partial x_j}}_{\rightarrow} : \left\{ \frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_j) \right\} u_i = 0 \text{ max const.}$$

$$\Rightarrow \frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = - \frac{1}{\rho} \frac{\partial p}{\partial x_i} + g_i$$

$$\Rightarrow \boxed{\frac{Du_i}{Dt} = - \frac{1}{\rho} \frac{\partial p}{\partial x_i} + g_i} \quad \text{Euler's eq.}$$

"n=0"

Note $\frac{Du_i}{Dt}$ = time derivative of u_i while moving with fluid
 \Rightarrow acceleration of fluid

\rightarrow Newton's 2nd law.

Vector notation:

$$\boxed{\frac{D\vec{u}}{Dt} = - \frac{1}{\rho} \vec{\nabla} p + \vec{g}}$$

Gravity:

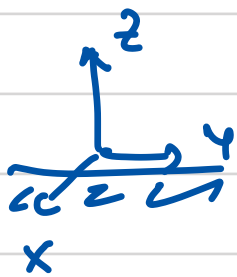


Define ζ as the altitude.

$$\vec{u} \sim \vec{\nabla} \zeta \Rightarrow \vec{g} \sim -\vec{\nabla} \zeta$$

$$|\vec{\nabla} \zeta| = 1 \Rightarrow \boxed{\vec{g} = -g \vec{\nabla} \zeta}$$

Test:



$$\Rightarrow \zeta = z \quad \vec{\nabla} \zeta = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{g} = -g \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \rho.$$

index notation:

$$\boxed{g_i = -g \frac{\partial \zeta}{\partial x_i}}$$

Back to Euler's equation:

$$\frac{Du_i}{Dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + g_i = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} - g \frac{\partial \zeta}{\partial x_i}$$

Assume:
 - Steady flow
 - incompressible.

$$\Rightarrow u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial}{\partial x_i} \left(\frac{p}{\rho} \right) - \frac{\partial}{\partial x_i} (g \zeta)$$

Take the inner product of this equation with the velocity vector.

$$\Rightarrow \underbrace{u_i u_j \frac{\partial u_i}{\partial x_j}}_{\text{double sum}} = - \underbrace{u_i \frac{\partial}{\partial x_i} \left(\frac{p}{\rho} \right)}_{\text{sum}} - \underbrace{u_i \frac{\partial}{\partial x_i} (g \zeta)}_{\text{sum}}$$

$$u_i u_j \frac{\partial u_i}{\partial x_j} = u_j u_i \frac{\partial u_i}{\partial x_j} = u_j \cdot \frac{\partial}{\partial x_j} \left(\frac{1}{2} u_i u_i \right)$$

$$\text{check: } \frac{\partial}{\partial x_j} \left(\frac{1}{2} u_i u_i \right) = \frac{1}{2} \left\{ \underbrace{\frac{\partial u_i}{\partial x_j} u_i}_{\text{sum}} + \underbrace{u_i \frac{\partial u_i}{\partial x_j}}_{\text{sum}} \right\} = \underbrace{u_i \frac{\partial u_i}{\partial x_j}}_{\text{sum}}$$

$$\text{Rewrite } \underbrace{u_j \frac{\partial}{\partial x_j} \left(\frac{1}{2} u_i u_i \right)}_{\text{double sum}} \equiv \underbrace{u_i \frac{\partial}{\partial x_i} \left(\frac{1}{2} u_j u_j \right)}_{\text{double sum.}}$$

Put everything together:

$$u_i \frac{\partial}{\partial x_i} \left\{ \frac{1}{2} u_j u_j + \frac{p}{\rho} + g \zeta \right\} = 0$$

$$\Rightarrow \vec{u} \cdot \vec{\nabla} \left\{ \frac{p}{\rho} + \frac{1}{2} \vec{u} \cdot \vec{u} + g \zeta \right\} = 0$$

$$\Rightarrow \vec{u} \perp \vec{\nabla} \{ \}$$

$$\Rightarrow \{ \} = \text{c.a.s.} \quad !$$

$$\Rightarrow \frac{p}{\rho} + \frac{1}{2} \bar{u}^2 + g\zeta = \text{c.a.s.} \quad \bar{u} \equiv |\vec{u}|$$

$$\rho = \text{const} \Rightarrow$$

$$p + \frac{1}{2} \rho \bar{u}^2 + \rho g \zeta = \text{c.a.s.}$$

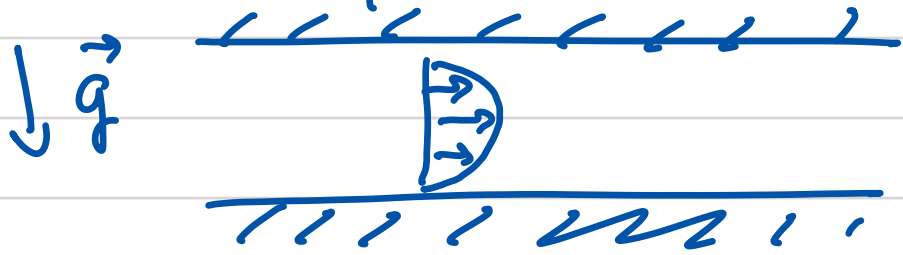
Bernoulli's equation.

if $\mu = 0$ (viscosity neglected)

- steady

- incompressible

Note: fully developed flow: lect 5?



steady ✓
incompressible ✓
viscous ✗

Bernoulli? ✗

$$\underbrace{p} + \underbrace{\frac{1}{2} \rho \bar{u}^2} + \underbrace{\rho g \zeta} \neq \text{c.a.s.}$$

$\neq \text{c.a.s.}$ see ch 5 $\frac{dp}{dx} < 0$
 $\underbrace{\quad}_{= \text{c.a.s.}} \quad \underbrace{\quad}_{= \text{c.a.s.}}$

Example Application:



assume: $\mu = 0$, $\rho = \text{const}$, $\frac{\partial}{\partial t}(\) = 0$

What is the pressure in the stagnation point?
↳ p_0

Bernoulli's equation is allowed to be used:

$$\left\{ p + \frac{1}{2} \rho |\vec{u}|^2 + \rho g \zeta \right\} = \text{c. a. s.}$$

$$\text{so here } \left\{ \right\}_\infty = \left\{ \right\}_0$$

$$\Rightarrow p_\infty + \frac{1}{2} \rho \bar{u}^2 + \cancel{\rho g \zeta} = p_0 + 0 + \cancel{\rho g \zeta}$$

$$\Rightarrow \boxed{p_0 = p_\infty + \frac{1}{2} \rho \bar{u}^2} \quad \equiv \text{total pressure}$$

How to use that in practice?



\bar{u}, ρ

$u \approx 0$



pressure factor
in stagnation
point $\Rightarrow p_0$ is known.

suppose you also know p_∞ from METEO

Bernoulli: $p_0 = p_\infty + \frac{1}{2} \rho \bar{u}^2$

$$\Rightarrow \bar{u} = \sqrt{\frac{2(p_0 - p_\infty)}{\rho}}$$

(with respect to the atmosphere