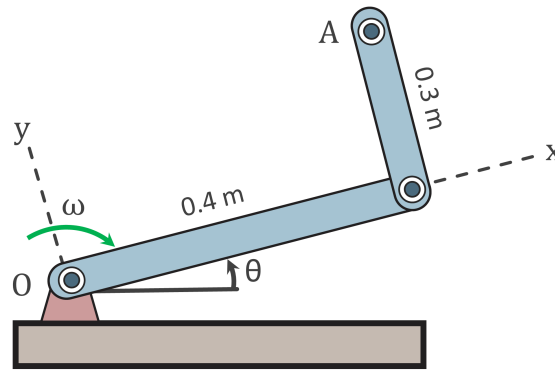




## Acceleration at end of Right-Angle Bar



The right-angle bar rotates clockwise with an angular velocity which is decreasing at the rate of  $4 \text{ rad/s}^2$ . Determine the vector expression for the acceleration of point A when  $\omega = 2 \text{ rad/s}$ .

Using known expressions:

$$\mathbf{a}_n = \boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) \quad (1)$$

$$\mathbf{a}_t = \boldsymbol{\alpha} \times \mathbf{r} \quad (2)$$

$$\mathbf{a} = \mathbf{a}_n + \mathbf{a}_t \quad (3)$$

Given:

Distance from O to A:  $\mathbf{r}_{A/O} = 0.4\mathbf{i} + 0.3\mathbf{j}$

Angular velocity:  $\omega = 2 \text{ rad/s}$

Angular acceleration:  $\alpha = -4 \text{ rad/s}^2$

Since the angular velocity is clockwise, and in the coordinate system positive is defined as counterclockwise, the angular velocity becomes:  $\omega = -2 \text{ rad/s}$ . The angular acceleration is clockwise and decreasing at a rate of  $4 \text{ rad/s}^2$ , thus this becomes:  $\alpha = - - 4 = 4 \text{ rad/s}^2$  in the defined coordinate system.

Inserting this in Equation 1 and 2 gives.

$$\mathbf{a}_n = \boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) \quad \Rightarrow \quad \mathbf{a}_n = \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} \times \begin{pmatrix} 0.4 \\ 0.3 \\ 0 \end{pmatrix} = \begin{pmatrix} -1.6 \\ -1.2 \\ 0 \end{pmatrix} \text{ m/s}^2 \quad (4)$$

$$\mathbf{a}_t = \boldsymbol{\alpha} \times \mathbf{r} \quad \Rightarrow \quad \mathbf{a}_t = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \times \begin{pmatrix} 0.4 \\ 0.3 \\ 0 \end{pmatrix} = \begin{pmatrix} -1.2 \\ 1.6 \\ 0 \end{pmatrix} \text{ m/s}^2 \quad (5)$$

Combining both gives the final answer for  $\mathbf{a}$ :

$$\mathbf{a} = \mathbf{a}_n + \mathbf{a}_t = \begin{pmatrix} -1.6 \\ -1.2 \\ 0 \end{pmatrix} + \begin{pmatrix} -1.2 \\ 1.6 \\ 0 \end{pmatrix} = \begin{pmatrix} -2.8 \\ 0.4 \\ 0 \end{pmatrix} \text{ m/s}^2 \quad (6)$$