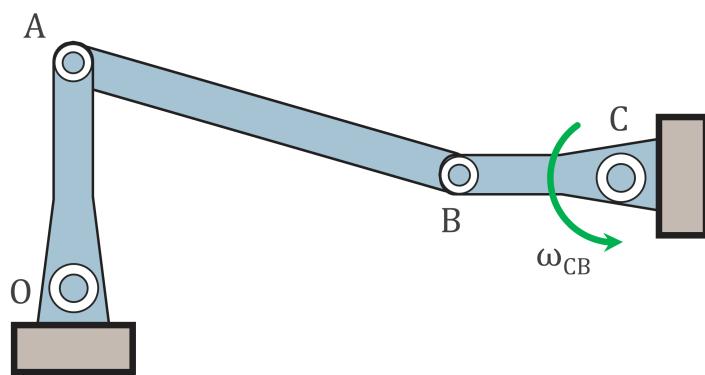


# Acceleration of Linkage



Crank CB has a constant angular velocity in the position shown during a short interval of its motion. To determine the angular acceleration of links AB and OA for this position two relations for the acceleration in point A can be written and set equal to each other. Select the two expressions for  $\mathbf{a}_A$  that must set equal to each other to solve for  $\alpha_{AB}$  and  $\alpha_{OA}$ .

Using known expressions (for rigid bodies):

$$\mathbf{a}_A = \mathbf{a}_O + \mathbf{a}_{A/O,n} + \mathbf{a}_{A/O,t} \quad (1)$$

$$\mathbf{a}_{A/O,n} = \boldsymbol{\omega}_{OA} \times (\boldsymbol{\omega}_{OA} \times \mathbf{r}_{A/O}) \quad (2)$$

$$\mathbf{a}_{A/O,t} = \boldsymbol{\alpha}_{OA} \times \mathbf{r}_{A/O} \quad (3)$$

*Solution:*

Inserting Equations (2) and (3) in Equation (1), together with the fact that point O is fixed to the base, hence  $\mathbf{a}_O = \mathbf{0}$  gives:

$$\mathbf{a}_A = \boldsymbol{\omega}_{OA} \times (\boldsymbol{\omega}_{OA} \times \mathbf{r}_{A/O}) + \boldsymbol{\alpha}_{OA} \times \mathbf{r}_{A/O} \quad (4)$$

We do the same for the second relation, only we start from the other side, so side B. Here  $\mathbf{a}_B \neq \mathbf{0}$  m/s, this results in:

$$\mathbf{a}_A = \mathbf{a}_B + \boldsymbol{\omega}_{BA} \times (\boldsymbol{\omega}_{BA} \times \mathbf{r}_{A/B}) + \boldsymbol{\alpha}_{BA} \times \mathbf{r}_{A/B} \quad (5)$$

These two equations can be set equal to each other to solve for  $\boldsymbol{\alpha}_{OA}$  and  $\boldsymbol{\alpha}_{BA}$ .