FIT5230 Malicious AI

Adversarial Machine Learning I

Overview

- Benign vs Adversarial: attacks on INTegrity
- Semantic adversarial attack
- Noise attack
- Fast Gradient Sign (FGS)
- Fast Gradient Value (FGV)
- Recent adversarial attacks on Al

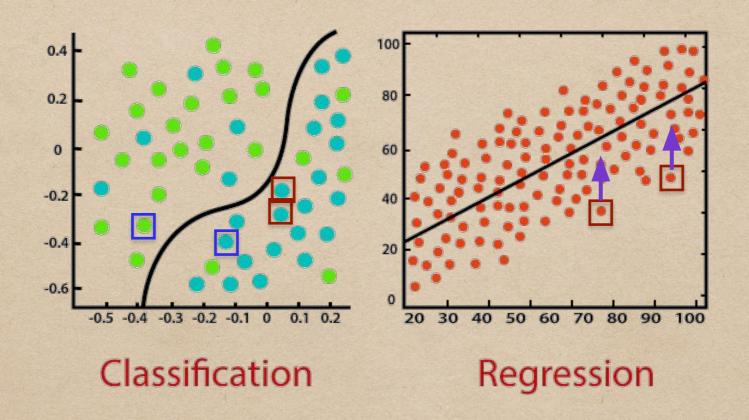
- Al with benign samples
 - all samples correct or (at worst) have random errors

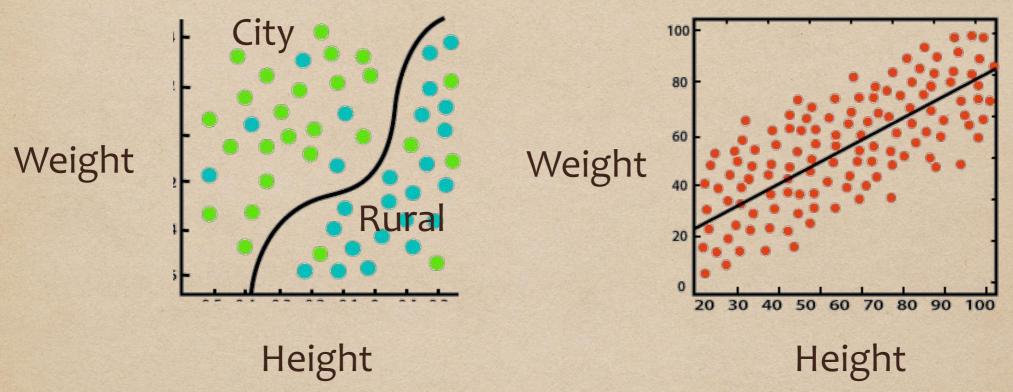
VS

- Al with malicious samples
 - some corrupted samples s.t.
 - bias the learning outcome
 - designed to be undetectable/innocent-looking/indistinguishable.
 Q: Why?

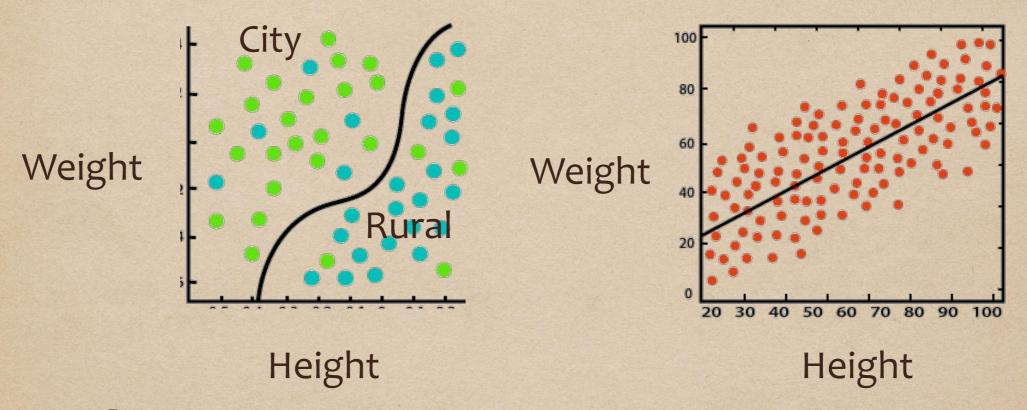
- Al without adversarial attack:
 - samples may be changed due to errors
- AI with adversarial attack:
 - samples intentionally corrupted
 - ?

- AI with adversarial attack:
 - samples intentionally corrupted

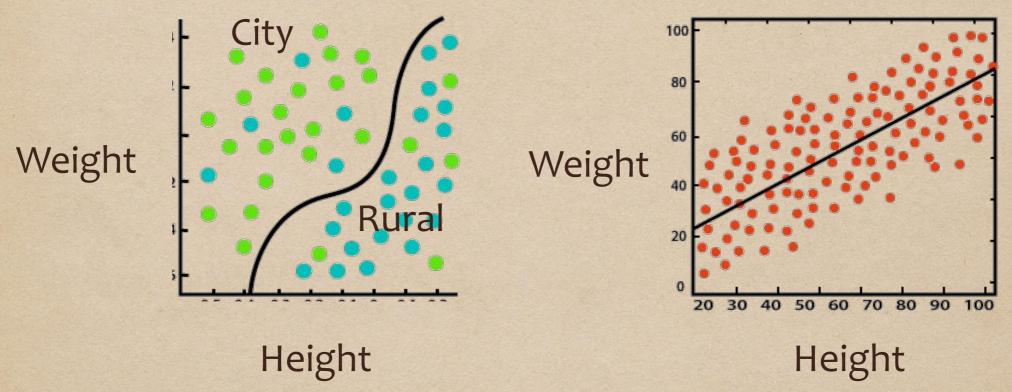




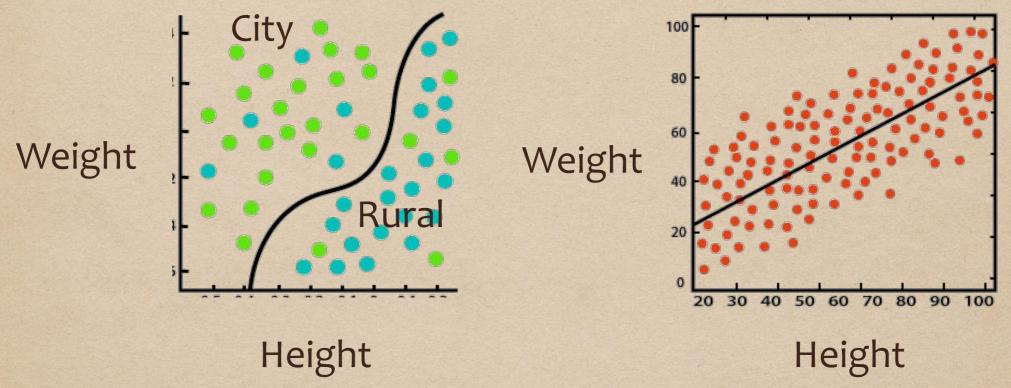
- Classification:
 - learn the boundary, separating classes
 - given unknown class, predict its class based on observed features/attributes



- Classification:
 - e.g. given observed height and weight, predict class/category: s/he's from city or rural?
 - predict discrete value: 0 or 1

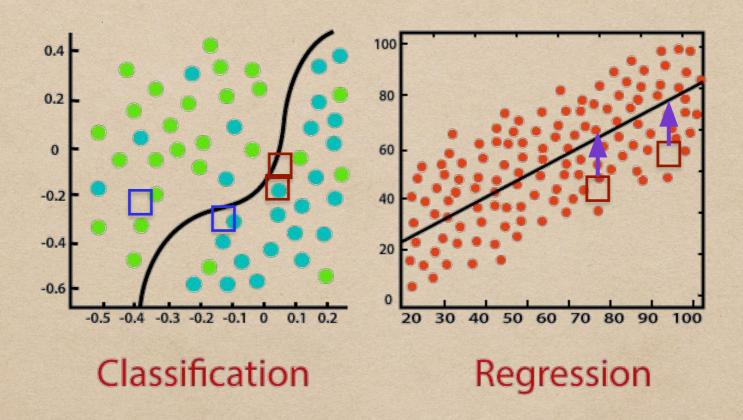


- Regression:
 - learn the function that best represents observed data
 - e.g. Weight depends on Height



- Regression:
 - e.g. given observed Height, predict Weight
 - predict continuous value: Weight

- Al with adversarial attack:
 - samples intentionally corrupted



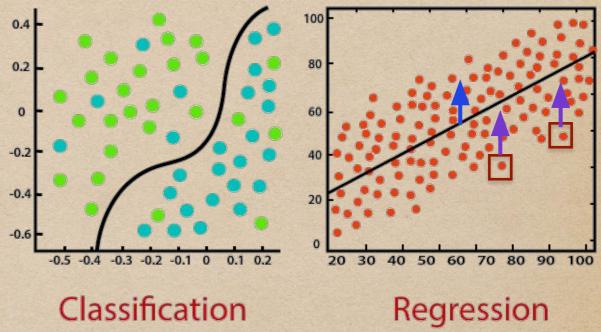
Q: what is the difference between the two cases?
 samples changed in both cases

- Al without adversarial attack: samples may be changed due to errors
 - learning outcome will change in a random manner
 - e.g. class 1 samples misclassified as class 2, class 2
 samples misclassified as class 1
- Al with adversarial attack: samples intentionally corrupted
 - learning outcome will be biased / targetted

An adversarial ML attack

is an attack on the INT security property of the

AI/ML algorithm



- the Means: attacks on AI samples' INT, i.e. samples modified
- the End Goal: attack on AI learning outcome's INT i.e. outcome changed

Adversarial ML

- Adversarial Classification: Dalvi et al. @KDD 2004
- Jul 2024: 1304 citations, 130/year

Adversarial classification

```
N Dalvi, P Domingos, Mausam, S Sanghai... - Proceedings of the tenth ..., 2004 - dl.acm.org
... We define adversarial classification ... Adversary, which attempts to make Classifier
classify positive instances in T as negative by modifying those instances from x to x = A(x). (Adversary ...
☆ Save 切 Cite Cited by 1304 Related articles All 10 versions
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- Can machine learning be secure?: Barreno et al. 2006
- Jul 2024: 1186 citations, 148/year

Can machine learning be secure?

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M Barreno, B Nelson, R Sears, AD Joseph... - Proceedings of the 2006 ..., 2006 - dl.acm.org
... However, machine learning algorithms themselves can ... "Can machine learning be secure?"
Novel contributions of this paper include a taxonomy of different types of attacks on machine ...

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Adversarial DL

- Intriguing properties of neural networks:
 Szegedy et al. (incl Goodfellow) @ICLR 2014
- Jul 2024: 16847 citations, 1684/year

Intriguing properties of neural networks

C Szegedy, W Zaremba, I Sutskever, J Bruna... - arXiv preprint arXiv ..., 2013 - arxiv.org
... neural networks learn input-output mappings that are fairly discontinuous to a significant
extent. We can cause the network to ... D has the following intriguing properties which we will sup...

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On the Limitation of Convolutional Neural Networks in Recognizing Negative Images

Hosseini, Baicen Xiao, Mayoore Jaiswal and Radha Poovendran
Network Security Lab (NSL), Department of Electrical Engineering, University of Washington, Seattle, WA

{hosseinh, bcxiao, mayoore, rp3}@uw.edu

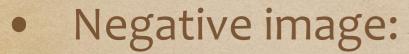
Abstract—Convolutional Neural Networks (CNNs) have chieved state-of-the-art performance on a variety of computer ision tasks, particularly visual classification problems, where ew algorithms reported to achieve or even surpass the human erformance. In this paper, we examine whether CNNs are apable of learning the semantics of training data. To this end, re evaluate CNNs on negative images, since they share the same tructure and semantics as regular images and humans can lassify them correctly. Our experimental results indicate that then training on regular images and testing on negative images, ne model accuracy is significantly lower than when it is tested in regular images. This leads us to the conjecture that current raining methods do not effectively train models to generalize the



https://arxiv.org/pdf/1703.06857.pdf

- Can Convolutional Neural Network (CNN) learn semantics of training samples?
- Gist of Semantic adversarial samples: semantically the same as original, but otherwise quite different, e.g.

negative images



- share same semantics & structure as regular image, humans can easily classify
- reversed brightness, large pixel-wise perturbation



- Negative image:
 - reversed brightness, large pixel-wise perturbation, though semantically same
 - e.g. consider a grayscale pixel:
 - o = black, (max) 255 = white
 - reverse the brightness: max-pixelvalue
 - black \rightarrow white: 0 \rightarrow 255-0 = 255
 - white→black: 255 → 255-255 = 0

- Limitation of DL based training
 - networks trained to memorise inputs, but not really learn the object structures, so cannot semantically differentiate
 - if test samples not distributed like training samples, won't work well: aka out-of-distribution (OOD) attack
 - Q: for negative images case, why it is OOD?
- Accuracy (measure) as performance metric not adequate
- Q: what is a good metric to measure performance in this case?

Noise Attack

- naïve untargetted black box attack
 - simply add random noise to affect the learning outcome
 - untargetted: not aiming to bias the outcome towards something specific, just be different
 - black box: not need info on the ML model
 - Q: is the semantic adversarial attack
 - an untargeted attack?
 - a black box attack?

Fast Gradient Signed (FGS) Method

- Goodfellow et al. Explaining & Harnessing Adversarial Examples @ICLR 2015
- Jul 2024: 21192 citations, 2354/year

Explaining and harnessing adversarial examples

IJ Goodfellow, J Shlens, C Szegedy arXiv preprint arXiv:1412.6572, 2014 - arxiv.org



Ian Goodfellow

DeepMind Verified email at deepmind.com Deep Learning

Several machine learning models, including neural networks, consistently misclassify adversarial examples---inputs formed by applying small but intentionally worst-case perturbations to examples from the dataset, such that the perturbed input results in the model outputting an incorrect answer with high confidence. Early attempts at explaining this phenomenon focused on nonlinearity and overfitting. We argue instead that the primary cause of neural networks' vulnerability to adversarial perturbation is their linear

SHOW MORE Y

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Generative Adversarial Networks

Generative adversarial nets

I Goodfellow, J Pouget-Abadie ... - Advances in neural ..., 2014 - proceedings.neurips.cc

... We propose a new framework for estimating generative models via adversarial nets, in which we simultaneously train two models: a generative model G that captures the data ...

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Ian Goodfellow

DeepMind Verified email at deepmind.com Deep Learning

- Aug 2023: 58748 citations, +12000/year
- Aug 2022: 47467 citations, +14000/year

Fast Gradient Sign (FGS) Method

 Paper: Goodfellow et al.: Explaining and Harnessing Adversarial Examples @ICLR 2015

Explaining and harnessing adversarial examples

IJ Goodfellow, J Shlens, C Szegedy arXiv preprint arXiv:1412.6572, 2014 - arxiv.org

Several machine learning models, including neural networks, consistently misclassify adversarial examples---inputs formed by applying small but intentionally worst-case perturbations to examples from the dataset, such that the perturbed input results in the model outputting an incorrect answer with high confidence. Early attempts at explaining this phenomenon focused on nonlinearity and overfitting. We argue instead that the primary cause of neural networks' vulnerability to adversarial perturbation is their linear

SHOW MORE Y

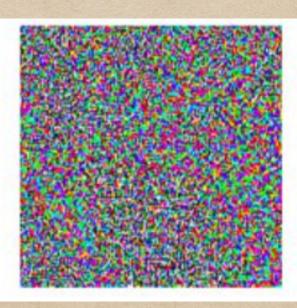
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Fast Gradient Sign (FGS) Method

- a white box attack:
 - attacker has complete access to the victim model
- add small perturbations/distortions δ until the classifier labels it as different class/category:
 - $x' = x + \delta$



+.007 ×



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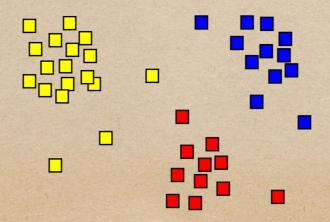
- supervised learning
 - given labelled samples $\{(x_i, y_i)\}$
- classification (y_i denotes the label of x_i): learn the mapping $f: X \to Y$, & given test sample x with $g: X \to Y$ of ground truth label $g: X \to Y$, predict its label $g: X \to Y$
 - * regression (y_i denotes the variable dependent on x_i): learn the mapping $f: X \to Y$, & given test sample x with ground truth variable y, predict its corresponding dependent variable \hat{y}

- supervised learning
 - given labelled samples $\{(x_i, y_i)\}$
 - classification (y_i denotes the label of x_i): learn the mapping $f: X \to Y$, & given test sample x with ground truth label y, predict its label \hat{y}
 - regression (y_i denotes the variable dependent on x_i): learn the mapping $f: X \to Y$, & given test sample x with ground truth variable y, predict its corresponding dependent variable \hat{y}

- unsupervised
 - given n unlabelled samples $\{x_i\}$, look for patterns
 - clustering: partition into k subsets S, s.t.

minimize:
$$\sum_{j=1}^{k} \sum_{i=1}^{n} ||x_i^{(j)} - c_j||^2$$

where c, is the centroid for cluster j



- loss(distance)/cost function J
 - distance between actual y & predicted ŷ
- Mean Squared Error (MSE)

$$MSE = \frac{1}{n} \sum (y_i - \hat{y}_i)^2$$

Root MSE (L2 norm)

$$RMSE = \sqrt{\sum_{i=1}^{n} \frac{(\hat{y}_i - y_i)^2}{n}}$$

- loss/cost function J
 - distance between actual y & predicted ŷ
- Mean Absolute Error (MAE) (based on L1 norm)

$$MAE = \frac{\sum_{i=1}^{n} |y_i - \hat{y}_i|}{n}$$

Mean Bias Error (MBE)

$$MBE = \frac{\sum_{i=1}^{n} (y_i - \hat{y}_i)}{n}$$

- loss/cost function J
 - distance between actual & predicted
- Cross Entropy (Negative Log Likelihood) loss

$$-\sum_i y_i \log(\hat{y}_i)$$

where y_i is the actual and \hat{y}_i is the predicted

Fast Gradient Sign (FGS) Method

• perturbation: use gradient ∇ of the loss J wrt the input image x, aiming to maximize that loss J

•
$$x' = x + \delta = x + \varepsilon * sign(\nabla_x J(\theta, x, y))$$

- y = original label of input image x
- ε = multiplier (learning rate) to keep the perturbation small
- θ = model parameters
- J = loss

partial derivative (in the direction of the axes)

e.g. $\frac{\partial f}{\partial x}$ means rate of change along direction of x-axis.

Q: rate of change in direction not along axes?

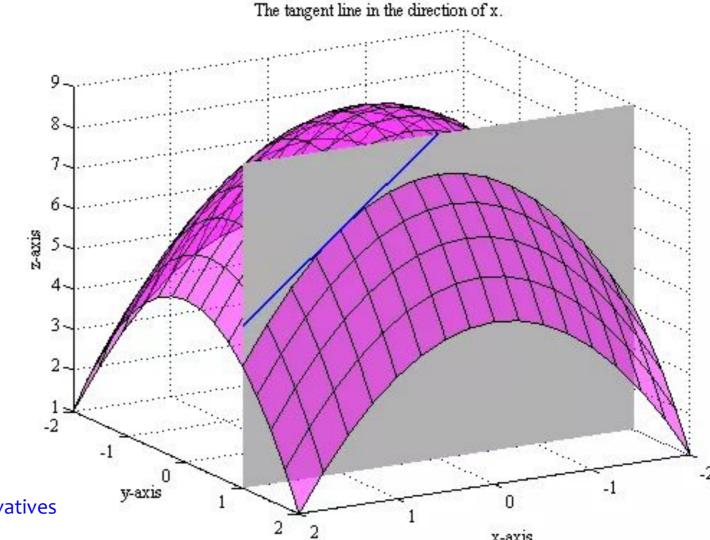
- directional derivative (in the direction denoted by u)
 - u = unit vector i.e. ||u|| = 1 representing any direction

partial derivative (in the direction of the axes)

 ∂f

e.g. ∂x means rate of change along direction of

x-axis:

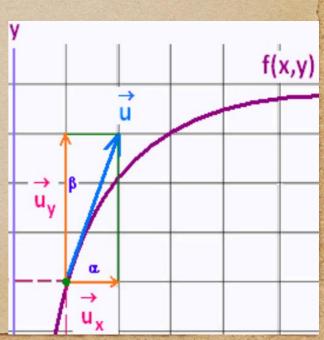


https://www.wikihow.com/Take-Partial-Derivatives

- partial derivative (in the direction of the axes)
 e.g. means rate of change along direction of
 x-axis. Q: rate of change in direction not along axes?
- directional derivative (in the direction denoted by u)
 - u = unit vector i.e. ||u|| = 1, representing any direction

$$D_{\mathbf{u}}f(\mathbf{a}) = \lim_{h \to 0} \frac{f(\mathbf{a} + h\mathbf{u}) - f(\mathbf{a})}{h}$$

• i.e. @ point a: when tiny change h in the direction of u, f(a) changes to f(a + hu)



directional derivative

$$D_{\mathbf{u}}f(\mathbf{a}) = \nabla f(\mathbf{a}) \cdot \mathbf{u} = ||\nabla f(\mathbf{a})|| \cos \theta$$

- this has max value when $\theta = 0$ (i.e. gradient ∇f in the same direction as u) since max of $\cos \theta = \cos \theta = 1$
 - ∇f ($-\nabla f$) points in direction of greatest increase of f, i.e. direction of steepest ascent (descent)

• Note: gradient $\nabla f(a)$ (is a vector) $\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial u}\right)$

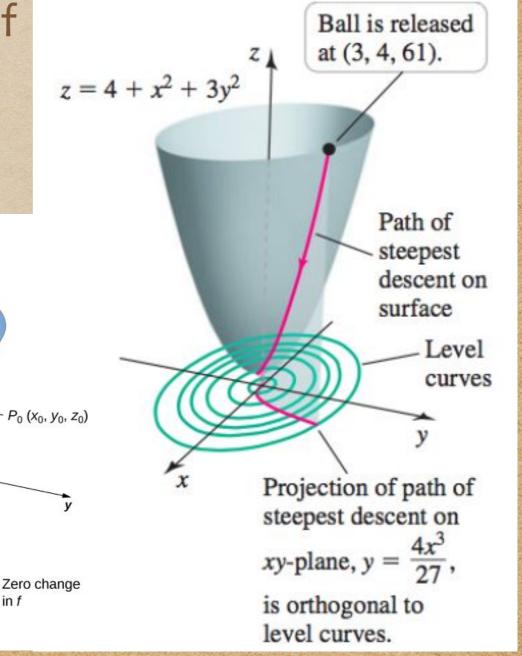
Most rapid / decrease in f

Most rapid

increase in f

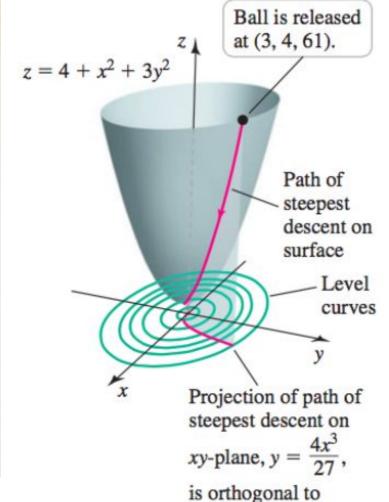
 direction of steepest ascent/descent

> ∇f (-∇f) points in direction of greatest increase of f, i.e. direction of steepest ascent (descent)



ML points*

direction of steepest ascent/descent



level curves.

EXAMPLE 7 Path of steepest descent Consider the paraboloid $z = f(x, y) = 4 + x^2 + 3y^2$ (Figure 13.73). Beginning at the point (3, 4, 61) on the surface, find the path in the xy-plane that points in the direction of steepest descent on the surface.

SOLUTION Imagine releasing a ball at (3, 4, 61) and assume that it rolls in the direction of steepest descent at all points. The projection of this path in the xy-plane points in the direction of $-\nabla f(x,y) = \langle -2x, -6y \rangle$, which means that at the point (x,y) the line tangent to the path has slope y'(x) = (-6y)/(-2x) = 3y/x. Therefore, the path in the xy-plane satisfies y'(x) = 3y/x and passes through the initial point (3,4). You can verify that the solution to this differential equation is $y = 4x^3/27$ and the projection of the path of steepest descent in the xy-plane is the curve $y = 4x^3/27$. The descent ends at (0,0), which corresponds to the vertex of the paraboloid (Figure 13.73). At all points of the descent, the curve in the xy-plane is orthogonal to the level curves of the surface.

- direction of steepest ascent/descent
 - ∇f (- ∇f) points in direction of greatest increase of f, i.e. direction of steepest ascent (descent)

• e.g.
$$f(x,y) = 4 + x^2 + 3y^2$$

•
$$\nabla f = (\partial f/\partial x, \partial f/\partial y) = (2x, 6y)$$

$$\bullet \quad -\nabla f = (-2x, -6y)$$

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}\right)$$

- slope dy/dx of this gradient:
 - dy/dx = (-6y)/(-2x) = 3y/x
 - solve this differential equation:
 - ...
 - $y = (4x^3)/(27)$

Fast Gradient Sign (FGS) Method

- perturbation: use gradient ∇ of the loss J wrt the input image x, aiming to maximize that loss
 - $x' = x + \delta = x + \varepsilon * sign(\nabla_x J(\theta, x, y))$

$$adv_x = x + \varepsilon * signedGrad$$

- ∇_x : Gradient only wrt x because model already trained, so parameters θ constant
- $\nabla_x J(\cdot,x,\cdot)$:

gradient = tape.gradient(J,x)

• sign($\nabla_x J(\cdot,x,\cdot)$):

signedGrad = tf.sign(gradient)

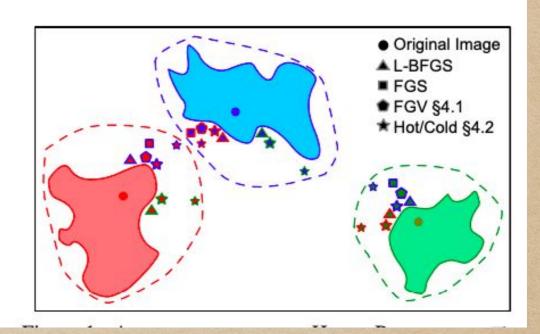
Fast Gradient Value (FGV) Method

Adversarial Diversity and Hard Positive Generation

Andras Rozsa, Ethan M. Rudd, and Terrance E. Boult*
University of Colorado at Colorado Springs
Vision and Security Technology (VAST) Lab
{arozsa,erudd,tboult}@vast.uccs.edu

Abstract

State-of-the-art deep neural networks suffer from a fundamental problem – they misclassify adversarial examples formed by applying small perturbations to inputs. In this paper, we present a new psychometric perceptual adversarial similarity score (PASS) measure for quantifying adversarial images, introduce the notion of hard positive generation, and use a diverse set of adversarial perturbations – not just the closest ones – for data augmentation. We introduce a novel hot/cold approach for adversarial example generation, which provides multiple possible adversarial pertur-



Fast Gradient Value (FGV) Method

• perturbation: use gradient ∇ of the loss J wrt the input image x, aiming to maximise that loss

•
$$x' = x + \delta = x + \varepsilon * sign(\nabla_x J(\theta, x, y)) \leftrightarrow FGS$$

•
$$x' = x + \delta = x + \varepsilon * \nabla_x J(\theta, x, y)$$
 $\longleftrightarrow FGV$

Recent Adversarial Attacks on AI

- https://proceedings.neurips.cc/paper_files/paper/2023/ hash/a97b58c4f7551053b0512f92244b0810-Abstract-C onference.html?
- https://ojs.aaai.org/index.php/AAAI/article/view/26739
- https://arxiv.org/abs/2403.09766
- https://arxiv.org/abs/2402.09132
- https://arxiv.org/abs/2402.15911
- https://openaccess.thecvf.com/content/CVPR2024/ht ml/Li_One_Prompt_Word_is_Enough_to_Boost_Adversarial_Robustness_for_CVPR_2024_paper.html
- https://arxiv.org/abs/2305.14950
- https://arxiv.org/abs/2406.04031
- https://proceedings.mlr.press/v239/schwinn23a.html