

Motor Pins

enable A = 6

forward A = 50

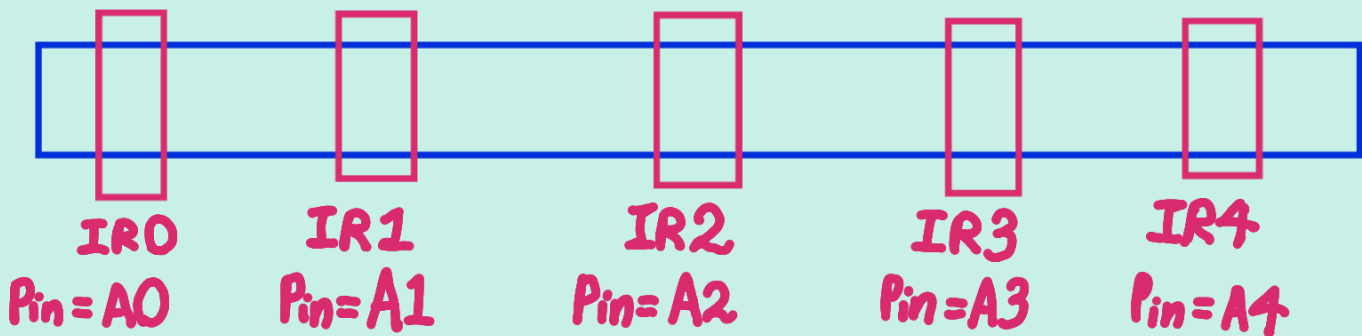
backwards A = 51

enable B = 7

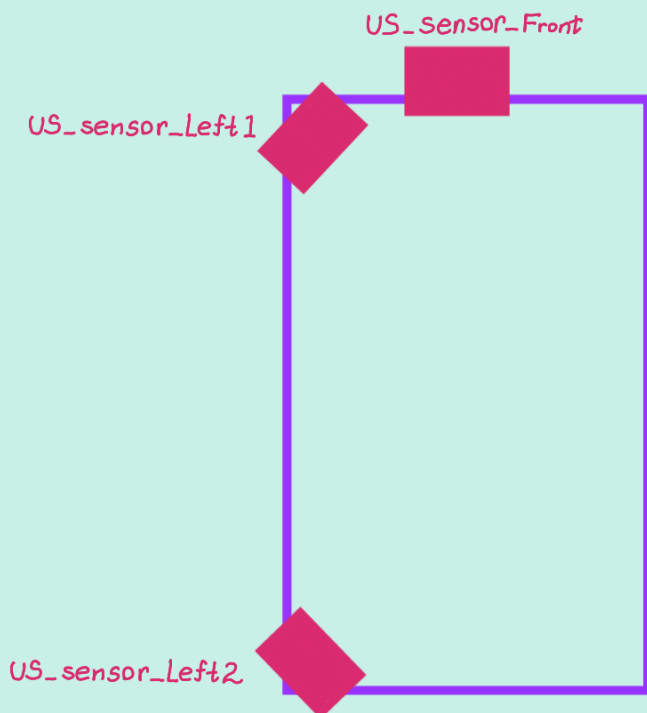
forward B = 53

backwards B = 52

IR Sensor Pins



Ultrasonic Sensor Pins



US_sensor_Front $\left\{ \begin{array}{l} \text{Trig} = 22 \\ \text{Echo} = 24 \end{array} \right.$

US_sensor_Left1 $\left\{ \begin{array}{l} \text{Trig} = 26 \\ \text{Echo} = 28 \end{array} \right.$

US_sensor_Left2 $\left\{ \begin{array}{l} \text{Trig} = 30 \\ \text{Echo} = 32 \end{array} \right.$

US_sensor_right1 $\left\{ \begin{array}{l} \text{Trig} = 34 \\ \text{Echo} = 36 \end{array} \right.$

US_sensor_right2 $\left\{ \begin{array}{l} \text{Trig} = 38 \\ \text{Echo} = 40 \end{array} \right.$

Potentiometer Pins for tuning

$K_p_potentiometer = A8$

$K_d_potentiometer = A10$

$Basespeed_potentiometer = A12$