Derivative of the first order SVD

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Consider computing the first order SVD expansion. By the Eckart–Young–Mirsky theorem, this is equivalent to solving

$$\underset{\sigma, u, v}{\operatorname{minimize}} \, \frac{1}{2} \|A - \sigma u v^{\top}\|_F^2 \quad \text{s.t.} \quad \|u\| = 1 \quad \text{and} \quad \|v\| = 1$$

Any triplet (σ, u, v) for a **unique** singular value satisfies

$$\sigma = u^{\top} A v$$
$$A v = \sigma u$$
$$A^{\top} u = \sigma v$$

from this we can derive

$$\Delta \sigma = \Delta u^{\top} A v + u^{\top} \Delta A v + u^{\top} A \Delta v$$
$$= \Delta u^{\top} u + u^{\top} \Delta A v + v^{\top} \Delta v$$
$$= u^{\top} \Delta A v$$

Where in the last step we used $\Delta u \perp u$ and $\Delta v \perp v$, which follows from the side condition. Further we have:

$$\begin{array}{c} \Delta A v + A \Delta v = \Delta \sigma u + \sigma \Delta u \\ \Delta A^\top u + A^\top \Delta u = \Delta \sigma v + \sigma \Delta v \end{array} \Longleftrightarrow \underbrace{ \begin{bmatrix} \sigma \mathbb{I}_m & -A \\ -A^\top & \sigma \mathbb{I}_n \end{bmatrix}}_{=:K} \cdot \begin{bmatrix} \Delta u \\ \Delta v \end{bmatrix} = \begin{bmatrix} \Delta A v - \Delta \sigma u \\ \Delta A^\top u - \Delta \sigma v \end{bmatrix}$$

1 The VJP

The last equation allows us to compute the VJP at ease:

$$\begin{split} \left\langle \begin{bmatrix} \phi \\ \psi \end{bmatrix} \mid \begin{bmatrix} \Delta u \\ \Delta v \end{bmatrix} \right\rangle &= \left\langle \begin{bmatrix} \phi \\ \psi \end{bmatrix} \mid K^{-1} \begin{bmatrix} \Delta A v - \Delta \sigma u \\ \Delta A^\top u - \Delta \sigma v \end{bmatrix} \right\rangle \\ &= \left\langle K^{-\top} \begin{bmatrix} \phi \\ \psi \end{bmatrix} \mid \begin{bmatrix} \Delta A v - \Delta \sigma u \\ \Delta A^\top u - \Delta \sigma v \end{bmatrix} \right\rangle \\ &= \left\langle \begin{bmatrix} \tilde{\phi} \\ \tilde{\psi} \end{bmatrix} \mid \begin{bmatrix} \Delta A v - \Delta \sigma u \\ \Delta A^\top u - \Delta \sigma v \end{bmatrix} \right\rangle \end{split}$$

Now, we compute the terms individually:

$$\begin{split} \langle \tilde{\phi} \mid \Delta A v - \Delta \sigma u \rangle &= \langle \tilde{\phi} v^\top \mid \Delta A \rangle - \langle u^\top \tilde{\phi} \mid \Delta \sigma \rangle \\ &= \langle \tilde{\phi} v^\top \mid \Delta A \rangle - \langle u^\top \tilde{\phi} \mid u^\top \Delta A v \rangle \\ &= \langle (\mathbb{I}_m - u u^\top) \tilde{\phi} v^\top \mid \Delta A \rangle \end{split}$$

And for the second term we get

$$\begin{split} \langle \tilde{\psi} \mid \Delta A^\top u - \Delta \sigma v \rangle &= \langle \tilde{\psi} u^\top \mid \Delta A^\top \rangle - \langle v^\top \tilde{\psi} \mid \Delta \sigma \rangle \\ &= \langle u \tilde{\psi}^\top \mid \Delta A \rangle - \langle \tilde{\psi}^\top v \mid u^\top \Delta A v \rangle \\ &= \langle u \tilde{\psi} (\mathbb{I}_n - v v^\top) \mid \Delta A \rangle \end{split}$$

Using the formula for inverting a block-matrix, we can give an explicit solution to $K^{-\top}$:

$$\begin{bmatrix} \sigma \mathbb{I}_m & -A \\ -A^\top & \sigma \mathbb{I}_n \end{bmatrix}^{-1} = \begin{bmatrix} (\sigma \mathbb{I}_m - \frac{1}{\sigma} A A^\top)^{-1} & \mathbf{0}_{m \times n} \\ \mathbf{0}_{n \times m} & (\sigma \mathbb{I}_n - \frac{1}{\sigma} A^\top A)^{-1} \end{bmatrix} \cdot \begin{bmatrix} \mathbb{I}_m & \frac{1}{\sigma} A \\ \frac{1}{\sigma} A^\top & \mathbb{I}_n \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{\sigma} (\mathbb{I}_m - \frac{1}{\sigma^2} A A^\top)^{-1} & \frac{1}{\sigma^2} (\mathbb{I}_m - \frac{1}{\sigma^2} A A^\top)^{-1} A \\ \frac{1}{\sigma^2} (\mathbb{I}_n - \frac{1}{\sigma^2} A^\top A)^{-1} A^\top & \frac{1}{\sigma} (\mathbb{I}_n - \frac{1}{\sigma^2} A^\top A)^{-1} \end{bmatrix}$$

$$= \frac{1}{\sigma} \begin{bmatrix} (\mathbb{I}_m - \tilde{A} \tilde{A}^\top)^{-1} & (\mathbb{I}_m - \tilde{A} \tilde{A}^\top)^{-1} \tilde{A} \\ (\mathbb{I}_n - \tilde{A}^\top \tilde{A})^{-1} \tilde{A}^\top & (\mathbb{I}_n - \tilde{A}^\top \tilde{A})^{-1} \end{bmatrix}$$

And we see it's basically projection operators with respect to the image/kernel of $\tilde{A} = \frac{1}{\sigma}A$. In summary, we obtain the following formula for the VJP:

$$\begin{bmatrix} \sigma \mathbb{I}_m & -A \\ -A^\top & \sigma \mathbb{I}_n \end{bmatrix}^{-\top} \begin{bmatrix} \tilde{\phi} \\ \tilde{\psi} \end{bmatrix} = \begin{bmatrix} \phi \\ \psi \end{bmatrix} \iff \begin{bmatrix} \tilde{\phi} \\ \tilde{\psi} \end{bmatrix} = \frac{1}{\sigma} \begin{bmatrix} (\mathbb{I}_m - \tilde{A}\tilde{A}^\top)^{-1} & (\mathbb{I}_m - \tilde{A}\tilde{A}^\top)^{-1}\tilde{A} \\ (\mathbb{I}_n - \tilde{A}^\top\tilde{A})^{-1}\tilde{A}^\top & (\mathbb{I}_n - \tilde{A}^\top\tilde{A})^{-1} \end{bmatrix}^\top \begin{bmatrix} \phi \\ \psi \end{bmatrix} \\ \iff \begin{bmatrix} \tilde{\phi} \\ \tilde{\psi} \end{bmatrix} = \frac{1}{\sigma} \begin{bmatrix} (\mathbb{I}_m - \tilde{A}\tilde{A}^\top)^{-1} & \tilde{A}(\mathbb{I}_n - \tilde{A}^\top\tilde{A})^{-1} \\ \tilde{A}^\top (\mathbb{I}_m - \tilde{A}\tilde{A}^\top)^{-1} & (\mathbb{I}_n - \tilde{A}^\top\tilde{A})^{-1} \end{bmatrix} \begin{bmatrix} \phi \\ \psi \end{bmatrix}$$

Thus, we need to solve 4 linear systems:

$$(\mathbb{I}_m - \tilde{A}\tilde{A}^\top)x = \phi \qquad (\mathbb{I}_n - \tilde{A}^\top\tilde{A})y = \tilde{A}\psi$$
$$(\mathbb{I}_m - \tilde{A}\tilde{A}^\top)z = \tilde{A}^\top\phi \qquad (\mathbb{I}_n - \tilde{A}^\top\tilde{A})w = \psi$$

Then $\tilde{\phi} = \frac{1}{\sigma}(x+y)$ and $\tilde{\psi} = \frac{1}{\sigma}(z+w)$, and the VJP are given by the previous equations:

$$\xi^{\top} \frac{\partial \sigma}{\partial A} = \xi u v^{\top}$$

$$\phi^{\top} \frac{\partial u}{\partial A} = (\mathbb{I}_m - u u^{\top}) \tilde{\phi} v^{\top}$$

$$\psi^{\top} \frac{\partial v}{\partial A} = u \tilde{\psi} (\mathbb{I}_n - v v^{\top})$$