

Border Guard Authorities - Industry meeting

Warsaw, 21.11.2018

Advanced features for Surveillance and Border Control Systems in the e-Navigation framework



Remember ?



14 April 1912

Forget the Crew, Drone Ships are here!

A Brief History 1

The first **radar based Port Control** station was established in Douglas, Isle of Man, in 1948.

Later the same year, the port of Liverpool established a radar site and similar trials took place in Rotterdam.



In 1950, a number of **shore-based radar** chains were established in other European ports, including the approaches to the port of Amsterdam in 1952 and the entire Rotterdam port area in 1956.



The idea of a Vessel Traffic Services (VTS) system comes by evidence of needs of **safety** and **efficiency** for vessels in port areas and their approaches, that traditional lighthouses and sound signals cannot guarantee

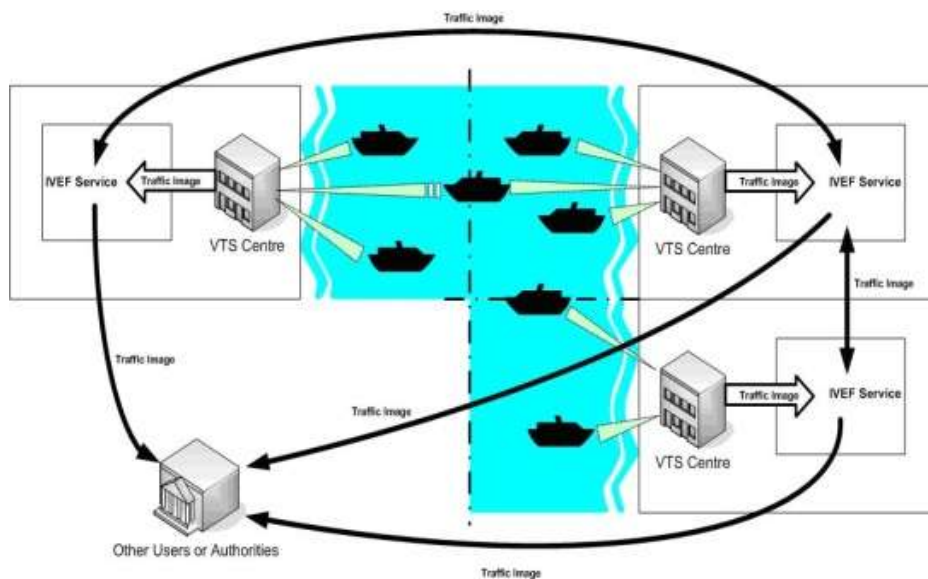
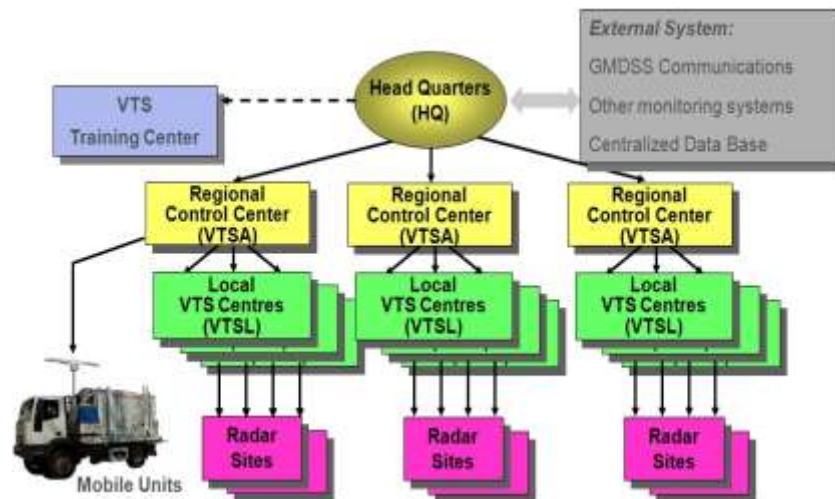
- Safety: reduce number of shipping accidents in port's approaches/areas
- Efficiency: increase traffic flows per time unit, avoid traffic delays, provide better port's capacity utilization (increasing port's operational hours)



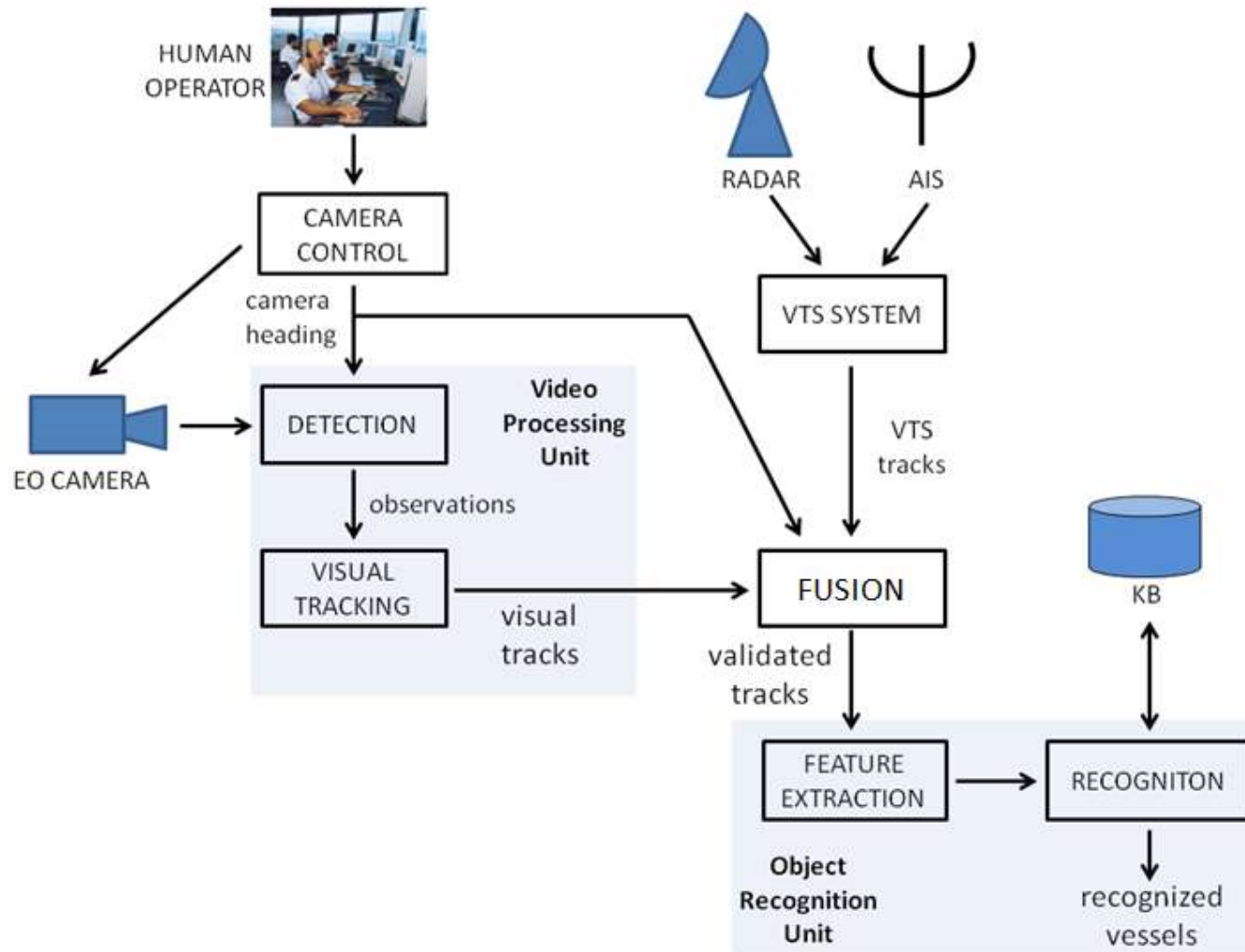
Early VTS systems were composed by just a primary **RADAR** and a **VHF radio**, by the meanings of communication among ships/base stations



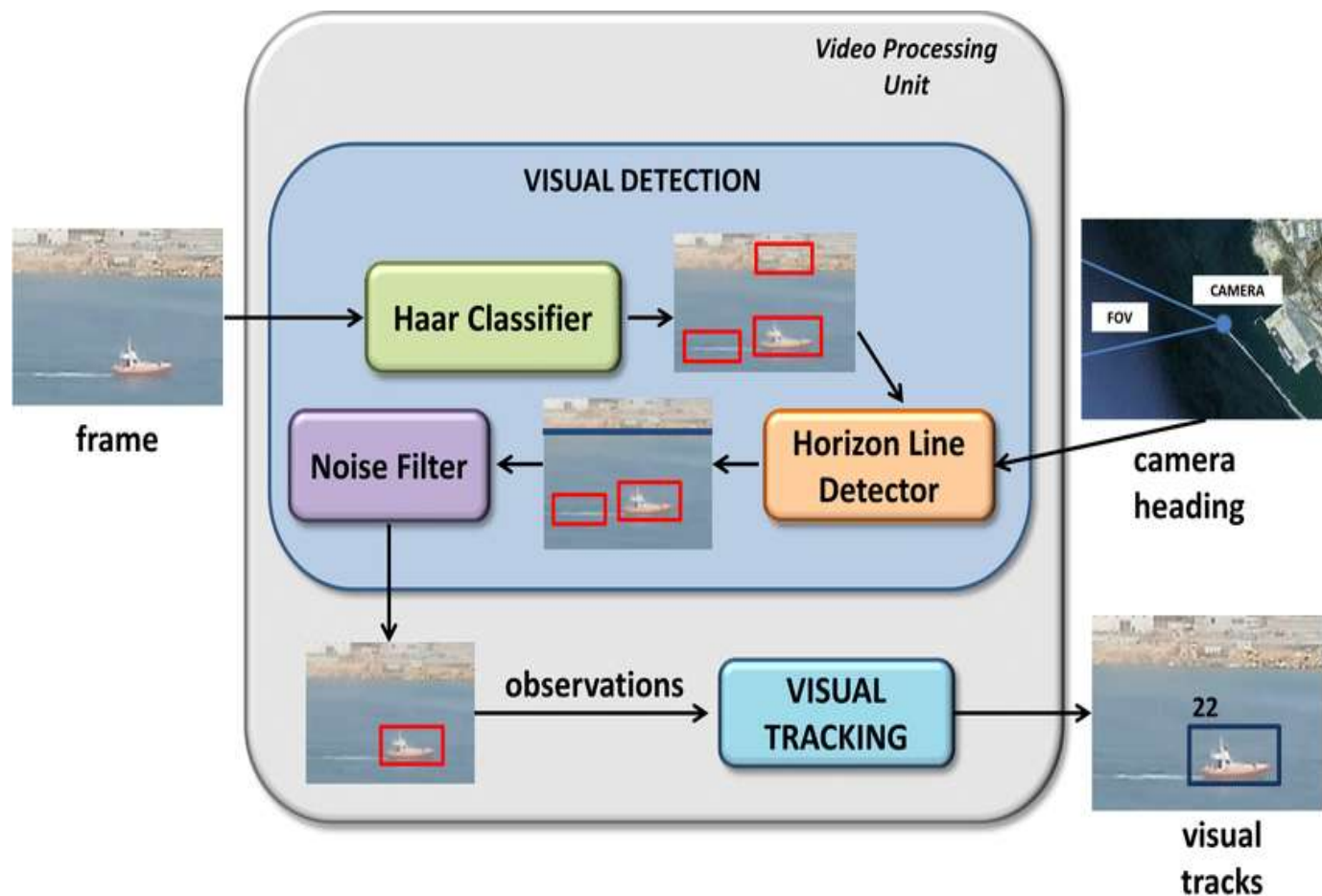
VTS - Evolution



BACKGROUND

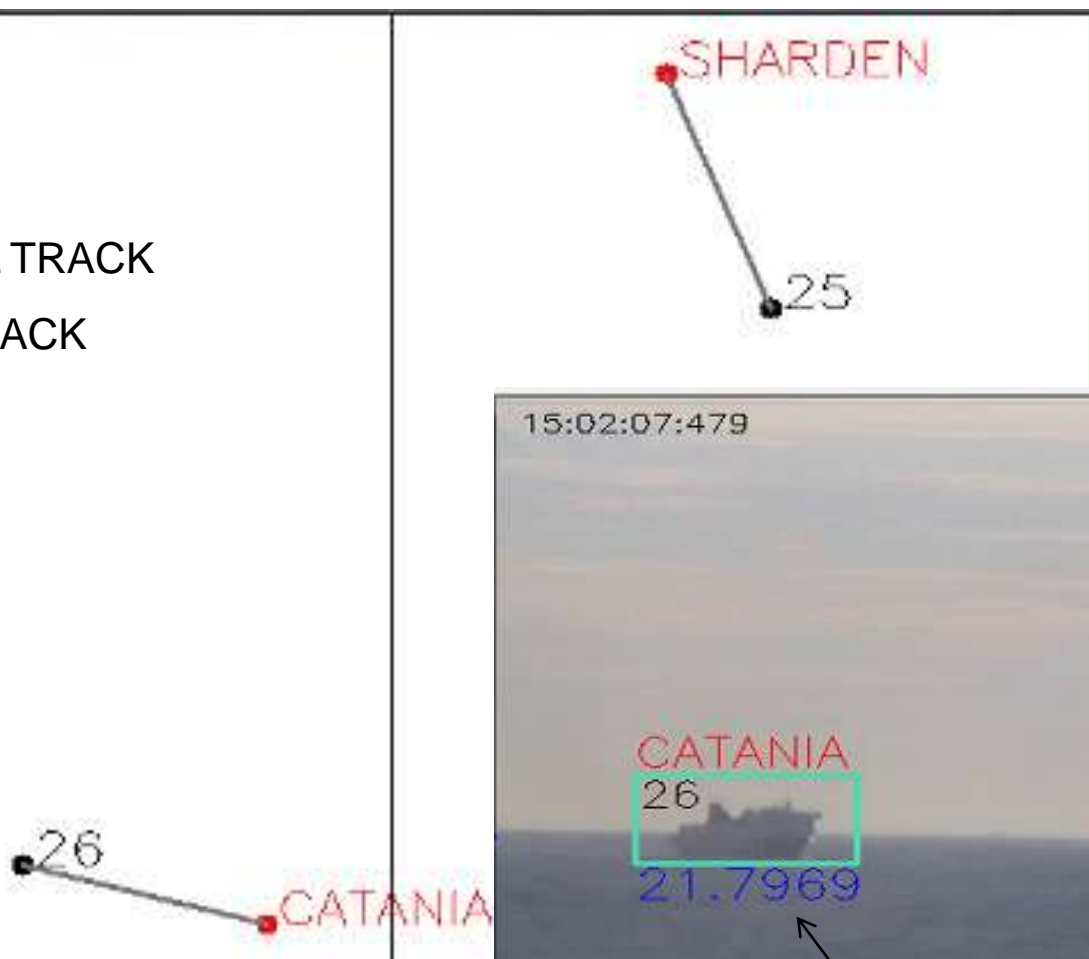


Video Processing Unit



DATA ASSOCIATION

- VISUAL TRACK
- VTS TRACK

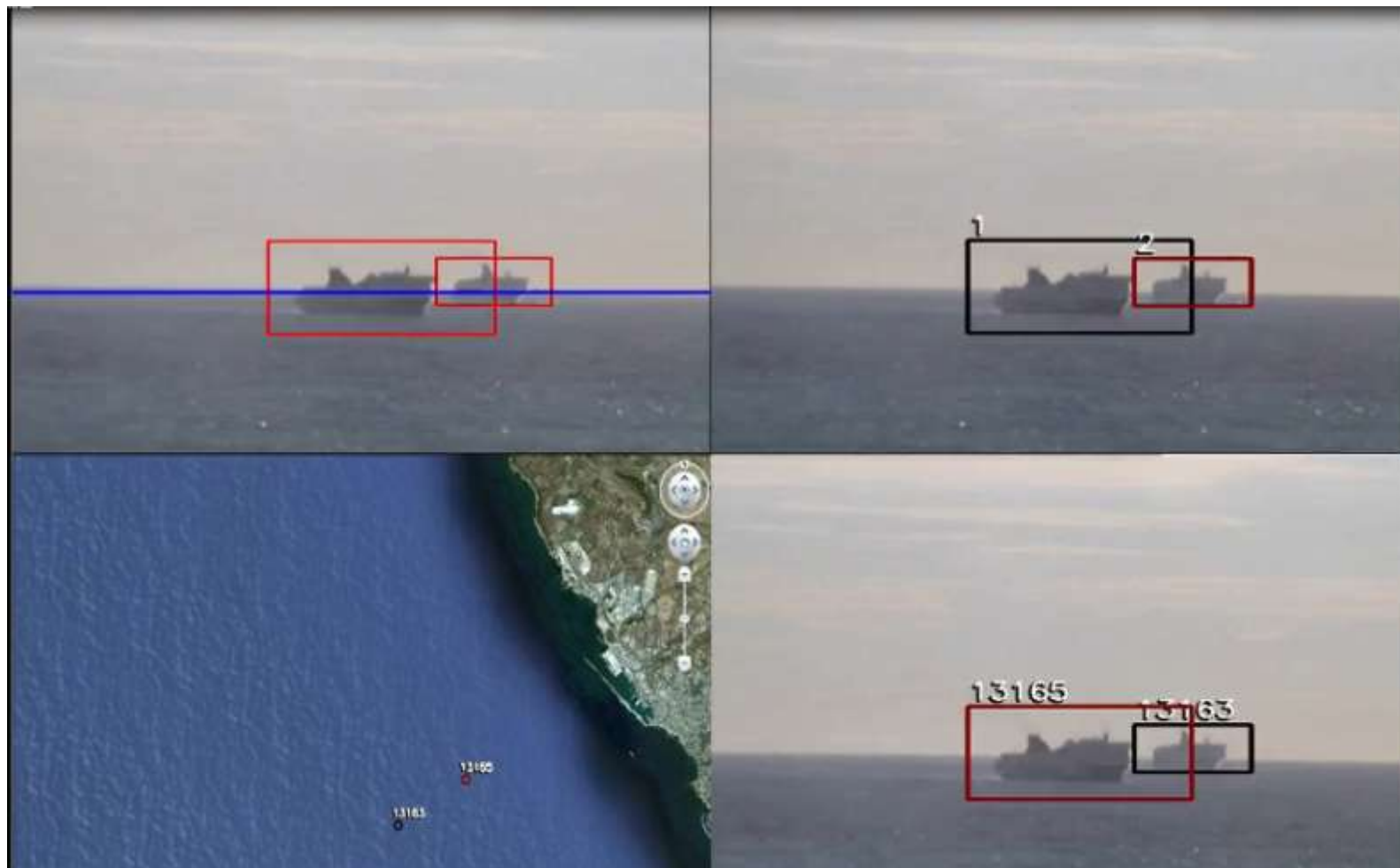


SHIP HEADING

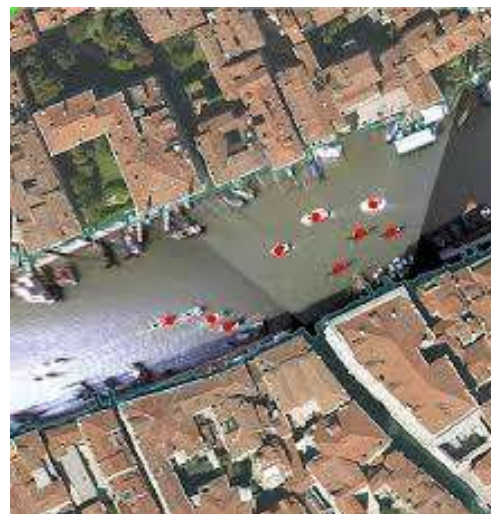
Test – X Path (Robustness)



Data Fusion with AIS

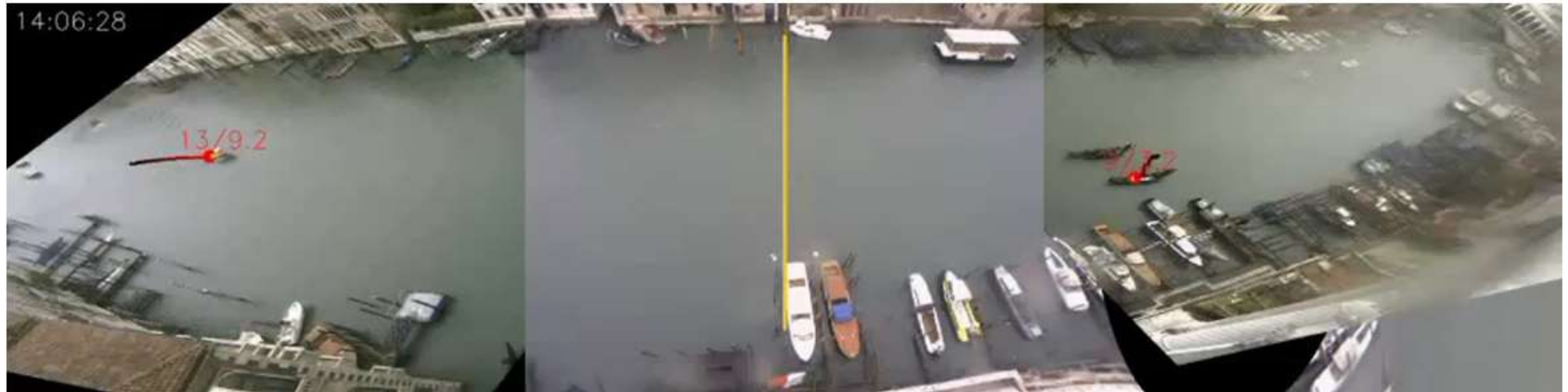


ARGOS SYSTEM



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ARGOS SYSTEM



MarDCT database

Maritime Detection, Classification, and Tracking database



The aim of MarDCT is to provide visual data that can be used to help in developing **intelligent surveillance system** for the maritime environment.

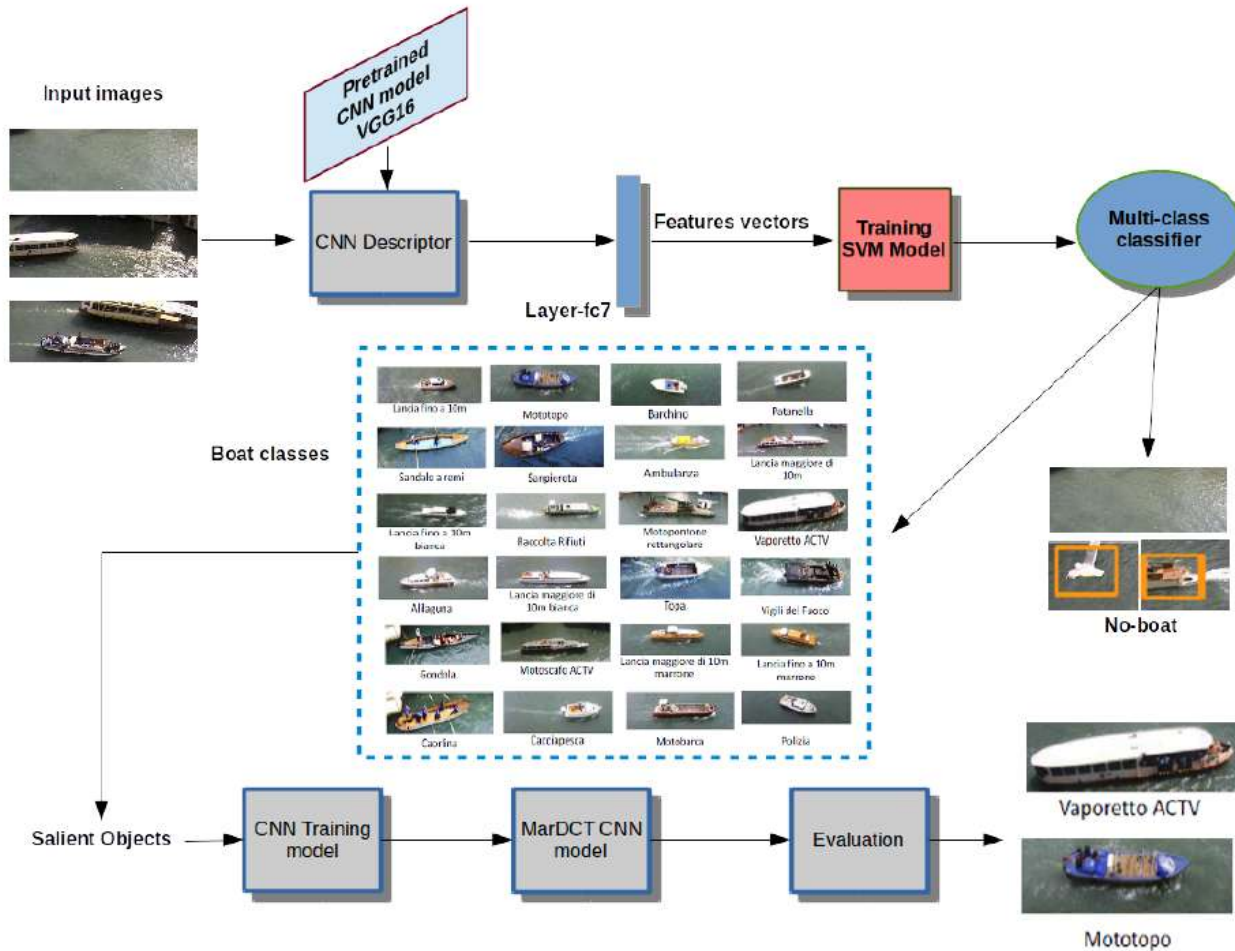
The data sets are divided according to the type of Ground Truth in:

- Detection
- Tracking
- Classification

FUNCTIONAL ARCHITECTURE



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CLASSIFICATION

CORRECTLY CLASSIFIED
INSTANCES



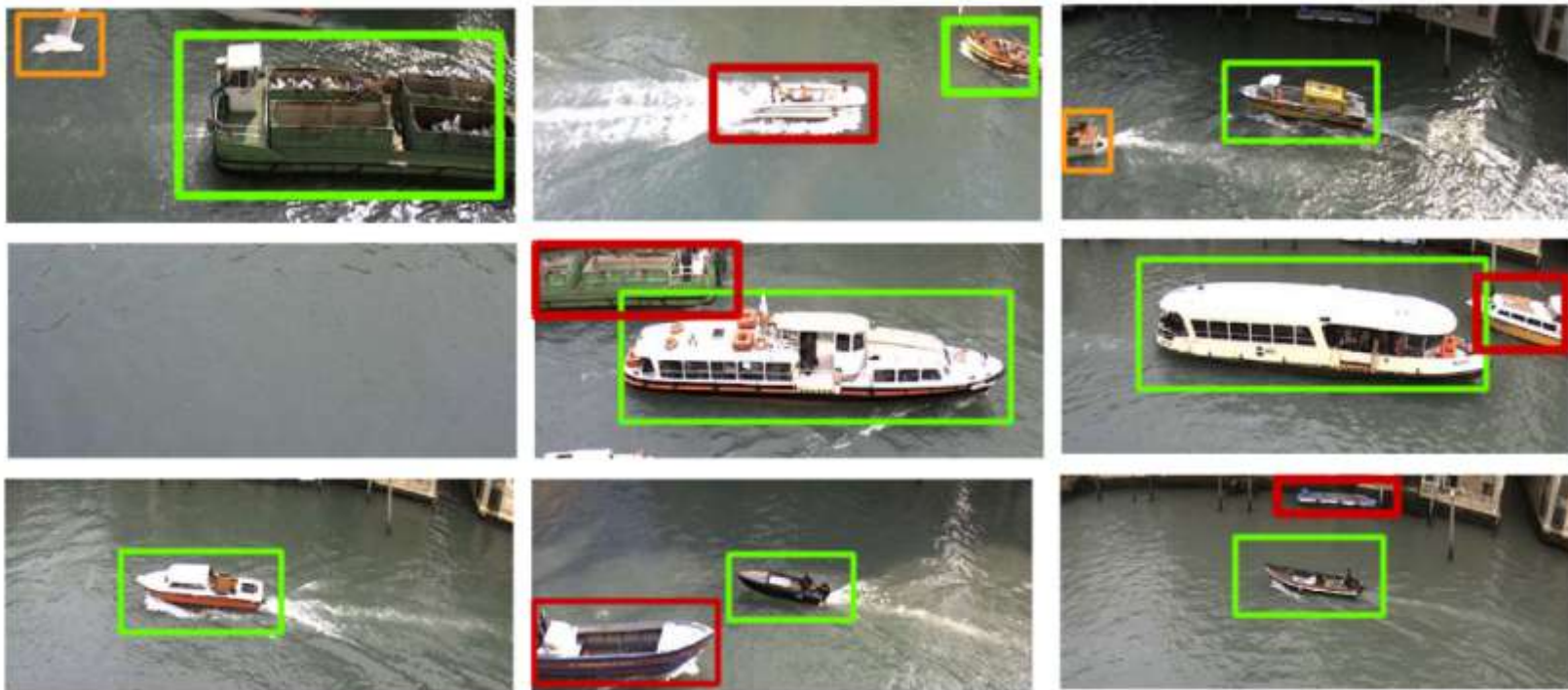
A)

INCCORRECTLY CLASSIFIED
INSTANCES

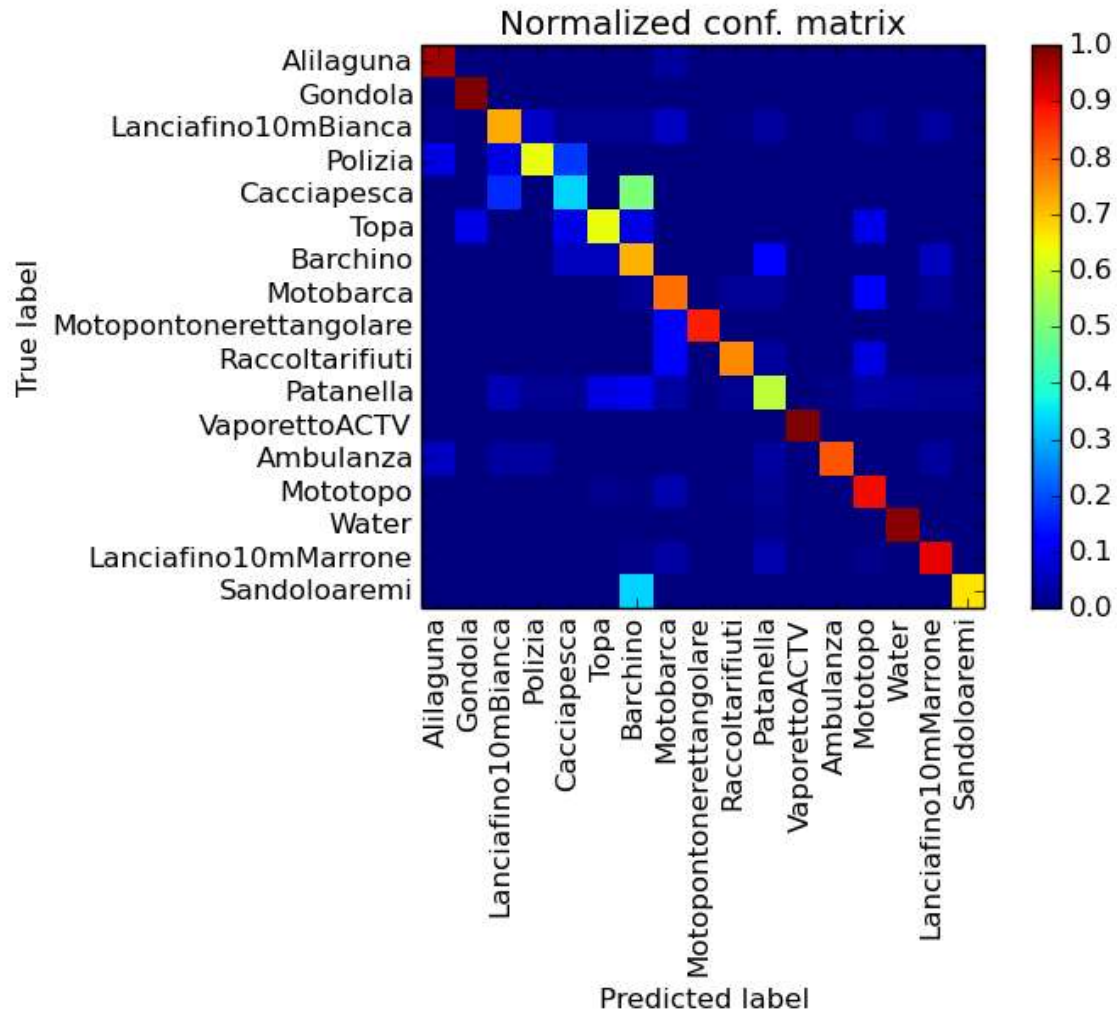


B)

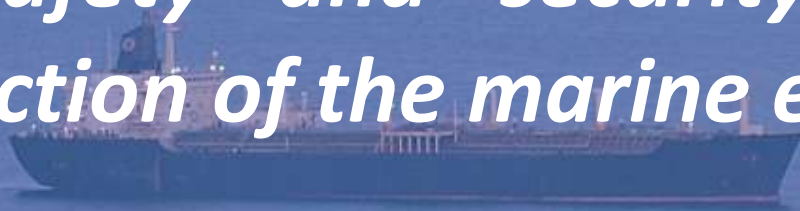
CLASSIFICATION OF MULTIPLE BOATS



CLASSIFICATION RESULTS



“e-Navigation is the harmonised collection, integration, exchange, presentation and analysis of maritime information onboard and ashore by electronic means to enhance berth to berth navigation and related services, for safety and security at sea and protection of the marine environment”



e-Navigation pre-requisites

- **Electronic Navigation Charts (ENC):** worldwide coverage required.
- **Electronic Positioning System:** a robust fail-safe (with redundancy).
- **Ship-Shore link:** an agreed communication infrastructure.

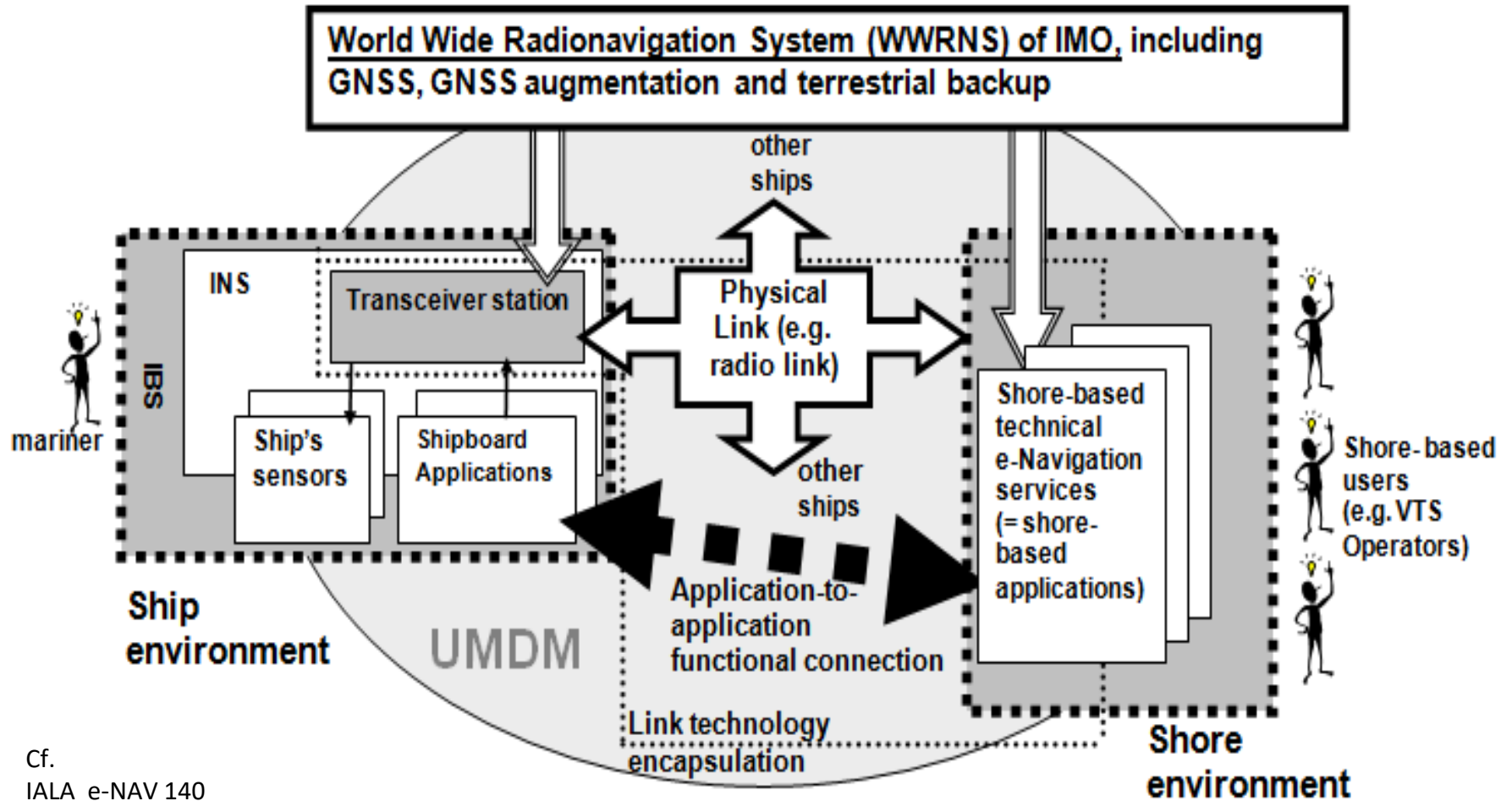


e-Navigation outcomes



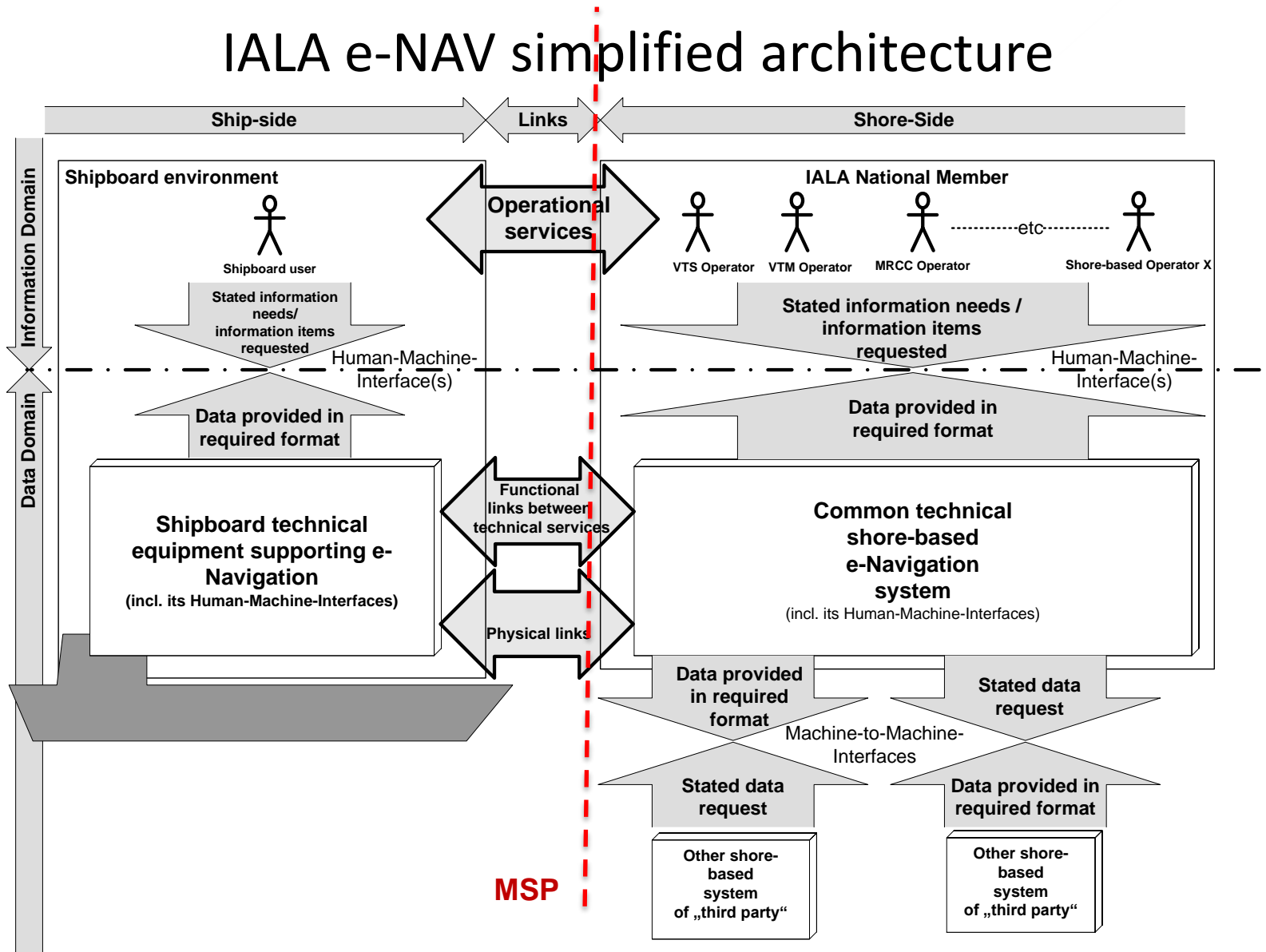
- **Ship based systems:**
 - integration of ship's own sensors;
 - electronic positioning;
 - Electronic Navigational Charts (ENC);
 - decision support capability to reduce human error.
- **Shore based systems:**
 - management of vessel traffic and related services from ashore;
- **Communications infrastructure:**
 - authorised information transfer onboard ship, ship-to-ship, ship-to-shore and shore-to shore.

e-Navigation architecture

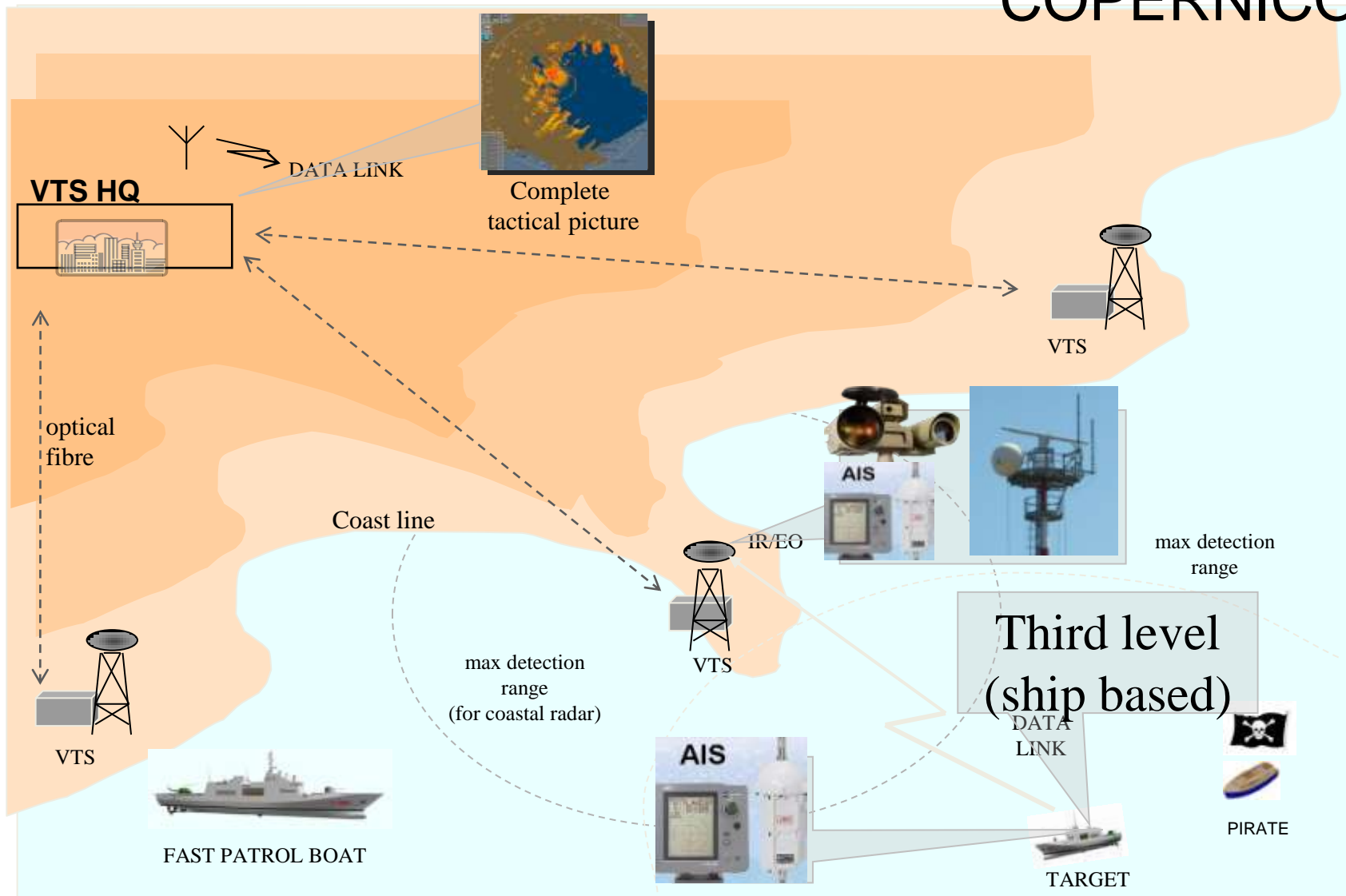


Cf.
IALA e-NAV 140

IALA e-NAV simplified architecture



COPERNICO



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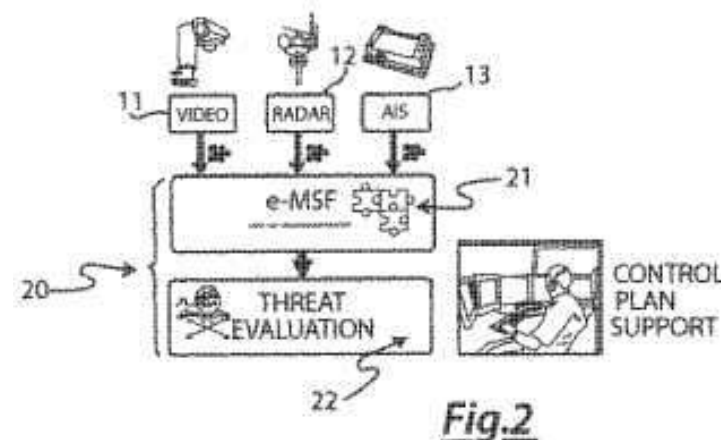
Patent Title:

ANTI-PIRACY SYSTEM FOR THE MARITIME NAVIGATION IN
CRITICAL AREAS, AND DEVICE FOR DATA EXTRACTION FROM
ON BOARD SENSORS

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