Robotics

Estimation and Learning with Dan Lee

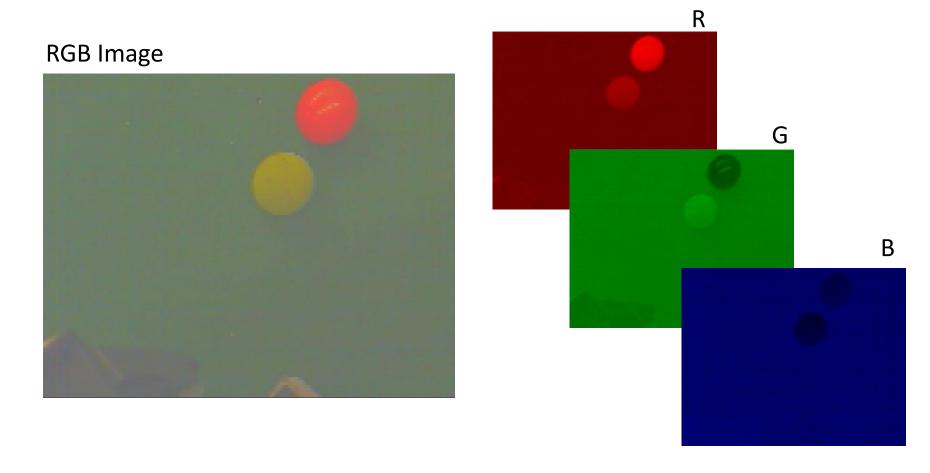
Week 1. Gaussian Model Learning

1.3.1 Multivariate Gaussian Distribution



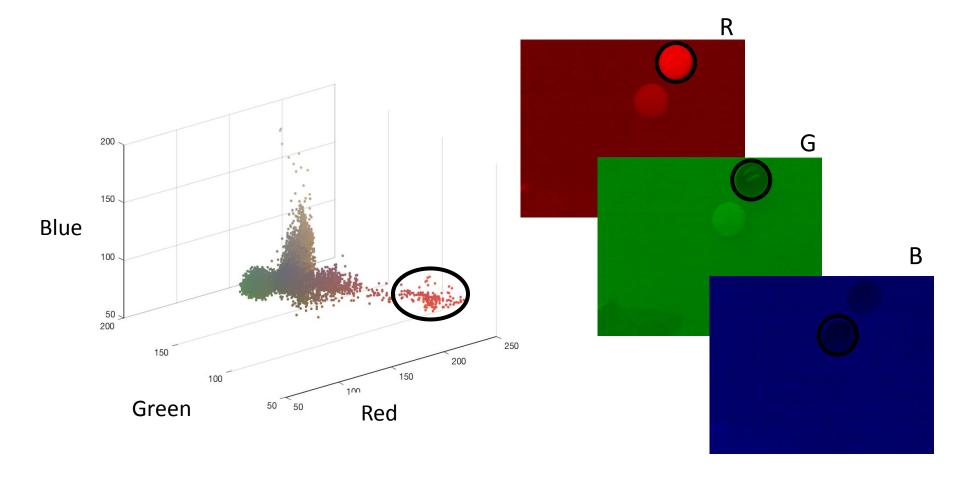
Multivariate Gaussian: Example

Ball color in multi-channels



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$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

D Number of Dimensions

X Variable

µ Mean *vector*

 \sum Covariance *matrix*

(Dimension = 1)

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(x-\mu)^2}{2\sigma^2}\right\}$$

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^{T} \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

\sum Covariance *matrix*

- * Diagonal terms: variance
- * Off-diagonal terms: correlation

(Dimension = 2)

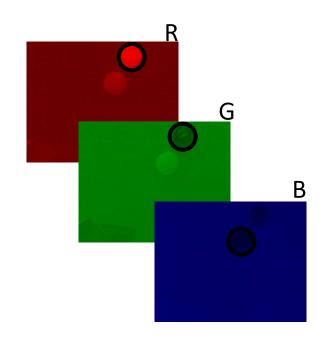
$$\Sigma = \begin{bmatrix} \sigma_{\chi_1}^2 & \sigma_{\chi_1} \sigma_{\chi_2} \\ \sigma_{\chi_2} \sigma_{\chi_1} & \sigma_{\chi_2}^2 \end{bmatrix} \quad (\sigma_{\chi_1} \sigma_{\chi_2} = \sigma_{\chi_2} \sigma_{\chi_1})$$

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

Determinant of Σ

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

Ball color in multi-channels



$$D=3$$
 $\mathbf{x}=\begin{bmatrix} x_R & x_G & x_B \end{bmatrix}$ $\mathbf{x}=\begin{bmatrix} \mu_R & \mu_G & \mu_B \end{bmatrix}$ $\mathbf{x}=\begin{bmatrix} \sigma_{x_R}^2 & \sigma_{x_R}\sigma_{x_G} & \sigma_{x_R}\sigma_{x_B} \\ \sigma_{x_R}\sigma_{x_G} & \sigma_{x_G}^2 & \sigma_{x_G}\sigma_{x_B} \\ \sigma_{x_R}\sigma_{x_B} & \sigma_{x_G}\sigma_{x_B} & \sigma_{x_B}^2 \end{bmatrix}$

$$p(\mathbf{x}) = \frac{1}{2\pi} \exp\left\{-\frac{x^2 + y^2}{2}\right\}$$

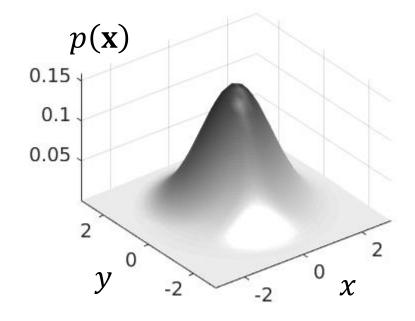
2D Zero-mean Spherical Case

$$D = 2$$

$$\mathbf{x} = \begin{bmatrix} x & y \end{bmatrix}^T$$

$$\mathbf{\mu} = \begin{bmatrix} 0 & 0 \end{bmatrix}^T$$

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$p(\mathbf{x}) = \frac{1}{2\pi} \exp\left\{-\frac{x^2 + y^2}{2}\right\}$$

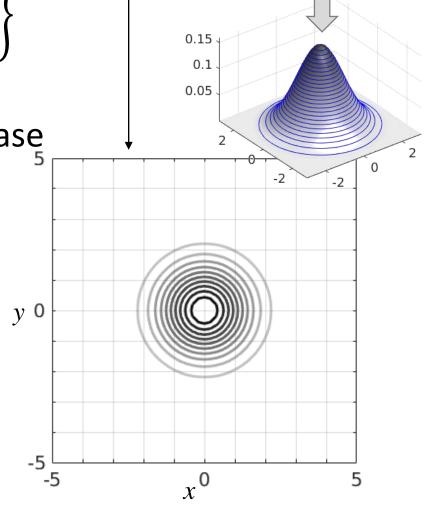
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View from above

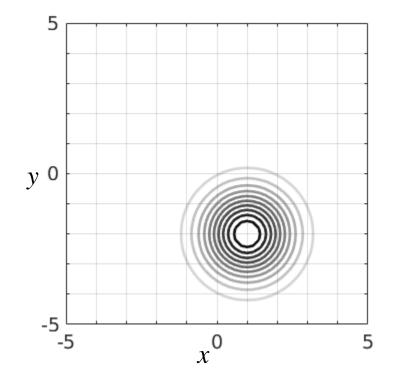
$$p(\mathbf{x}) = \frac{1}{2\pi} \exp\left\{-\frac{(x - \mu_x)^2 + (y - \mu_y)^2}{2}\right\}$$

$$D = 2$$

$$\mathbf{x} = \begin{bmatrix} x & y \end{bmatrix}^T$$

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_x & \mu_y \end{bmatrix}^T$$

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



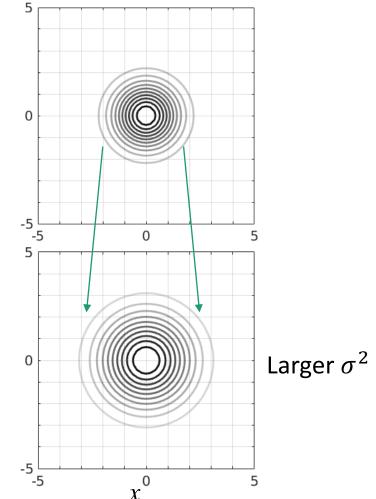
$$p(\mathbf{x}) = \frac{1}{2\pi\sigma^2} \exp\left\{-\frac{x^2 + y^2}{2\sigma^2}\right\}^{-5}$$

$$D = 2$$

$$\mathbf{x} = [x \quad y]^T$$

$$\boldsymbol{\mu} = [0 \quad 0]^T$$

$$\Sigma = \begin{bmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{bmatrix}$$



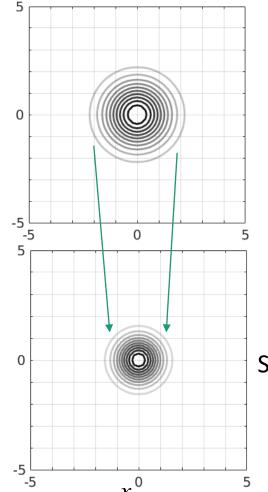
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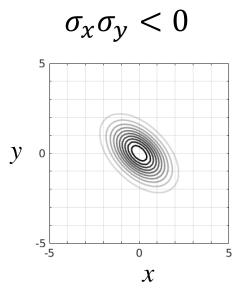
Smaller σ^2

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

 \mathcal{X}

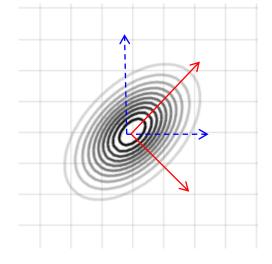
2D General Case

$$\Sigma = \begin{bmatrix} \sigma_x^2 & \sigma_x \sigma_y \\ \sigma_x \sigma_y & \sigma_y^2 \end{bmatrix} \int_{y=0}^{\sigma_x \sigma_y > 0} \int_{y=0}^{z} \int_{y=0}^{z}$$



$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

- Properties of Covariance Matrix Σ
 - 1) Σ is Symmetric and Positive Definite.
 - 2) Diagonalization: Σ can be decomposed in the form of UDU^T . (D is a Diagonal matrix.)



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