Randolph C. Voorhies

www.randolphvoorhies.com
703 1/2 East Edgeware Road. Los Angeles, Ca. 90026
voorhies@usc.edu

Education

Ph.D. in Computer Science
In Progress
University of Southern California
GPA: 3.930

M.S. in Computer Science - Intelligent Robotics
August 2009
University of Southern California
GPA: 3.910

B.S. in Computer Engineering & Computer Science
December 2006
University of Southern California
GPA: 3.497

Technical Skills

Programming Languages
C++ (11) · C · Python · MATLAB · Javascript · Perl · Spin

Software Libraries
Boost · ZeroC Ice · Eigen · OpenCV · ROS · Qt · Thrust · Arduino

Electrical Engineering Tools
Altium Designer · Cadsoft Eagle · Surface Mount Assembly

Engineering Abilities
Image Processing · Robotics Perception & Localization · Distributed Programming · Circuit Board Design

Experience

USC Computer Science Department
Fall 2007 - Present
Graduate Research Assistant in Laurent Itti's iLab
- Currently researching biologically inspired methods for monocular figure/ground segmentation.
- Implemented NRT, a C++ modular programming framework for image processing and robotics.
- Implemented tracking and object recognition systems for DARPA's Neovision2 project.
- Implemented a distributed attention system for DARPA's Cognitive Technologies Threat Warning System (CT2WS) project.
- Performed circuit design, assembly, and embedded programming for Beobot2.0, iLab's next generation 16-core robot.

South Pasadena Educational Foundation
Summers 2007 - 2011
Teacher Trainer
- Designed a robotics curriculum to be taught to middle school students.
- Provided weekly training sessions for teachers.

USC Computer Science Department
Fall 2007 - 2009
CS445 Introduction to Robotics Lab Assistant
- Designed and taught curricula for weekly three-hour lab sessions.
- Designed and built a custom robotics controller board based on a 600Mhz Overo processor.
- Built a software architecture and library to help the students cross-compile and upload code, as well as libraries for motion control, data acquisition, image processing, and communication.

Microsoft
Summer 2004
Intern in the Security Division
- Developed security database migration tools in C#.

Publications

Centralized Server Environment for Educational Robotics
R.C. Voorhies, C. Siagian, L. Elazary, L. Itti
Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2009

Application of a Bottom-Up Visual Surprise Model for Event Detection in Dynamic Natural Scenes
R.C. Voorhies, L. Elazary, L. Itti
Vision Science Society Annual Meeting (VSS) 2010

Beobot 2.0: Cluster Architecture for Mobile Robotics
C. Siagian, C. Chang, R.C. Voorhies, L. Itti
Journal of Field Robotics (JFR) 2010

Honors

Member Phi Kappa Phi

Co-Chair of the "Education Robotics" session for IROS 2009