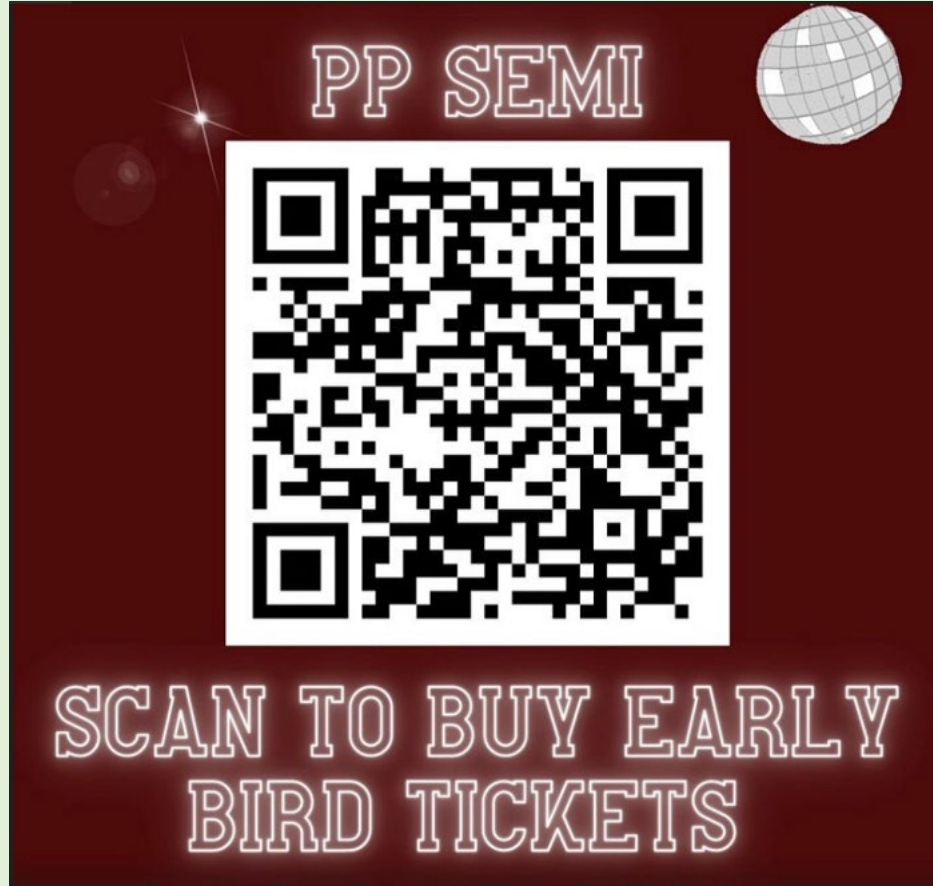


# Announcement



From: Engineering Undergraduate Society

To celebrate the end of midterms, we are putting on one more event called "PP semi" which is essentially a semi formal dance for first year engineering students and their plus ones. The event will take place on the **27th of March from 7:30-10:00pm.**

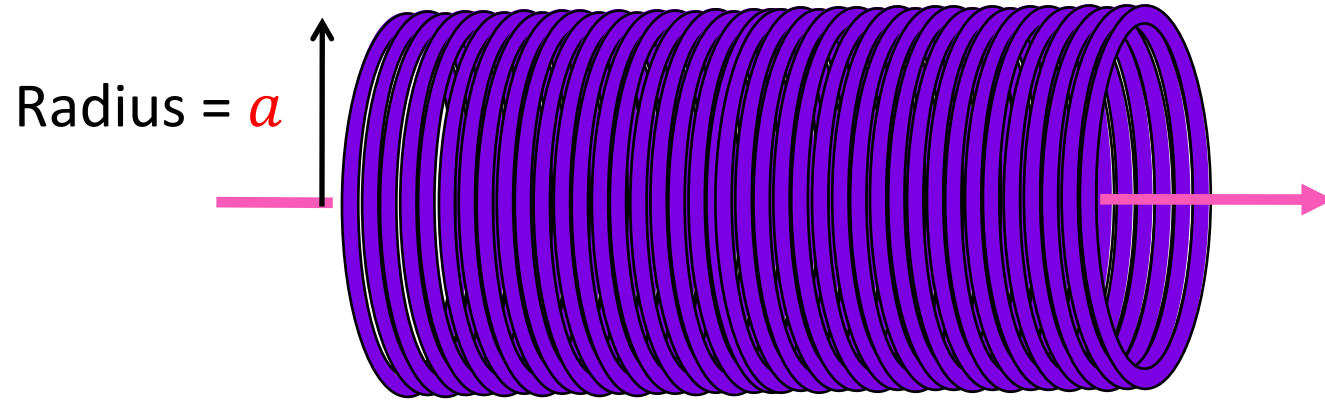
Lecture 31.

Real-life solenoids.

Faraday's law & Lenz's law: making sense

## Ideal solenoid

Last Time:

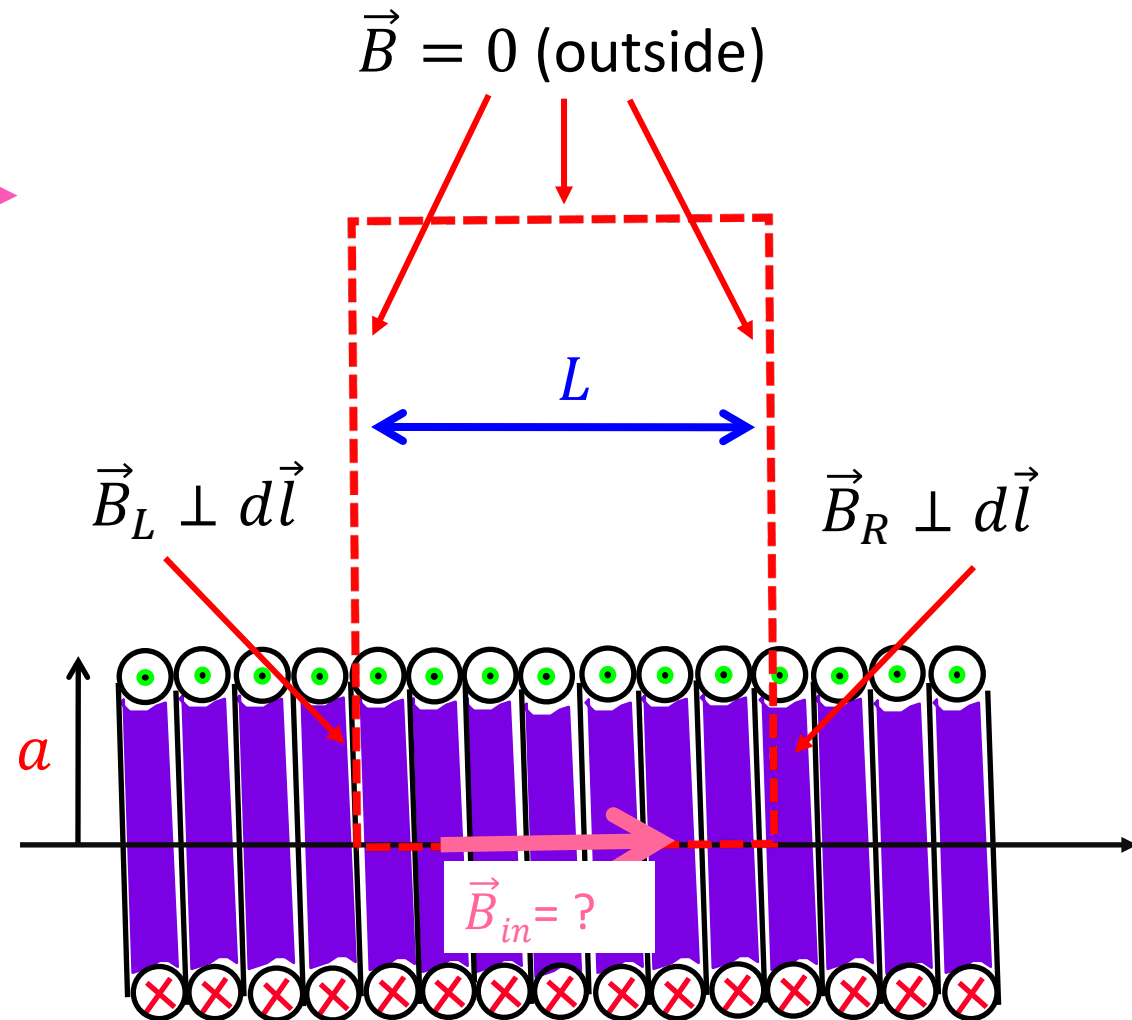


- Ampere's law:  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{encl}}$

$$\oint \vec{B} \cdot d\vec{l} = B_{\text{in}} L$$

$$I_{\text{encl}} = InL$$

$$B_{\text{in}} = \mu_0 In$$



## Finite Length Solenoid

Unfortunately, Engineers have to deal with finite length solenoids!

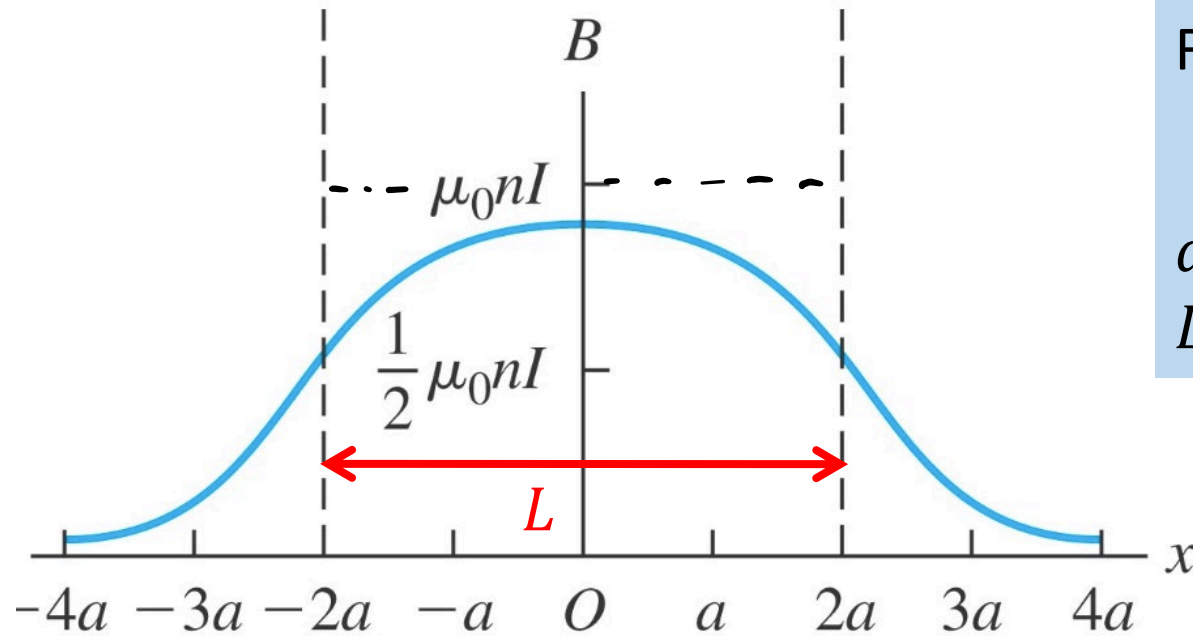


Fig 28.24

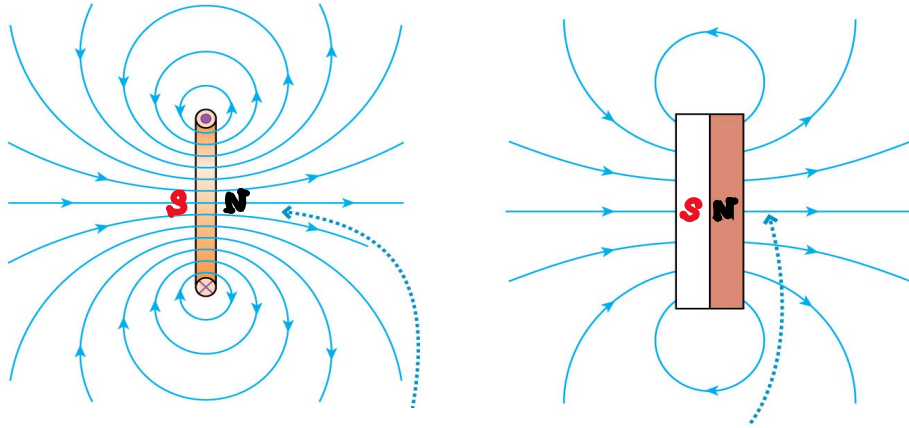
$$L = 4a$$

$a$  = radius

$L$  = length

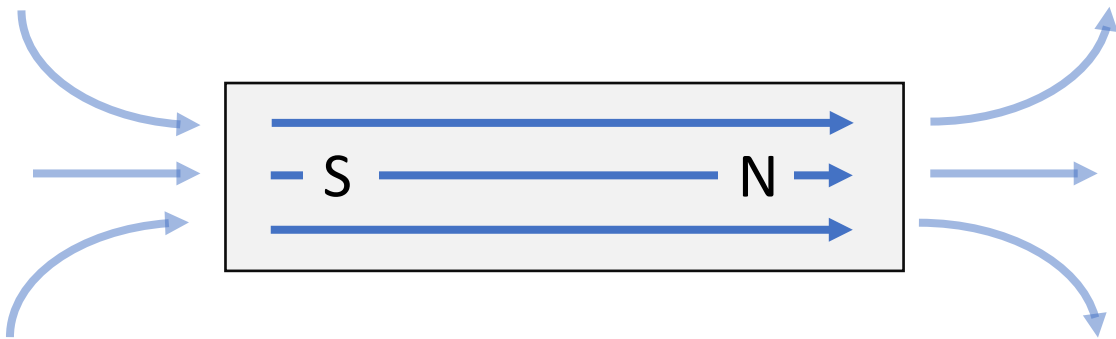
## Fringe effects

To better understand fringe effects, let's look at the B-field of one ring

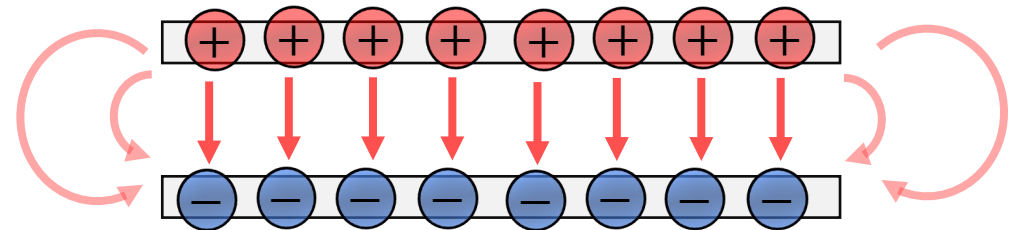


- If we look at the field of a current-carrying ring, we see that it is equivalent to the field of a tiny magnet!
- You can even define North and South poles for such a loop...

- Putting many loops together (solenoid / magnet):

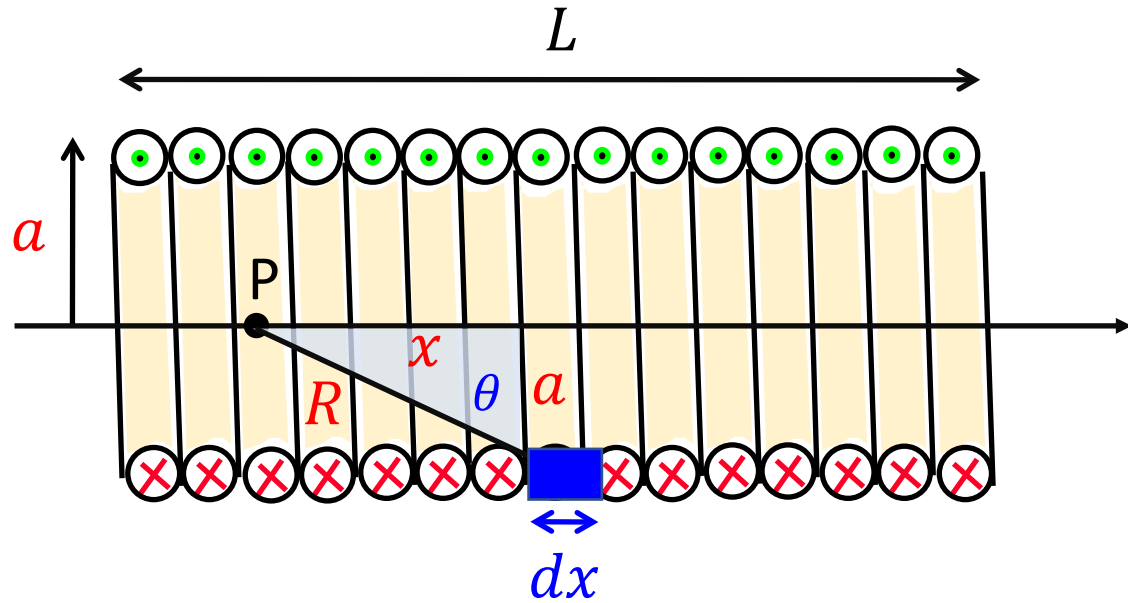


- Doesn't it remind a capacitor?



- Store magnetic / electric energy, uniform field...

## Finite Length Solenoid



- Same way as with a finite wire: introduce  $\theta$

$$x = a \tan \theta \Rightarrow dx = \frac{a d\theta}{\cos^2 \theta}, \text{ and } R \cos(\theta) = a \Rightarrow dB_x = \frac{\mu_0 N}{2 L} I \cos(\theta) d\theta$$

check  
it!

$$B_{\text{real solenoid}}(P) = \int dB_x = \frac{\mu_0 N}{2 L} I \left\{ \sin(\theta) = \pm \frac{x}{\sqrt{x^2 + a^2}} \right\} \Big|_{x_L}^{x_R}$$

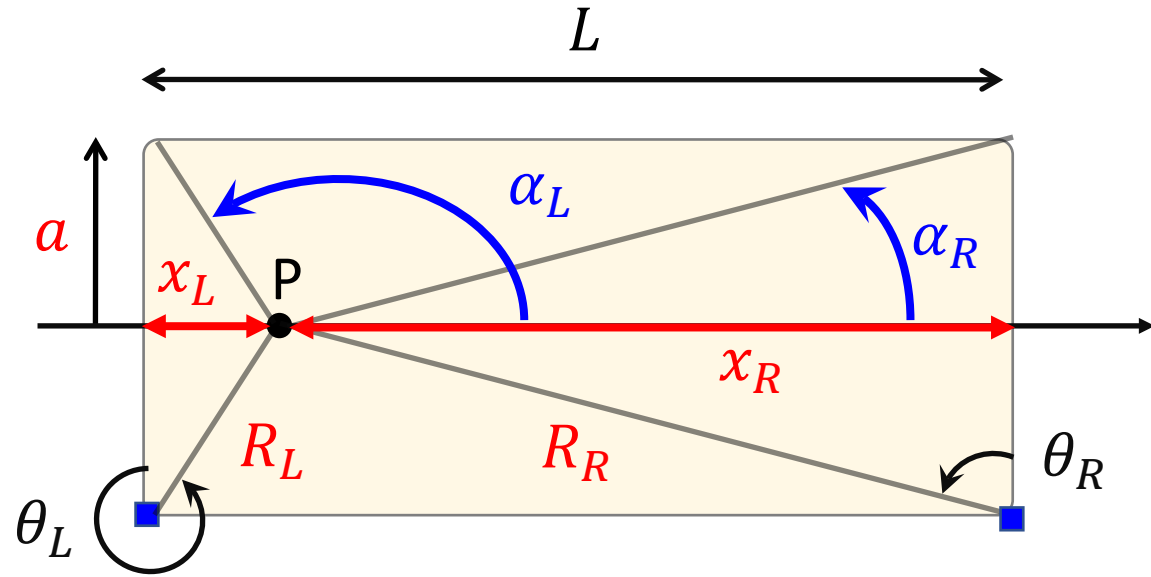
- Recall  $B_x$  on the axis of a circular loop:

$$B_x(x) = \frac{\mu_0}{2} \frac{I a^2}{(x^2 + a^2)^{3/2}}$$

- Consider magnetic field created at the observation point P by a tiny segment of solenoid (thickness  $dx$ ):

$$dB_x(x) = \frac{\mu_0}{2} \frac{N dx}{L} \frac{I a^2}{(x^2 + a^2)^{3/2}}$$

## Finite Length Solenoid & Trigonometry



$$B_{\text{real solenoid}}(@P) = \frac{\mu_0}{2} \frac{N}{L} I (\sin \theta_R - \sin \theta_L)$$

- Let's brush it up:

$$\sin \theta_L = -\sin(2\pi - \theta_L) = -\frac{x_L}{R_L} = \cos \alpha_R$$

$$\sin \theta_R = \frac{x_R}{R_R} = \cos \alpha_R$$

- We get:

$$B_{\text{real solenoid}}(@P) = \frac{\mu_0}{2} n I (\cos \alpha_R - \cos \alpha_L)$$

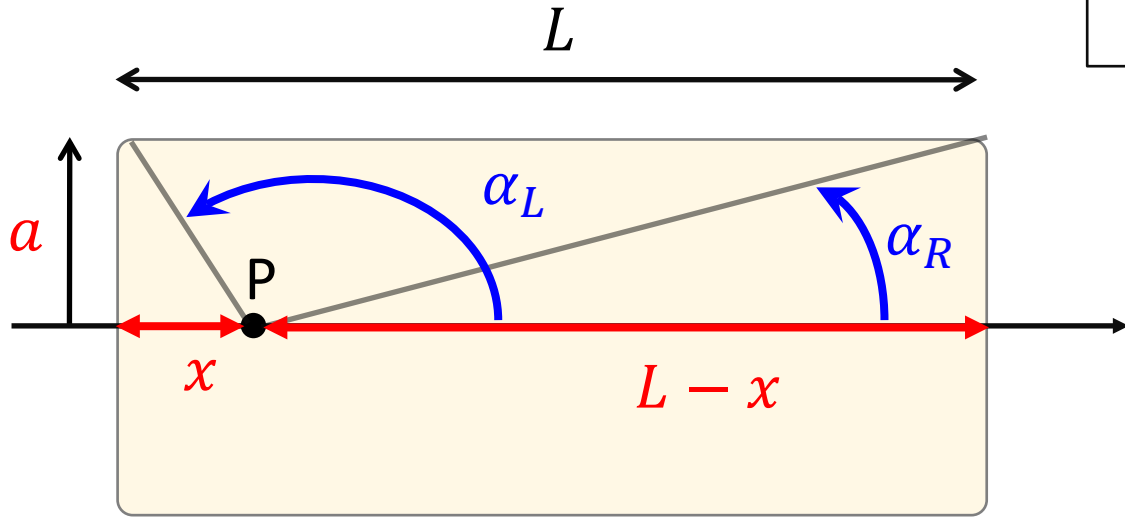
- $n = N/L$  is the density of coils
- $\alpha_L$  and  $\alpha_R$  are the angles at which you see the edges of the solenoid from point P.

- For a long solenoid:  $\alpha_R \rightarrow 0$  &  $\alpha_L \rightarrow \pi$

$\Rightarrow$

$$B_{\text{ideal solenoid}} = \mu_0 n I = \text{const}$$

## Finite Length Solenoid & Trigonometry



$$B_{\text{real solenoid}}(@P) = \frac{\mu_0}{2} n I (\cos \alpha_R - \cos \alpha_L)$$

$$B_{\text{ideal solenoid}} = \mu_0 n I = \text{const}$$

$$B_{\text{real solenoid}}(x) = B_{\text{ideal}} \times \frac{1}{2} \left( \frac{L - x}{\sqrt{a^2 + (L - x)^2}} + \frac{x}{\sqrt{a^2 + x^2}} \right)$$

- Show that the approximation of ideal solenoid works well when  $L \gg a$

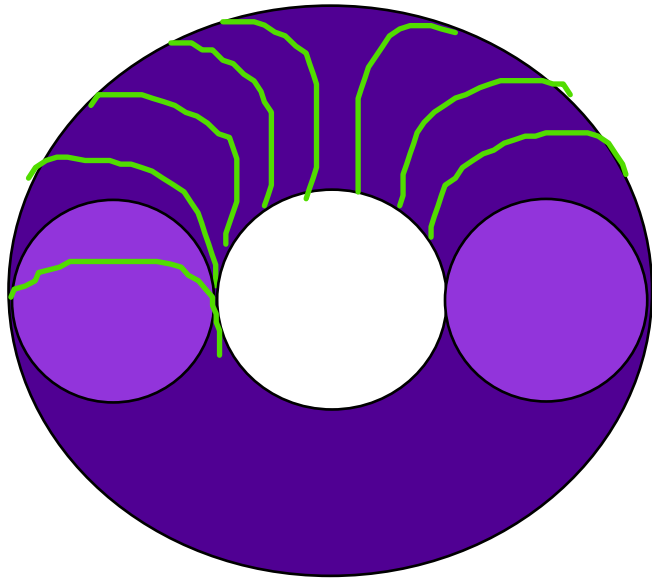
*$L \sim 4a$  - fringe effects*

<https://www.desmos.com/calculator/maau7qidjc>



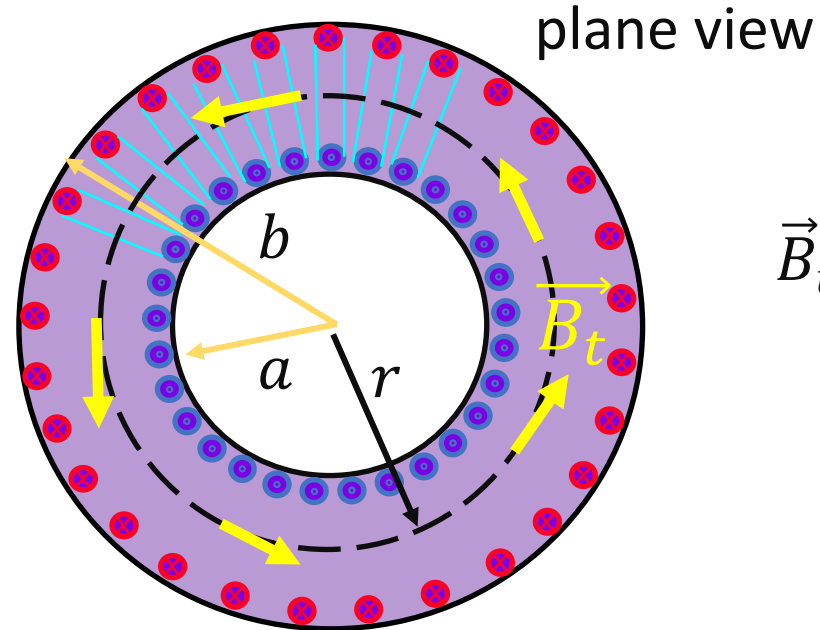
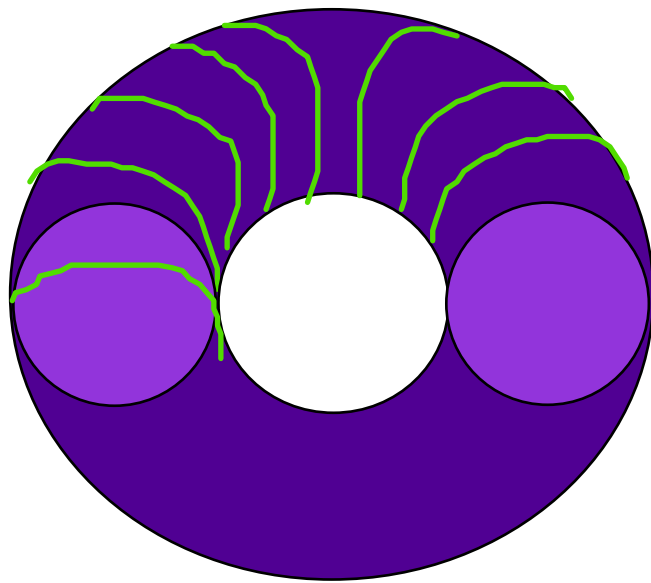
## Magnetic Applications – Toroid Solenoid

- Let's get rid of fringes at the ends – by getting rid of the ends themselves!



- Here we show a toroid with a circular cross-section, i.e. a “doughnut” wrapped with  $N$  “turns” of wire.
  - The wire carries current  $I$
  - This is a solenoid twisted into a circle.
- 
- What the magnetic field in this structure is?

## Magnetic Applications – Toroid Solenoid



$\vec{B}_t$  = tangential B-field

$$\oint \vec{B} \cdot d\vec{l} = 2\pi r B_t = \mu_0 I_{encl} = \mu_0 IN$$

$$B_t = \frac{\mu_0 IN}{2\pi r}$$

Note --  $B \cong 0$  for  $r < a$  or  $r > b$

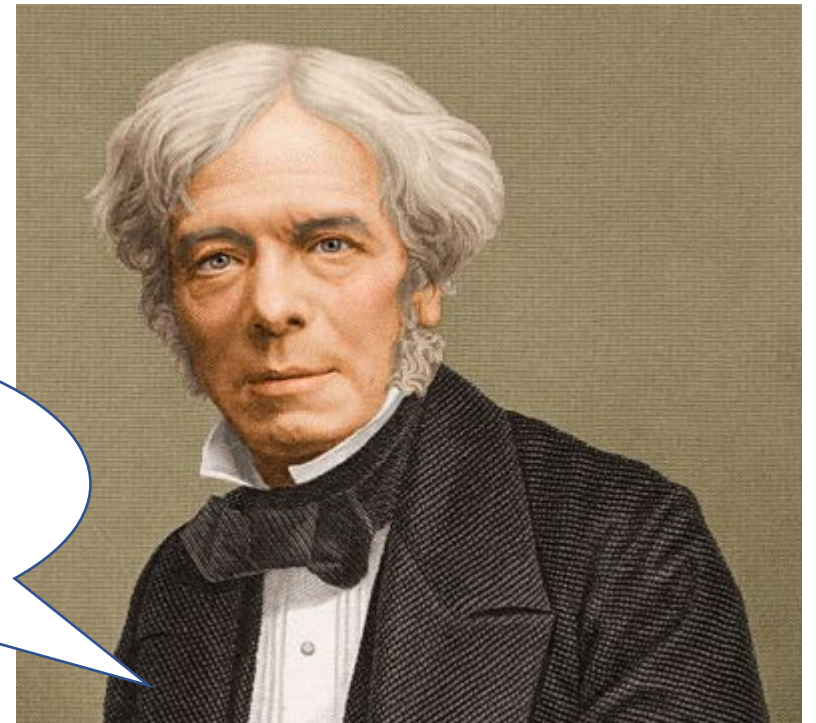
Fig 28.25

## Lenz's law



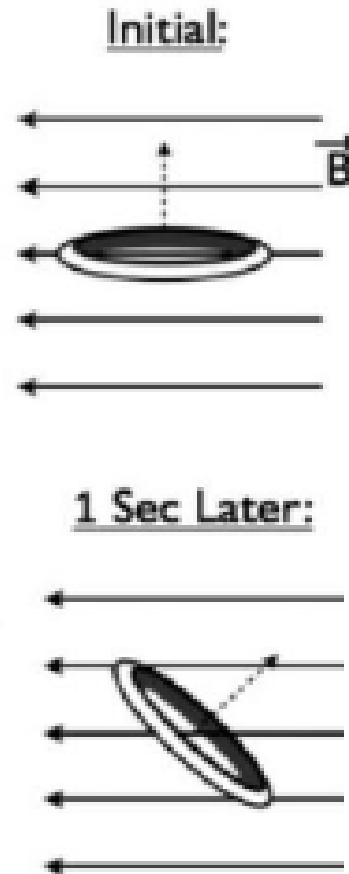
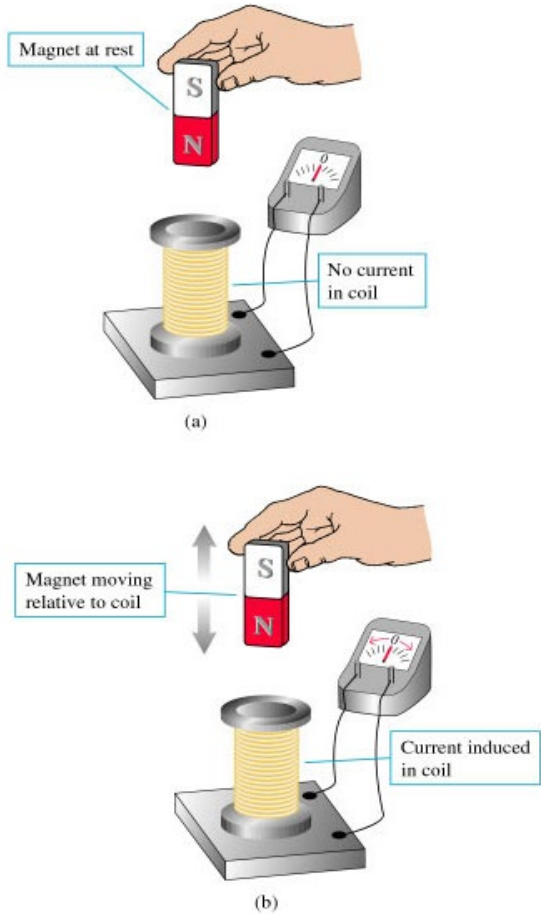
$$\varepsilon = -\frac{d\Phi_B}{dt}$$

## Faraday's law

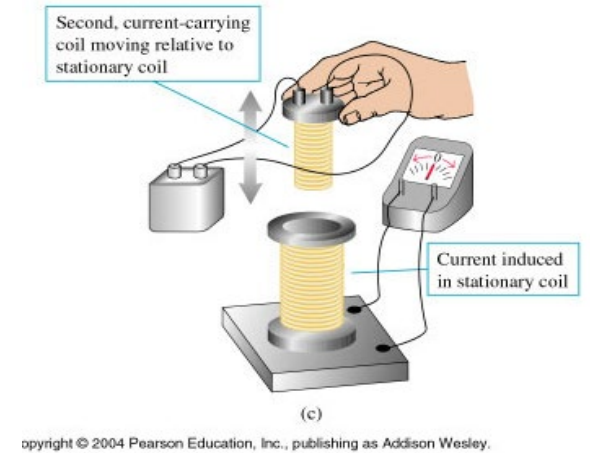


$$\varepsilon = \left| \frac{d\Phi_B}{dt} \right|$$

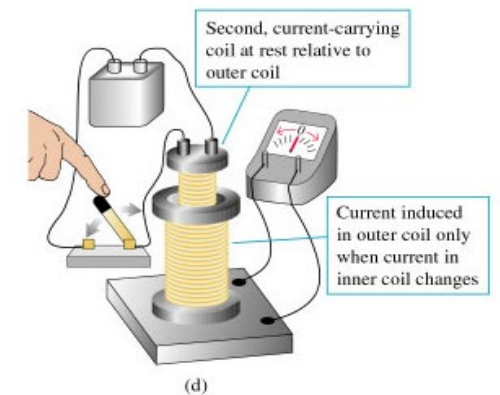
# Experiments on induced EMF



- Moving a current-carrying solenoid around a coil creates current in the solenoid

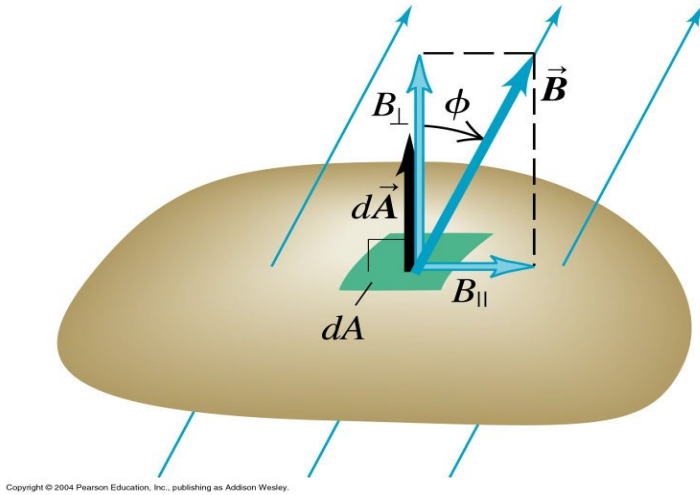


- Switching a current on in the inner coil momentarily creates current in the outer coil



- This experiment works for any closed (so that it can support electric current) loop

# Induced EMF



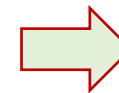
$$\Phi_B = \oint \underbrace{\vec{B} \cdot d\vec{A}}_{\text{area}}$$

- Common denominator:
  - In these experiments, there is no battery in the loop. The current is excited literally by changing the magnetic flux through the loop!

- Okay, we have current  $\Rightarrow$  there must be EMF
- We can define the so-called “motional emf”: (emf = electromotive force)

$$\varepsilon = \left| \frac{d\Phi_B}{dt} \right|$$

an emf induced in a conducting loop if the magnetic flux  $\Phi_B$  through it changes



“emf responsible for that current”

Q: Which of the following could light up the bulb?

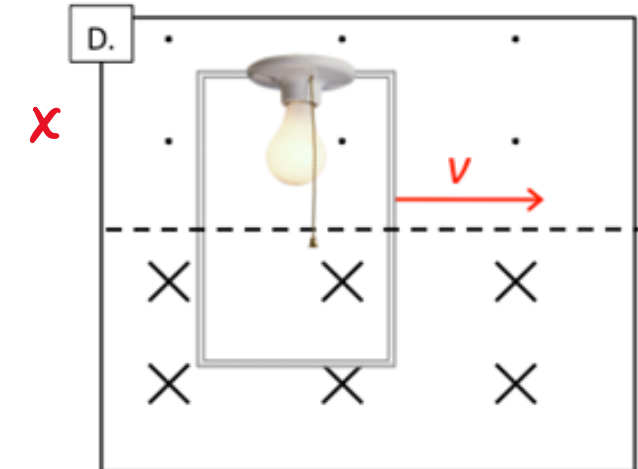
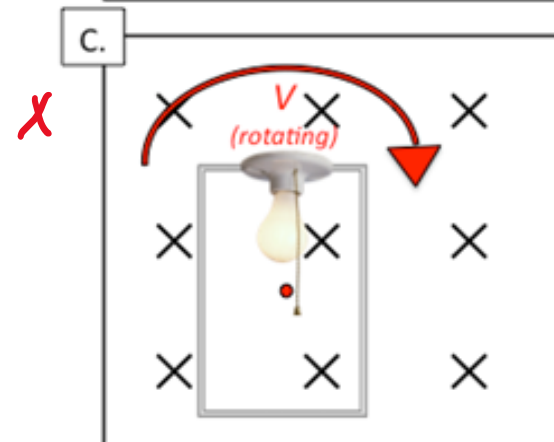
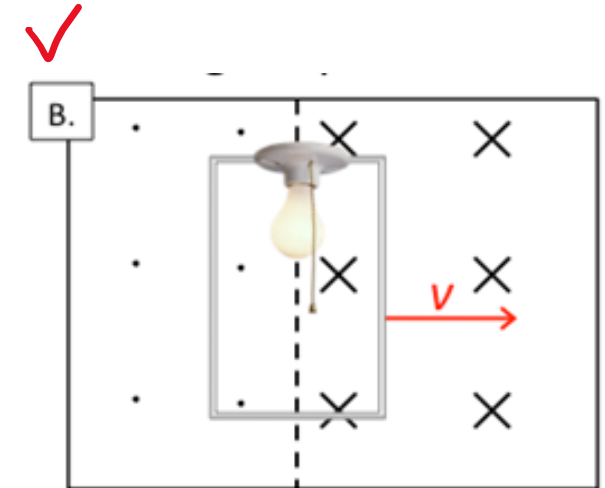
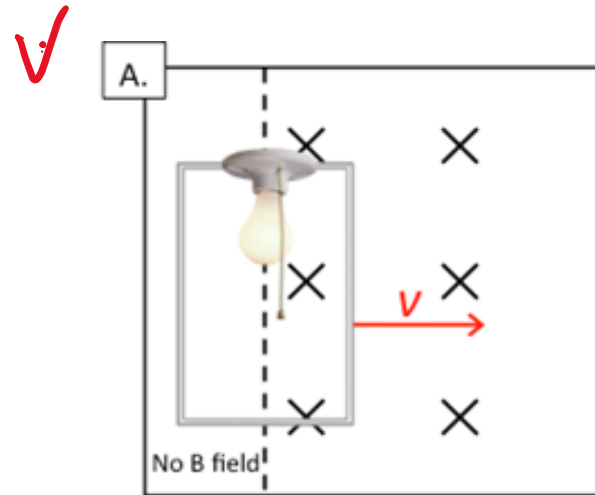
- A. A only
- ☒ B. A and B
- C. A, B and C
- D. A and C
- E. All of them

Q: Which of these will light the bulb most strongly?

- A. A
- ☒ B. B
- C. Same

$$\xi = \max$$

$$\frac{d\Phi}{dt} = \max$$



## Direction of Induced EMF

- So  $\varepsilon = \left| \frac{d\Phi_B}{dt} \right|$  is the **magnitude** of induced EMF. We need to know its **direction**, CW or CCW
- **Induced current** is a current, and hence it creates (**induces**) **magnetic field**!
- Their directions are related by the RHR.
- The **direction of the induced magnetic field** (and, therefore, the **direction of the induced current**!) is determined by the Lenz law:

The direction of the induced current is such that the induced magnetic field **opposes the change in the flux**.

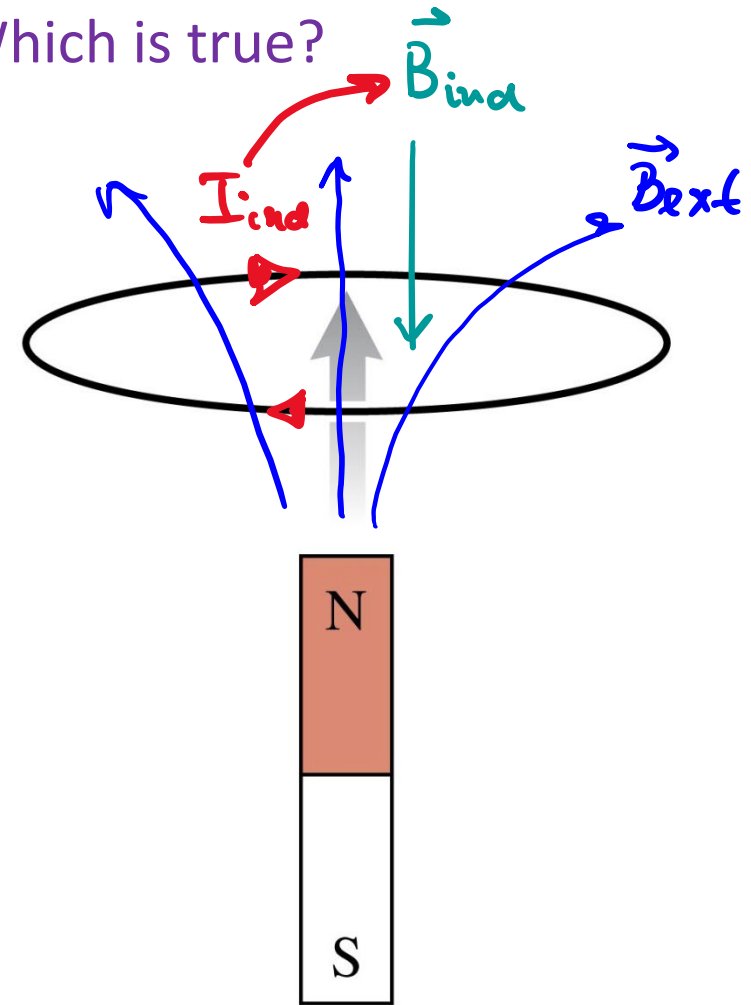
$$\varepsilon = - \frac{d\Phi_m}{dt}$$





Q: The bar magnet is pushed toward the center of a wire loop. Which is true?

- A. There is a clockwise induced current in the loop.
- B. There is a counterclockwise induced current in the loop.
- C. There is no induced current in the loop.
- D. Not sure



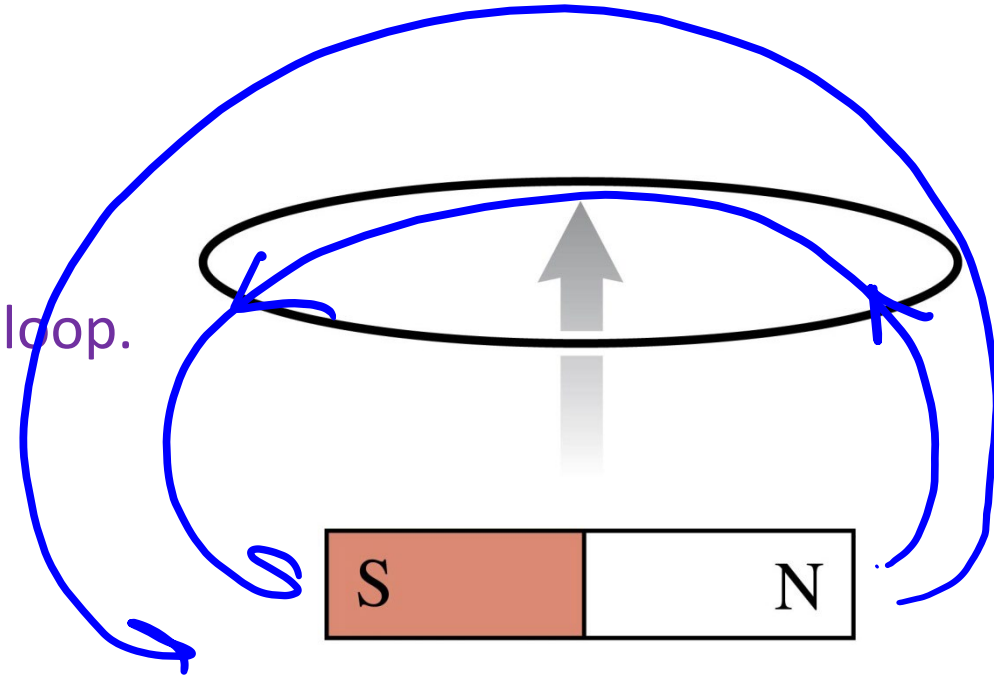
$\vec{B}_{ext} \uparrow$ , increasing       $\vec{B}_{ind} \downarrow$   
 $\vec{B}_{ind} \uparrow \downarrow \vec{B}_{ext}$

(assume we look at the loop from above)



Q: The bar magnet is pushed toward the center of a wire loop. Which is true?

- A. There is a clockwise induced current in the loop.
- B. There is a counterclockwise induced current in the loop.
- ☒ C. There is no induced current in the loop.
- D. Not sure



(assume we look at the loop from above)