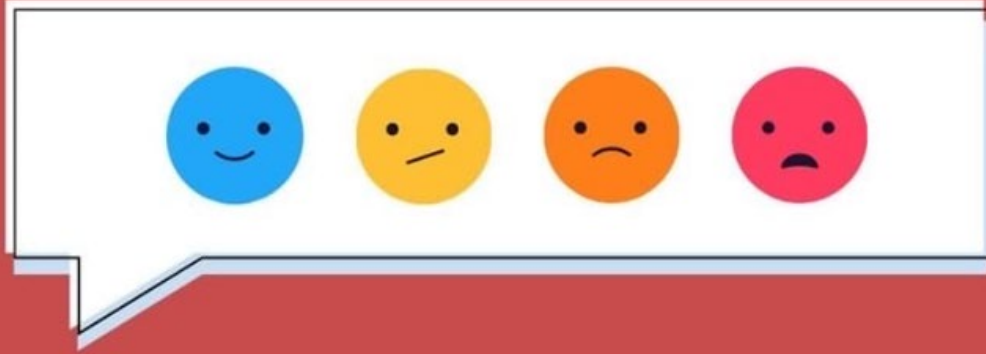


BEEF AND PIZZA TERM 2



MARCH 6TH

@ESC

5PM -7PM



FREE PIZZA

RSVP: SCAN QR OR CLICK LINK IN BIO



This event is one where students come in to provide feedback or "Beef" about their current classes and receive free pizza in return for their participation. "Feedback" can include a variety of things extending from lecture pacing, to test material, to office hours and tutorial help.

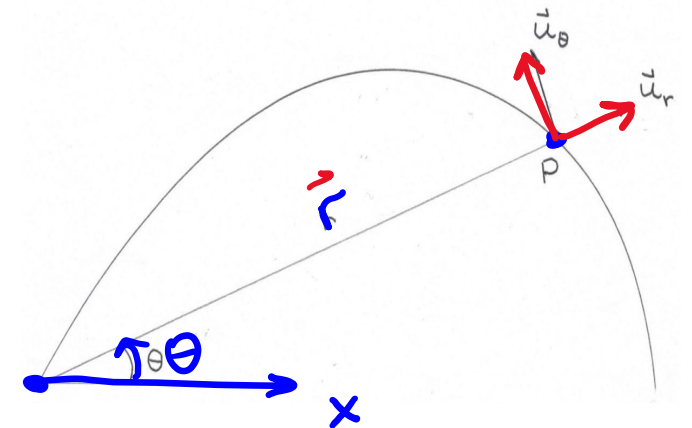
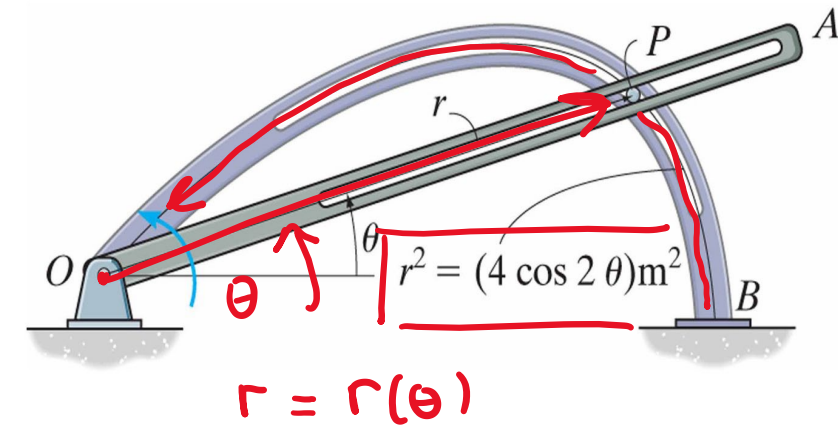
W8-1. $\dot{\theta} = 3t^{3/2}$ rad/s where t is in seconds, and $\theta = 0$ when $t = 0$. Also, $r^2 = (4 \cos 2\theta)m^2$.

a) Determine the time when $\theta = 30^\circ$.

b) Determine the radial and transverse components of the ball's velocity and acceleration when $\theta = 30^\circ$.

$$\frac{d\theta}{dt} = 3t^{3/2} \frac{\text{rad}}{\text{s}} \rightarrow \int_{\theta=0}^{\theta} d\theta = \int_{t=0}^t 3t^{3/2} dt$$

$$\theta(t) = \theta_0 + \int_0^t 3t^{3/2} dt = 3 \left. \frac{t^{5/2}}{5/2} \right|_{t=0}^{t=t} = \frac{6}{5} t^{5/2}$$

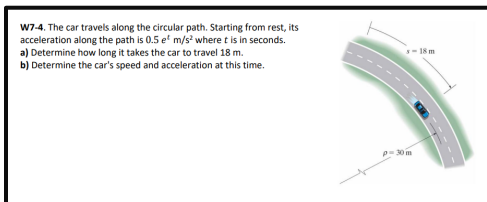


Last
Time

$$t: \theta(t) = \frac{6}{5} t^{5/2} = \frac{\pi}{6}$$

$$t^{5/2} = \frac{5\pi}{36}$$

$$t = \left(\frac{5\pi}{36} \right)^{2/5} = 0.7177 \text{ s}$$



W8-1. $\dot{\theta} = 3t^{3/2}$ rad/s where t is in seconds, and $\theta = 0$ when $t = 0$. Also, $\boxed{r^2 = (4 \cos 2\theta)m^2.}$ $\vec{u}_r, \vec{u}_\theta$

a) Determine the time when $\theta = 30^\circ \Rightarrow \underline{t = 0.7177 \text{ s}}$

b) Determine the radial and transverse components of the ball's velocity and acceleration when $\theta = 30^\circ$.

➤ Find $\theta, \dot{\theta}, \ddot{\theta}$.

$$\theta = \frac{\pi}{6}$$

$v_r = \dot{r},$	$v_\theta = r\dot{\theta}$
$a_r = \ddot{r} - r\dot{\theta}^2,$	$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta}$

(1) $\theta = \pi/6$

(2) $\dot{\theta} = 3t^{3/2} \xrightarrow{t=0.7177} \dot{\theta} = 1.8240 \frac{\text{rad}}{\text{s}}$

(3) $\ddot{\theta} = \frac{d}{dt} \dot{\theta} = \frac{d}{dt} (3t^{3/2}) = 3 \cdot \frac{3}{2} t^{1/2} \xrightarrow{t=0.7177} 3.8123 \frac{\text{rad}}{\text{s}^2}$

$$r = \sqrt{4 \cdot \cos(2\theta)} \xrightarrow{\theta = \pi/6} \dots$$

$$\frac{dr}{dt} = \frac{dr}{d\theta} \cdot \frac{d\theta}{dt} = \frac{dr}{d\theta} \cdot \dot{\theta}$$

W8-1. $\dot{\theta} = 3t^{3/2}$ rad/s where t is in seconds, and $\theta = 0$ when $t = 0$. Also, $r^2 = (4 \cos 2\theta)m^2$.

a) Determine the time when $\theta = 30^\circ \Rightarrow t_* = 0.7177 \text{ s}$

b) Determine the radial and transverse components of the ball's velocity and acceleration when $\theta = 30^\circ$.

➤ Find r, \dot{r}, \ddot{r} :

$$r^2 = (4 \cos 2\theta)$$

$v_r = \dot{r},$	$v_\theta = r\dot{\theta}$
$a_r = \ddot{r} - r\dot{\theta}^2,$	$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta}$

✓ (1) $\theta = \frac{\pi}{6}$

✓ (2) $\dot{\theta}(t) = 3t^{3/2} = 1.8240 \frac{\text{rad}}{\text{s}}$

(3) $\ddot{\theta} = \frac{9}{2} t^{1/2} = 3.8123 \frac{\text{rad}}{\text{s}^2}$

\dot{r} : $\frac{d}{dt} [r^2 = 4 \cos 2\theta]$

$$2r\dot{r} = 4 \cdot (-\sin 2\theta) 2\dot{\theta}$$

$$\rightarrow r\dot{r} = -4\dot{\theta} \sin 2\theta$$

$$\dot{r} = -\frac{4\dot{\theta} \sin 2\theta}{r} \xrightarrow{t=0.7177} -4.4673 \frac{\text{m}}{\text{s}}$$

(4) $r(t = 0.7177) = r(\theta = \pi/6)$

$$r^2 = 4 \cdot \frac{1}{2} = 2 \quad \checkmark \quad r(t = \dots) = \sqrt{2}$$

\ddot{r} : $\frac{d}{dt} [r\dot{r} = -4\dot{\theta} \sin 2\theta]$

$$\dot{r}\dot{r} + r\ddot{r} = -4 [\ddot{\theta} \sin 2\theta + \dot{\theta} \cos 2\theta \cdot 2\dot{\theta}]$$

$$\dot{r}^2 + r\ddot{r} = -4 [\ddot{\theta} \sin 2\theta + 2\dot{\theta}^2 \cos 2\theta]$$

$$\ddot{r} = \frac{-4 [\ddot{\theta} \sin 2\theta + 2\dot{\theta}^2 \cos 2\theta] - \dot{r}^2}{r} \xrightarrow{t=0.7177} -32.864 \frac{\text{m}}{\text{s}^2}$$

W8-1. $\dot{\theta} = 3t^{3/2}$ rad/s where t is in seconds, and $\theta = 0$ when $t = 0$. Also, $r^2 = (4 \cos 2\theta)m^2$.

a) Determine the time when $\theta = 30^\circ \Rightarrow t_* = \mathbf{0.7177\ s}$

$$t = 0.7177\ s$$

b) Determine the radial and transverse components of the ball's velocity and acceleration when $\theta = 30^\circ$.

$$(1): \theta = \frac{\pi}{6}$$

$$(2): \dot{\theta}(t) = 3 t^{3/2} = 1.8240 \frac{\text{rad}}{s}$$

$$(3): \ddot{\theta} = \frac{9}{2} t^{1/2} = 3.8123 \frac{\text{rad}}{s^2}$$

$$(4): r = 2\sqrt{\cos 2\theta} = \sqrt{2}\ m$$

$$(5): \dot{r} = -\frac{4\dot{\theta} \sin(2\theta)}{r} = -4.4679 \frac{m}{s}$$

$$(6): \ddot{r} = \frac{-4[\ddot{\theta} \sin 2\theta + 2\dot{\theta}^2 \cos 2\theta] - \dot{r}^2}{r} = -32.864 \frac{m}{s^2}$$

$v_r = \dot{r},$	$v_\theta = r\dot{\theta}$
$a_r = \ddot{r} - r\dot{\theta}^2,$	$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta}$

$$v_r = -4.47\ \text{m/s}$$

$$v_\theta = 2.58\ \text{m/s}$$

$$v = \sqrt{v_r^2 + v_\theta^2} =$$

$$= \dots$$

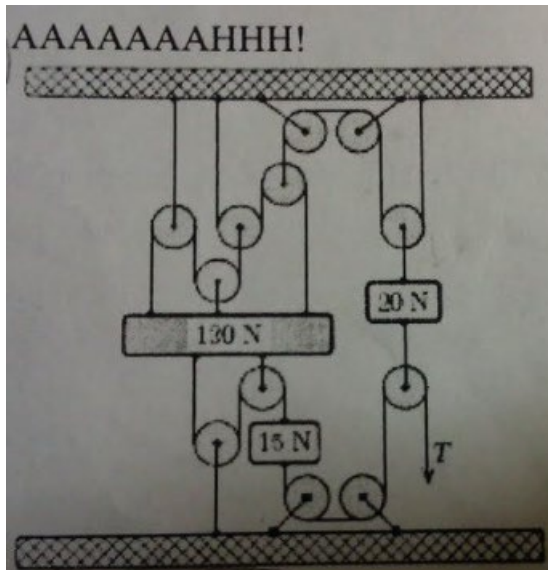
$$a_r = -37.6\ \frac{m}{s^2}$$

$$a_\theta = -10.9\ \frac{m}{s^2}$$

$$a = \sqrt{a_r^2 + a_\theta^2} =$$

$$= \dots$$

Absolute Dependent Motion: Pulleys and Ropes

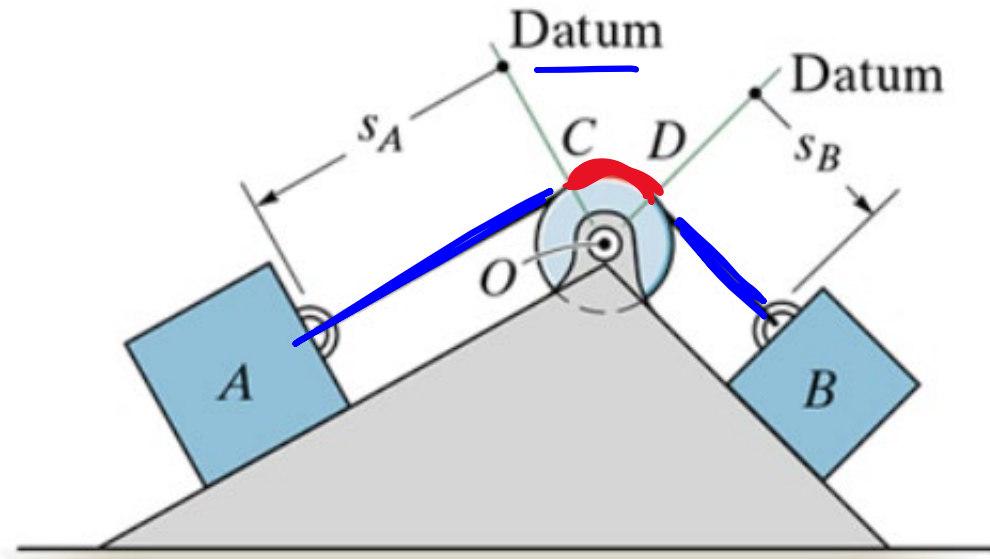


Text: 12.9

Content:

- Rope equation and paths equations
- Solving scary systems of blocks and pulleys

CONSTRAINED MOTION



- Big idea:

The motion of A and B are subject to the constraint dictated by the length of the rope:

$$\frac{d}{dt} [s_A + s_B + CD = \text{const} = L_{\text{rope}}]$$

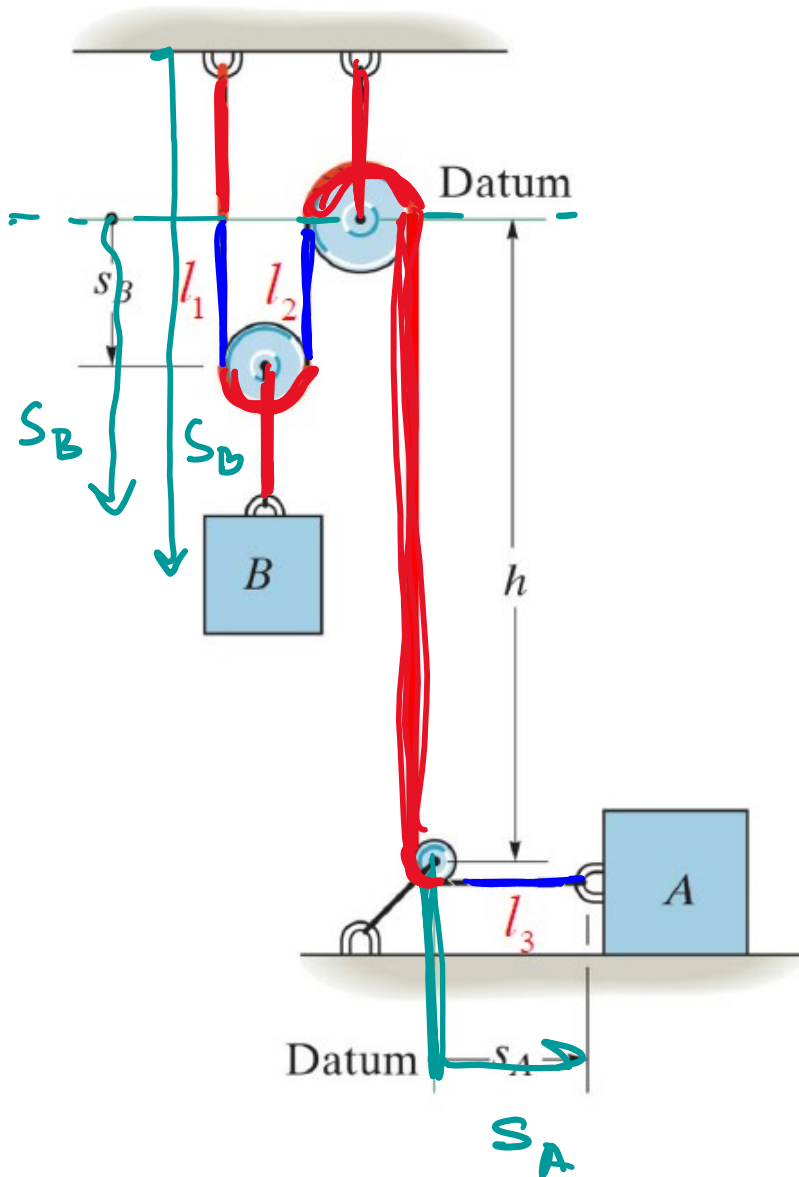
The derivative of this equation tells us that

$$\dot{s}_A = -\dot{s}_B$$

That means that these two blocks:

- Have the same speeds!
- When block A moves parallel to s_A , block B moves anti-parallel to $s_B \Rightarrow$ know the direction of motion!

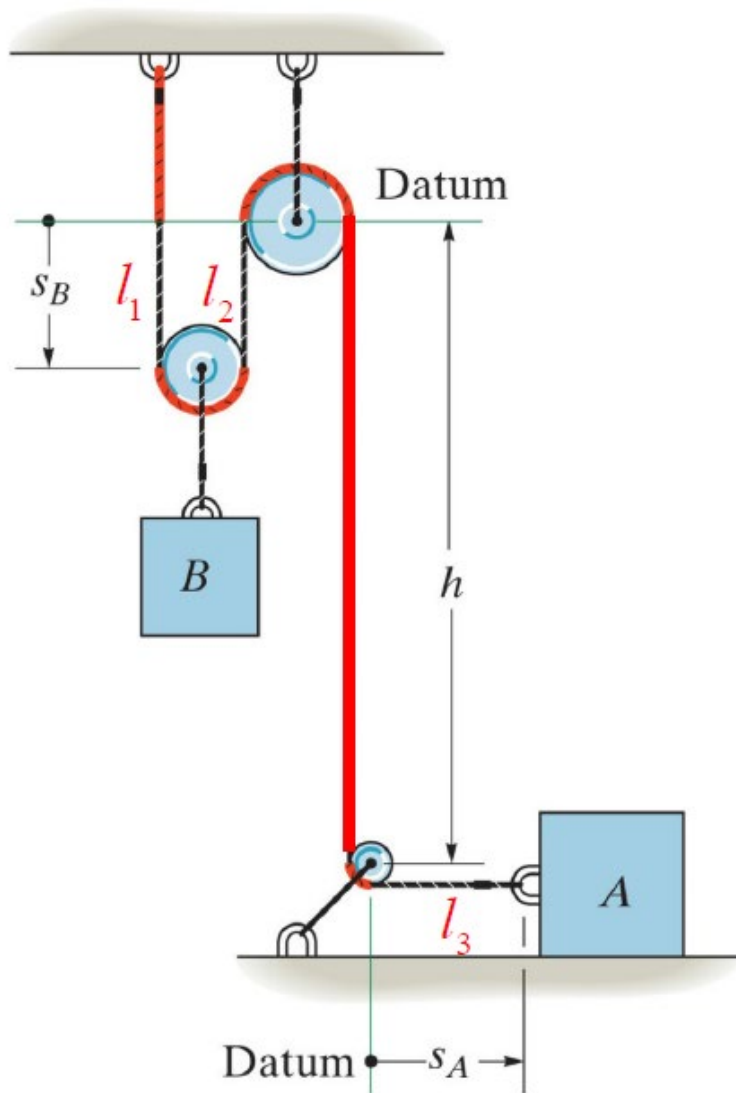
ROPE EQUATION & PATH EQUATION



Q: Determine the relationship between v_A and v_B

- Paths: s_A and s_B
 - Distances from a fixed point ("datum") to the object
 - Paths are directional
- Rope segments: l_1 , l_2 and l_3
 - All non-constant segments of the rope
 - They are just magnitudes
- Highlighted in red are all constant segments of the rope

ROPE EQUATION & PATH EQUATION



- Rope equation(s):

$$(1) \quad \triangleright L_{rope} = \underline{l_1} + \underline{l_2} + \underline{l_3} + const \Rightarrow \boxed{\underline{l_1 + l_2 + l_3 = const'}}$$

↑ All red segments ↑ L_{rope} - const

- Path equation(s):

$$(a) + (b) + (c) :$$

$$(a) \quad \triangleright \underline{l_1} = s_B \quad (b) \quad \triangleright \underline{l_2} = s_B \quad (c) \quad \triangleright \underline{l_3} = s_A$$

- Combine path equations to get a const :

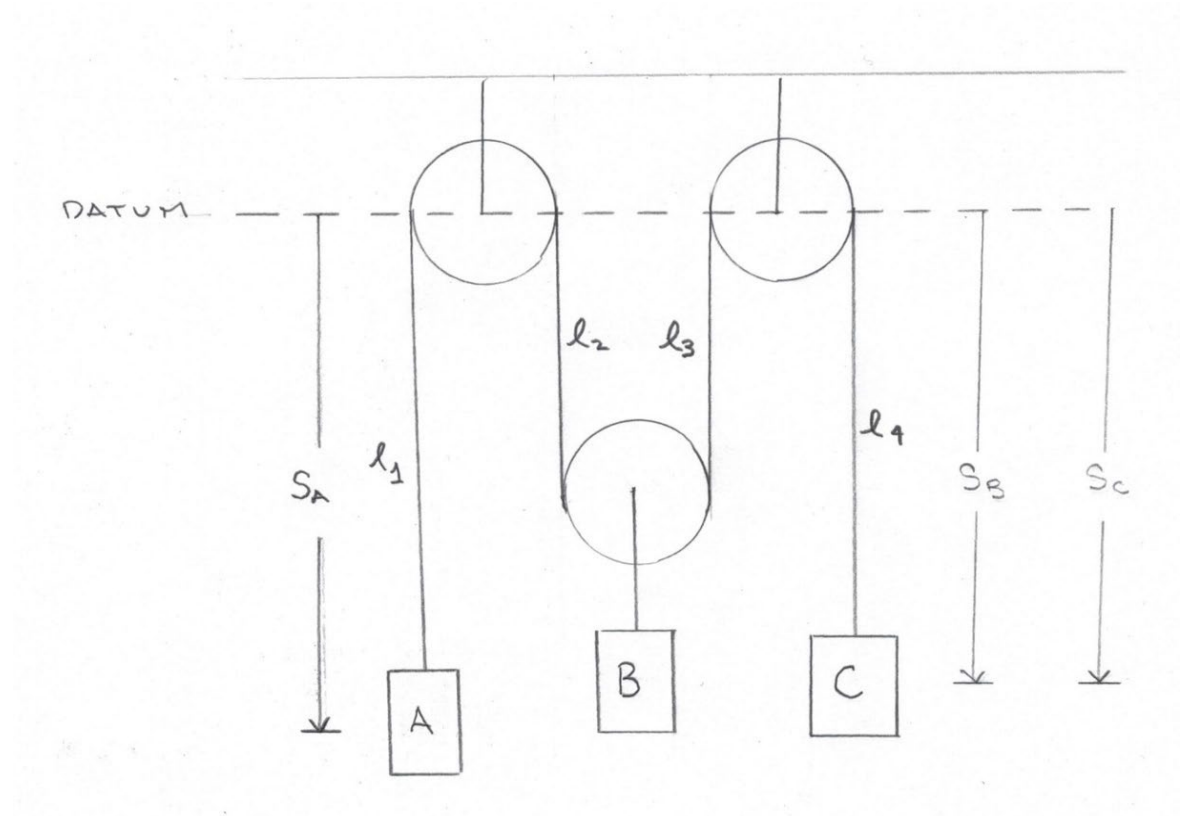
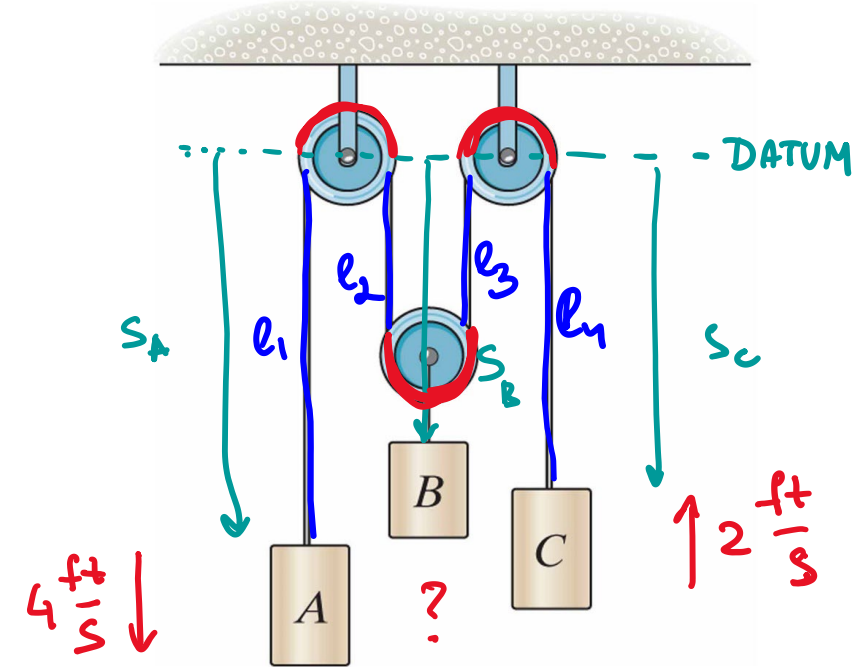
$$\triangleright \boxed{l_1 + l_2 + l_3} \frac{d}{dt} [s_A + 2s_B = const]$$

$$\triangleright 0 = \dot{s}_A + 2\dot{s}_B$$

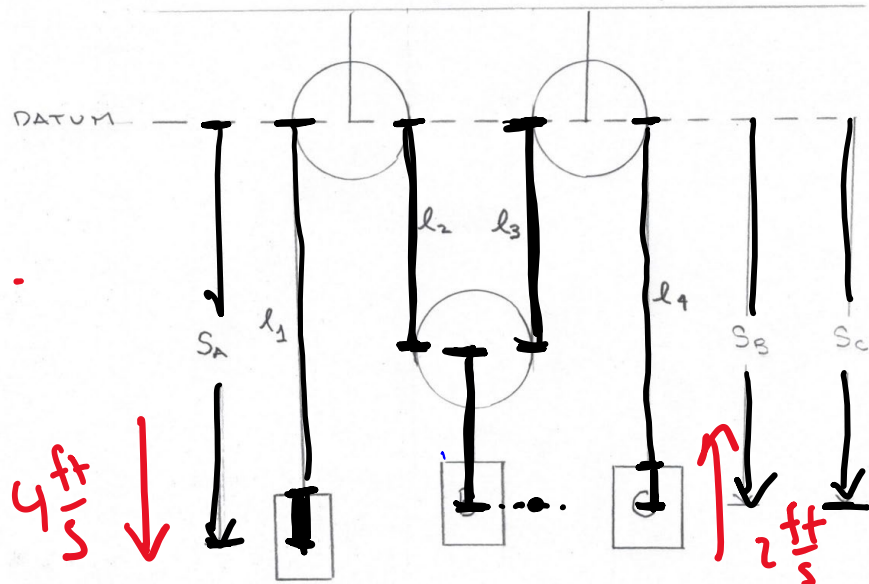
$$\triangleright v_A = -2v_B$$

- “-” tells us about their mutual directions
(if B moves along s_B , then A moves against s_A)

W8-2. Block A is moving down at 4 ft/s. Block C is moving up at 2 ft/s. Determine the speed and direction of motion of block B.



W8-2. Block A is moving down at 4 ft/s. Block C is moving up at 2 ft/s. Determine the speed and direction of motion of block B.



Q: v_B is:

- A. 1 ft/s, up
- B. 1 ft/s, down
- C. 2 ft/s, up
- D. 3 ft/s, down
- E. Something else

$$\dot{S}_A = +4 \frac{\text{ft}}{\text{s}}$$

$$\dot{S}_C = -2 \frac{\text{ft}}{\text{s}}$$

$$v_B = 1 \frac{\text{ft}}{\text{s}}, \text{ up}$$

Rope equation :

$$l_1 + l_2 + l_3 + l_4 + \text{const} = L_{\text{rope}}$$

$$(1) \quad \underline{l_1 + l_2 + l_3 + l_4 = \text{const}}$$

Path eqs:

$$(a) \quad \underline{l_1} + \text{const} = S_A$$

$$(b) \quad \underline{l_2} + \text{const} = S_B$$

$$(c) \quad \underline{l_3} + \text{const} = S_B$$

$$(d) \quad \underline{l_4} + \text{const} = S_C$$

(a) + (b) + (c) + (d):

$$\underline{l_1 + \text{const}} + \underline{l_2 + \text{const}} + \underline{l_3 + \text{const}} + \underline{l_4 + \text{const}} = S_A + 2S_B + S_C$$

$$\underline{l_1 + l_2 + l_3 + l_4} + \text{const} = S_A + 2S_B + S_C$$

$$\frac{d}{dt} [S_A + 2S_B + S_C = \text{const}]$$

$$\dot{S}_A + 2\dot{S}_B + \dot{S}_C = 0$$

$$\dot{S}_B = -\frac{1}{2}(\dot{S}_A + \dot{S}_C) = -1 \frac{\text{ft}}{\text{s}}$$