

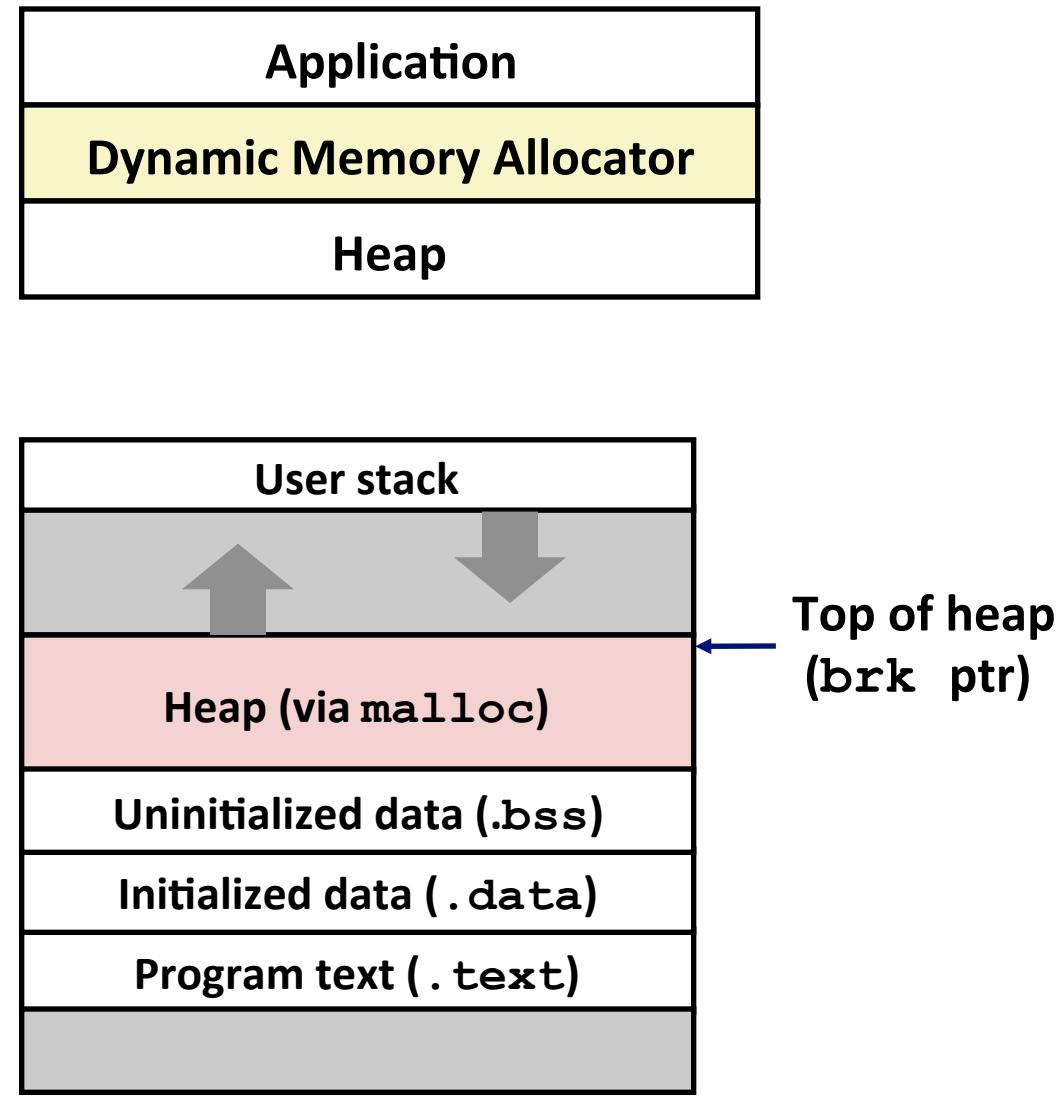
# **Dynamic Memory Allocation: Basic Concepts**

**adapted for CS367@GMU**

# **BASIC CONCEPTS**

# Dynamic Memory Allocation

- Programmers use *dynamic memory allocators* (such as `malloc`) to acquire VM at run time.
  - For data structures whose size is only known at runtime.
- Dynamic memory allocators manage an area of process virtual memory known as the *heap*.



# Dynamic Memory Allocation

- Allocator maintains heap as collection of variable sized *blocks*, which are either *allocated* or *free*
- Types of allocators
  - *Explicit allocator*: application allocates and frees space
    - E.g., malloc and free in C
  - *Implicit allocator*: application allocates, but does not free space
    - E.g. garbage collection in Java, ML, and Lisp

# The `malloc` Package

```
#include <stdlib.h>

void *malloc(size_t size)
```

- Successful:
  - Returns a pointer to a memory block of at least `size` bytes aligned to an 8-byte (x86) or 16-byte (x86-64) boundary
  - If `size == 0`, returns NULL
- Unsuccessful: returns NULL (0) and sets `errno`

```
void free(void *p)
```

- Returns the block pointed at by `p` to pool of available memory
- `p` must come from a previous call to `malloc` or `realloc`

## Other functions

- `calloc`: "clear-alloc". A `malloc` that initializes allocated block to 0's.
- `realloc`: Changes the size of a previously allocated block.
- `sbrk`: Used internally by allocators to grow or shrink the heap

# malloc Example

```
#include <stdio.h>
#include <stdlib.h>

void foo(int n) {
    int i, *p;

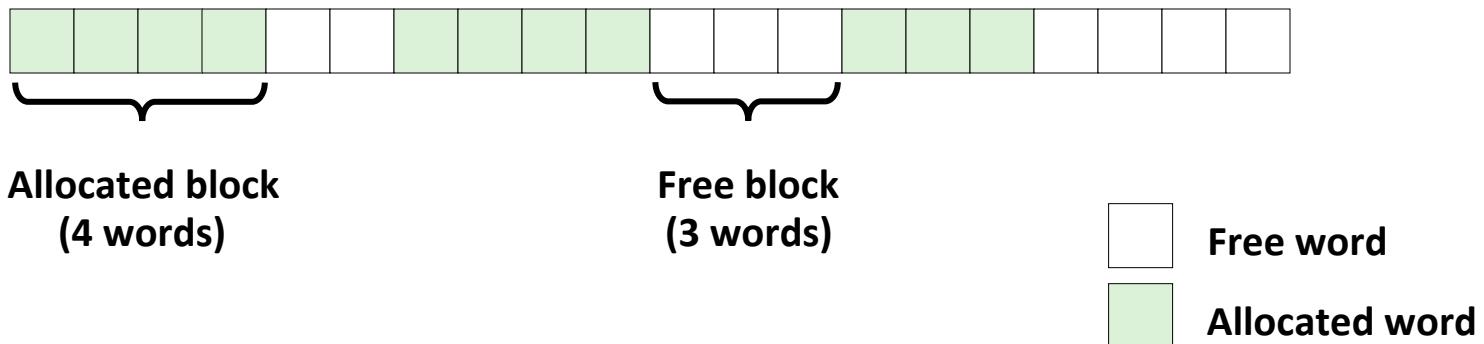
    /* Allocate a block of n ints */
    p = (int *) malloc(n * sizeof(int));
    if (p == NULL) {
        perror("malloc");
        exit(0);
    }

    /* Initialize allocated block */
    for (i=0; i<n; i++)
        p[i] = i;

    /* Return allocated block to the heap */
    free(p);
}
```

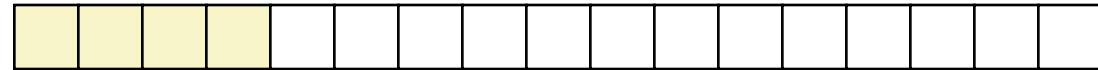
# Assumptions Made in This Lecture

- Memory is word addressed (each word can hold a pointer)
  - boxes ≠ bytes in these diagrams

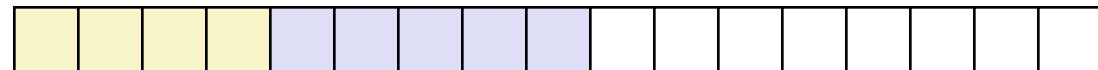


# Allocation Example

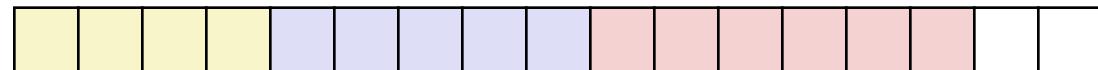
```
p1 = malloc(4)
```



```
p2 = malloc(5)
```



```
p3 = malloc(6)
```



```
free(p2)
```



```
p4 = malloc(2)
```



# Constraints

## ■ Applications

- Can issue arbitrary sequence of `malloc` and `free` requests
- `free` request must be to a `malloc`'d block

## ■ Allocators

- Can't control number or size of allocated blocks
- Must respond immediately to `malloc` requests
  - *i.e.*, can't reorder or buffer requests
- Must allocate blocks from free memory
  - *i.e.*, can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements
  - 8-byte (x86) or 16-byte (x86-64) alignment on Linux boxes
- Can manipulate and modify only free memory
- Can't move the allocated blocks once they are `malloc`'d
  - *i.e.*, compaction is not allowed

# Goals of Good malloc/free

## ■ Primary goals

- Good time performance for malloc and free
  - Ideally should take constant time (not always possible)
  - Should certainly not take linear time in the number of blocks
- Good space utilization
  - User allocated structures should be large fraction of the heap.
  - Want to minimize “fragmentation”.

## ■ Some other goals

- Good locality properties
  - Structures allocated close in time should be close in space
  - “Similar” objects should be allocated close in space
- Robust
  - Can check that free(p1) is on a valid allocated object p1
  - Can check that memory references are to allocated space

# Performance Goal: Throughput

- Given some sequence of `malloc` and `free` requests:
  - $R_0, R_1, \dots, R_k, \dots, R_{n-1}$
- Goals: maximize throughput and peak memory utilization
  - These goals are often conflicting
- Throughput:
  - Number of completed requests per unit time
  - Example:
    - 5,000 `malloc` calls and 5,000 `free` calls in 10 seconds
    - Throughput is 1,000 operations/second

# Performance Goal: Peak Memory Utilization

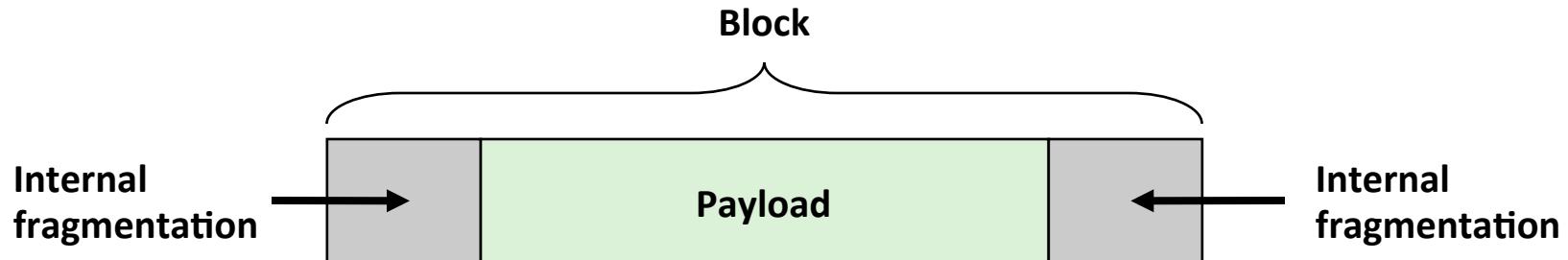
- Given some sequence of `malloc` and `free` requests:
  - $R_0, R_1, \dots, R_k, \dots, R_{n-1}$
- **Def:** *Aggregate payload*  $P_k$ 
  - `malloc(p)` results in a block with a *payload* of  $p$  bytes
  - After request  $R_k$  has completed, the *aggregate payload*  $P_k$  is the sum of currently allocated payloads
- **Def:** *Current heap size*  $H_k$ 
  - Assume  $H_k$  is monotonically nondecreasing
    - i.e., heap only grows when allocator uses `sbrk`
- **Def:** *Peak memory utilization after k+1 requests*
  - $U_k = (\max_{i \leq k} P_i) / H_k$

# Fragmentation

- Poor memory utilization caused by *fragmentation*
  - *internal* fragmentation
  - *external* fragmentation

# Internal Fragmentation

- For a given block, *internal fragmentation* occurs if payload is smaller than block size

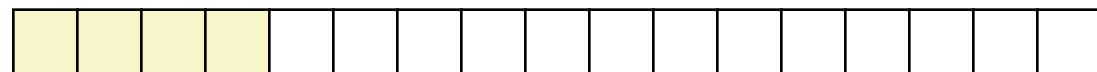


- Caused by
  - Overhead of maintaining heap data structures
  - Padding for alignment purposes
  - Explicit policy decisions  
(e.g., to return a big block to satisfy a small request)
- Depends only on the pattern of *previous* requests
  - Thus, easy to measure

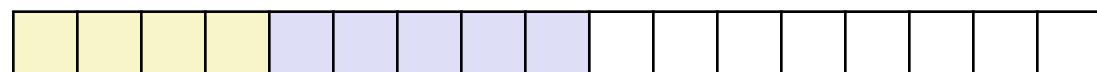
# External Fragmentation

- Occurs when there is enough aggregate heap memory, but no single free block is large enough

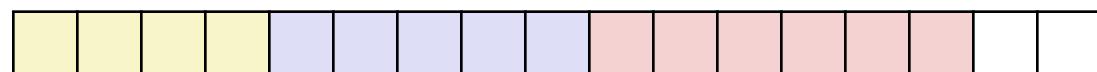
`p1 = malloc(4)`



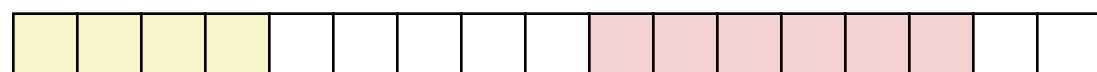
`p2 = malloc(5)`



`p3 = malloc(6)`



`free(p2)`



`p4 = malloc(6)`

*Oops! (what would happen now?)*

- Depends on the pattern of future requests
  - Thus, difficult to measure

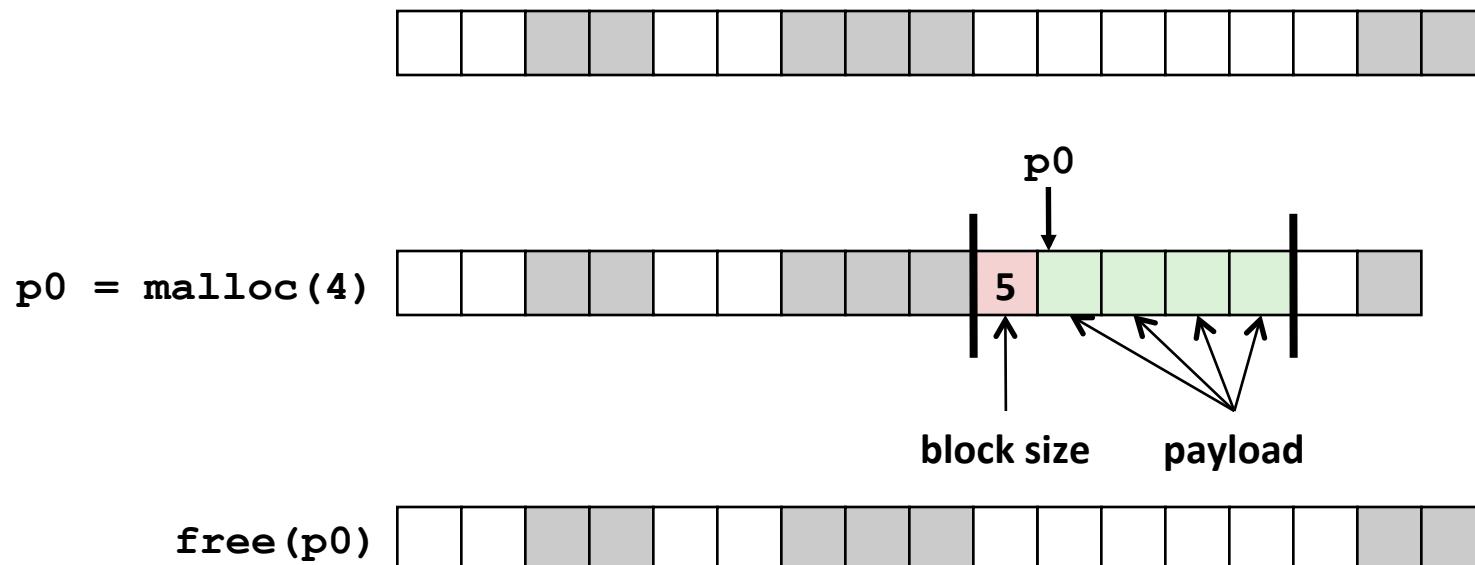
# Implementation Issues

- How do we know how much memory to free given just a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?

# Knowing How Much to Free

## ■ Standard method

- Keep the length of a block in the word preceding the block.
  - This word is often called the **header field** or **header**
- Requires an extra word for every allocated block

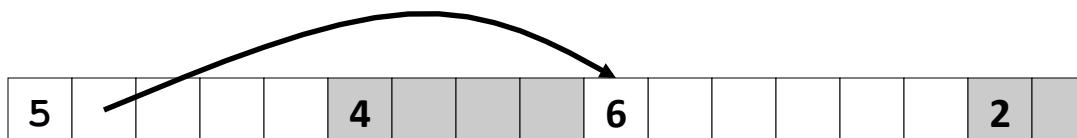


# Keeping Track of Free Blocks

- Method 1: *Implicit list* using length—links all blocks



- Method 2: *Explicit list* among the free blocks using pointers



- Method 3: *Segregated free list*

- Different free lists for different size classes

- Method 4: *Blocks sorted by size*

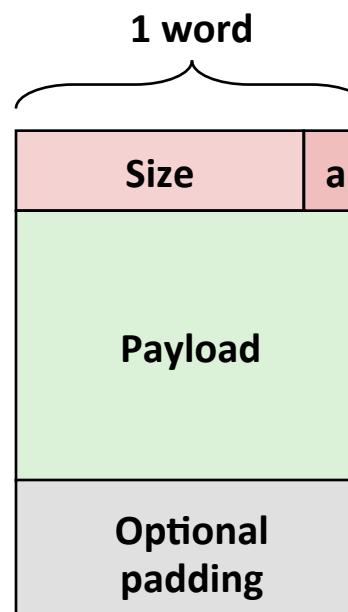
- Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

# **IMPLICIT FREE LISTS**

# Method 1: Implicit List

- For each block we need both size and allocation status
  - Could store this information in two words: wasteful!
- Standard trick
  - If blocks are aligned, some low-order address bits are always 0
  - Instead of storing an always-0 bit, use it as a allocated/free flag
  - When reading size word, must mask out this bit

*Format of  
allocated and  
free blocks*

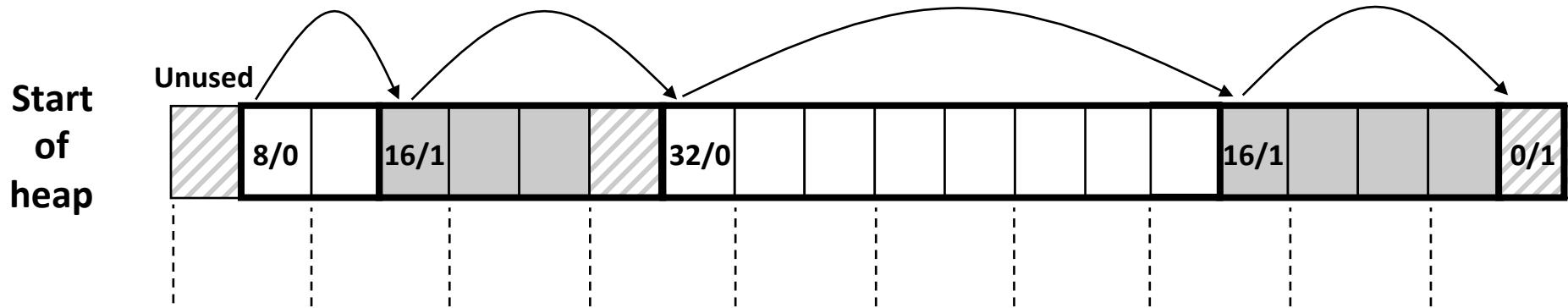


**a = 1: Allocated block**  
**a = 0: Free block**

**Size: block size**

**Payload: application data  
(allocated blocks only)**

# Detailed Implicit Free List Example



Double-word aligned

Allocated blocks: shaded  
Free blocks: unshaded  
Headers: labeled with size in bytes/allocated bit

# Implicit List: Finding a Free Block

## ■ *First fit:*

- Search list from beginning, choose *first* free block that fits:

```
p = start;
while ((p < end) &&      \\ not passed end
       ((*p & 1) ||      \\ already allocated
        (*p <= len)))    \\ too small
    p = p + (*p & -2); \\ goto next block (word addressed)
```

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause “splinters” at beginning of list

## ■ *Next fit:*

- Like first fit, but search list starting where previous search finished
- Should often be faster than first fit: avoids re-scanning unhelpful blocks
- Some research suggests that fragmentation is worse

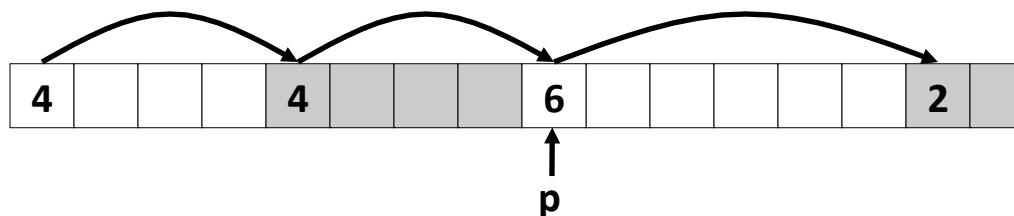
## ■ *Best fit:*

- Search the list, choose the *best* free block: fits, with fewest bytes left over
- Keeps fragments small—usually improves memory utilization
- Will typically run slower than first fit

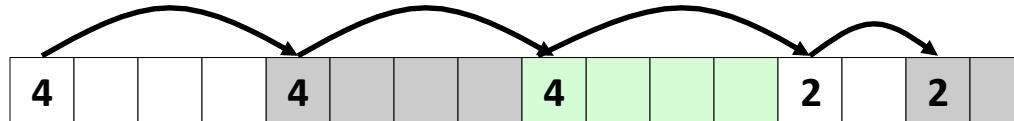
# Implicit List: Allocating in Free Block

## ■ Allocating in a free block: *splitting*

- Since allocated space might be smaller than free space, we might want to split the block



`addblock(p, 4)`



```
void addblock(ptr p, int len) {
    int newsize = ((len + 1) >> 1) << 1;      // round up to even
    int oldsize = *p & -2;                      // mask out low bit
    *p = newsize | 1;                          // set new length
    if (newsize < oldsize)
        *(p+newsize) = oldsize - newsize;      // set length in remaining
                                                // part of block
}
```

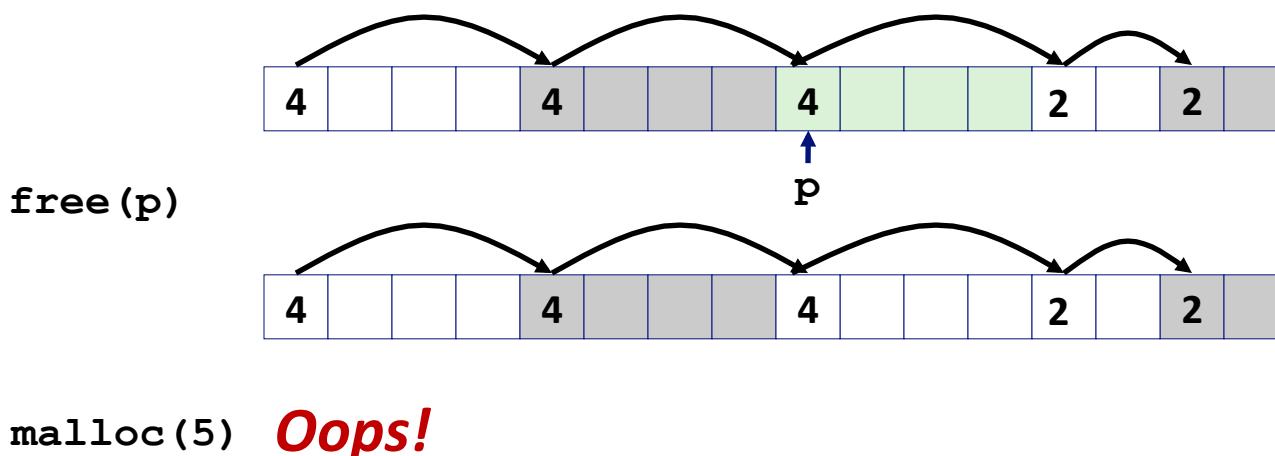
# Implicit List: Freeing a Block

## ■ Simplest implementation:

- Need only clear the “allocated” flag

```
void free_block(ptr p) { *p = *p & -2 }
```

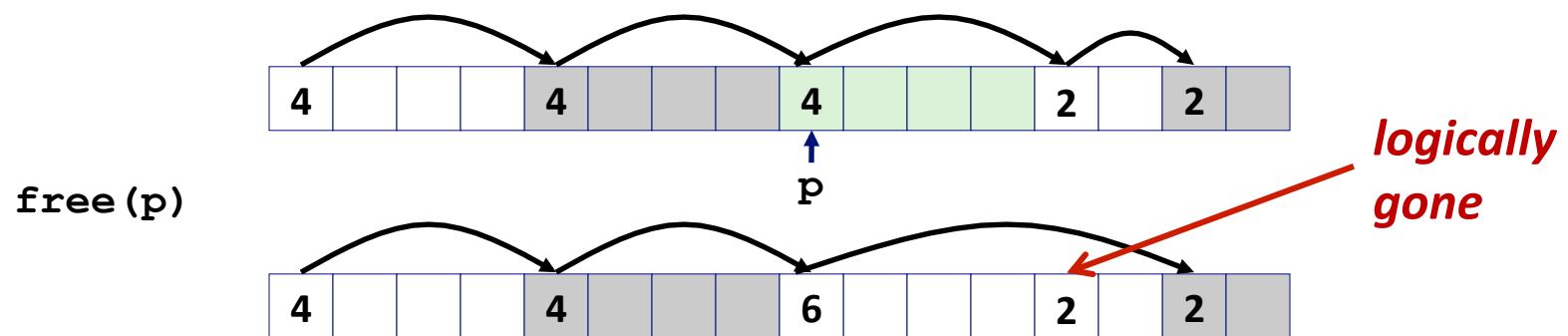
- But can lead to “false fragmentation”



*There is enough free space, but the allocator won't be able to find it*

# Implicit List: Coalescing

- Join (*coalesce*) with next/previous blocks, if they are free
  - Coalescing with next block



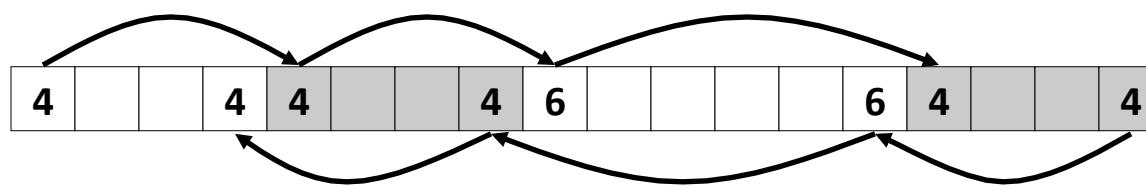
```
void free_block(ptr p) {
    *p = *p & -2;                      // clear allocated flag
    next = p + *p;                       // find next block
    if ((*next & 1) == 0)
        *p = *p + *next;                // add to this block if
                                         //      not allocated
}
```

- But how do we coalesce with *previous* block?

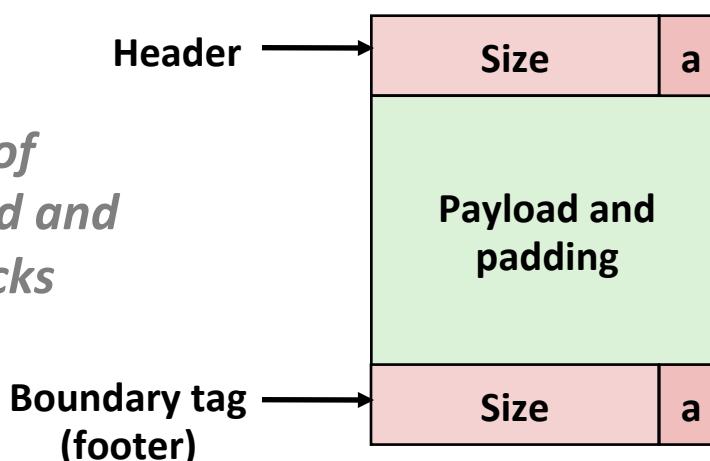
# Implicit List: Bidirectional Coalescing

## ■ **Boundary tags** [Knuth73]

- Replicate size/allocated word at “bottom” (end) of free blocks
- Allows us to traverse the “list” backwards, but requires extra space
- Important and general technique!



*Format of  
allocated and  
free blocks*

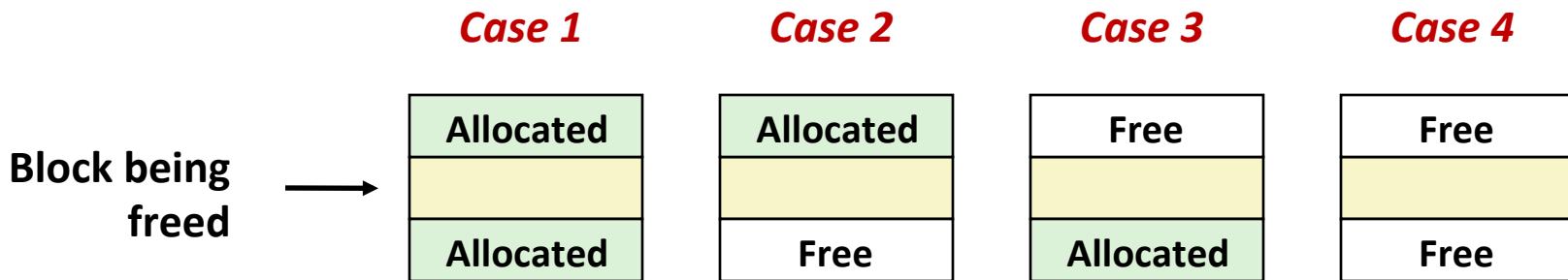


$a = 1$ : Allocated block  
 $a = 0$ : Free block

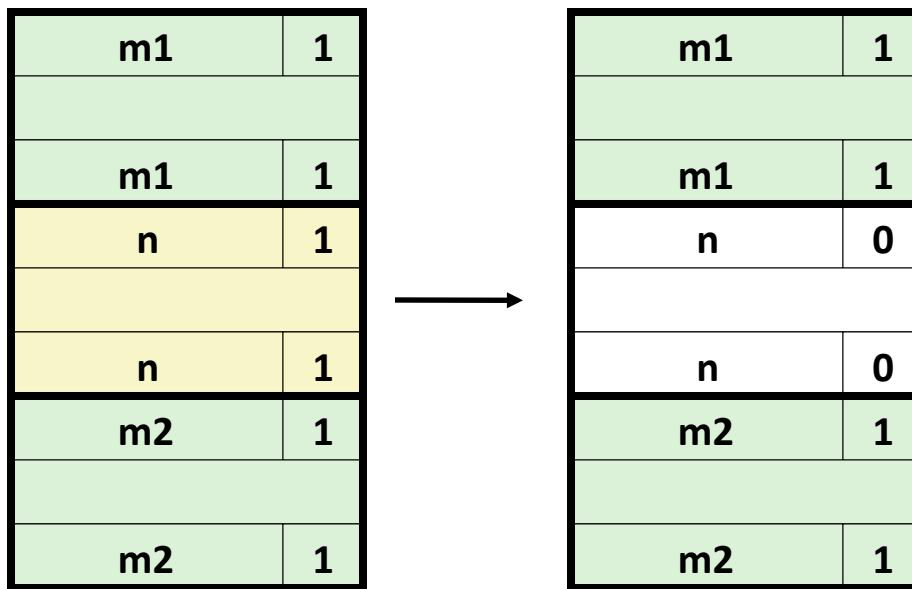
Size: Total block size

Payload: Application data  
(allocated blocks only)

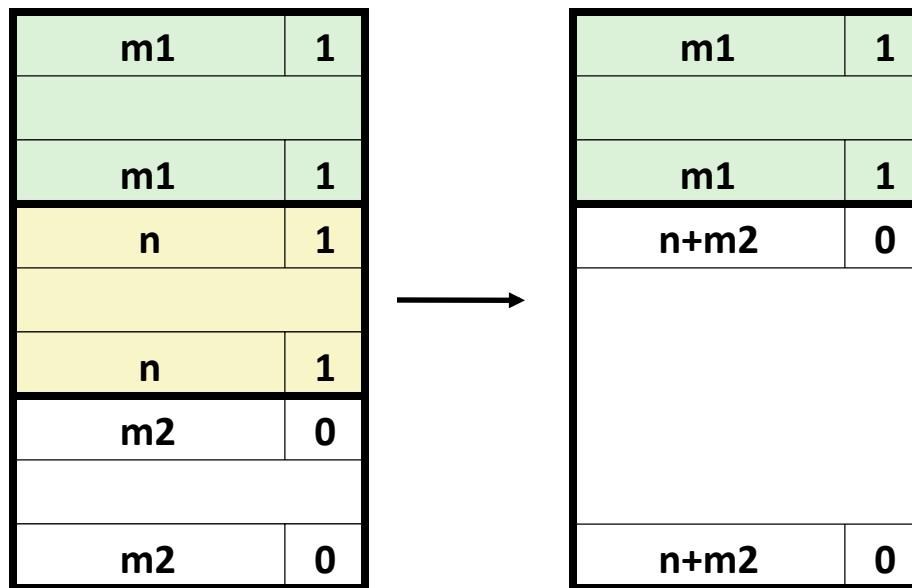
# Constant Time Coalescing



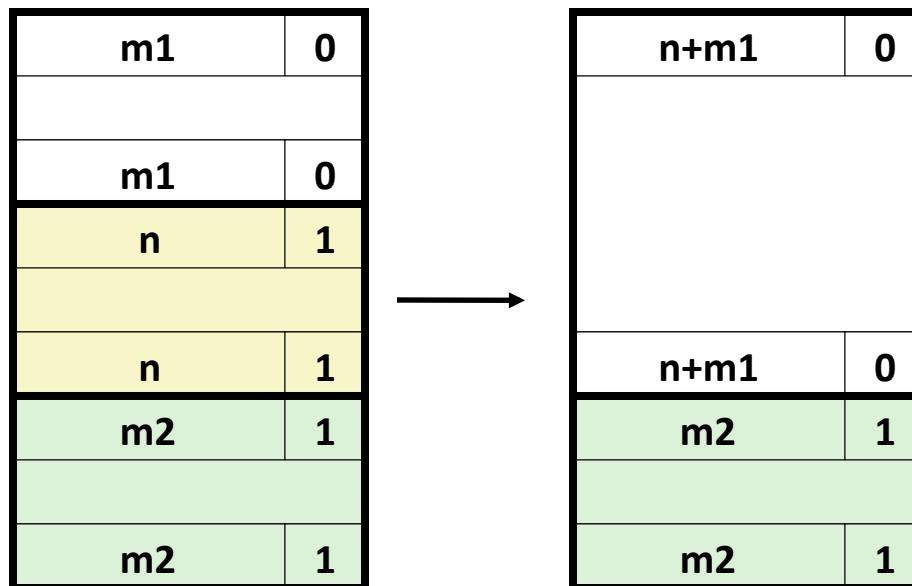
# Constant Time Coalescing (Case 1)



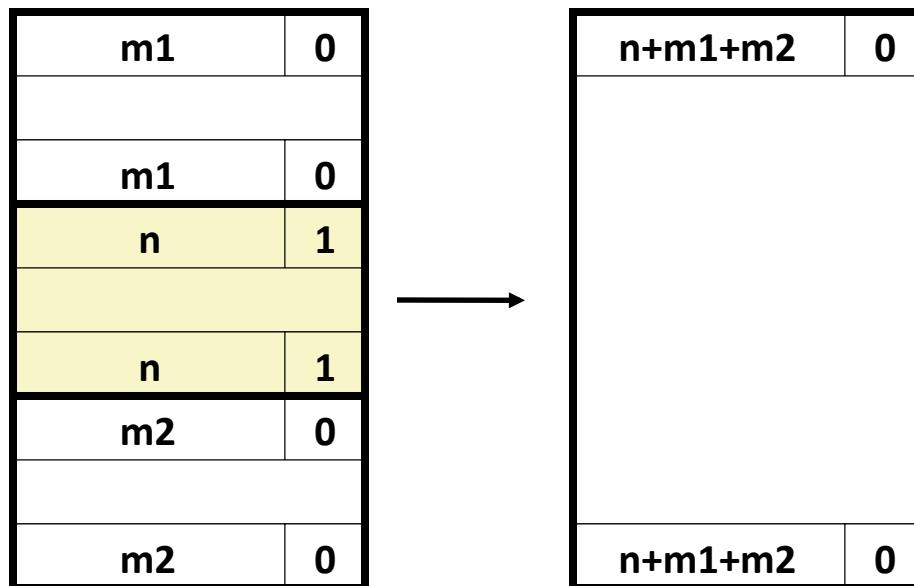
# Constant Time Coalescing (Case 2)



# Constant Time Coalescing (Case 3)



# Constant Time Coalescing (Case 4)



# Disadvantages of Boundary Tags

- Internal fragmentation
- Can it be optimized?
  - Which blocks need the footer tag?
  - What does that mean?

# Summary of Key Allocator Policies

## ■ Placement policy:

- First-fit, next-fit, best-fit, etc.
- Trades off lower throughput for less fragmentation
- ***Interesting observation:*** segregated free lists (next lecture) approximate a best fit placement policy without having to search entire free list

## ■ Splitting policy:

- When do we go ahead and split free blocks?
- How much internal fragmentation are we willing to tolerate?

## ■ Coalescing policy:

- ***Immediate coalescing:*** coalesce each time `free` is called
- ***Deferred coalescing:*** try to improve performance of `free` by deferring coalescing until needed. Examples:
  - Coalesce as you scan the free list for `malloc`
  - Coalesce when the amount of external fragmentation reaches some threshold

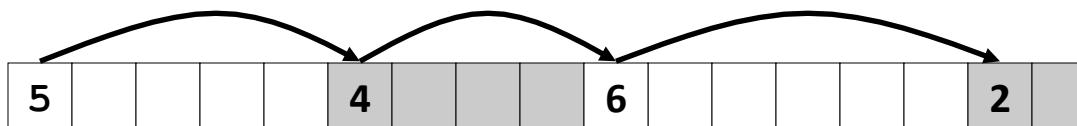
# Implicit Lists: Summary

- **Implementation:** very simple
- **Allocate cost:**
  - linear time worst case
- **Free cost:**
  - constant time worst case
  - even with coalescing
- **Memory usage:**
  - will depend on placement policy
  - First-fit, next-fit or best-fit
- **Not used in practice for `malloc/free` because of linear-time allocation**
  - used in many special purpose applications
- **However, the concepts of splitting and boundary tag coalescing are general to *all* allocators**

# **EXPLICIT FREE LISTS**

# Keeping Track of Free Blocks

- Method 1: *Implicit free list* using length—links all blocks



- Method 2: *Explicit free list* among the free blocks using pointers



- Method 3: *Segregated free list*

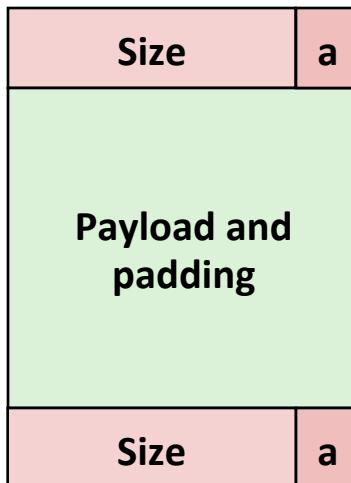
- Different free lists for different size classes

- Method 4: *Blocks sorted by size*

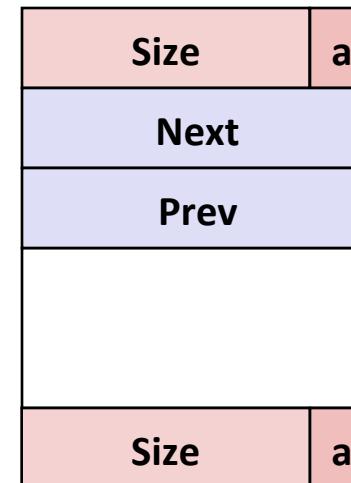
- Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

# Explicit Free Lists

Allocated (as before)



Free



## ■ Maintain list(s) of *free* blocks, not *all* blocks

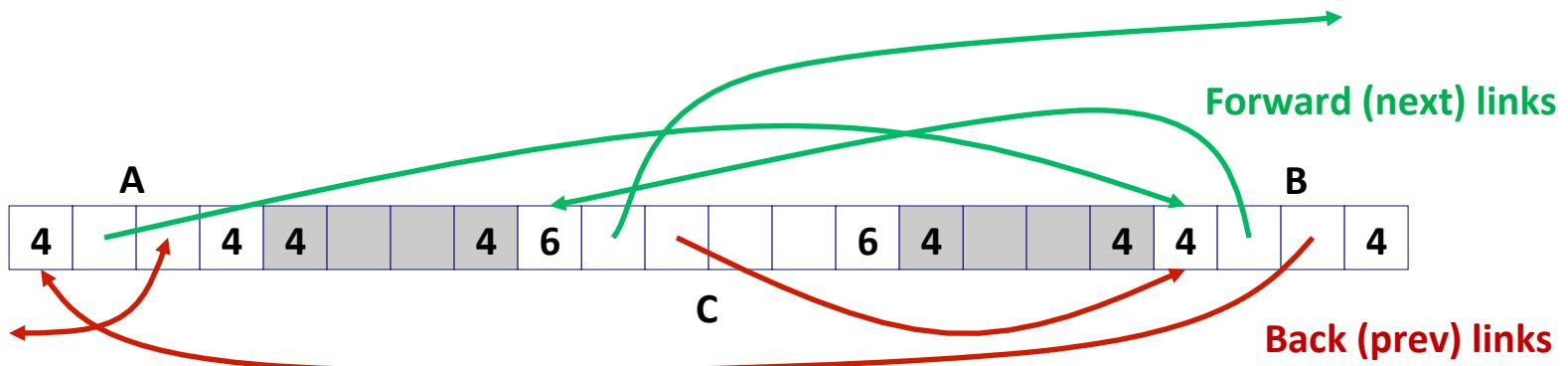
- The “next” free block could be anywhere
  - So we need to store forward/back pointers, not just sizes
- Still need boundary tags for coalescing
- Luckily we track only free blocks, so we can use payload area

# Explicit Free Lists

- Logically:



- Physically: blocks can be in any order



# Allocating From Explicit Free Lists

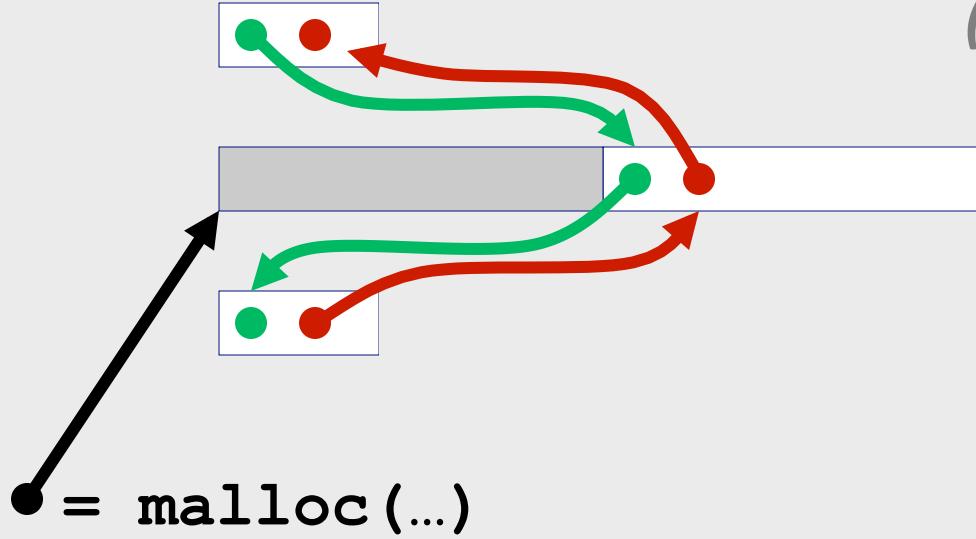
conceptual graphic

*Before*



*After*

*(with splitting)*



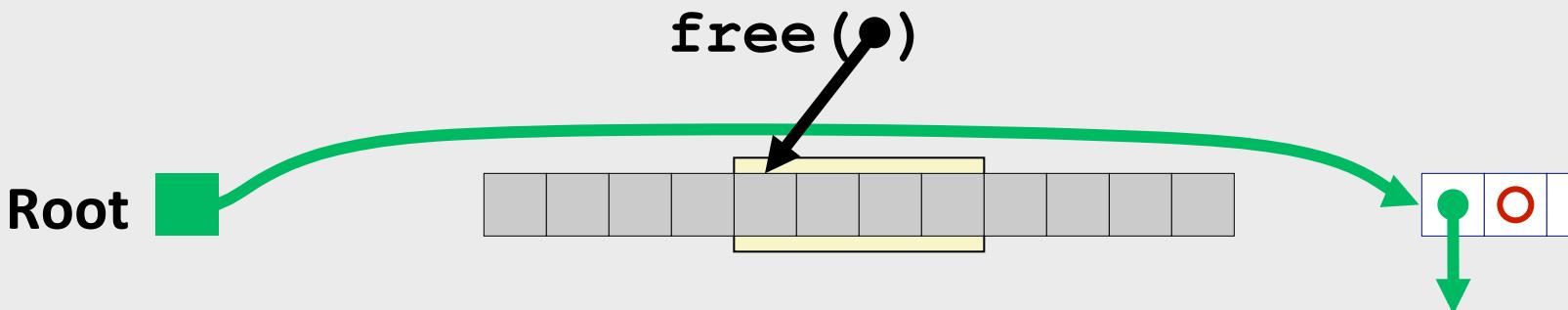
# Freeing With Explicit Free Lists

- ***Insertion policy:*** Where in the free list do you put a newly freed block?
- **LIFO (last-in-first-out) policy**
  - Insert freed block at the beginning of the free list
  - ***Pro:*** simple and constant time
  - ***Con:*** studies suggest fragmentation is worse than address ordered
- **Address-ordered policy**
  - Insert freed blocks so that free list blocks are always in address order:  
 $addr(prev) < addr(curr) < addr(next)$
  - ***Con:*** requires search
  - ***Pro:*** studies suggest fragmentation is lower than LIFO

# Freeing With a LIFO Policy (Case 1)

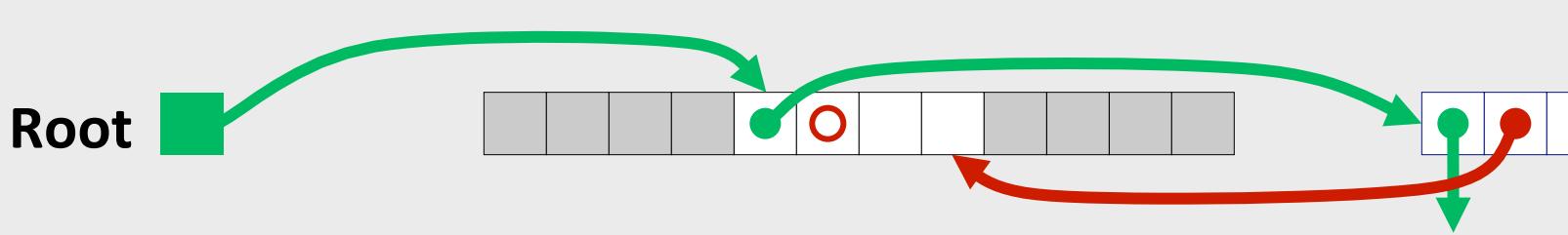
conceptual graphic

*Before*



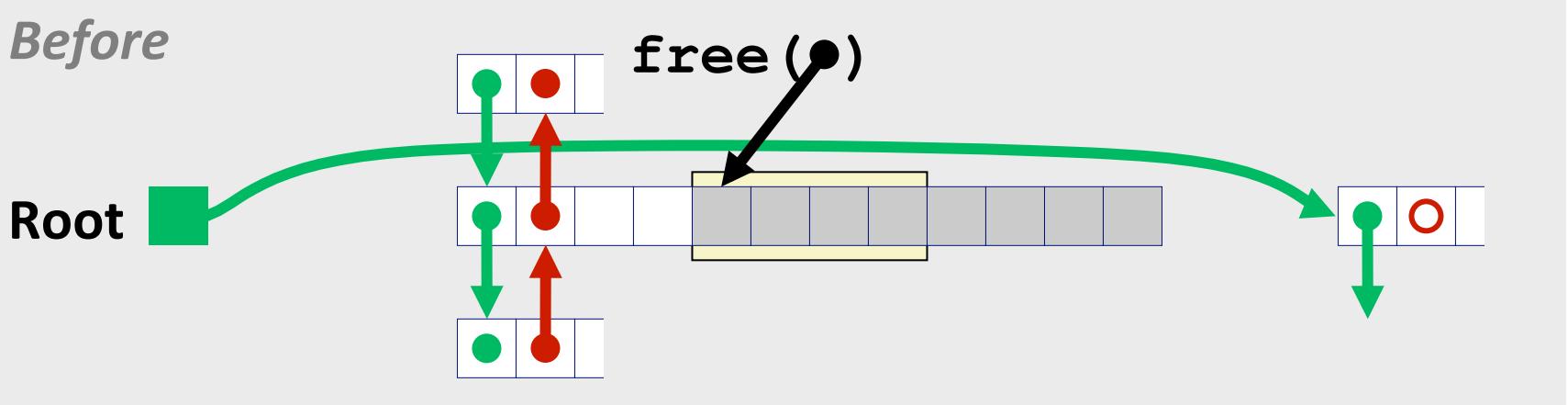
- Insert the freed block at the root of the list

*After*

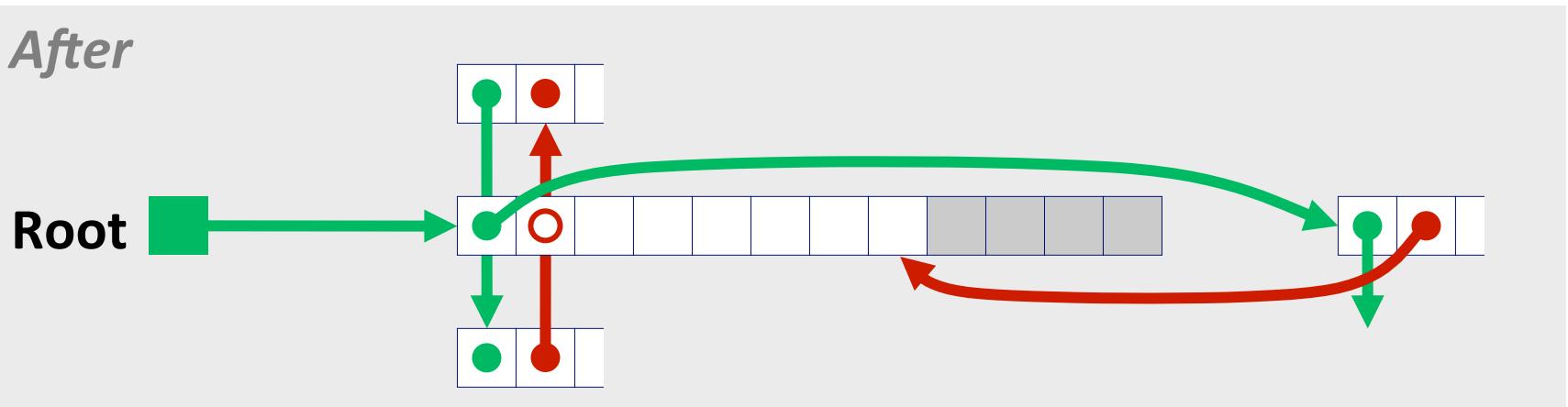


# Freeing With a LIFO Policy (Case 2)

conceptual graphic



- Splice out predecessor block, coalesce both memory blocks, and insert the new block at the root of the list



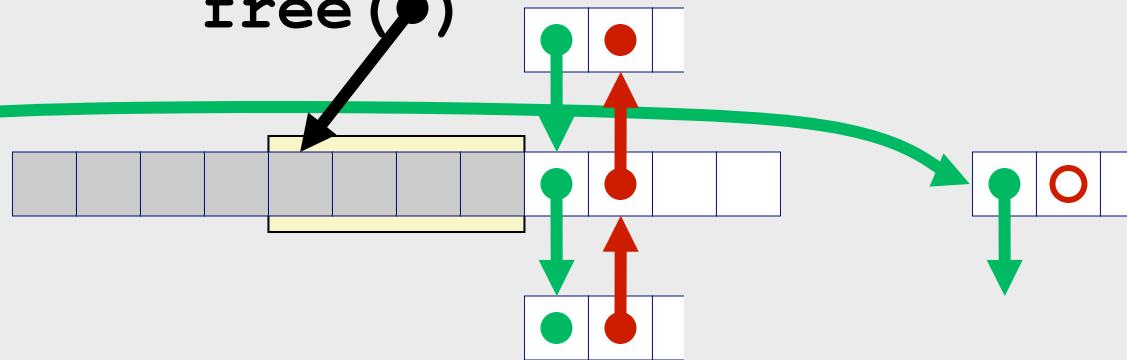
# Freeing With a LIFO Policy (Case 3)

conceptual graphic

*Before*

Root

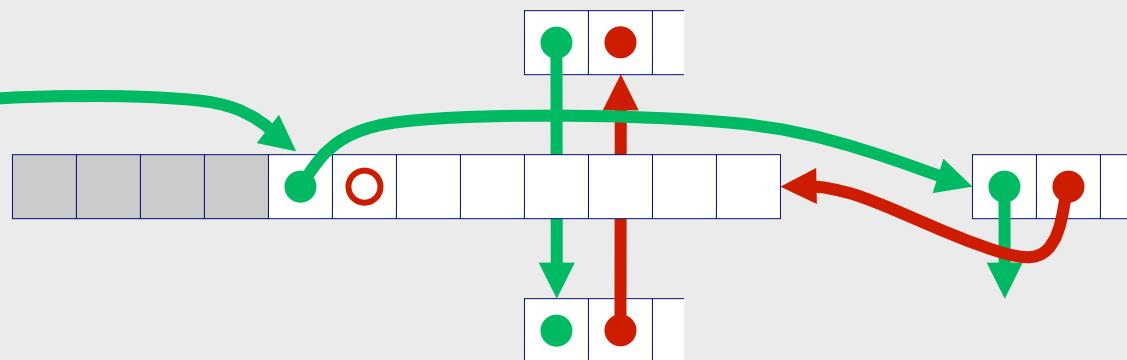
`free (•)`



- Splice out successor block, coalesce both memory blocks and insert the new block at the root of the list

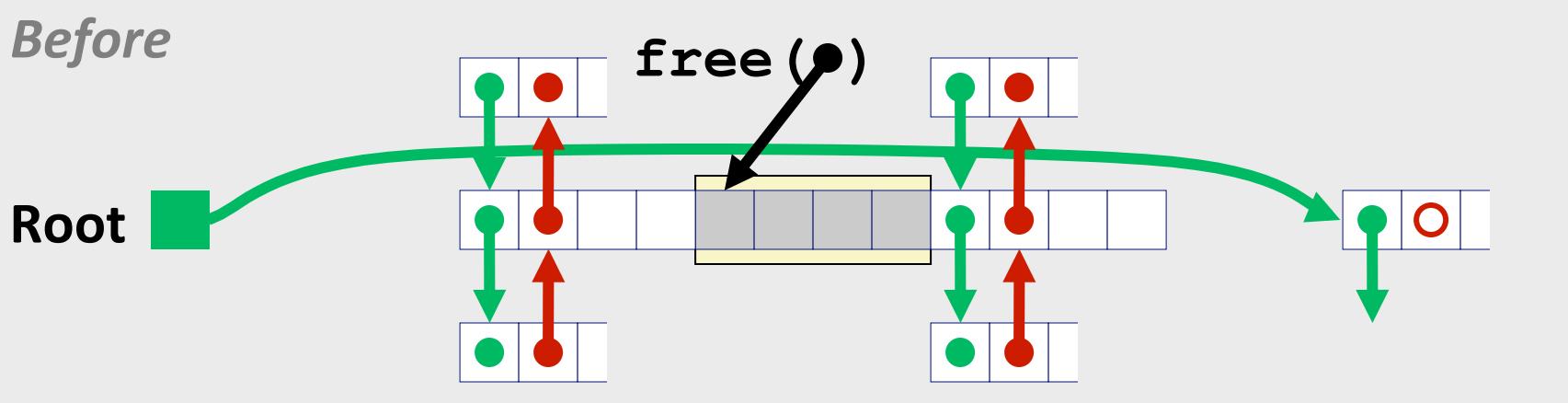
*After*

Root

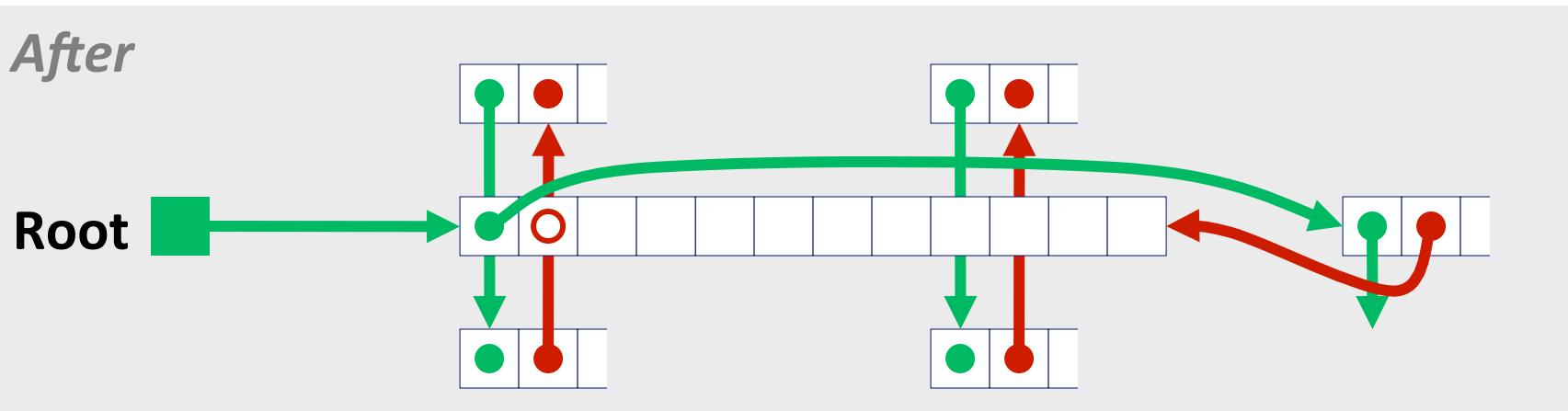


# Freeing With a LIFO Policy (Case 4)

conceptual graphic



- Splice out predecessor and successor blocks, coalesce all 3 memory blocks and insert the new block at the root of the list



# Explicit List Summary

## ■ Comparison to implicit list:

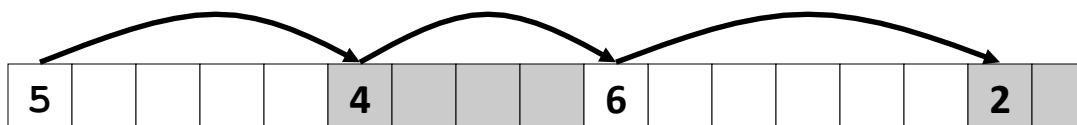
- Allocate is linear time in number of *free* blocks instead of *all* blocks
  - *Much faster* when most of the memory is full
- Slightly more complicated allocate and free since needs to splice blocks in and out of the list
- Some extra space for the links (2 extra words needed for each block)
  - Does this increase internal fragmentation?

## ■ Most common use of linked lists is in conjunction with segregated free lists

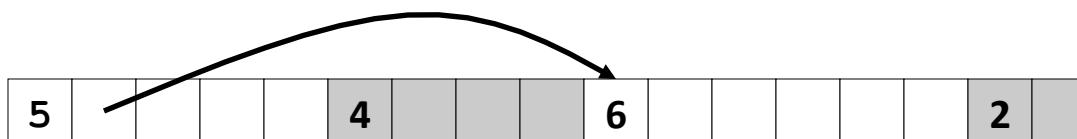
- Keep multiple linked lists of different size classes, or possibly for different types of objects

# Keeping Track of Free Blocks

- Method 1: *Implicit list* using length—links all blocks



- Method 2: *Explicit list* among the free blocks using pointers



- Method 3: *Segregated free list*

- Different free lists for different size classes

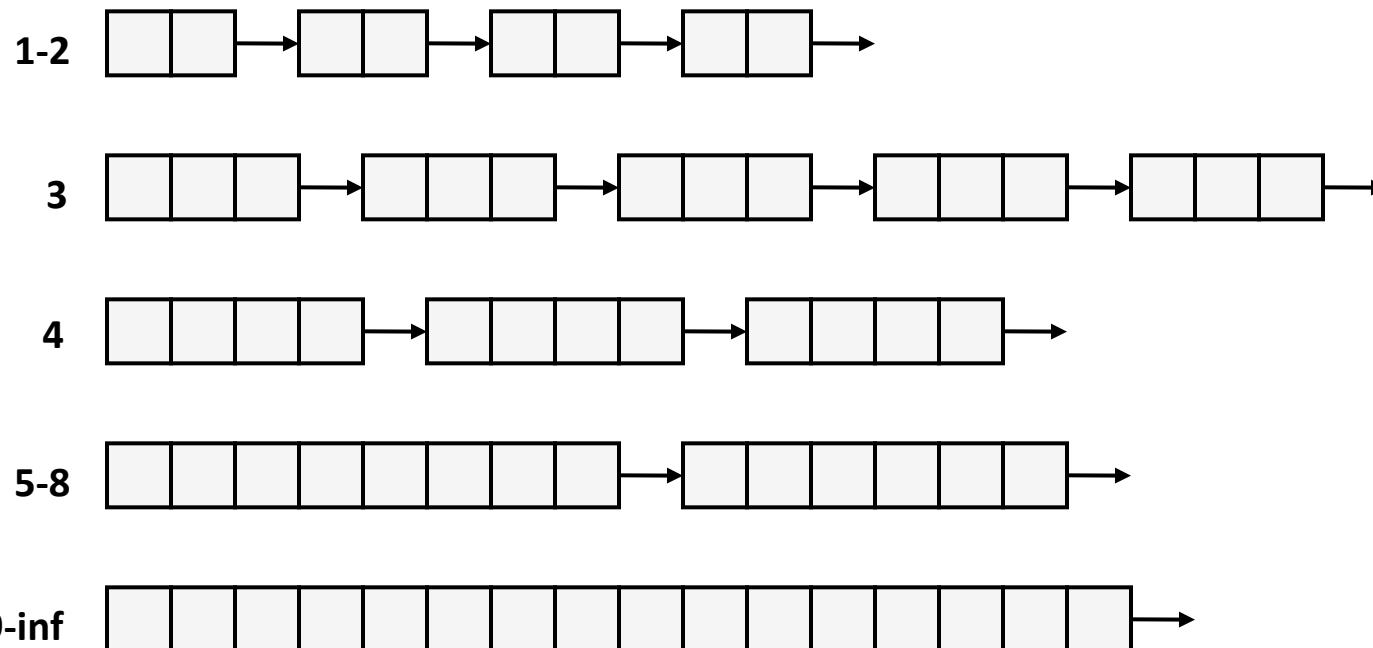
- Method 4: *Blocks sorted by size*

- Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

# **SEGREGATED FREE LISTS**

# Segregated List (Seglist) Allocators

- Each *size class* of blocks has its own free list



- Often have separate classes for each small size
- For larger sizes: One class for each two-power size

# Seglist Allocator

- Given an array of free lists, each one for some size class
- To allocate a block of size  $n$ :
  - Search appropriate free list for block of size  $m > n$
  - If an appropriate block is found:
    - Split block and place fragment on appropriate list (optional)
  - If no block is found, try next larger class
  - Repeat until block is found
- If no block is found:
  - Request additional heap memory from OS (using `sbrk()`)
  - Allocate block of  $n$  bytes from this new memory
  - Place remainder as a single free block in largest size class.

# Seglist Allocator (cont.)

- To free a block:
  - Coalesce and place on appropriate list
- Advantages of seglist allocators
  - Higher throughput
    - log time for power-of-two size classes
  - Better memory utilization
    - First-fit search of segregated free list approximates a best-fit search of entire heap.
    - Extreme case: Giving each block its own size class is equivalent to best-fit.

# More Info on Allocators

- D. Knuth, “*The Art of Computer Programming*”, 2<sup>nd</sup> edition, Addison Wesley, 1973
  - The classic reference on dynamic storage allocation
- Wilson et al, “*Dynamic Storage Allocation: A Survey and Critical Review*”, Proc. 1995 Int’l Workshop on Memory Management, Kinross, Scotland, Sept, 1995.
  - Comprehensive survey
  - Available from CS:APP student site ([csapp.cs.cmu.edu](http://csapp.cs.cmu.edu))

# **GARBAGE COLLECTION**

# Implicit Memory Management: Garbage Collection

- ***Garbage collection:*** automatic reclamation of heap-allocated storage—application never has to free

```
void foo() {  
    int *p = malloc(128);  
    return; /* p block is now garbage */  
}
```

- Common in many dynamic languages:
  - Python, Ruby, Java, Perl, ML, Lisp, Mathematica
- Variants (“conservative” garbage collectors) exist for C and C++
  - However, cannot necessarily collect all garbage

# Garbage Collection

- **How does the memory manager know when memory can be freed?**
  - In general we cannot know what is going to be used in the future since it depends on conditionals
  - But we can tell that certain blocks cannot be used if there are no pointers to them
- **Must make certain assumptions about pointers**
  - Memory manager can distinguish pointers from non-pointers
  - All pointers point to the start of a block
  - Cannot hide pointers  
(e.g., by coercing them to an `int`, and then back again)

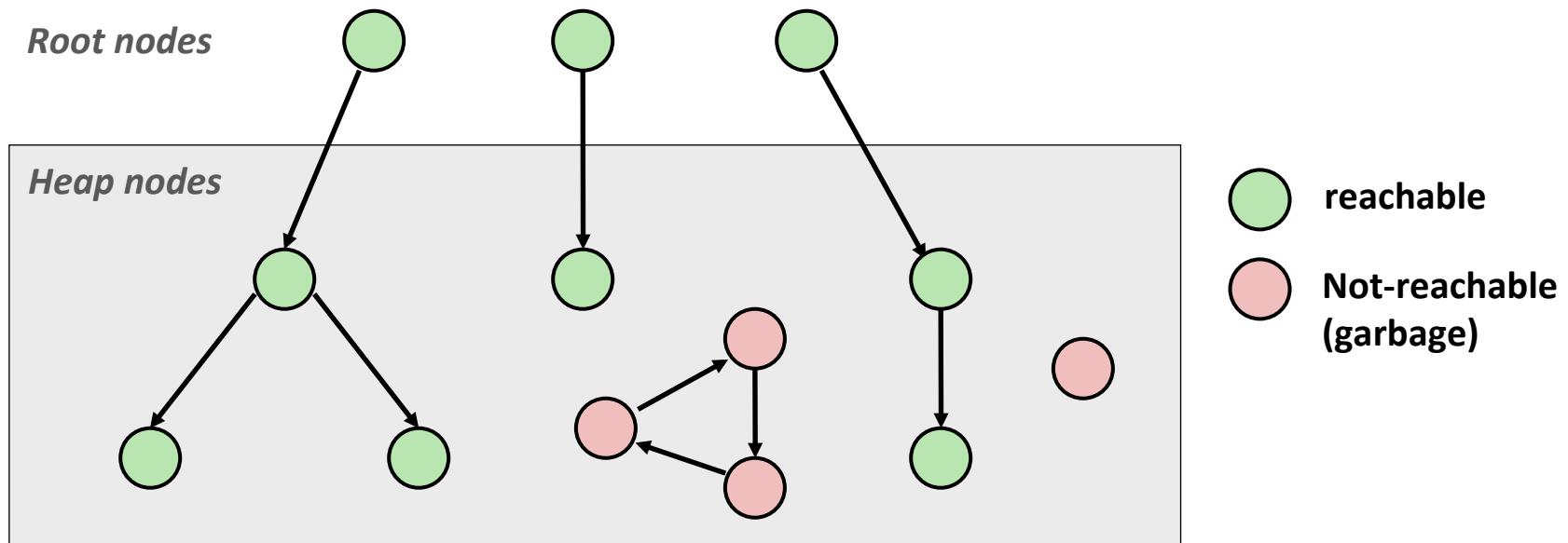
# Classical GC Algorithms

- **Mark-and-sweep collection (McCarthy, 1960)**
  - Does not move blocks (unless you also “compact”)
- **Reference counting (Collins, 1960)**
  - Does not move blocks (not discussed)
- **Copying collection (Minsky, 1963)**
  - Moves blocks (not discussed)
- **Generational Collectors (Lieberman and Hewitt, 1983)**
  - Collection based on lifetimes
    - Most allocations become garbage very soon
    - So focus reclamation work on zones of memory recently allocated
- **For more information:**  
**Jones and Lin, “*Garbage Collection: Algorithms for Automatic Dynamic Memory*”, John Wiley & Sons, 1996.**

# Memory as a Graph

## ■ We view memory as a directed graph

- Each block is a node in the graph
- Each pointer is an edge in the graph
- Locations not in the heap that contain pointers into the heap are called **root** nodes (e.g. registers, locations on the stack, global variables)

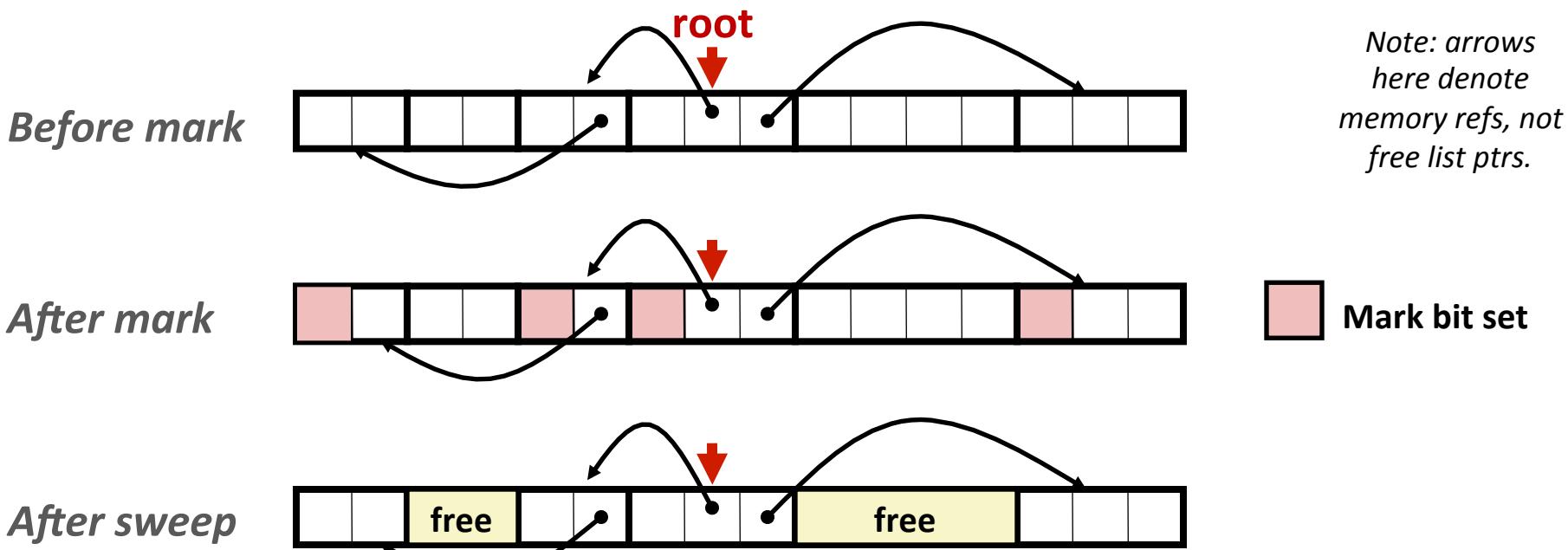


A node (block) is **reachable** if there is a path from any root to that node.

Non-reachable nodes are **garbage** (cannot be needed by the application)

# Mark and Sweep Collecting

- Can build on top of malloc/free package
  - Allocate using malloc until you “run out of space”
- When out of space:
  - Use extra **mark bit** in the head of each block
  - **Mark:** Start at roots and set mark bit on each reachable block
  - **Sweep:** Scan all blocks and free blocks that are not marked



# Assumptions For a Simple Implementation

## ■ Application

- **new (n)**: returns pointer to new block with all locations cleared
- **read (b, i)** : read location **i** of block **b** into register
- **write (b, i, v)** : write **v** into location **i** of block **b**

## ■ Each block will have a header word

- addressed as **b [-1]**, for a block **b**
- Used for different purposes in different collectors

## ■ Instructions used by the Garbage Collector

- **is\_ptr (p)** : determines whether **p** is a pointer
- **length (b)**: returns the length of block **b**, not including the header
- **get\_roots ()**: returns all the roots

# Mark and Sweep (cont.)

## Mark using depth-first traversal of the memory graph

```
ptr mark(ptr p) {
    if (!is_ptr(p)) return;           // do nothing if not pointer
    if (markBitSet(p)) return;        // check if already marked
    setMarkBit(p);                  // set the mark bit
    for (i=0; i < length(p); i++)   // call mark on all words
        mark(p[i]);                //     in the block
    return;
}
```

## Sweep using lengths to find next block

```
ptr sweep(ptr p, ptr end) {
    while (p < end) {
        if markBitSet(p)
            clearMarkBit();
        else if (allocateBitSet(p))
            free(p);
        p += length(p);
    }
}
```

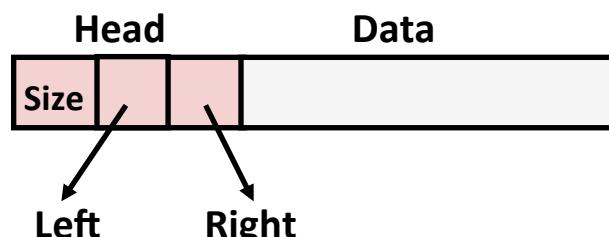
# Conservative Mark & Sweep in C

- A “conservative garbage collector” for C programs
  - `is_ptr()` determines if a word is a pointer by checking if it points to an allocated block of memory
  - But, in C pointers can point to the middle of a block



## ■ So how to find the beginning of the block?

- Can use a balanced binary tree to keep track of all allocated blocks (key is start-of-block)
- Balanced-tree pointers can be stored in header (use two additional words)



**Left:** smaller addresses  
**Right:** larger addresses

# **MEMORY-RELATED PERILS AND PITFALLS**

# Memory-Related Perils and Pitfalls

- Dereferencing bad pointers
- Reading uninitialized memory
- Overwriting memory
- Referencing nonexistent variables
- Freeing blocks multiple times
- Referencing freed blocks
- Failing to free blocks

# C operators

## Operators

( )	[ ]	->	.							
!	~	++	--	+	-	*	& (type)	sizeof		
*	/	%								
+	-									
<<	>>									
<	<=	>	>=							
==	!=									
&										
^										
&&										
? :										
=	+=	-=	*=	/=	%=	&=	^=	!=	<<=	>>=
,										

## Associativity

left to right
right to left
left to right
right to left
right to left
left to right

- ->, (), and [] have high precedence, with \* and & just below
- Unary +, -, and \* have higher precedence than binary forms

# C Pointer Declarations: Test Yourself!

`int *p`

p is a pointer to int

`int *p[13]`

p is an array[13] of pointer to int

`int *(p[13])`

p is an array[13] of pointer to int

`int **p`

p is a pointer to a pointer to an int

`int (*p) [13]`

p is a pointer to an array[13] of int

`int *f()`

f is a function returning a pointer to int

`int (*f) ()`

f is a pointer to a function returning int

`int (*(*f()) [13]) ()`

f is a function returning ptr to an array[13] of pointers to functions returning int

`int (*(*x[3]) ()) [5]`

x is an array[3] of pointers to functions returning pointers to array[5] of ints

# Dereferencing Bad Pointers

## ■ The classic `scanf` bug

```
int val;  
...  
scanf("%d", val);
```

# Reading Uninitialized Memory

- Assuming that heap data is initialized to zero

```
/* return y = Ax */
int *matvec(int **A, int *x) {
    int *y = malloc(N*sizeof(int));
    int i, j;

    for (i=0; i<N; i++)
        for (j=0; j<N; j++)
            y[i] += A[i][j]*x[j];
    return y;
}
```

# Overwriting Memory

- Allocating the (possibly) wrong sized object

```
int **p;  
  
p = malloc(N*sizeof(int));  
  
for (i=0; i<N; i++) {  
    p[i] = malloc(M*sizeof(int));  
}
```

# Overwriting Memory

- Off-by-one error

```
int **p;  
  
p = malloc(N*sizeof(int *));  
  
for (i=0; i<=N; i++) {  
    p[i] = malloc(M*sizeof(int));  
}
```

# Overwriting Memory

- Not checking the max string size

```
char s[8];
int i;

gets(s); /* reads "123456789" from stdin */
```

- Basis for classic buffer overflow attacks

# Overwriting Memory

## ■ Misunderstanding pointer arithmetic

```
int *search(int *p, int val) {  
  
    while (*p && *p != val)  
        p += sizeof(int);  
  
    return p;  
}
```

# Overwriting Memory

- Referencing a pointer instead of the object it points to

```
int *BinheapDelete(int **binheap, int *size) {  
    int *packet;  
    packet = binheap[0];  
    binheap[0] = binheap[*size - 1];  
    *size--;  
    Heapify(binheap, *size, 0);  
    return(packet);  
}
```

# Referencing Nonexistent Variables

- Forgetting that local variables disappear when a function returns

```
int *foo () {  
    int val;  
  
    return &val;  
}
```

# Freeing Blocks Multiple Times

## ■ Nasty!

```
x = malloc(N*sizeof(int));
    <manipulate x>
free(x);

y = malloc(M*sizeof(int));
    <manipulate y>
free(x);
```

# Referencing Freed Blocks

- Evil!

```
x = malloc(N*sizeof(int));
    <manipulate x>
free(x);
    ...
y = malloc(M*sizeof(int));
for (i=0; i<M; i++)
    y[i] = x[i]++;
```

# Failing to Free Blocks (Memory Leaks)

- Slow, long-term killer!

```
foo() {  
    int *x = malloc(N*sizeof(int));  
    ...  
    return;  
}
```

# Failing to Free Blocks (Memory Leaks)

- Freeing only part of a data structure

```
struct list {
    int val;
    struct list *next;
};

foo() {
    struct list *head = malloc(sizeof(struct list));
    head->val = 0;
    head->next = NULL;
    <create and manipulate the rest of the list>
    ...
    free(head);
    return;
}
```

# Dealing With Memory Bugs

- **Debugger: gdb**
  - Good for finding bad pointer dereferences
  - Hard to detect the other memory bugs
- **Data structure consistency checker**
  - Runs silently, prints message only on error
  - Use as a probe to zero in on error
- **Binary translator: valgrind**
  - Powerful debugging and analysis technique
  - Rewrites text section of executable object file
  - Checks each individual reference at runtime
    - Bad pointers, overwrites, refs outside of allocated block
- **glibc malloc contains checking code**
  - `setenv MALLOC_CHECK_ 3`