

Machine-Level Programming IV: Data

adapted for CS367@GMU

Arrays

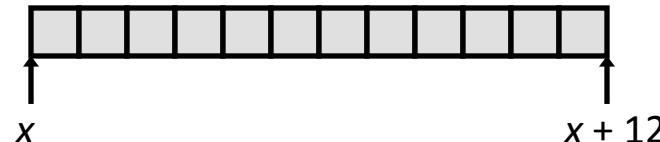
Array Allocation

■ Basic Principle

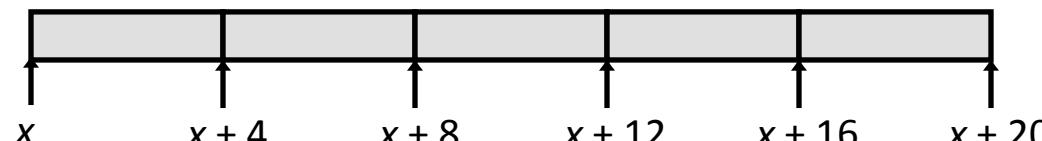
$T \ A[L];$

- Array of data type T and length L
- Contiguously allocated region of $(L * \text{sizeof}(T))$ bytes in memory

`char string[12];`



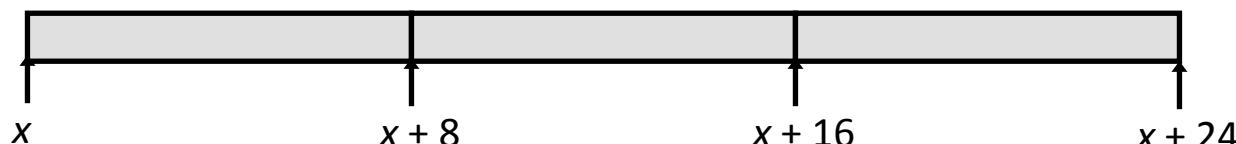
`int val[5];`



`double a[3];`



`char *p[3];`

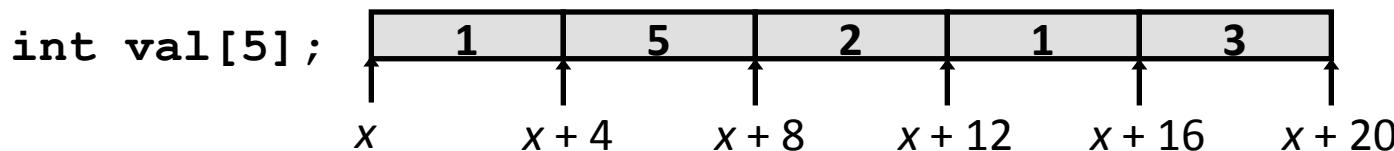


Array Access

■ Basic Principle

$T \mathbf{A}[L]$;

- Array of data type T and length L
- Identifier \mathbf{A} can be used as a pointer to array element 0: Type T^*



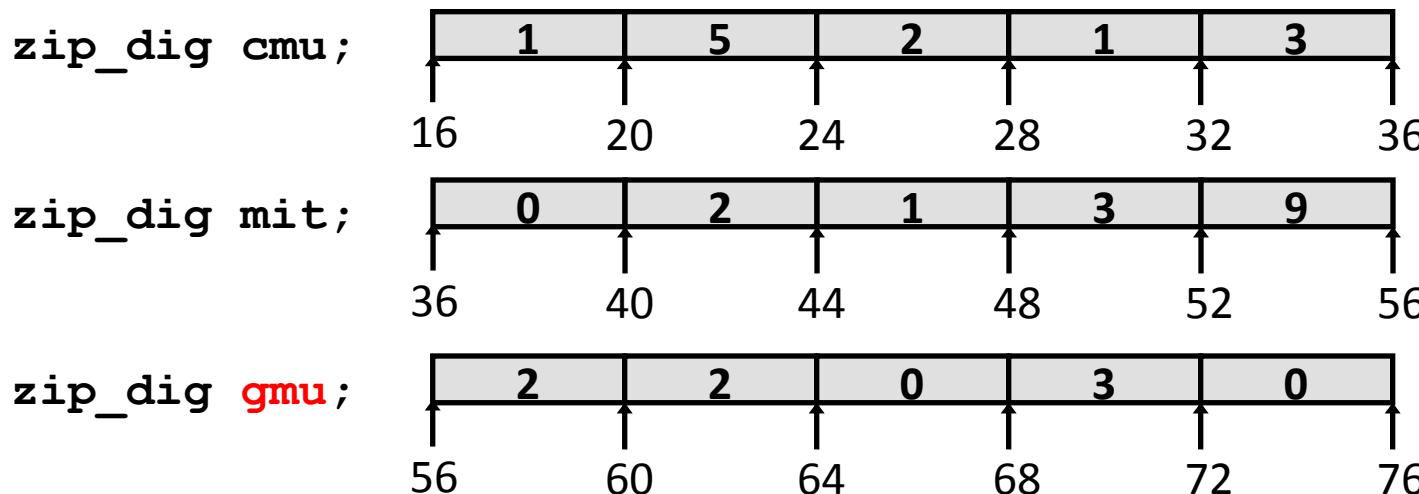
■ Reference Type Value

<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	x
<code>val+1</code>	<code>int *</code>	$x + 4$
<code>&val[2]</code>	<code>int *</code>	$x + 8$
<code>val[5]</code>	<code>int</code>	??
<code>* (val+1)</code>	<code>int</code>	5
<code>val + i</code>	<code>int *</code>	$x + 4i$

Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

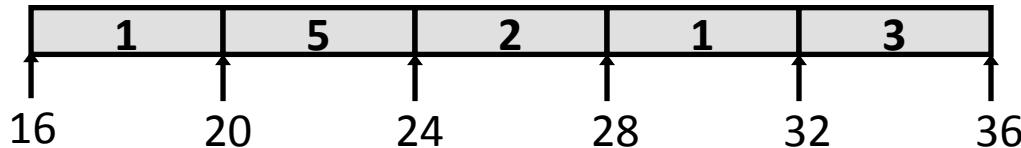
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig gmu = { 2, 2, 0, 3, 0 };
```



- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

Array Accessing Example

```
zip_dig cmu;
```



```
int get_digit (zip_dig z, int digit)
{
    return z[digit];
}
```

```
# %rdi = z
# %rsi = digit
movl (%?,%?,?), %? # z[digit]
```

- Register `%rdi` contains starting address of array
- Register `%rsi` contains array index

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

```
# %rdi = z
movl    $0, %eax          # i = 0
jmp     .L3                # goto middle
.L4:                           # loop:
    addl    $1, (%rdi,%rax,4) # z[i]++
    addq    $1, %rax          # i++
.L3:                           # middle
    cmpq    $4, %rax          # i:4
    jbe     .L4                # if <=, goto loop
rep; ret
```

Multidimensional (Nested) Arrays

■ Declaration

$T \ A[R][C];$

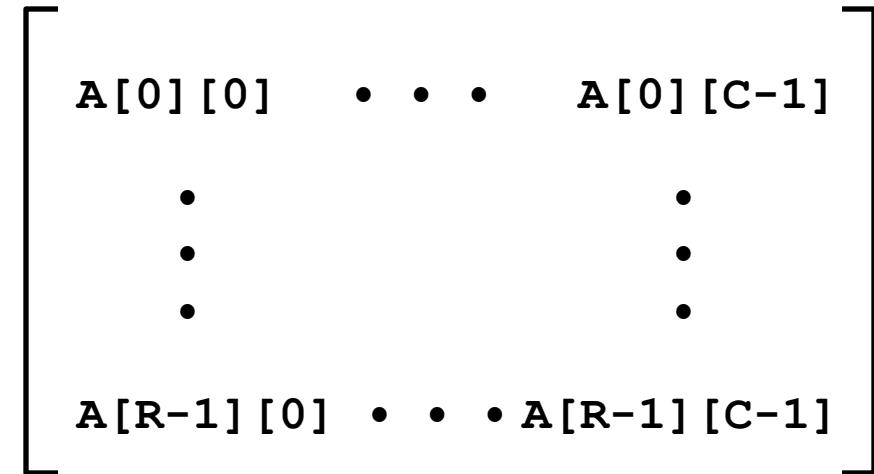
- 2D array of data type T
- R rows, C columns
- Type T element requires K bytes

■ Array Size

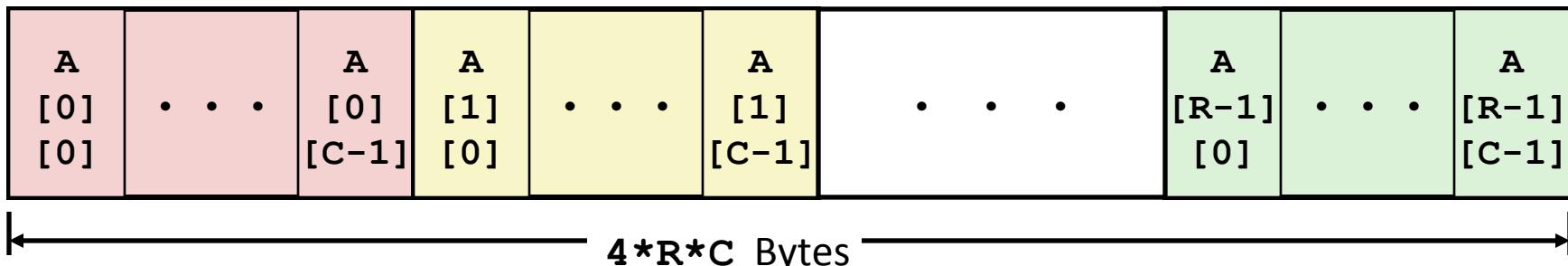
- $R * C * K$ bytes

■ Arrangement

- Row-Major Ordering



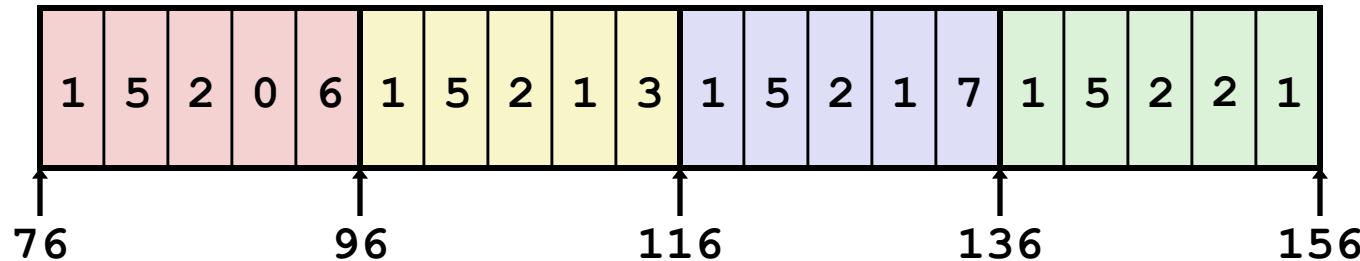
`int A[R][C];`



Nested Array Example

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
{{1, 5, 2, 0, 6},
 {1, 5, 2, 1, 3 },
 {1, 5, 2, 1, 7 },
 {1, 5, 2, 2, 1 }};
```

zip_dig
pgh[4];



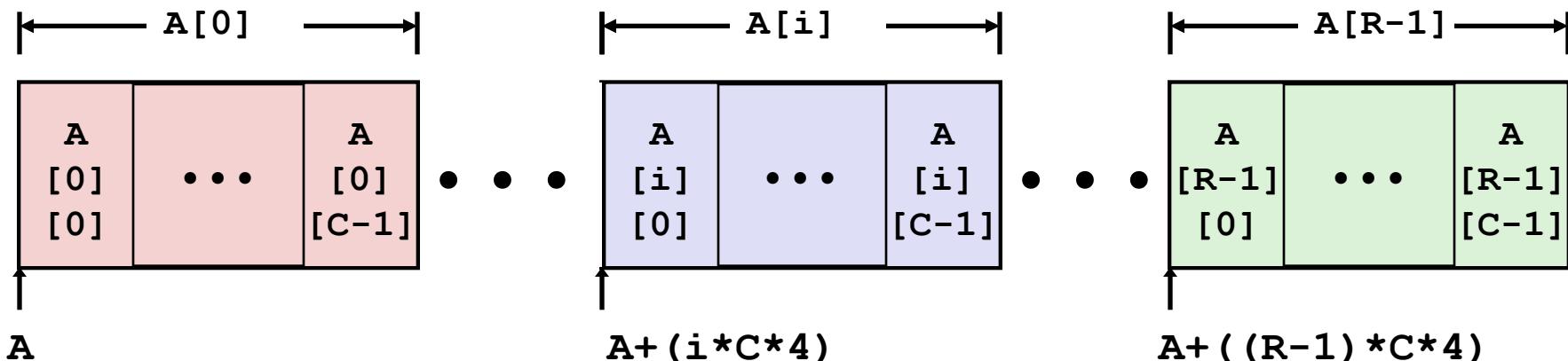
- “`zip_dig pgh[4]`” equivalent to “`int pgh[4][5]`”
 - Variable `pgh`: array of 4 elements, allocated contiguously
 - Each element is an array of 5 `int`'s, allocated contiguously
- “Row-Major” ordering of all elements in memory

Nested Array Row Access

■ Row Vectors

- $\mathbf{A}[i]$ is array of C elements
- Each element of type T requires K bytes
- Starting address $\mathbf{A} + i*(C*K)$

```
int A[R][C];
```

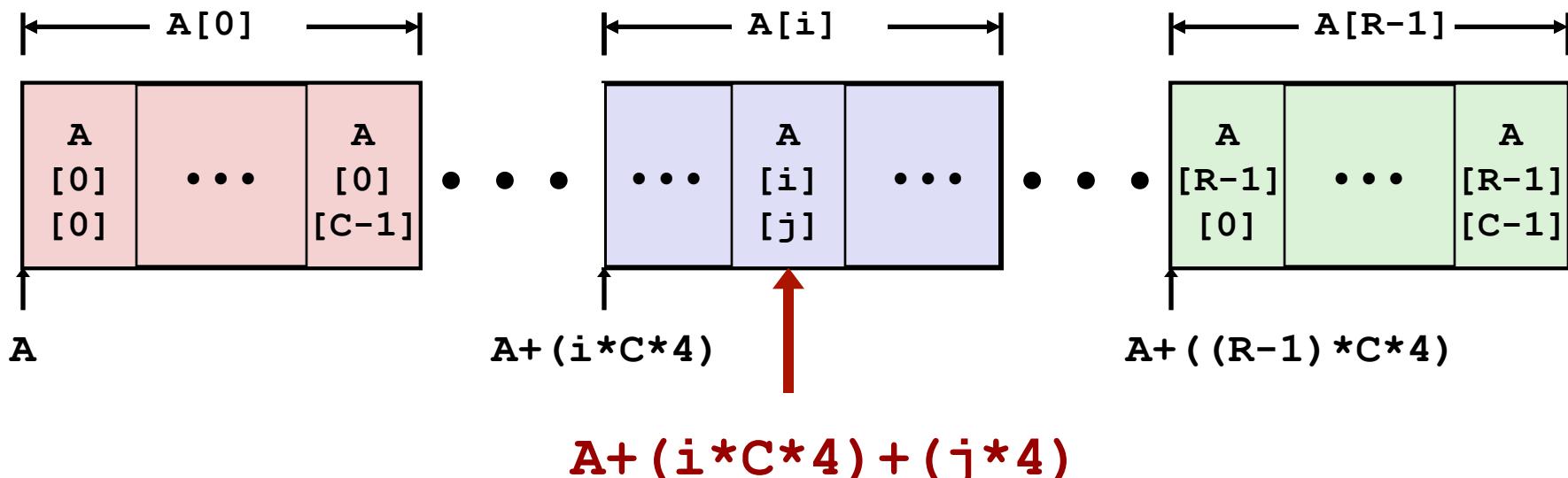


Nested Array Element Access

■ Array Elements

- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i*(C*K) + j*K = A + (i*C+j)*K$

```
int A[R][C];
```



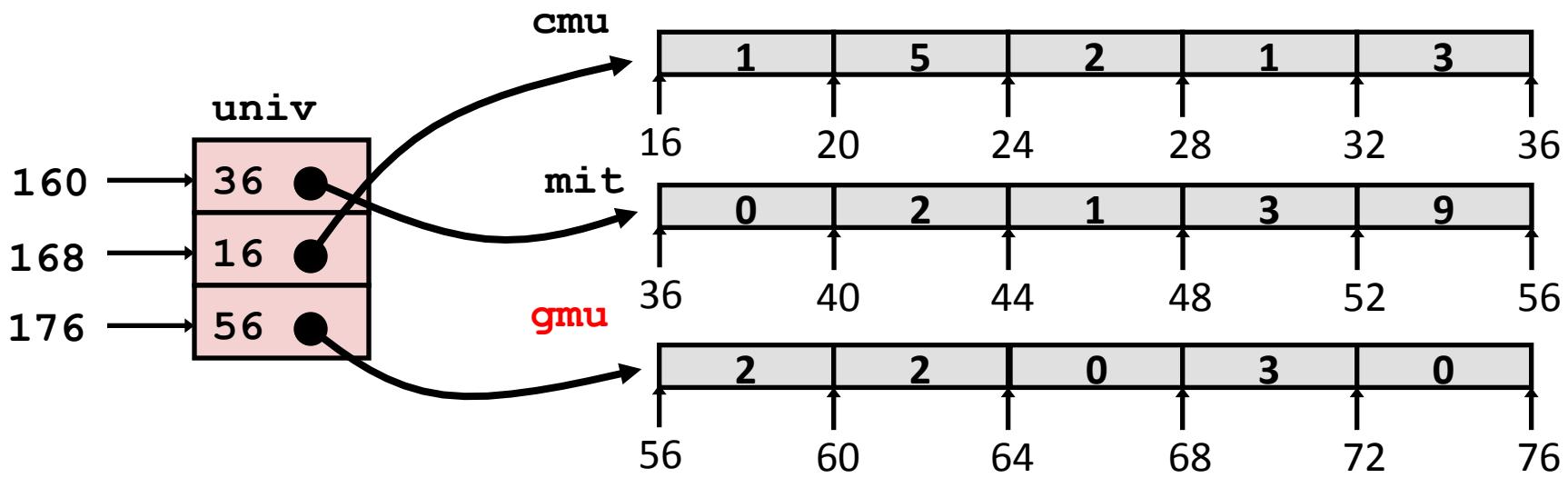
$$A + (i * C * 4) + (j * 4)$$

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig gmu = { 2, 2, 0, 3, 0 };
```

```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, gmu};
```

- Variable **univ** denotes array of 3 elements
- Each element is a pointer
 - 8 bytes
- Each pointer points to array of int's



Element Access in Multi-Level Array

```
int get_univ_digit (size_t index, size_t digit)
{
    return univ[index][digit];
}
```

```
salq    $2, %rsi          # 4*digit
addq    univ(,%rdi,8), %rsi # p = univ[index] + 4*digit
movl    (%rsi), %eax       # return *p
ret
```

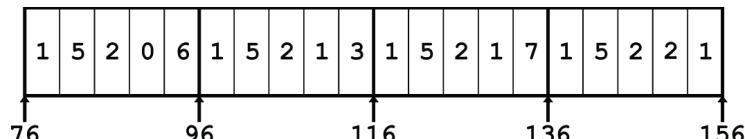
■ Computation

- Element access **Mem[Mem[univ+8*index] + 4*digit]**
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

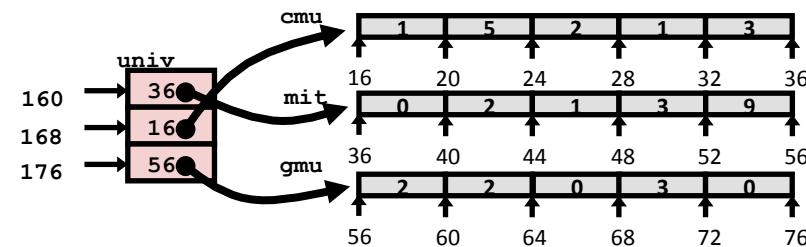
Nested array

```
int get_pgh_digit  
  (size_t index, size_t digit)  
{  
    return pgh[index] [digit];  
}
```



Multi-level array

```
int get_univ_digit  
  (size_t index, size_t digit)  
{  
    return univ[index] [digit];  
}
```



Accesses looks similar in C, but address computations very different:

`Mem[pgh+20*index+4*digit]`

`Mem[Mem[univ+8*index]+4*digit]`

N X N Matrix Code

■ Fixed dimensions

- Know value of N at compile time

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element a[i][j] */
int fix_ele(fix_matrix a,
            size_t i, size_t j)
{
    return a[i][j];
}
```

■ Variable dimensions, explicit indexing

- Traditional way to implement dynamic arrays

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element a[i][j] */
int vec_ele(size_t n, int *a,
            size_t i, size_t j)
{
    return a[IDX(n,i,j)];
}
```

■ Variable dimensions, implicit indexing

- Now supported by gcc

```
/* Get element a[i][j] */
int var_ele(size_t n, int a[n][n],
            size_t i, size_t j) {
    return a[i][j];
}
```

16 X 16 Matrix Access

■ Array Elements

- Address $\mathbf{A} + i*(C*K) + j*K$
- $C = 16, K = 4$

`fix_matrix` is always `int[16][16]`

```
/* Get element a[i][j] */  
int fix_ele(fix_matrix a, size_t i, size_t j) {  
    return a[i][j];  
}
```

```
# a in %rdi, i in %rsi, j in %rdx  
salq    $6, %rsi          #      64*i  
addq    %rsi, %rdi        #  a + 64*i  
movl    (%rdi,%rdx,4), %eax # M[a + 64*i + 4*j]  
ret
```

$n \times n$ Matrix Access

■ Array Elements

- Address $\mathbf{A} + i * (C * K) + j * K$
- $C = n, K = 4$
- Must perform integer multiplication

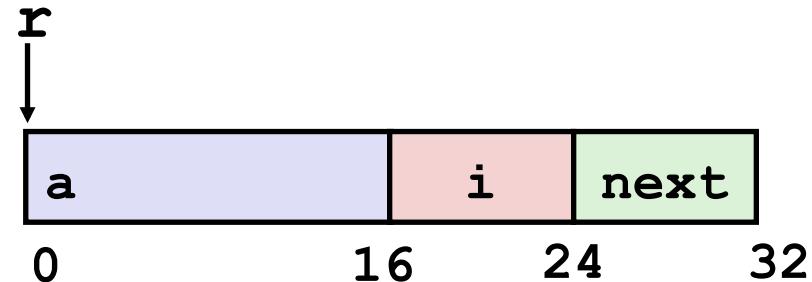
```
/* Get element a[i][j] */
int var_ele(size_t n, int a[n][n], size_t i, size_t j)
{
    return a[i][j];
}
```

```
# n in %rdi, a in %rsi, i in %rdx, j in %rcx
imulq  %rdx, %rdi          #      n*i
leaq    (%rsi,%rdi,4), %rax # a + 4*n*i
movl    (%rax,%rcx,4), %eax # a + 4*n*i + 4*j
ret
```

Structures

Structure Representation

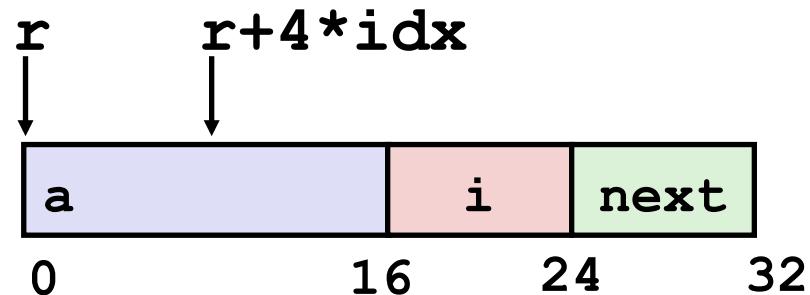
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- Structure represented as block of memory
 - Big enough to hold all of the fields
- Fields ordered according to declaration
 - Even if another ordering could yield a more compact representation
- Compiler determines overall size + positions of fields
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



■ Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as $\mathbf{r} + 4 * \mathbf{idx}$

```
int *get_ap  
(struct rec *r, size_t  
idx)  
{  
    return &r->a[idx];  
}
```

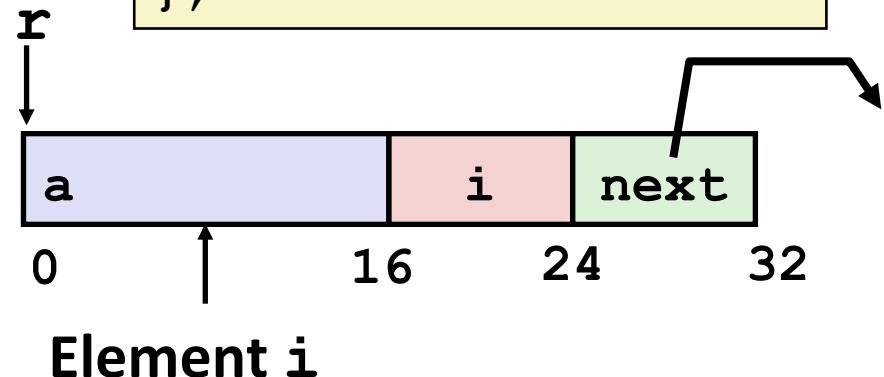
```
# r in %rdi, idx in %rsi  
leaq (%rdi,%rsi,4), %rax  
ret
```

Following Linked List

■ C Code

```
void set_val
    (struct rec *r, int val)
{
    while (r) {
        int i = r->i;
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[3];
    int i;
    struct rec *next;
};
```

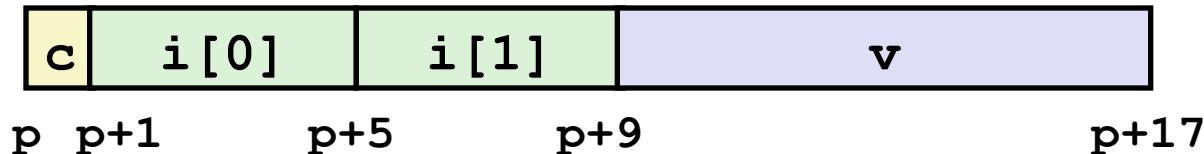


Register	Value
%rdi	r
%rsi	val

```
.L11:                                # loop:
    movslq  16(%rdi), %rax      #   i = M[r+16]
    movl    %esi, (%rdi,%rax,4) #   M[r+4*i] = val
    movq    24(%rdi), %rdi      #   r = M[r+24]
    testq   %rdi, %rdi         #   Test r
    jne     .L11                #   if !=0 goto loop
```

Structures & Alignment

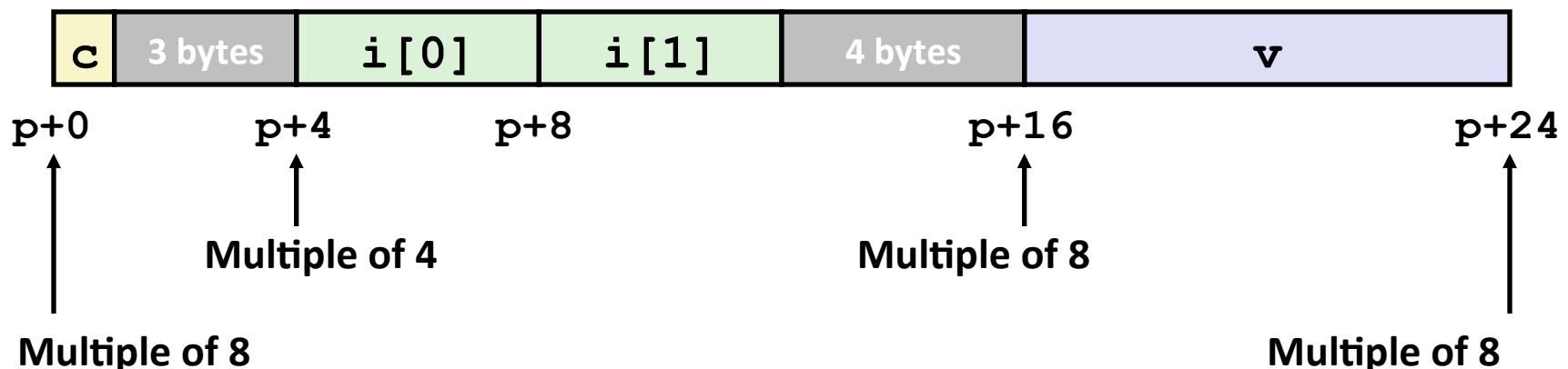
■ Unaligned Data



```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

■ Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K



Alignment Principles

■ Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K
- Required on some machines; advised on x86-64

■ Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - Inefficient to load or store datum that spans quad word boundaries
 - Virtual memory trickier when datum spans 2 pages

■ Compiler

- Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

- **1 byte: `char`, ...**
 - no restrictions on address
- **2 bytes: `short`, ...**
 - lowest 1 bit of address must be 0_2
- **4 bytes: `int`, `float`, ...**
 - lowest 2 bits of address must be 00_2
- **8 bytes: `double`, `long`, `char *`, ...**
 - lowest 3 bits of address must be 000_2
- **16 bytes: `long double` (GCC on Linux)**
 - lowest 4 bits of address must be 0000_2

Satisfying Alignment with Structures

■ Within structure:

- Must satisfy each element's alignment requirement

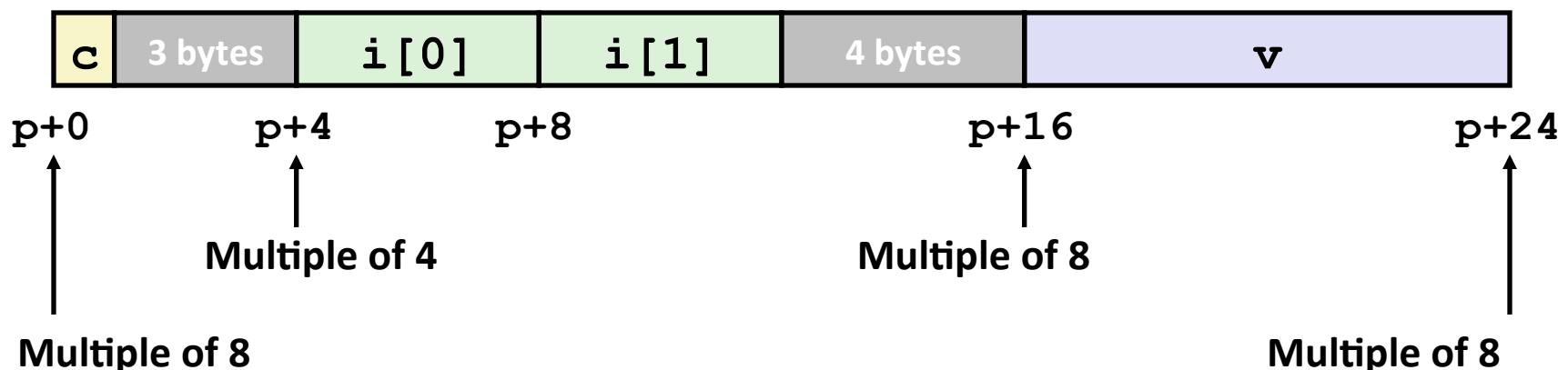
■ Overall structure placement

- Each structure has alignment requirement K
 - $K = \text{Largest alignment of any element}$
- Initial address & structure length must be multiples of K

■ Example:

- $K = 8$, due to `double` element

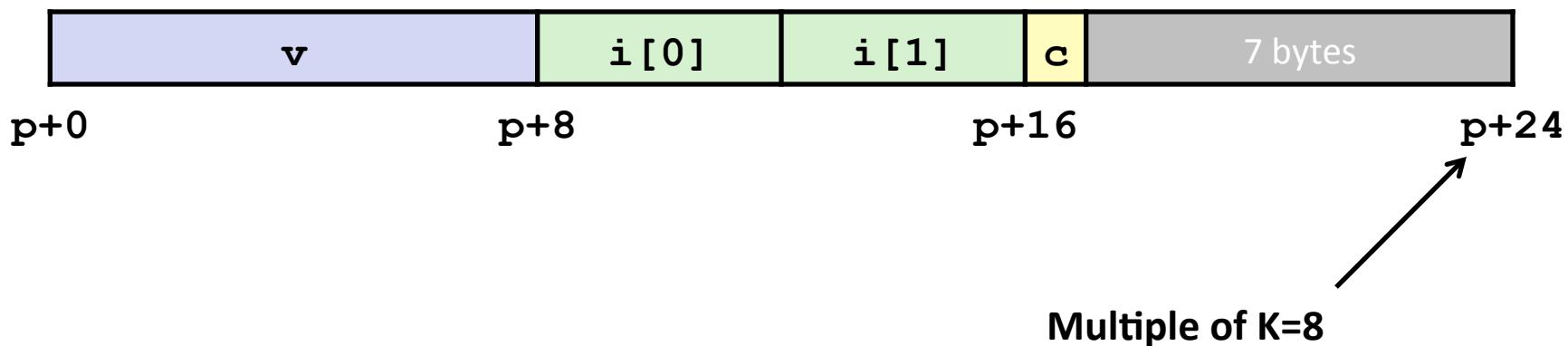
```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K

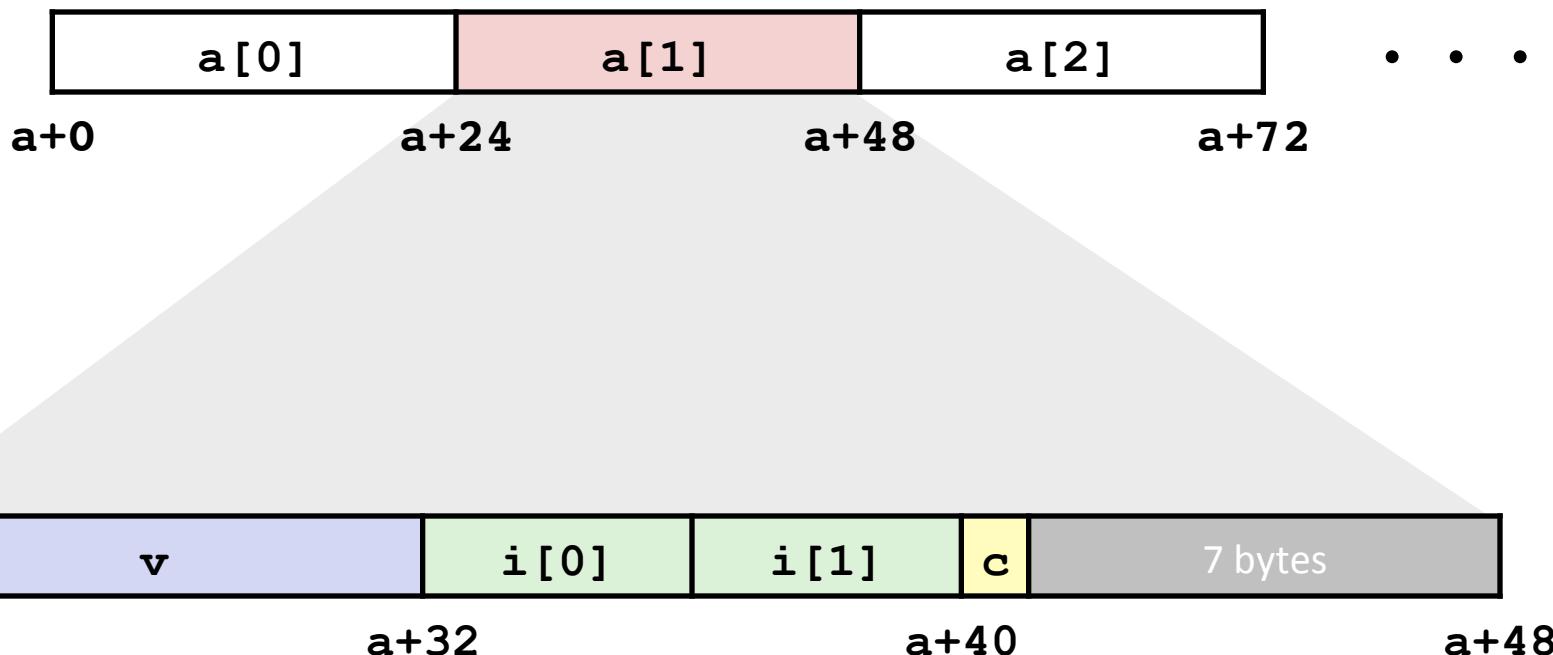
```
struct s2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



Arrays of Structures

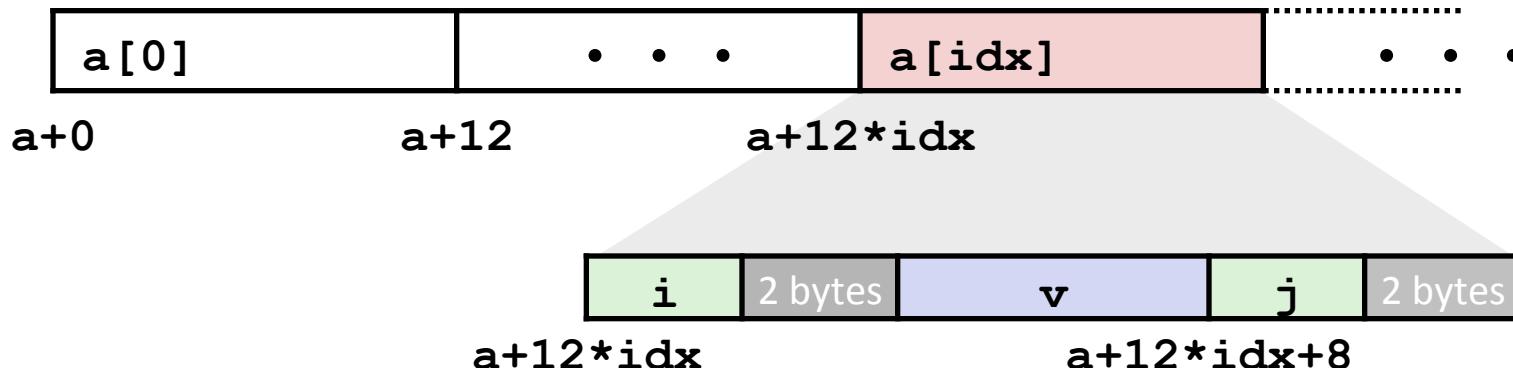
- Overall structure length multiple of K
- Satisfy alignment requirement for every element

```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} a[10];
```



Accessing Array Elements

- Compute array offset $12 * \text{idx}$
 - `sizeof(S3)`, including alignment spacers
- Element **j** is at offset 8 within structure
- Assembler gives offset **a+8**
 - Resolved during linking



```
short get_j(int idx)
{
    return a[idx].j;
}
```

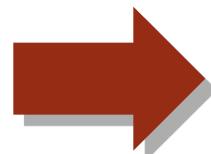
```
# %rdi = idx
leaq (%rdi,%rdi,2),%rax # 3*idx
movzwl a+8(%rax,4),%eax
```

```
struct S3 {
    short i;
    float v;
    short j;
} a[10];
```

Saving Space

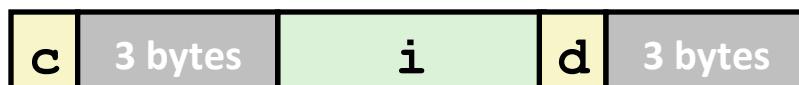
■ Put large data types first

```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```



```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```

■ Effect (K=4)



Floating Point

Background

■ History

- x87 FP
 - Legacy, very ugly
- SSE FP
 - Special case use of vector instructions
- AVX FP
 - Newest version
 - Similar to SSE
 - Documented in book

Programming with SSE3

XMM Registers

- 16 total, each 16 bytes
- 16 single-byte integers



- 8 16-bit integers



- 4 32-bit integers



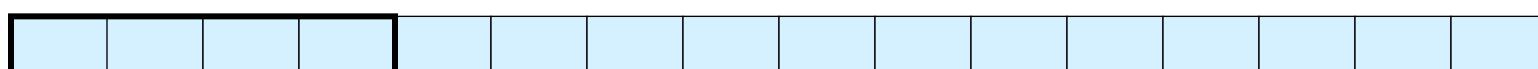
- 4 single-precision floats



- 2 double-precision floats



- 1 single-precision float

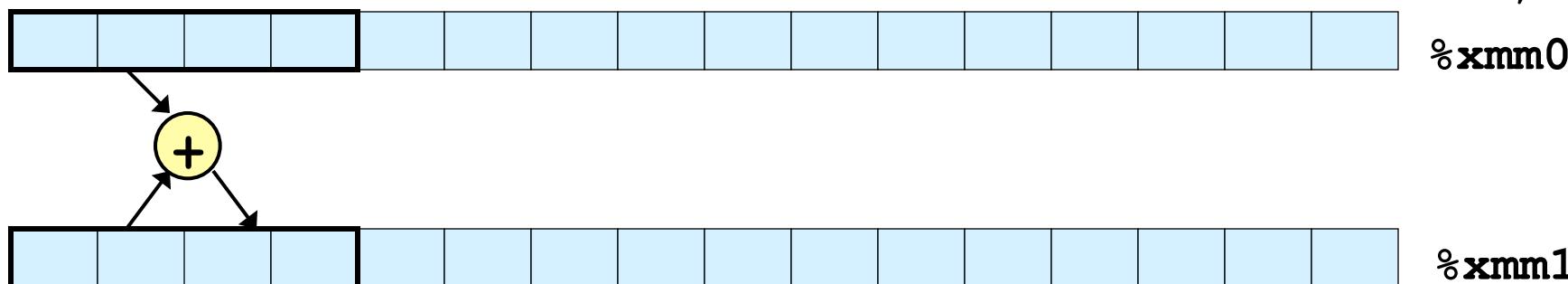


- 1 double-precision float



Scalar & SIMD Operations

■ Scalar Operations: Single Precision

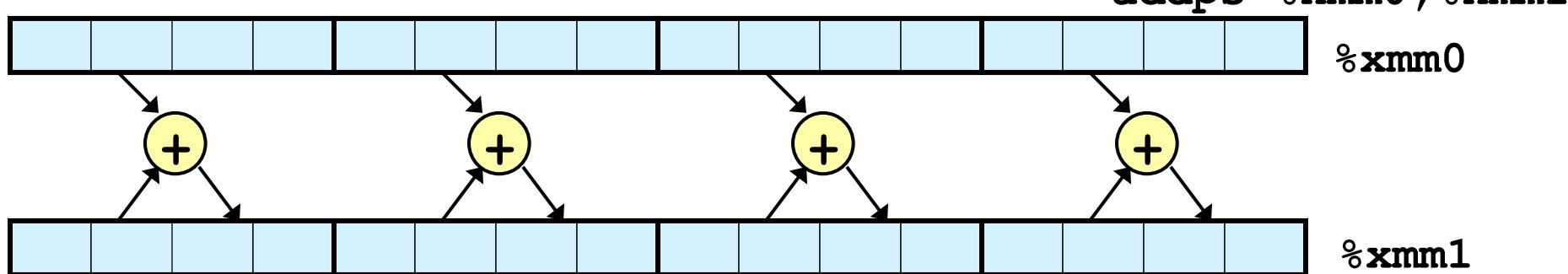


`addss %xmm0, %xmm1`

`%xmm0`

`%xmm1`

■ SIMD Operations: Single Precision

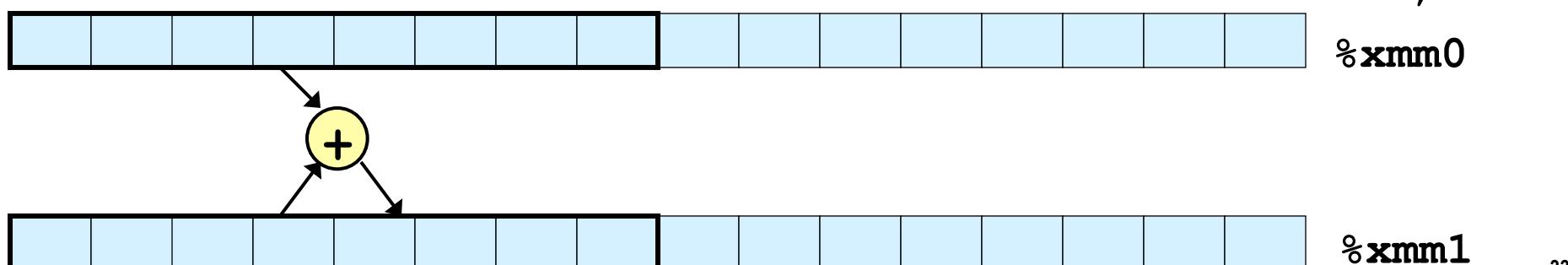


`addps %xmm0, %xmm1`

`%xmm0`

`%xmm1`

■ Scalar Operations: Double Precision



`addsd %xmm0, %xmm1`

`%xmm0`

`%xmm1`

FP Basics

- Arguments passed in `%xmm0, %xmm1, ...`
- Result returned in `%xmm0`
- All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd  %xmm0, %xmm1    # Copy v
movsd   (%rdi), %xmm0  # x = *p
addsd   %xmm0, %xmm1   # t = x + v
movsd   %xmm1, (%rdi)  # *p = t
ret
```

Other Aspects of FP Code

■ Lots of instructions

- Different operations, different formats, ...

■ Floating-point comparisons

- Instructions **ucomiss** and **ucomisd**
 - *Unordered COMpare (I?) Scalar (Single/Double)*
 - *Unordered: allows <, >, ==, unordered (NaN args)*
- Set condition codes CF, ZF, and PF (parity flag – set if NaN arg)

■ Using constant values

- Set XMM0 register to 0 with instruction **xorpd %xmm0, %xmm0**
- Others loaded from memory

Summary

■ Arrays

- Elements packed into contiguous region of memory
- Use index arithmetic to locate individual elements

■ Structures

- Elements packed into single region of memory
- Access using offsets determined by compiler
- Possible require internal and external padding to ensure alignment

■ Combinations

- Can nest structure and array code arbitrarily

■ Floating Point

- Data held and operated on in XMM registers