

Radial Bias Pilot 1

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1 Goal of Pilot 1

To measure radial direction bias with 1D drifting gratings at 8 polar angle locations at 7 deg eccentricity. A total of 3 motion conditions will be tested, 2 radial (inwards and outwards) and 1 tangential (combined), to measure the performance differences between (1) centrifugal and centripetal motion directions, and (2) radial and tangential motion directions.

1.1 Parameters

Eccentricity from central fixation: 7 degrees

Locations tested (polar angle relative to fixation): 0-315 degrees in 45 degree increments

Stimulus: sine wave gratings w/ 0.4 deg sigma gaussian mask

Stimulus spatial frequency: 1 c/deg

Stimulus drift speed: 8 deg/s

Stimulus contrast: full contrast + gaussian mask

Stimulus aperture diameter: 2.5 deg

Black circular aperture was put onto screen to avoid perceptual artifacts from screen edges

Number of subjects: 1-2

1.2 Experimental Design

The pilot uses a 2AFC paradigm, within a block each trial includes a drifting grating presented at 1 of 4 possible positions, while the subject maintains fixation at the central dot. A method of constant stimuli is used which is set based on the performance of the training session (see Methods). The angular values added to the internal reference frame is chosen at random from the following constants $[-8, -4, -2, -1, -0.5, 0.5, 1, 2, 4, 8]$ – logarithmic spacing from 0.5 to 8. The observer must determine whether the direction of motion is clockwise or counterclockwise relative to the internal reference. The sequence of each trial for the 4 motion standards (specific to diagonal locations) at one location is depicted below:

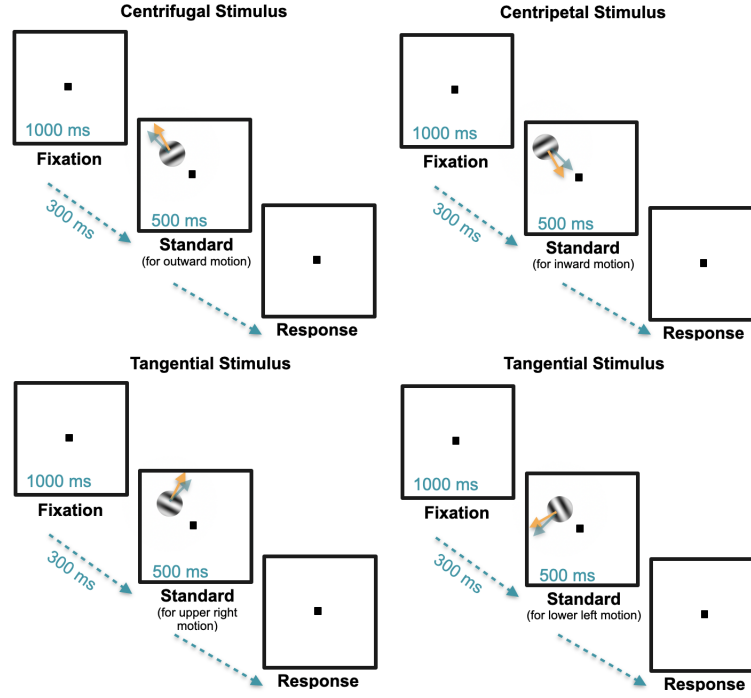
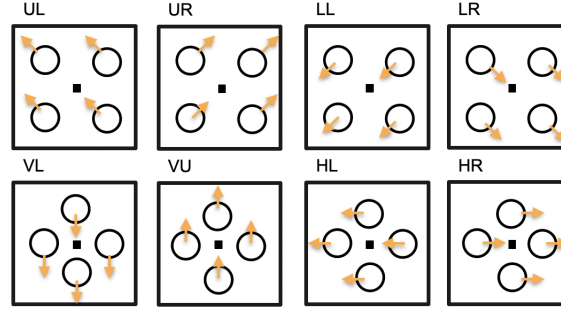


Figure 1: Blue arrow represents the internal reference, the orange arrow represents an example of the direction at which the stimulus is presented (can be clockwise or counterclockwise to the blue arrow).

1.3 Block sequence

Four blocks were run, and each block corresponded to 1 of the 4 conditions being tested (tangential lower left motion, tangential upper right motion, radial upper left motion, radial lower right motion). The internal reference frames for each block is shown below:



Prior to the actual experiment, the "standard" motion direction corresponding to that specific block will be showed to the observer to use as an internal reference. Then a training session is conducted to determine how much tilt is required to meet 75% accuracy with staircase procedure (MLPest), and to allow subject to practice task with feedback. The estimated angular value to add/subtract to the standard to achieve 75% performance of the clockwise/counterclockwise will be used to determine constants. For this pilot, constants $[-8, -4, -2, -1, -0.5, 0.5, 1, 2, 4, 8]$ were chosen for all 8 blocks. Note positive and negative values for clockwise v. counterclockwise tilt. Each block contained 4 locations x 5 tilt values x 2 (clock v cc) x 20 repetitions = 800 trials. There are 8 blocks * 800 trials = 6400 total trials (3200 tang, 1600 radial-in, 1600 radial-out). Each full-block takes 35 min; all 8 blocks took 280 min.

RE sequence of blocks

1. diag-UL [angles: +- 0.5, 1, 2, 4, 8] (35 min)
2. card-HR [angles: +- 0.5, 1, 2, 4, 8] (35 min)
3. diag-LR [angles: +- 0.5, 1, 2, 4, 8] (35 min)
4. card-VL [angles: +- 0.5, 1, 2, 4, 8] (35 min)
5. diag-UR [angles: +- 0.5, 1, 2, 4, 8] (35 min)
6. card-HL [angles: +- 0.5, 1, 2, 4, 8] (35 min)
7. diag-LL [angles: +- 0.5, 1, 2, 4, 8] (35 min)
8. card-VU [angles: +- 0.5, 1, 2, 4, 8] (35 min)

2 Data

2.1 Psychometric Function (Cumulative normal)

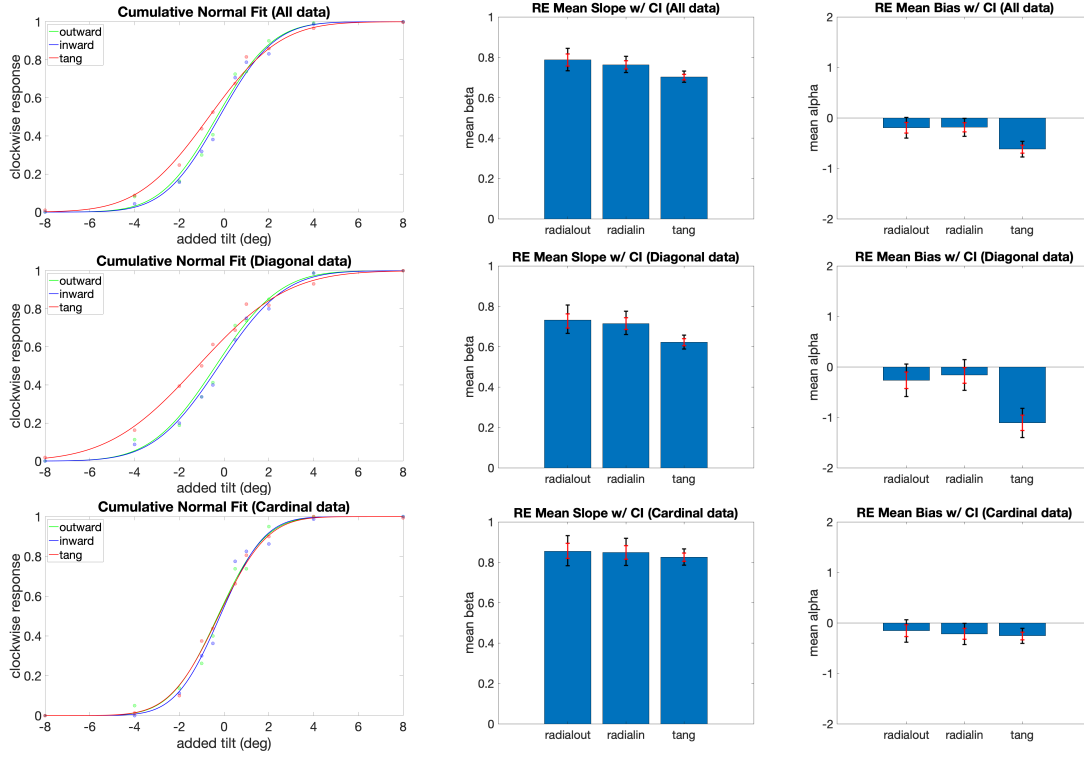


Figure 2: RE new data (speed 8 cyc/deg) across 8 blocks that each contain 1 reference vector. Top row: All trials (combining cardinal and oblique blocks). Each point = (20 x 8 locations); Second row: subset of data in first row, including only the oblique motion directions (diagonal locations). Each point = (20 x 4 locations); Last row: subset of data in first row, including only the cardinal motion directions (cardinal locations). Each point = (20 x 4 locations). Positive bias = more counterclockwise responses. All means/confidence intervals were computed from samples of posterior distribution using Markov chain Monte Carlo method (from PAL_PFHB_fitModel.m) - 5000 samples, 3 chains.

RE SENSITIVITY/SLOPE

Radial out beta = [cardinal & diagonal directions = 0.51, cardinal = 0.6, diagonal = 0.44]

Radial in beta = [cardinal & diagonal directions = 0.52, cardinal = 0.64, diagonal = 0.44]

Tangential beta = [cardinal & diagonal directions = 0.4, cardinal = 0.58, diagonal = 0.32]

RE BIAS

Radial out alpha = [cardinal & diagonal directions = -0.32, cardinal = -0.28, diagonal = -0.37]

Radial in alpha = [cardinal & diagonal directions = -0.21, cardinal = -0.18, diagonal = -0.22]

Tangential alpha = [cardinal & diagonal directions = 0.67, cardinal = -0.25, diagonal = -1.17]

2.2 Polar Angle Plot

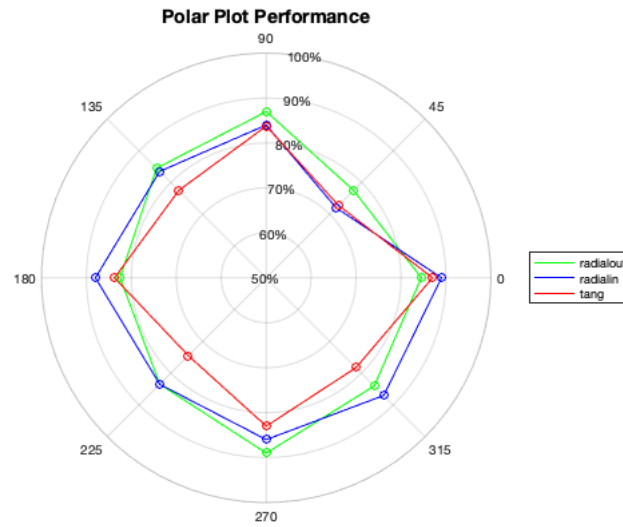


Figure 3: Polar plots by performance (range 50-100%). Each point is 400 trials (collapsed across blocks).

2.3 Quality Control & Misc.

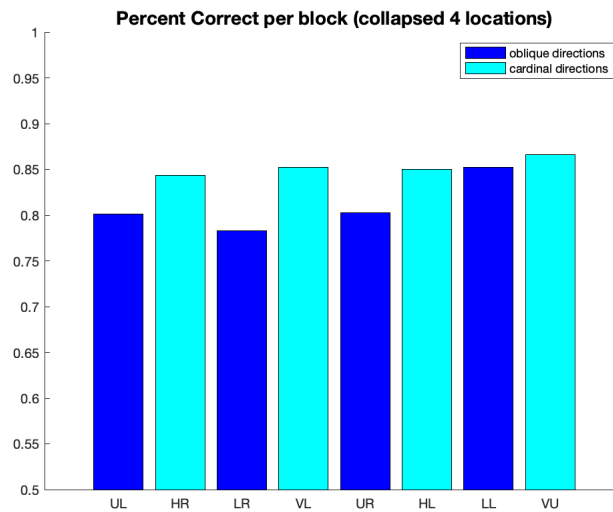


Figure 4: To check that performance does not vary too much between blocks. Cardinal blocks are interleaved with diagonal blocks, and consistently show better performance.

3 Current Goals

1. Does radial bias occur in respect to motion direction or orientation of 1D drifting gratings? So far, evidence points to motion direction (but potentially conflicts with Hong paper).
2. Is there a difference in sensitivity to radial-inward vs. radial-outwards motion? So far, there doesn't seem to be a difference at 7 deg eccentricity.
3. Does radial bias increase with eccentricity? Within radial condition, does difference of sensitivity between inwards/outwards motion increase with eccentricity?
4. Is sensitivity to cardinal locations (i.e. orientations/directions) greater than sensitivity to diagonal locations (oblique orientations/directions)? Radial bias and cardinal bias might jointly result in better performance.
5. Is there an HVA or VMA present at given eccentricities?
6. How does this extend to plaid stimuli? Does the bias apply to the component motion direction or the apparent motion direction?

4 Updates

- Design Related
 - Now running trials using 4 polar angles per block (block 1 = diagonal (e.g. upper left), block 2 = cardinal (upper vertical), block 3 = diagonal (upper left), etc.)
 - * Note: For cardinal locations, it feels difficult to not perform task based on orientation
 - Implemented log spacing (0.5 - 8) for stimuli for whenever eye tracking.
 - Same number of trials run for tangential left/right, and radial in/out for balance.
- Analysis Related
 - Tested higher speed (8 deg / s) and full block runs for all polar angles.
- Other improvements
 - Added more intuitive feedback beeps.
- For discussion
 - **Eye tracker in RM 956**
 - * Got the eye tracker to run, and CRT monitor to work with computer
 - * Still need to figure out Matlab licensing issue
 - * Matlab version issue (need 2020, 2018 also needs to be maintained)
 - * No server connection in that room.
 - * Where to get photometer? Denis?
 - **Subject payments, grant**
 - **Traveling to AD (July?)**
 - **VSS expenses**

5 To Do

- Feedback from Feb 17, 2021
 - Re-plot polar angle plot with arrows pointing in direction (length indicating performance)
 - Difficulty level is good as is, and block design is ok
 - Finalize eye-tracking set up
 - If we want to capture polar angle differences, might need to increase SF? (confirmed in other exp around 6 cpd, 6 deg ecc)
 - Titration for cardinal v. oblique? Or keep the constant stimuli? Dynamic staircase methods?
- Other
 - Double check sigma of gaussian (and at what eccentricity contrast drops below 1 perc)

6 Software to Cite

- PsychToolbox Extensions (Brainard, 1997; Pelli, 1997; Kleiner et al, 2007)
- Prins, N & Kingdom, F. A. A. (2018) Applying the Model-Comparison Approach to Test Specific Research Hypotheses in Psychophysical Research Using the Palamedes Toolbox. *Frontiers in Psychology*, 9:1250. doi: 10.3389/fpsyg.2018.01250
- Plummer, M. (2003, March). JAGS: A program for analysis of Bayesian graphical models using Gibbs sampling. In *Proceedings of the 3rd international workshop on distributed statistical computing* (Vol. 124, No. 125.10, pp. 1-10). (<http://mcmc-jags.sourceforge.net/>)