

APPLICATION OF CP DECOMPOSITION

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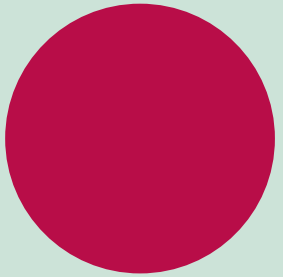
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of
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Date:
May 3, 2023

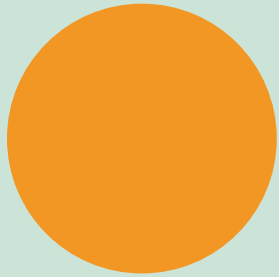


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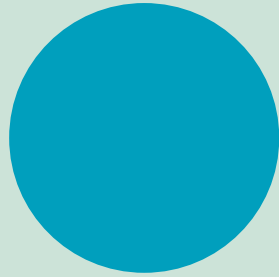
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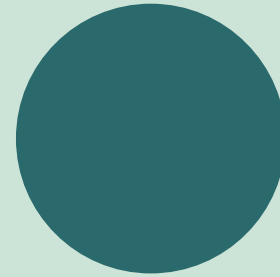
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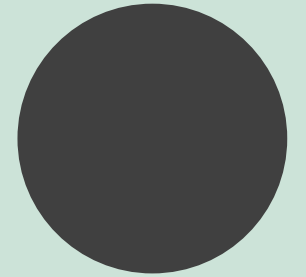


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A **Tensor** is a multi-dimensional array, a general form of a Matrix (which is a 2-dim array). More formally, an N-way or Nth-order tensor is an element of the tensor product of N vector spaces, each of which has its own coordinate system.

- A first-order tensor is a vector,
- a second-order tensor is a matrix,
- and tensors of order 3 or higher are called higher-order tensors.

1-dim array - $(1, 2, 3) = \mathbf{a}$ (Vector)

2 -dim array - $\begin{pmatrix} 3 & 3 & 9 \\ 3 & 3 & 2 \end{pmatrix} = \mathbf{A}$ (2×3 Matrix)

3-way array - $\left(\begin{pmatrix} 2 & 8 & 2 & 9 \\ 3 & 0 & 1 & 0 \end{pmatrix}, \begin{pmatrix} 6 & 8 & 1 & 1 \\ 2 & 2 & 3 & 3 \end{pmatrix} \right) = \chi$ ($2 \times 2 \times 4$ Tensor)

Introduction

Norm

The **norm of a tensor** $\mathcal{X} \in \mathbb{R}^{I_1 \times I_2 \times \cdots \times I_N}$ is the square root of the sum of the squares of all its elements, i.e.,

$$\|\mathcal{X}\| = \sqrt{\sum_{i_1=1}^{I_1} \sum_{i_2=1}^{I_2} \cdots \sum_{i_N=1}^{I_N} x_{i_1 i_2 \cdots i_N}^2}$$

Rank 1 Matrix

The *rank* of this matrix is **1**. So we can write it as a product of two vectors or simply if we take a *product of a column with a row* we will get **Rank-One Matrix**.

$$\begin{bmatrix} 4 & 6 \\ -6 & -9 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} \begin{bmatrix} 2 & 3 \end{bmatrix}$$

Introduction

Rank 1 Tensor

An N-way tensor $\mathcal{X} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N}$ is rank one if it can be written as the outer product of N vectors, i.e.,

$$\mathcal{X} = \mathbf{a}^{(1)} \circ \mathbf{a}^{(2)} \circ \dots \circ \mathbf{a}^{(N)}.$$

The symbol "o" represents the vector outer product. This means that each element of the tensor is the product of the corresponding vector elements:

$$x_{i_1 i_2 \dots i_N} = a_{i_1}^{(1)} a_{i_2}^{(2)} \dots a_{i_N}^{(N)} \text{ for all } 1 \leq i_n \leq I_n$$

✓ Example of 3rd order Rank-One Tensor -

$$\begin{aligned} X &= \begin{pmatrix} 1 & 2 \end{pmatrix} \circ \begin{pmatrix} -1 & 1 \end{pmatrix} \circ \begin{pmatrix} 3 & 2 \end{pmatrix} \\ &= \left[\begin{bmatrix} -3 & -2 \\ 3 & 2 \end{bmatrix}, \begin{bmatrix} -6 & -4 \\ 6 & 4 \end{bmatrix} \right] \end{aligned}$$

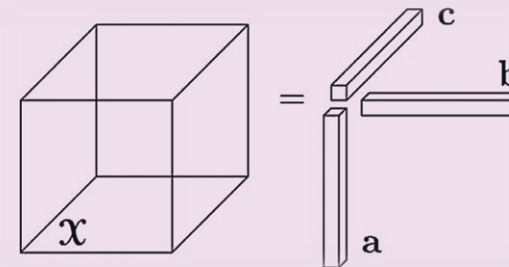


Figure 1. A third-order Rank 1 Tensor
(Reprinted)

Tensor Operations

Matricization

Matricization, also known as **unfolding** or **flattening**, is the process of reordering the elements of an N-way array into a matrix.

For instance, a **2 × 3 × 4 tensor** can be arranged as a **6 × 4 matrix** or a **3 × 8 matrix**, and so on. The mode- n matricization of a tensor $\mathbf{X} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N}$ is denoted by $\mathbf{X}_{(n)}$ and arranges the mode- n fibers to the columns of the resulting matrix.

Tensor element (i_1, i_2, \dots, i_N) maps to matrix element (i_n, j) where,

$$j = 1 + \sum_{\substack{k=1 \\ k \neq n}}^N (i_k - 1) J_k \quad \text{with} \quad J_k = \prod_{\substack{m=1 \\ m \neq n}}^{k-1} I_m$$

✓ Example:

$$\mathcal{X} = \left[\begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}, \begin{bmatrix} 13 & 14 & 15 & 16 \\ 17 & 18 & 19 & 20 \\ 21 & 22 & 23 & 24 \end{bmatrix} \right]$$

The 3 mode n unfoldings are

$$\mathbf{X}_{(1)} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 & 17 & 18 & 19 & 20 & 21 & 22 & 23 & 24 \end{bmatrix}$$

$$\mathbf{X}_{(2)} = \begin{bmatrix} 1 & 2 & 3 & 4 & 13 & 14 & 15 & 16 \\ 5 & 6 & 7 & 8 & 17 & 18 & 19 & 20 \\ 9 & 10 & 11 & 12 & 21 & 22 & 23 & 24 \end{bmatrix}$$

$$\mathbf{X}_{(3)} = \begin{bmatrix} 1 & 5 & 9 & 13 & 17 & 21 \\ 2 & 6 & 10 & 14 & 18 & 22 \\ 3 & 7 & 11 & 15 & 19 & 23 \\ 4 & 8 & 12 & 16 & 20 & 24 \end{bmatrix}$$

Tensor Operations

Kronecker Product

The Kronecker product of matrices $\mathbf{A} \in \mathbb{R}^{I \times J}$ and $\mathbf{B} \in \mathbb{R}^{K \times L}$ is denoted by $\mathbf{A} \otimes \mathbf{B}$. The result is a matrix of size $(IK) \times (JL)$ and defined by

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}\mathbf{B} & a_{12}\mathbf{B} & \cdots & a_{1J}\mathbf{B} \\ a_{21}\mathbf{B} & a_{22}\mathbf{B} & \cdots & a_{2J}\mathbf{B} \\ \vdots & \vdots & \ddots & \vdots \\ a_{I1}\mathbf{B} & a_{I2}\mathbf{B} & \cdots & a_{IJ}\mathbf{B} \end{bmatrix}$$

✓ Example:

$A \in \mathbb{R}^{2 \times 2}, B \in \mathbb{R}^{2 \times 2}$, then $A \otimes B \in \mathbb{R}^{4 \times 4}$

$$A = \begin{bmatrix} 1 & 2 \\ -1 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix}, \quad \text{then } A \otimes B = \begin{bmatrix} 1 & -1 & 2 & -2 \\ -2 & 3 & -4 & 6 \\ -1 & 1 & 0 & 0 \\ 2 & -3 & 0 & 0 \end{bmatrix}$$

Tensor Operations

Khatri-Rao Product

The Khatri-Rao product is the "**matching columnwise**" **Kronecker product**. Given matrices $\mathbf{A} \in \mathbb{R}^{I \times K}$ and $\mathbf{B} \in \mathbb{R}^{J \times K}$, their Khatri-Rao product is denoted by $\mathbf{A} \odot \mathbf{B}$. The result is a matrix of size $(IJ) \times K$ defined by

✓ Example:

$$A \in \mathbb{R}^{2 \times 2}, B \in \mathbb{R}^{3 \times 2}, \text{ then } A \odot B \in \mathbb{R}^{6 \times 2}$$

$$A = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & -2 \\ 2 & 1 \\ 3 & 0 \end{pmatrix}, \quad \text{then } A \odot B = \begin{pmatrix} 2 & -2 \\ 4 & 1 \\ 6 & 0 \\ -1 & 0 \\ -2 & 0 \\ -3 & 0 \end{pmatrix}$$

CP Decomposition

The **CANDECOMP/PARAFAC (CP) decomposition** factorizes a tensor into a sum of component rank-one tensors. For example, given a third-order tensor

$$\mathbf{X} \approx \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r, \quad (1)$$

where R is a positive integer and $\mathbf{a}_r \in \mathbb{R}^I, \mathbf{b}_r \in \mathbb{R}^J$, and $\mathbf{c}_r \in \mathbb{R}^K$ for $r = 1, \dots, R$.

The rank of a tensor \mathbf{X} , denoted **rank** (\mathbf{X}), is defined as the smallest number of rank-one tensors that generate \mathbf{X} as their sum.

The factor matrices refer to the combination of the vectors from the rank-one components, i.e., $\mathbf{A} = [\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_R]$ and likewise for \mathbf{B} and \mathbf{C} . Using these definitions, Eq (1) may be written in matricized form:

$$\begin{aligned} \mathbf{X}_{(1)} &\approx \mathbf{A}(\mathbf{B} \odot \mathbf{C})^\top \\ \mathbf{X}_{(2)} &\approx \mathbf{B}(\mathbf{A} \odot \mathbf{C})^\top \\ \mathbf{X}_{(3)} &\approx \mathbf{C}(\mathbf{A} \odot \mathbf{B})^\top \end{aligned} \quad (2)$$

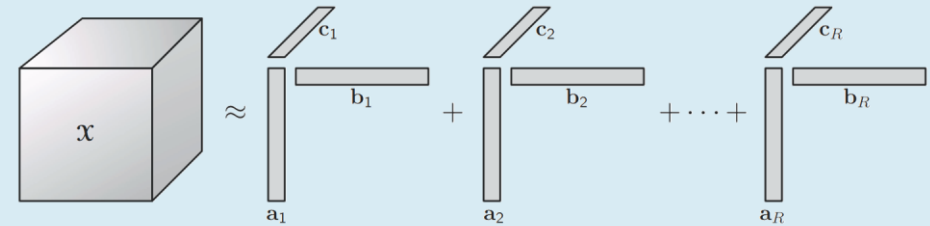


Figure 2: *CP Decomposition of a 3-way tensor **

* Reprinted from given references.

SVD: Singular Value Decomposition

For matrices (2 way tensor), Eckart and Young showed that a best rank- k approximation is given by the leading k factors of the **SVD (Singular Value Decomposition)**. In other words, let R be the rank of a matrix \mathbf{A} and assume its SVD is given by

$$\mathbf{A} = \sum_{r=1}^R \sigma_r \mathbf{u}_r \circ \mathbf{v}_r \quad \text{with } \sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_R > 0.$$

Then a *rank- k approximation* that minimizes $\|\mathbf{A} - \mathbf{B}\|$ is given by

$$\mathbf{B} = \sum_{r=1}^k \sigma_r \mathbf{u}_r \circ \mathbf{v}_r.$$

This type of result does not hold true for higher-order tensors. For instance, consider a third-order tensor of rank R with the following CP decomposition:

$$\mathbf{X} = \sum_{r=1}^R \lambda_r \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r.$$

It is possible that the best rank- k approximation may not even exist. The problem is referred to as one of degeneracy. A tensor is degenerate if it may be approximated arbitrarily well by a factorization of lower rank

Suppose that the $\mathbf{m} \times \mathbf{n}$ matrix \mathbf{A} is tall, i.e., there are more equations (\mathbf{m}) than variables (\mathbf{n}).
So the system of linear equations,

$$\mathbf{Ax} = \mathbf{b}$$

These equations have a solution only if \mathbf{b} is a linear combination of the columns of \mathbf{A} .

- For the approximate solution,
we would find such \mathbf{x} so that the residual $\mathbf{r} = (\mathbf{Ax} - \mathbf{b})$ as small as possible.
- Similar to, Minimize the norm of \mathbf{r} i.e. *Minimize* $\|\mathbf{Ax} - \mathbf{b}\|$
- Same as, *Minimize* $\|\mathbf{Ax} - \mathbf{b}\|^2$

Solution of Least Square

From calculus, any minimizer \hat{x} of the function $f(x) = \|Ax - b\|^2$ must satisfy,

$$\nabla f(\hat{x}) = 2A^T(A\hat{x} - b) = 0,$$

$$\text{Solution: } \hat{x} = (A^T A)^{-1} A^T b$$

$$\hat{x} = A^\dagger b$$

A^\dagger is called *Pseudo-inverse* of \mathbf{A}

Suppose that the $\mathbf{m} \times \mathbf{n}$ matrix \mathbf{A} is tall, i.e., there are more equations (\mathbf{m}) than variables (\mathbf{n}).
So the system,

$$\mathbf{AX} = \mathbf{B}$$

These equations have a solution only if the columns of \mathbf{B} is a linear combination of the columns of \mathbf{A} .

- For the approximate solution,
we would find such \mathbf{x} so that the residual $\mathbf{R} = (\mathbf{AX} - \mathbf{B})$ as small as possible.
- Similar to, Minimize the norm of \mathbf{R} i.e. *Minimize* $\| \mathbf{AX} - \mathbf{B} \|$
- Same as, *Minimize* $\| \mathbf{AX} - \mathbf{B} \|^2$

Solution of Matrix Least Square

The matrix least squares problem is in fact nothing but a set of k ordinary least squares problems.

Solution: $\hat{X} = A^{\dagger}B$

A^{\dagger} is called *Pseudo-inverse* of \mathbf{A}

For a 3-way data (say, \mathbf{X}), we have 3 types of matricization techniques and thus we will get 3 matrix $\mathbf{X}_{(1)}$, $\mathbf{X}_{(2)}$ and $\mathbf{X}_{(3)}$. suppose our approximated Tensor is going to be \mathbf{A} (we will start with a random initial \mathbf{A})

$$\begin{aligned}\mathbf{X}_{(1)} &\approx \mathbf{A}_1(\mathbf{A}_2 \odot \mathbf{A}_3)^\top \\ \mathbf{X}_{(2)} &\approx \mathbf{A}_2(\mathbf{A}_1 \odot \mathbf{A}_3)^\top \\ \mathbf{X}_{(3)} &\approx \mathbf{A}_3(\mathbf{A}_1 \odot \mathbf{A}_2)^\top\end{aligned}\tag{3}$$

Now, we have 3 Least Square Minimization Problem,

$$\begin{aligned}\text{Min } &\|\mathbf{A}_1(\mathbf{A}_2 \odot \mathbf{A}_3)^\top - \mathbf{X}_{(1)}\| \\ \text{Min } &\|\mathbf{A}_2(\mathbf{A}_1 \odot \mathbf{A}_3)^\top - \mathbf{X}_{(2)}\| \\ \text{Min } &\|\mathbf{A}_3(\mathbf{A}_1 \odot \mathbf{A}_2)^\top - \mathbf{X}_{(3)}\|\end{aligned}\tag{4}$$

The first one of these minimization problem can be written,

$$\text{Min } \|(\mathbf{A}_2 \odot \mathbf{A}_3)\mathbf{A}_1^\top - \mathbf{X}_{(1)}^\top\|\tag{5}$$

Here, we will fix the co-efficient of A_1^\top i.e. $(\mathbf{A}_2 \odot \mathbf{A}_3) = \mathbf{B}_1$ (say).

$$\text{Min } \|\mathbf{B}_1 \mathbf{A}_1^\top - \mathbf{X}_{(1)}^\top\| \quad (6)$$

So, here A_1 is the unknown and the Matrix Least Square solution is,

$$\begin{aligned} \hat{\mathbf{A}}_1^\top &= (\mathbf{B}_1^\top \mathbf{B}_1)^{-1} \mathbf{B}_1^\top \mathbf{X}_{(1)}^\top \\ \text{i.e. } \hat{\mathbf{A}}_1 &= \mathbf{X}_{(1)} \mathbf{B}_1 (\mathbf{B}_1^\top \mathbf{B}_1)^{-1} \end{aligned}$$

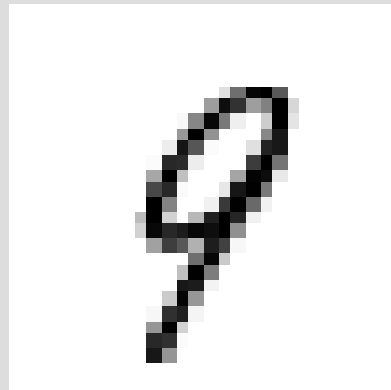
Main Updating Formula

$$\begin{aligned} \hat{\mathbf{A}}_1 &= \mathbf{X}_{(1)} \mathbf{B}_1 (\mathbf{B}_1^\top \mathbf{B}_1)^{-1} \\ \hat{\mathbf{A}}_2 &= \mathbf{X}_{(2)} \mathbf{B}_2 (\mathbf{B}_2^\top \mathbf{B}_2)^{-1} \\ \hat{\mathbf{A}}_3 &= \mathbf{X}_{(3)} \mathbf{B}_3 (\mathbf{B}_3^\top \mathbf{B}_3)^{-1} \end{aligned}$$

Image Compression

Example of 8 rank approximation

Actual



Compressed



MNIST Dataset

Actual Image

Resolution = 28 x 28
No. of Pixels = 784

Compressed Image

No. of Pixels = $8 * (28 + 28)$
= 448

* Compression has been done by Python implementation of this theory

Image Compression

Example of 8 rank approximation

Actual



Compressed



IIT Kgp Logo

Actual Image

Resolution = $896 * 800 * 3$
No. of Pixels = 2150400

Compressed Image

No. of Pixels = $8 * (896 + 800 + 3)$
= 13592

So, Computational Complexity = $o(iter * nmk^3)$

$iter$ = no. of iteration

shape of tensor = (i_1, i_2, \dots, i_n)

Rank approximation = k

order of tensor = n

$m = \max(i_1, i_2, \dots, i_n)$

Reference

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Thank You!
