

## LAB 3:

### 8 Puzzle Game Problem

class Node:

```
def __init__(self, state, parent=None, move=None, depth=0):
    self.state = state      # Current state of the puzzle (3x3 grid)
    self.parent = parent    # Parent node for backtracking
    self.move = move        # Move made to reach this node
    self.depth = depth      # Depth of this node in DFS tree

def calculate_manhattan_distance(self):
    """Calculate the Manhattan distance for the current state."""
    total_distance = 0

    # Define goal positions of each tile in the target configuration
    goal_positions = {
        1: (0, 0), 2: (0, 1), 3: (0, 2),
        4: (1, 0), 5: (1, 1), 6: (1, 2),
        7: (2, 0), 8: (2, 1), 0: (2, 2) # 0 represents the empty space
    }

    # Calculate the total Manhattan distance
    for i in range(3):
        for j in range(3):
            tile = self.state[i][j]
            if tile != 0: # Don't count the empty space
                goal_x, goal_y = goal_positions[tile]
                total_distance += abs(goal_x - i) + abs(goal_y - j)

    return total_distance
```

```
def is_solvable(state):
    """Check if the puzzle is solvable by counting inversions."""
    flat = [tile for row in state for tile in row if tile != 0]
    inversions = sum(1 for i in range(len(flat)) for j in range(i + 1, len(flat)) if flat[i] > flat[j])
    return inversions % 2 == 0 # Solvable if inversions are even
```

```
def dfs_with_manhattan(initial_state, goal_state, max_depth=30):
    """Perform DFS to solve the 8-puzzle, guided by Manhattan distance."""
    stack = [Node(initial_state)] # DFS stack initialized with the starting configuration
    visited = set() # To track visited states and avoid cycles
```

```
while stack:
    node = stack.pop() # Pop from stack (LIFO behavior for DFS)

    # If the current state matches the goal, return the solution path
    if node.state == goal_state:
        return construct_solution(node)
```

```
    # Mark the current state as visited
    visited.add(tuple(map(tuple, node.state)))
```

```
    # Limit the depth to prevent infinite loops
    if node.depth >= max_depth:
        continue
```

```
    # Get possible moves (up, down, left, right)
    for new_state, move in get_possible_moves(node.state):
        state_tuple = tuple(map(tuple, new_state))
        if state_tuple not in visited:
```

```
# Push the new state to the stack
```

```
new_node = Node(new_state, parent=node, move=move, depth=node.depth + 1)
```

```
stack.append(new_node)
```

```
return None # If no solution found
```

```
def get_possible_moves(state):
```

```
    """Generate all valid moves from the current state."""
```

```
    moves = []
```

```
    empty_x, empty_y = find_empty_space(state)
```

```
    # Define directions for up, down, left, right
```

```
    directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]
```

```
    for dx, dy in directions:
```

```
        new_x, new_y = empty_x + dx, empty_y + dy
```

```
        if 0 <= new_x < 3 and 0 <= new_y < 3: # Valid move
```

```
            new_state = [row[:] for row in state] # Copy current state
```

```
            # Swap empty space with the adjacent tile
```

```
            new_state[empty_x][empty_y], new_state[new_x][new_y] = new_state[new_x][new_y],  
new_state[empty_x][empty_y]
```

```
            moves.append((new_state, (dx, dy))) # Append new state and move direction
```

```
    return moves
```

```
def find_empty_space(state):
```

```
    """Find the coordinates of the empty space (represented by 0)."""
```

```
    for i in range(3):
```

```
        for j in range(3):
```

```
        if state[i][j] == 0:
            return i, j
    return None
```

```
def construct_solution(node):
```

```
    """Construct the path of moves that leads to the solution."""
    path = []
    while node.parent is not None: # Trace back from goal to start
        path.append(node)
        node = node.parent
    path.reverse() # Reverse the path to get the correct order
```

```
    # Print each state along the solution path
```

```
    for step in path:
        print_puzzle(step.state)
        print()
```

```
    return path
```

```
def print_puzzle(state):
```

```
    """Helper function to print the puzzle state in a 3x3 grid format."""
    for row in state:
        print(" ".join(str(tile) if tile != 0 else " " for tile in row))
```

```
# Example usage:
```

```
if __name__ == "__main__":
    # Define the initial and goal states of the puzzle
    initial_state = [
```

```
[1, 2, 3],  
[5, 6, 0],  
[7, 8, 4]  
]
```

```
goal_state = [  
    [1, 2, 3],  
    [4, 5, 6],  
    [7, 8, 0]  
]
```

```
# Check if the puzzle is solvable  
if not is_solvable(initial_state):  
    print("The puzzle is not solvable.")  
else:  
    # Solve the puzzle using DFS with Manhattan distance  
    solution = dfs_with_manhattan(initial_state, goal_state)  
  
    # Output the solution, if found  
    if solution:  
        print("Solution found!")  
        print(f"Number of moves: {len(solution)}")  
    else:  
        print("No solution found.")
```

OUTPUT:

```
1 2 3
4   5
7 8 6
```

```
1 2 3
   4 5
7 8 6
```

```
1 2 3
7 4 5
   8 6
```

```
1 2 3
7 4 5
8   6
```

```
1 2 3
7 4 5
8 6
```

```
1 2 3
7 4
8 6 5
```

```
1 2 3
7   4
8 6 5
```

```
1 2 3
   7 4
8 6 5
```

```
1 2 3
8 7 4
   6 5
```

1 2 3  
8 7 4  
6 5

1 2 3  
8 7 4  
6 5

1 2 3  
8 7  
6 5 4

1 2 3  
8 7  
6 5 4

1 2 3  
8 7  
6 5 4

1 2 3  
6 8 7  
5 4

1 2 3  
6 8 7  
5 4

1 2 3  
6 8 7  
5 4

1 2 3  
6 8  
5 4 7

```
1 2 3
5 6 8
4 7
```

```
1 2 3
5 6 8
4 7
```

```
1 2 3
5 6
4 7 8
```

```
1 2 3
5 6
4 7 8
```

```
1 2 3
5 6
4 7 8
```

```
1 2 3
4 5 6
7 8
```

```
1 2 3
4 5 6
7 8
```

```
1 2 3
4 5 6
7 8
```

Solution found!

Number of moves: 29

=== Code Execution Successful ===