

Assignment 30 (Constraint Handling)

Take a look at the constraint handling techniques from the lecture and answer the following questions.

- What is constraint handling and why is it needed in optimization algorithms?
- Constraint handling the process of adding constraints (equality, inequality, box constraints) to an optimization problem such that it performs the task in a more constrained manner.
- Two variations of constraint handling:

- For SOP

$$\begin{aligned} \min f(x) \\ \text{subj to } h_j(x) &= 0; j = 1 \dots J \\ g_k(x) &\geq 0; k = 1 \dots K \\ x^L &\leq x \leq x^U \end{aligned}$$

- For MOP

$$\begin{aligned} \min F(x) &= (f_1(x), \dots, f_m(x)) \\ \text{subj to } h_j(x) &= 0; j = 1 \dots J \\ g_k(x) &\geq 0; k = 1 \dots K \\ x^L &\leq x \leq x^U \end{aligned}$$

Relevance:

- Real-world optimization problems and decision making almost always have constraints.
- Engineering design problems: stress constraints, material properties.

- Consider the following single-objective problem with 2 decision variables and 2 inequality constraints.

$$\begin{aligned} \min \quad & f(\vec{x}) = 3 \cdot x_1 + 4 \cdot x_2 \\ \text{subject to} \quad & g_1(\vec{x}) = 0.4 \cdot x_1 - 0.6 \cdot x_2 \geq 0 \\ & g_2(\vec{x}) = -0.1 \cdot x_1 + 0.8 \cdot x_2 - 0.1 \geq 0 \end{aligned}$$

For this problem, we decided to use the static penalty method with one fixed value of $R = 3$ as shown on slide EMO-6-35. For the three solutions $\vec{x}^{(a)} = (2, 4)$, $\vec{x}^{(b)} = (1, 5)$ and $\vec{x}^{(c)} = (7, 2)$, please compute the fitness of the solutions, their constraint violations for each of the two constraints and the penalized objective function values.

Fitness values, constraint violations & penalized objective function values,

$$\begin{aligned} f(\vec{x}^{(a)}) &= 3(2) + 4(4) = \mathbf{22} \\ g_1(\vec{x}^{(a)}) &= 0.4(2) - 0.6(4) = \mathbf{1.6} \geq 0 \\ g_2(\vec{x}^{(a)}) &= -0.1(2) + 0.8(4) - 0.1 = \mathbf{2.9} \geq 0 \\ F(\vec{x}^{(a)}) &= 22 + 3(1.6 + 2.9) = \mathbf{35.5} \end{aligned}$$

$$\begin{aligned} f(\vec{x}^{(b)}) &= 3(1) + 4(5) = \mathbf{23} \\ g_1(\vec{x}^{(b)}) &= 0.4(1) - 0.6(5) = \mathbf{2.6} \geq 0 \\ g_2(\vec{x}^{(b)}) &= -0.1(1) + 0.8(5) - 0.1 = \mathbf{3.8} \geq 0 \\ F(\vec{x}^{(b)}) &= 23 + 3(2.6 + 3.8) = \mathbf{42.2} \end{aligned}$$

$$\begin{aligned} f(\vec{x}^{(c)}) &= 3(7) + 4(2) = \mathbf{29} \\ g_1(\vec{x}^{(c)}) &= 0.4(7) - 0.6(2) = \mathbf{1.6} \geq 0 \\ g_2(\vec{x}^{(c)}) &= -0.1(7) + 0.8(2) - 0.1 = \mathbf{0.8} \geq 0 \\ F(\vec{x}^{(c)}) &= 29 + 3(1.6 + 0.8) = \mathbf{36.2} \end{aligned}$$