

## Assignment 2

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### Problem 1

#### question 1

**Indices:**  $i = 1, 2, \dots, m$  for different boundary ids of the polyhedron P.  $j = 1, 2, \dots, n$  for different dimensions in space  $R^n$ .

**Data:**  $a_i$  and  $b_i$  together form the  $i$ th boundary of the polyhedron P.  $A_{i,j}$  is a matrix where  $a_i = A_{i, \cdot}$ , and  $b_i$  is a vector.

**Variables:**  $y \in R^n$  is the center of the ball we want that is inside the polyhedron.  $r$  is the radius of that ball.

**Objective:** maximize  $r$

**Constraints:**  $a_i y + r \leq b_i$  for every  $i$ .

**Bounds:**  $r$  needs not to be negative numbers.

#### question 2

Result as shown in Figure 1.

```

Coefficient statistics:
  Matrix range      [3e-06, 1e+00]
  Objective range   [1e+00, 1e+00]
  Bounds range      [0e+00, 0e+00]
  RHS range         [1e+00, 1e+01]
Presolve time: 0.03s
Presolved: 101 rows, 1000 columns, 101000 nonzeros

Iteration   Objective          Primal Inf.    Dual Inf.      Time
     0      0.0000000e+00      1.000000e+00   9.999945e+08    0s
   542      1.4853767e+00      0.000000e+00   0.000000e+00    0s

Solved in 542 iterations and 0.16 seconds
Optimal objective  1.485376717e+00

```

Figure 1

### Problem 2

#### question 1

**Indices:**  $i = 1, 2, \dots, M$  are the indices for oil fields.  $j = 1, 2, \dots, N$  are the indices for processing plants.

**Data:**  $c_i$  is the cost of extracting crude oil from oil field  $i$ , its unit: dollars per barrel.  $a_i$  is the percentage of sulfur from oil field  $i$ , each barrel of crude oil has  $a_i$  barrels of sulfur.  $m_i$  is the maximum of total crude extracted at field  $i$ , its unit: barrels.  $f_{i,j}$  is the cost of transporting from oil field  $i$  to processing plant  $j$ , its unit: dollars per barrel.  $u_j$  is the maximum percentage of sulfur in the final product after blending in processing plant  $j$ .  $d_j$  is the minimum of total crude transported to processing plant  $j$ , its unit: barrels.

**Variables:**  $x_{i,j}$  is how much oil to transport from field i to plant j, its unit: barrels.

**Objective:** minimize  $\sum_{i=1}^M \sum_{j=1}^N (c_i + f_{i,j})x_{i,j}$

**Constraints:**  $\sum_{i=1}^M x_{i,j}a_i \leq u_j \sum_{i=1}^M x_{i,j}$  for every j,  $\sum_{i=1}^M x_{i,j} \geq d_j$  for every j,  $\sum_{j=1}^N x_{i,j} \leq m_i$  for every i.

**Nonnegativity:**  $x_{i,j}$  needs not to be negative numbers.

## question 2

Result as shown in Figure 2.

```
Barrier statistics:
AA' NZ : 1.991e+05
Factor NZ : 2.489e+05 (roughly 40 MBytes of memory)
Factor Ops : 5.705e+07 (less than 1 second per iteration)
Threads : 3

Objective          Residual
Iter  Primal      Dual      Primal  Dual    Compl   Time
0     7.12025725e+06  0.00000000e+00  7.04e+03  0.00e+00  1.28e+02  0s
1     2.58562855e+05 -3.41859297e+04  1.86e+02  2.80e-01  5.02e+00  0s

Barrier performed 1 iterations in 0.24 seconds
Barrier solve interrupted - model solved by another algorithm

Solved with dual simplex
Solved in 538 iterations and 0.25 seconds
Optimal objective 1.362806158e+03
```

Figure 2

## Problem 3

### question 1

**Indices:**  $t = 1, 2, \dots, T$  for different months.  $s = 1, 2, \dots, T - 1$ , also for different months. Here  $T = 12$ .  $t$  has the same meaning with  $s$  except that  $s = T$  does not exist.

**Data:**  $D_t$  is the demand for the additive in month t, its unit: lbs,  $L_s$  is the maximum of absolute difference between production in month s and month (s + 1), its unit: lbs,  $C_t$  is the cost of production in month t, its unit: dollars per lb,  $H_t$  is the cost of holding in month t, its unit: dollars per lb.

**Variables:**  $p_t$  is how much additive to produce in month t.  $s_t$  is how much additive that they still have in month t.

**Objective:** minimize  $\sum_{t=1}^T p_t C_t + s_t H_t$

**Constraints:**  $s_1 = 100 + p_1 - D_1$ ,  $h_t = h_{t-1} * 0.95 + p_t - D_t$  for t except  $t = 1$ ,  $p_{s+1} - p_s \leq L_s$ , and  $t = 1$ ,  $p_{s+1} - p_s \geq -L_s$ .

**Bounds:**  $p_t$  and  $s_t$  all need not to be negative numbers.

### question 2

Result as shown in Figure 3.

```

MODEL FINGERPRINT: 0X0E1C0B04
Coefficient statistics:
  Matrix range      [9e-01, 1e+00]
  Objective range   [7e-02, 1e+00]
  Bounds range      [0e+00, 0e+00]
  RHS range         [5e+00, 2e+02]
Presolve removed 23 rows and 12 columns
Presolve time: 0.00s
Presolved: 11 rows, 23 columns, 43 nonzeros

Iteration    Objective    Primal Inf.    Dual Inf.    Time
     0        6.5536160e+02    3.430187e+01    0.000000e+00    0s
    12        8.0984260e+02    0.000000e+00    0.000000e+00    0s

Solved in 12 iterations and 0.00 seconds
Optimal objective  8.098426008e+02

```

Figure 3

## Problem 4

### question 1

**Indices:**  $i = 1, 2, \dots, m$  are the different indices/ids of boundaries.  $j = 1, 2, \dots, n$  is the dimension of vector in  $R^n$  space.

**Data:**  $a_i$  and  $b_i$  together form the center of the  $i$ th boundary of the polyhedron  $P$ .  $A_{i,j}$  is a matrix where  $a_i = A_i$ , and  $b_i$  is a vector.  $\delta_i$  is the uncertainty of each element of the vector  $a_i$ .

**Variables:**  $x \in R^n$  is a vector representing the center of that ball, where  $x_j$  is the  $n$ th item.  $posix \in R^n$  is all positive items of  $x$  and  $negx \in R^n$  is all negative items of  $x$ . For  $posix$  and  $negx$ , all items that does not satisfy the positive or negative criterion equal to zero.

**Objective:** No objective since we are trying to find feasible point.

**Constraints:**  $a_i x + \delta_i(posix - negx) \leq b_i$  for every  $i$ .  $posix_j + negx_j = x_j$  for every dimension  $j$ .

**Bounds:**  $posix_j \geq 0$  and  $negx_j \leq 0$  for every dimension  $j$ .

### question 2

With the same indices, data, bounds, and variables as above, to have a numerical measure of feasibility, we change the objective and constraints as below:

**New variables:**  $k$  is a number, which is a numerical measure of feasibility.

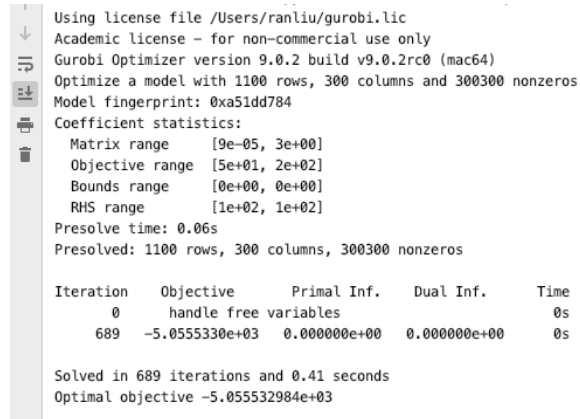
**Objective:** minimize  $k$

**Constraints:**  $a_i x + \delta(posix - negx) \leq b_i + k$  for every  $i$ .  $posix_j + negx_j = x_j$  for every dimension  $j$ .

**Explanation:** when  $k$  equals to zero or is less than zero, the previous model is feasible at the beginning. When  $k$  is greater than zero, the previous model is not feasible since it needs a  $k$  greater than zero to satisfy all the constraints. Hence, the  $k$  can be a numerical measure of feasibility, where the greater the  $k$  is the less feasible the model is. Now, the point  $x$  that is as feasible as possible is the variable  $x$ .

**question 3**

Result as shown in Figure 4.



```

Using license file /Users/ranliu/gurobi.lic
Academic license - for non-commercial use only
Gurobi Optimizer version 9.0.2 build v9.0.2rc0 (mac64)
Optimize a model with 1100 rows, 300 columns and 300300 nonzeros
Model fingerprint: 0xa51dd784
Coefficient statistics:
  Matrix range      [9e-05, 3e+00]
  Objective range   [5e+01, 2e+02]
  Bounds range      [0e+00, 0e+00]
  RHS range         [1e+02, 1e+02]
Presolve time: 0.06s
Presolved: 1100 rows, 300 columns, 300300 nonzeros

Iteration   Objective          Primal Inf.    Dual Inf.      Time
     0      handle free variables                0s
    689  -5.0555330e+03  0.000000e+00  0.000000e+00   0s

Solved in 689 iterations and 0.41 seconds
Optimal objective -5.055532984e+03

```

Figure 4