

Ranul Vithanage

Undergraduate, University of Moratuwa, Moratuwa, Sri Lanka

vithanagetvrh.19@uom.lk — +94 71 1049 350 — [linkedin.com/in/ranul-helitha](https://www.linkedin.com/in/ranul-helitha) — [ranulv.github.io](https://github.com/ranulv)

RESEARCH INTERESTS

Human-Computer Interaction, Human-Robot Interaction, Robotics, Computer Vision, Autonomous Systems

EDUCATION

University of Moratuwa, Moratuwa, Sri Lanka

BSc Eng (Hons) in Mechanical Engineering

Dean's List in Semesters 1, 2, 6, and 7

January 2020 — Present

Cumulative GPA: 3.71/4.20

PUBLICATIONS

[ranulv.github.io/publications](https://github.com/ranulv/publications)

Smart Music Therapist 1.0: Rhythmic Auditory Stimulation Integrated Robotic Walker as a Therapeutic Companion for Gait Rehabilitation

(submitted to IEEE Int. Workshop on Robot and Human Communication (RO-MAN) 2024)

[\[PDF\]](#)

- Robot-facilitated Music Therapy towards a semi-autonomous solution for gait rehabilitation
- Telerehabilitation platform for Music Therapist to remotely monitor and consult patients
- Intelligent companionship (voice interaction, graphical user interface, music recommendation, etc.) integrated with a robotic walker fusing rehabilitation and socially assistive robotics

Robust Autonomous Summoning Capabilities for a Patient Assistive Mobile Robot

(submitted to IEEE Int. Conference on Advanced Robotics and Mechatronics (ICARM) 2024)

[\[PDF\]](#)

- Robust navigation without reliance on Indoor Positioning Systems (IPS) for infrastructure-limited areas
- LiDAR-based SLAM for Localization and Mapping
- Sound Source Localization for out-of-line-of-sight navigation and Gesture Recognition with Depth estimation by Stereo Vision for line-of-sight navigation

Intelligent Control System for Active Walking Guidance of a Robotic Walker

(submitted to Moratuwa Engineering Research Conference 2024)

[\[PDF\]](#)

- Active Navigation Control Interface using armrest-mounted force-sensitive resistor matrix
- Comparative evaluation of Rule-based and Fuzzy Control Methods on intuitiveness and smoothness of control
- Armrest-integrated Haptic feedback for direction-specific obstacle avoidance

Design and Simulation of a Thermally Actuated Microgripper with a Compliant Bistable Release Mechanism for Biomanipulation

(submitted to Moratuwa Engineering Research Conference 2024)

[\[PDF\]](#)

- MEMS-based Microgripper with an Active Plunger working on the principle of Bistable Compliant Mechanism
- Featuring Double and Cascaded V-shaped (Chevron-shaped) actuators for effective manipulation
- Simulation results of displacement and temperature in the range preferred for bio samples

mWalker: Towards Independent living with a Multi-functional Robotic Walker providing intelligent patient assistance

(Journal Paper in Preparation)

- Human height prediction from anthropometric data obtained using pose estimation for sit-to-stand assistance
- Emergency detection and alerting system, Active guidance, Posture and emotion monitoring
- Fabrication of the Robotic Walker platform with experimental evaluation of compliance to ISO standards using static and dynamic tests

PROJECTS

ranulv.github.io/projects

Design and Development of a Multi-functional Robotic Walker (Final Year Project)

- Able to autonomously be summoned to the user's location for line-of-sight and non-line-of-sight scenarios
- Provides active user guidance suiting the user's pace with intuitive control methodology
- Provides sit-to-stand assistance upon the estimation of user height through computer vision
- Performs onboard Gait Analysis using a walker-mounted 2D LiDAR device and user-worn IMU
- Performs Emotion recognition and posture analysis for fatigue and emergency detection

Design and Development of a Remote Monitoring Robot for Gait Rehabilitation

- Performs Rhythmic Auditory Stimulation as a rehabilitation aid for users with gait disorders
- Able to monitor real-time gait data remotely by a medical professional using wearable IMUs worn by the user
- Provides feedback for gait improvement to the user even without external monitoring

PROFESSIONAL EXPERIENCE

Visiting Instructor

Department of Mechanical Engineering - University of Moratuwa

Moratuwa, Sri Lanka

March 2023 — Present

- Designed a Glove Washing Station following a Latex Dipping Tank for an automated production line
- Designed an automated glove folding mechanism that integrates with a conveyor belt
- Designed an automated glove cuff-cutting mechanism for Supported gloves improving safety and efficiency
- Designed an automated mechanism for transferring glove formers from drying ovens to latex dipping stations
- Completed 3D designs and detailed drawings for fabrication of components in Glove manufacturing plants

Industrial Automation Intern

Dipped Products PLC

Kottawa, Sri Lanka

January 2023 — June 2023

- Designed a Glove Washing Station following a Latex Dipping Tank for an automated production line
- Designed an automated glove folding mechanism that integrates with a conveyor belt.
- Designed an automated glove cuff-cutting mechanism for Supported gloves improving safety and efficiency
- Designed an automated mechanism for transferring glove formers from drying ovens to latex dipping stations
- Completed 3D designs and detailed drawings for fabrication of components in Glove manufacturing plants

National Head of Talent Management and Organizational Development

AIIESEC in Nepal

Kathmandu, Nepal

July 2022 — January 2023

- Responsible for Membership Experience Program (MXP) implementation
- Responsible for the National Project Managers
- Responsible for the National Ethics Subcommittee and Membership Subcommittee
- Management of the Talent Management Commission and Network
- Responsible for implementation of the Organizational Development (OD) model
- Responsible for local entity process assessment, improvement, and coaching

COURSES

Bachelor's Courses

- | | |
|--|---------------------------------------|
| • Robotics Technology | • Biomedical Engineering Applications |
| • Object Oriented Programming Using C++ | • Calculus |
| • Control Systems & Instrumentation | • Linear Algebra |
| • Industrial Automation | • Operational Research |
| • Micro/Nano Electro Mechanical Systems and Nanotechnology | • Applied Statistics |
| | • Graph Theory |

Additional Courses

CIMA (Chartered Institute of Management Accountants)

Certificate Level Completed (Self-learned)

VOLUNTEERING EXPERIENCES

Diriya Arunalu (Link)

Co-Founder & Educator

Galle, Sri Lanka

Jan 2019 - Dec 2019

- Co-founded the initiative to support Mathematics education in underprivileged schools in Galle
- Organized numerous teaching sessions in correspondence with school management
- Taught Mathematics to students in Grades 10 and 11 preparing for the G.C.E. O/L Examination
- Organized book donations among peers to donate to ill-resourced libraries in the local area

SKILLS

- **Programming:** Python, C++, MATLAB
- **Frameworks:** ROS, Gazebo
- **Libraries:** OpenCV, Numpy, Matplotlib, SciKit-Learn, TensorFlow, PyTorch
- **Software:** SOLIDWORKS, COMSOL, Solid Edge
- **Soft Skills:** Collaboration, Critical thinking, Written/Oral communication.

REFERENCES

Prof. Y.W.R. Amarasinghe

Mechanical Engineering Department, University of Moratuwa, Sri Lanka

E-mail: ranama@uom.lk, ranamajp@gmail.com

Dr. Palitha Dassanayake

Mechanical Engineering Department, University of Moratuwa, Sri Lanka

E-mail: palitha@uom.lk

Dr. Dumith Jayathilaka

Mechanical Engineering Department, University of Moratuwa, Sri Lanka

E-mail: dumithj@uom.lk