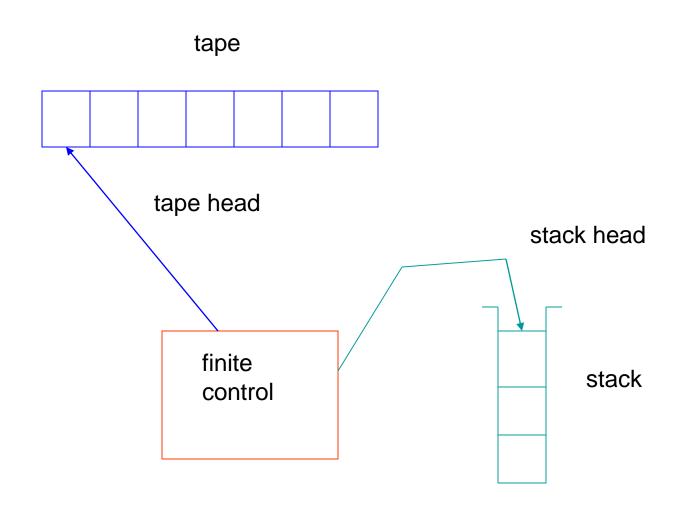
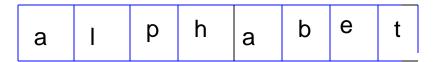
Pushdown Automata





The tape is divided into finitely many cells. Each cell contains a symbol in an alphabet Σ .

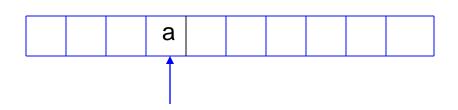


The stack head always scans the top symbol of the stack. It performs two basic operations:

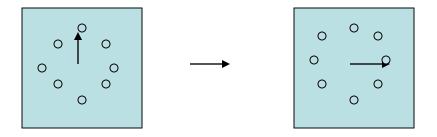
Push: add a new symbol at the top.

Pop: read and remove the top symbol.

Alphabet of stack symbols: \(\Gamma \)

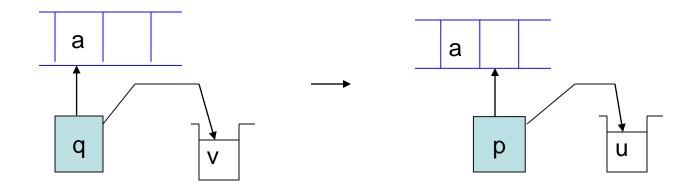


 The head scans at a cell on the tape and can read a symbol on the cell. In each move, the head can move to the right cell.

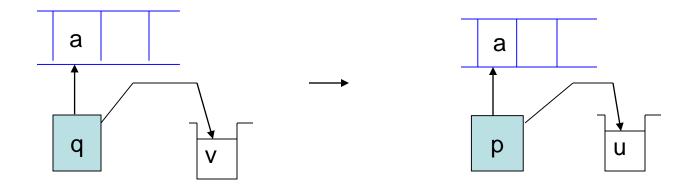


 The finite control has finitely many states which form a set Q. For each move, the state is changed according to the evaluation of a transition function

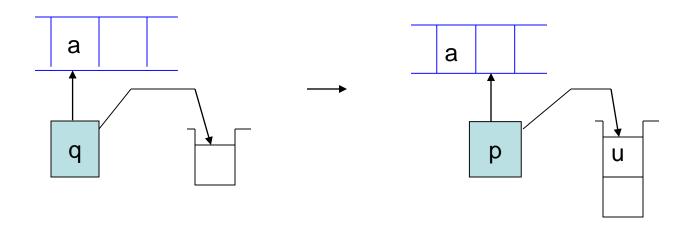
$$\delta: Q \; x \; (\Sigma \; U \; \{\epsilon\}) \; x \; (\Gamma \; U \; \{\epsilon\}) \; \rightarrow \; 2^{\; Q \; x \; (\Gamma \; U \; \{\epsilon\})}$$



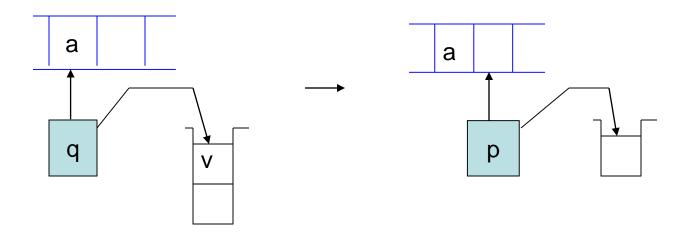
(p, u) ∈ δ(q, a, v) means that if the tape head reads a, the stack head read v, and the finite control is in the state q, then one of possible moves is that the next state is p, v is replaced by u at stack, and the tape head moves one cell to the right.



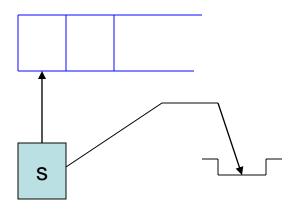
• $(p, u) \in \delta(q, \varepsilon, v)$ means that this a ε -move.



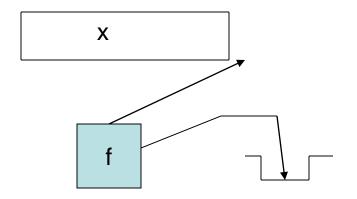
• $(p, u) \in \delta(q, a, \varepsilon)$ means that a push operation performs at stack.



• $(p, \varepsilon) \in \delta(q, a, v)$ means that a pop operation performs at stack



- There are some special states: an initial state s and a final set F of final states.
- Initially, the PDA is in the initial state s and the head scans the leftmost cell. The tape holds an input string. The stack is empty.



- When the head gets off the tape, the PDA stops. An input string x is accepted by the PDA if the PDA stops at a final state and the stack is empty.
- Otherwise, the input string is rejected.

The PDA can be represented by

$$M = (Q, \Sigma, \Gamma, \delta, s, F)$$

- where Σ is the alphabet of input symbols and Γ is the alphabet of stack symbols.
- The set of all strings accepted by a PDA M
 is denoted by L(M). We also say that the
 language L(M) is accepted by M.

- The transition diagram of a PDA is an alternative way to represent the PDA.
- For $M = (Q, \Sigma, \Gamma, \delta, s, F)$, the transition diagram of M is an edge-labeled digraph G=(V, E) satisfying the following:

$$V = Q (s = 0, f = 0)$$
 for $f \in F$

$$E = \{ q \xrightarrow{a, v/u} p \mid (p,u) \in \delta(q, a, v) \}.$$