

GATE (ALL BRANCHES)

Engineering Mathematics

**Differential Equation +
Partial differential**



Lecture No. 04

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TOPICS TO BE COVERED

o1

Problems based on Linear Differential equation

o2

Reducible to Linear Differential Equation

o3

Higher order Linear Differential Equations with constant coefficients

Linear Diff. Equⁿ [Reducible Form]

$$\underbrace{f'(y) \frac{dy}{dx}}_{\text{Derivative of Middle term}} + \underbrace{f(y) P(x)}_{\text{Middle Term}} = Q(x)$$

Where P and Q are Function of x only.

Linear D.E $\rightarrow \frac{dy}{dx} + Py = Q$

$\rightarrow f'(y) \frac{dy}{dx} = \text{Non Linear} = (\text{Dependent var}) \times \text{derivative of Dependent variable}$

$f(y) = t$ w.r.t to x

$$f'(y) \frac{dy}{dx} = \frac{dt}{dx} \frac{dx}{dx}$$

$$\frac{dt}{dx} + t \cdot P(x) = Q(x)$$

This is Linear D.E which is linear in t

$$\frac{dy}{dx} + y P(x) = Q(x)$$

Integrating Factor = $e^{\int P(x) dx}$

Solution of Differential Equⁿ

$$y \cdot (I \cdot F) = \int (RHS) \cdot (I \cdot F) dx + C$$

solⁿ of D.E

Bernoulli Equⁿ

Reduced to Linear D.E

$$\frac{dy}{dx} + P_y = y^n$$

Non Linear

Linear

$$\frac{dy}{dx} + P_y = Q$$

$$\frac{dy}{dx} + Py = Qy^n \longrightarrow \frac{dy}{dx} + Py = Q$$

Divide via y^n

$$\Rightarrow \frac{1}{y^n} \frac{dy}{dx} + P \cancel{y^{1-n}} = Q$$

$$\Rightarrow \frac{1}{(1-n)} \frac{dt}{dx} + Pt = Q$$

$$= \frac{dt}{dx} + P(1-n)t = Q(1-n)$$

Where n is a Integer

Which is linear in t

Integrating factor = $e^{\int P(1-n)dx}$

$$y^{1-n} = t$$

both sides Differentiate It
 $(1-n) y^{1-n} \frac{dy}{dx} = \frac{dt}{dx}$

$$(1-n) \frac{1}{y^n} \frac{dy}{dx} = \frac{dt}{dx}$$

$$\Rightarrow \frac{1}{y^n} \frac{dy}{dx} = \frac{1}{(1-n)} \frac{dt}{dx}$$

$$t \times (I.F) = \int Q(1-n) \cdot e^{\int (1-n)dx} dx + C$$

Q.

Questions

#Q. A curve passes through the point $(x = 1, y = 0)$ satisfies the differential equation

$$\frac{dy}{dx} = \frac{x^2 + y^2}{2y} + \frac{y}{x}$$

The equation is

(a) $\ln\left(1 + \frac{y^2}{x^2}\right) = x - 1$

(c) $\frac{1}{2} \ln\left(1 + \frac{y^2}{x^2}\right) = x - 1$

(b) $\ln(1 + y/x) = x - 1$

(d) $\frac{1}{2} \ln(1 + y/x) = x - 1$

$$\left(\frac{dy}{dx} = \frac{(x^2 + y^2)}{2y} + \frac{y}{x} \right) \rightarrow \text{solution}$$

$y = 0 \text{ at } x = 0$

(Do yourself) **M.W**

Q.

Questions

#Q. Consider the differential equation $(t^2 - 81) \frac{dy}{dt} + 5ty = \sin(t)$ with $y(1) = 2\pi$. There exists a unique solution for this differential equation when t belongs to the interval

- (a) ☒ $(-2, 2)$
- (b) ☒ $(-10, 10)$
- (c) ☒ $(-10, 2)$
- (d) ☒ $(0, 10)$

$$\frac{dy}{dt} + \frac{5t}{(t^2 - 81)} y = \frac{\sin t}{(t^2 - 81)}$$

$$P = \frac{5t}{(t^2 - 81)}$$

$$Q = \frac{\sin t}{(t^2 - 81)}$$

$$I.F = e^{\int \frac{5t}{(t^2 - 81)} dt}$$

Solution

$$y \cdot e^{\int \frac{5t}{(t^2 - 81)} dt} = \int \frac{\sin t}{(t^2 - 81)} e^{\int \frac{5t}{(t^2 - 81)} dt} dt + C$$

does Not exists

$t = -9, 9$

$t \in [-2, 2]$

$t = 9$

$t = -9$

Q.

Questions

#Q. $\frac{dy}{dx} + \frac{xy}{1-x^2} = xy^{1/2}$

$$\frac{dy}{dx} + \frac{xy}{(1-x^2)} = xy^{1/2}$$

$$= \frac{1}{y^{1/2}} \frac{dy}{dx} + \frac{xy}{y^{1/2}(1-x^2)} = x$$

$$= \frac{1}{y^{1/2}} \frac{dy}{dx} + \frac{x}{(1-x^2)} y^{1/2} = x$$

$$P = \frac{x}{2(1-x^2)} \quad Q = \frac{x}{2}$$

$$\Rightarrow y^{1/2} = t$$

$$\Rightarrow 2 \frac{dt}{dx} + \frac{x}{(1-x^2)} \cdot t = x$$

$$\frac{1}{2} y^{-1/2} \frac{dy}{dx} = \frac{dt}{dx}$$

$$\frac{dt}{dx} + \frac{x}{2(1-x^2)} \cdot t = \frac{x}{2}$$

$$\frac{1}{y^{1/2}} \frac{dy}{dx} = 2 \frac{dt}{dx}$$

$$\text{Integrating factor} = e^{\int p dx}$$

$$= e^{\int \frac{x}{2(1-x^2)} dx}$$

$$I = \frac{1}{2} \int \frac{x}{(1-x)(1+x)} dx$$

Using Partial Fraction

Solution of D.E

$$I \cdot (I.F) = \int (RHS)(I.F) dx$$

Solution of D.E

Q.

Questions



#Q. $y^2 \frac{dy}{dx} = x + y^3$

$$y^2 \frac{dy}{dx} = x + y^3$$

$$y^2 \frac{dy}{dx} - y^3 \cdot 1 = x$$

$$y^3 = t$$
$$3y^2 \frac{dy}{dx} = \frac{dt}{dx}$$

$$\Rightarrow \frac{1}{3} \frac{dt}{dx} - t \cdot 1 = x$$

$$\Rightarrow \frac{dt}{dx} - 3t \cdot 1 = 3x$$

$$P = -3 \quad Q = 3x$$

$$y^2 \frac{dy}{dx} = \text{Non Linear}$$

Linear D.E $\frac{dy}{dx} + Py = Q.$

Integrating factor

$$= e^{\int P dx}$$
$$= e^{\int -3 dx}$$
$$= e^{-3x}$$

$$t \cdot e^{-3x} = \int 3x e^{-3x} dx$$

$$= y^3 e^{-3x} = \frac{1}{3} \int \underset{\text{I}}{t} \underset{\text{II}}{e^{-t}} dt$$

$$\begin{aligned} 3x &= t \\ 3dx &= dt \\ dt &= \frac{dt}{3} \end{aligned}$$

$$\begin{array}{l} t \cdot e^{-t} \\ \downarrow \\ 1 \cdot e^{-t} \\ \downarrow \\ 0 \cdot e^{-t} \end{array}$$

$$= y^3 e^{-3x} = \frac{1}{3} \left[-y^3 e^{-y^3} - e^{-y^3} \right] + C$$

$$= -te^{-t} - e^{-t}$$

Ans

2 Marks
100%
GATE

Higher Order Linear Diff. Equation:

$$x^n K_1 \frac{d^n y}{dx^n} + x^{n-1} K_2 \frac{d^{n-1} y}{dx^{n-1}} + x^{n-2} K_3 \frac{d^{n-2} y}{dx^{n-2}} + \dots + K_n y = X$$

Where $K_1, K_2, K_3, \dots, K_n$ are constants X is a Function of ' x '

Two Parts
Break

$$(A) \underbrace{K_1 \frac{d^n y}{dx^n} + K_2 \frac{d^{n-1} y}{dx^{n-1}} + \dots + K_n y = X}_{\text{Linear Diff. Eqn}^n \text{ with constant coefficients}}$$

Linear Diff. Eqnⁿ with constant coefficients

$$(B) K_1 x^n \frac{d^n y}{dx^n} + K_2 x^{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + K_n y = X$$

Linear Diff. with variable coefficients

- ✓ Constant coefficients
- ✓ Variable coefficients

LINEAR D.E with constant coefficients:

$$K_1 \frac{d^n y}{dx^n} + K_2 \frac{d^{n-1} y}{dx^{n-1}} + K_3 \frac{d^{n-2} y}{dx^{n-2}} + \dots + K_n y = X$$

Where $K_1, K_2, K_3, \dots, K_n$ Are constants 'X' is a Function of x only.

→ For $n=2$ (SECOND order)

$$\Rightarrow \boxed{K_1 \frac{d^2 y}{dx^2} + K_2 \frac{dy}{dx} + K_3 y = X}$$

Where K_1, K_2, K_3 are constants
'X' is a function of 'x' only

CHECK The Linearity:

Using The superposition principle

$$\begin{cases} L[X_1 \pm X_2] = L[X_1] \pm L[X_2] \\ L[cX_1] = cL[X_1] \end{cases}$$

Check The Linear Property

$$L[x_1 + x_2] = L[x_1] + L[x_2]$$

$$y \longrightarrow x_1 + x_2$$

$$K_1 \frac{d^2}{dx^2}(x_1 + x_2) + K_2 \frac{d}{dx}(x_1 + x_2) + K_3(x_1 + x_2)$$

$$\Rightarrow \left[K_1 \frac{d^2 x_1}{dx^2} + K_2 \frac{dx_1}{dx} + K_3 x_1 \right] + \left[K_1 \frac{d^2 x_2}{dx^2} + K_2 \frac{dx_2}{dx} + K_3 x_2 \right]$$

$L[x_1] \quad + \quad L[x_2]$

This is a Linear Differential Equⁿ.

Holds The Linear Property

$$L[x_1 + x_2] = L[x_1] + L[x_2]$$

$$K_1 \frac{d^2 y}{dx^2} + K_2 \frac{dy}{dx} + K_3 y = X$$

If $X=0$ (Homogenous system)

= Transient state

= Natural oscillations

= No force apply.

Solution

$y =$ Natural oscillations

OR

Transients or Homogenous Equⁿ

$y_c =$ Complementary function

c_1, c_2

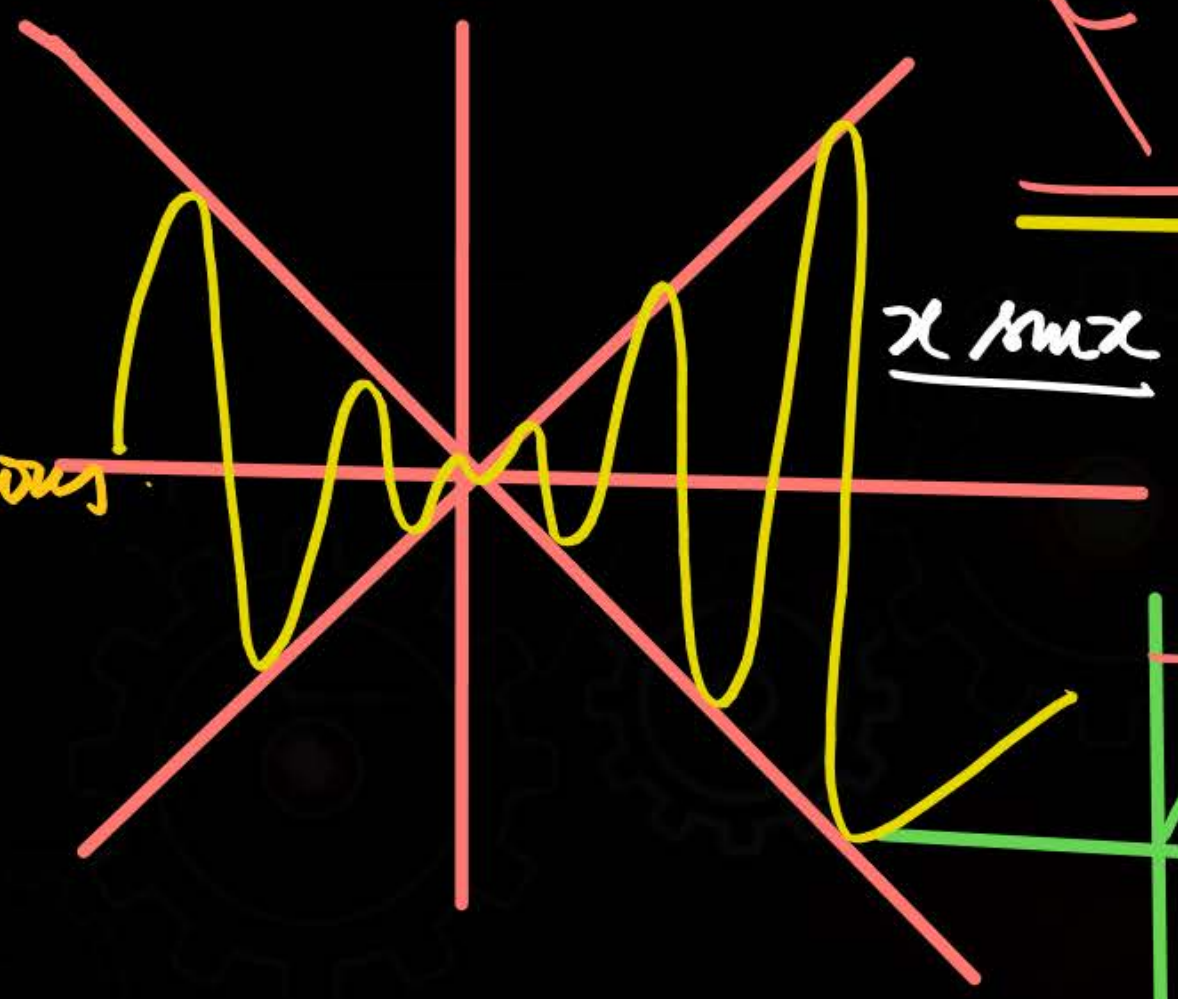
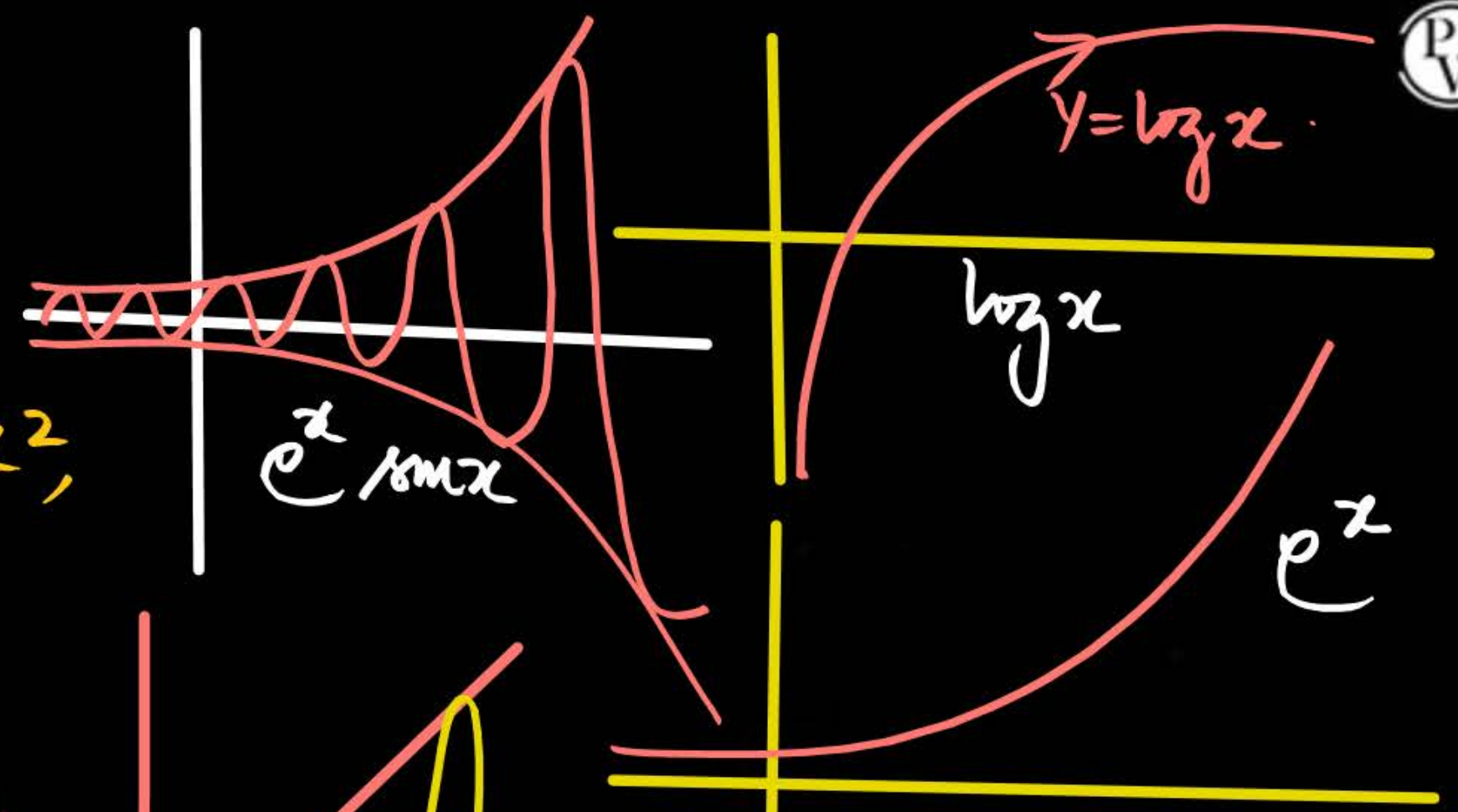
This is Linear D.E

Where K_1, K_2, K_3 Are const.

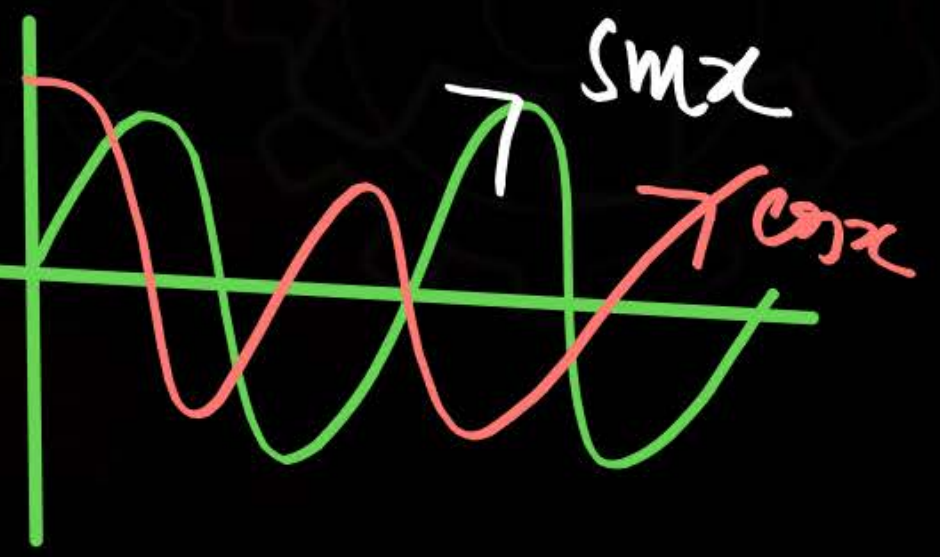
X is a Function of x only

If $x \neq 0$
 $x = e^x, \log x,$
 $\sin x, \cos x, x^2,$
 etc

- ✓ Non Homogeneous
- ✓ Forced oscillations
- ✓ Steady state
- ✓ force apply.



$y = \text{Homogenous} + \text{Non Homogenous}$
 $= \text{ZERO} + \text{NonZERO}$
 solution
 $= \text{C.F} + \text{Particular Integral}$



CASE 01 If $X=0$ $K_1 \frac{d^2 y}{dx^2} + K_2 \frac{dy}{dx} + K_3 y = X$

$$K_1 \frac{d^2 y}{dx^2} + K_2 \frac{dy}{dx} + K_3 y = 0, \quad \frac{d^2 y}{dx^2} + \underbrace{\left(\frac{K_2}{K_1}\right)}^p \frac{dy}{dx} + \underbrace{\left(\frac{K_3}{K_1}\right)}^q y = 0$$

Solution of this D.E

$$\Rightarrow \frac{d^2 y}{dx^2} + p \frac{dy}{dx} + q y = 0$$

$$\frac{d^2 y}{dx^2} + p \frac{dy}{dx} + q y = 0 \quad \text{Using hit and trial method}$$

Put $y = e^{rx}$ is a solution of This D.E

$$\frac{d^2}{dx^2}(e^{rx}) + p \frac{d}{dx}(e^{rx}) + q e^{rx} = 0$$

$$\Rightarrow \boxed{[r^2 + pr + q] e^{rx} = 0}$$

Roots

$$\begin{aligned} \frac{d}{dx}(e^{rx}) &= r e^{rx} \\ \frac{d^2}{dx^2}(e^{rx}) &= r \cdot r e^{rx} = r^2 e^{rx} \end{aligned}$$

$$\Rightarrow [x^2 + px + q] e^{rx} = 0$$

Two Roots

$$\Rightarrow x = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$$

- ✓ $p^2 - 4q = 0$ Roots Real + Equal
- ✓ $p^2 - 4q > 0$ Roots real + Diff.
- ✓ $p^2 - 4q < 0$ Roots Are Imaginary.

Linear
Diff. Equⁿ

Solution

$$y = C_1 y_1 + C_2 y_2 + C_3 y_3 + C_4 y_4 + \dots + C_n y_n$$

Linear form

CASE 01:

If Roots Are Real and Distinct

Solution of D.E

$$y = C_1 y_1 + C_2 y_2 + C_3 y_3 + \dots + C_n y_n$$

y_1, y_2, y_3 Are function of x only

$$\begin{aligned} r=2 & \quad y = e^{rx} \\ r=3 & \quad y_1 = e^{2x} \\ & \quad y_2 = e^{3x} \end{aligned}$$

Solution

$$y = C_1 e^{2x} + C_2 e^{3x}$$

$$\frac{d^2 y}{dx^2} - 5 \frac{dy}{dx} + 6y = 0$$

✓ SECOND order ✓

✓ $X=0$ Homogenous

✓ LINEAR

Put $y = e^{rx}$ is a solution
D.E

$$= [r^2 - 5r + 6] e^{rx} = 0$$

factor

$$r^2 - 3r - 2r + 6 = 0$$

$$(r-3)(r-2) = 0$$

$$\begin{aligned} r &= 3 \\ r &= 2 \end{aligned}$$

$$y = c_1 e^{2x} + c_2 e^{3x}$$

where c_1 and c_2 are constants

→ e^{2x}, e^{3x} are independent solutions {²₃} Indep.

Check the solutions Dependent / Independent

Wronskian = $\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \neq 0$ Independent Solution

W
SECOND
order:

$$W = \begin{vmatrix} e^{2x} & e^{3x} \\ 2e^{2x} & 3e^{3x} \end{vmatrix} \neq 0$$

Wronskian = $\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = 0$ Dependent solutions

If $\lambda \leftarrow \begin{matrix} r_1 \\ r_2 \\ r_3 \end{matrix}$

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x} + c_3 e^{r_3 x}$$

Independent condition

Wronskian

$$W = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} \neq 0$$

Independent

for n Roots

$\swarrow \downarrow \searrow \nearrow$

$r_1 \quad r_2 \quad r_3 \quad r_n$

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x} + c_3 e^{r_3 x} + \dots + c_n e^{r_n x}$$

Thank You!

PW Soldiers