

# Mapping V4 to Artificial Neurons via Autoencoder allows Decoding Visual Information

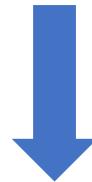
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# AI as a tool to analyze neural / behavioral data

## External World (stimuli)



An AI to **encode** (simulate) neural signals?

**$10^{12}$  neurons in human brain**



Another AI to **decode** neural signals?

**Senses**

**Action**

**Emotion**

**Cognition**

...

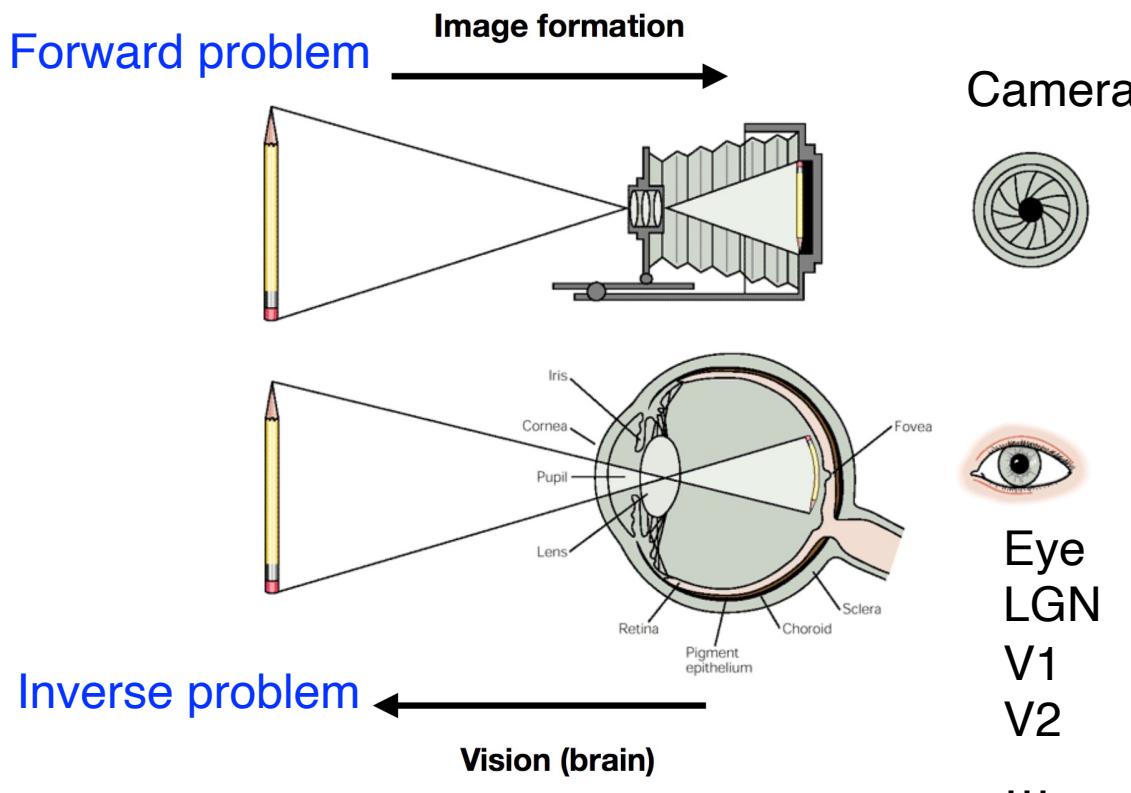
What are problems of the end-to-end

- Not possible to record all neurons
- No enough training datasets
- No enough computational power to fit data
- Even though we can do all these, we know **nothing** from the model.

A good AI in neuroscience shall not only fit the data, but also provide insights to **explain the underlying mechanisms** of how the brain works.

# Function of the visual system

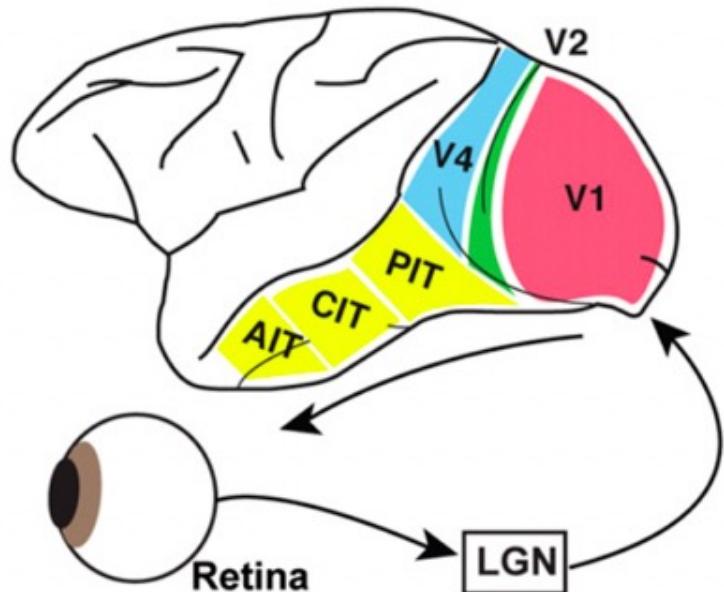
The **visual system** is a part of the central nervous system (CNS) that gives organisms the ability to **detect, process, interpret** information from **visible light**, with the goal of building a **representation** of the surrounding environment.



NOT a camera:  
Visual system solves inverse problem

**Detect  
Process  
Interpret**

# Inverse problem in the visual system

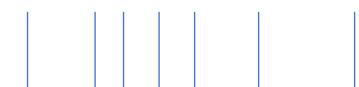


Information presented in brain

Neuron 1

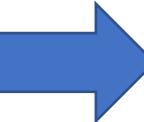


Neuron n



Time (ms)

**infer**



Information in world

Tree  
Flower  
Cat  
Table  
...

Our brain is an inference machine.

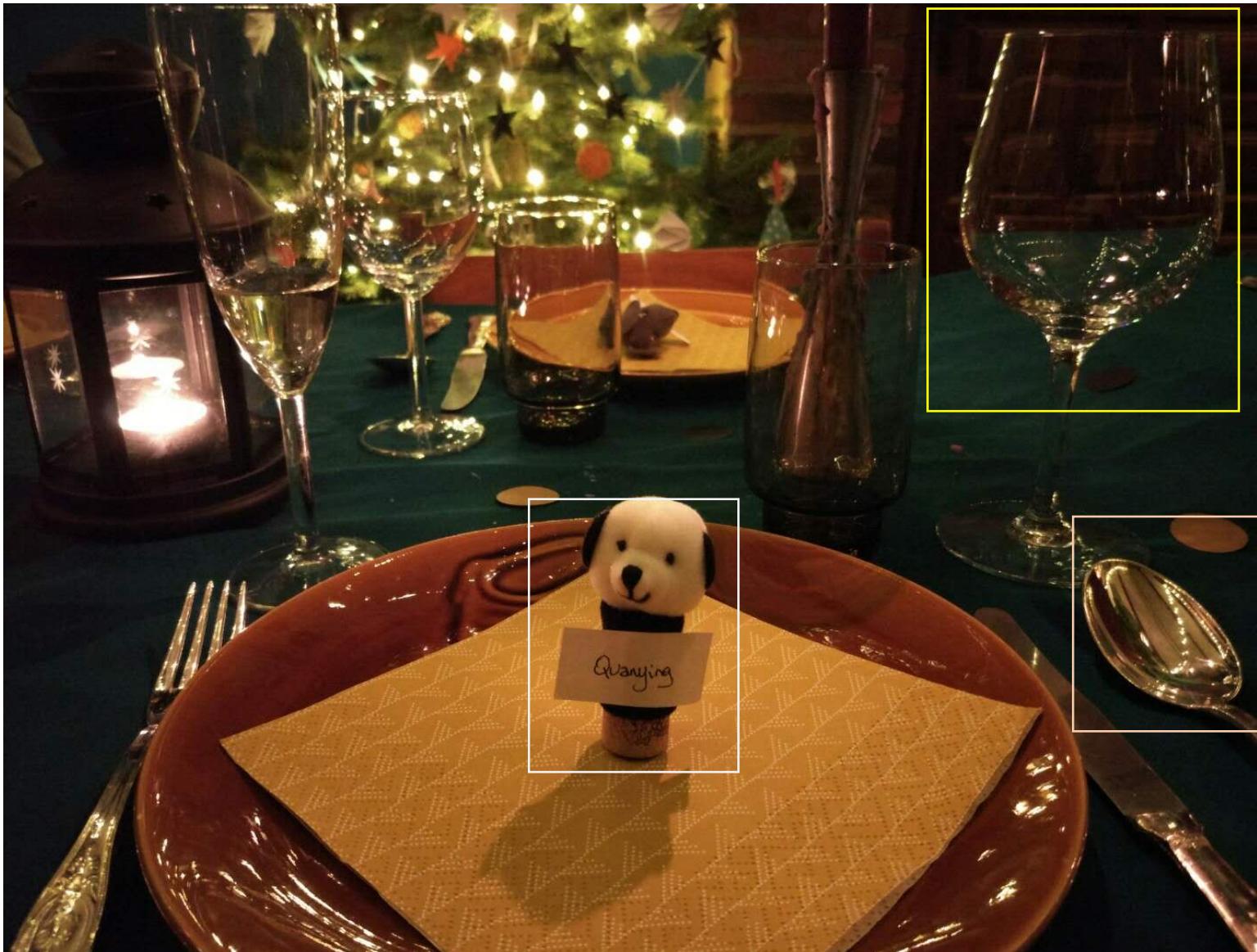
The visual system rapidly solve the inverse problem.

# Our visual system rapidly solves object recognition task.

Visual system solves the core object recognition task ~ 200ms, robustly and accurately.



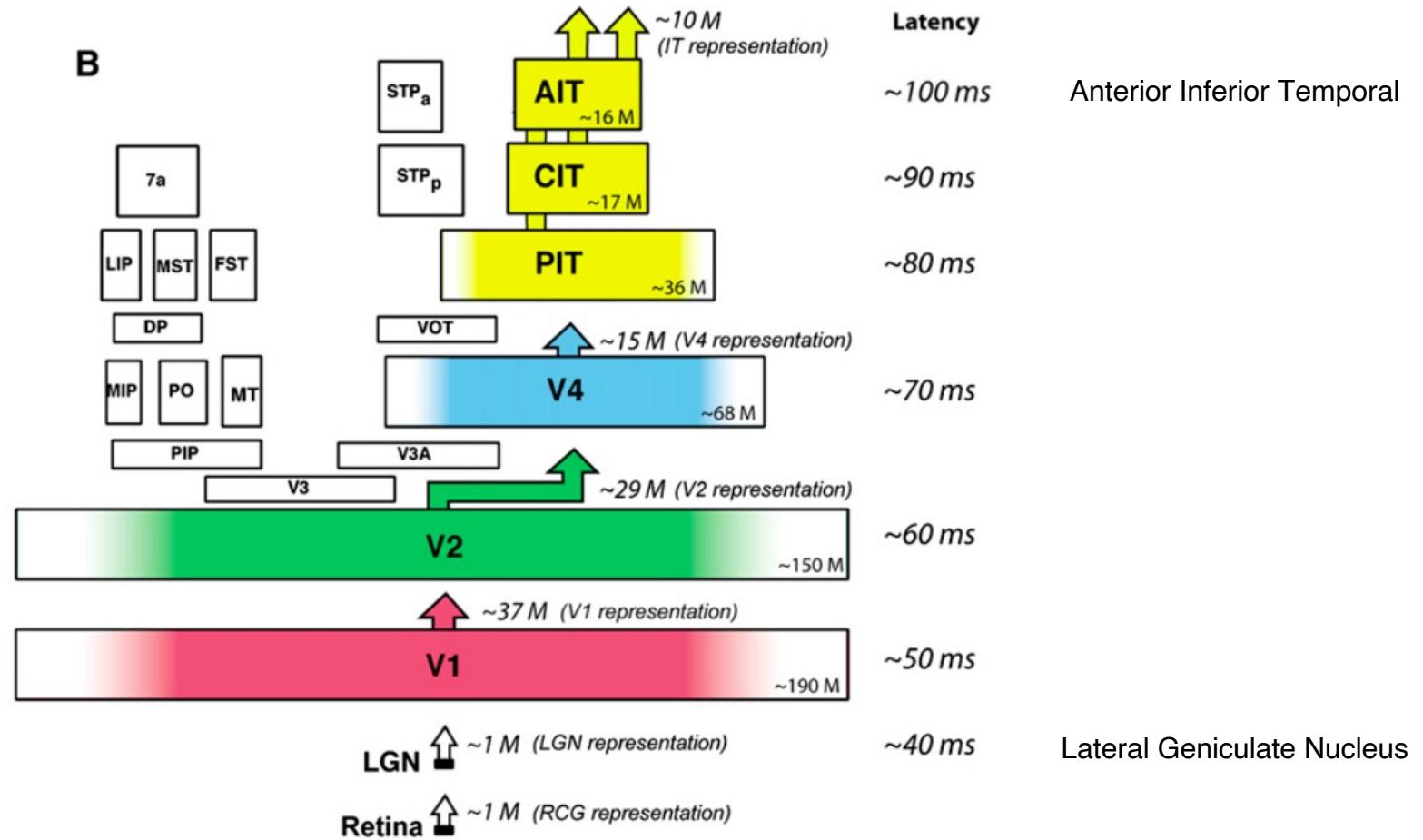
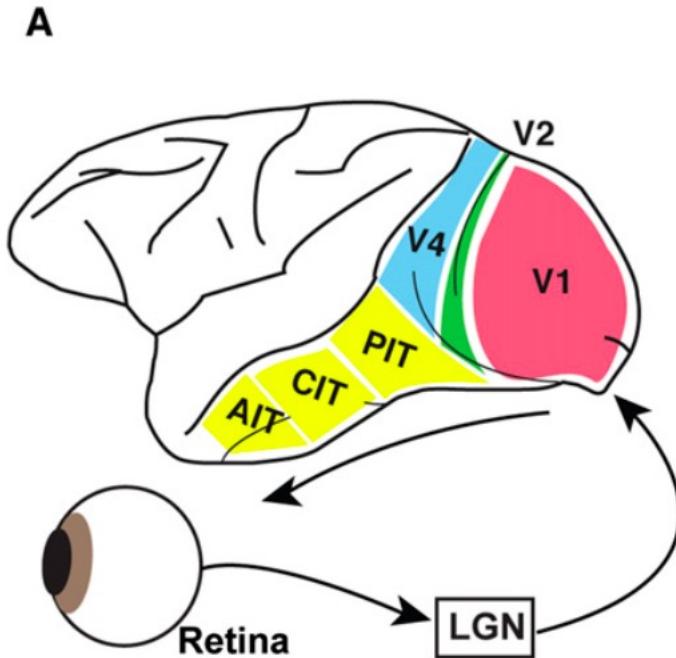
# AI can also rapidly solve object recognition task.



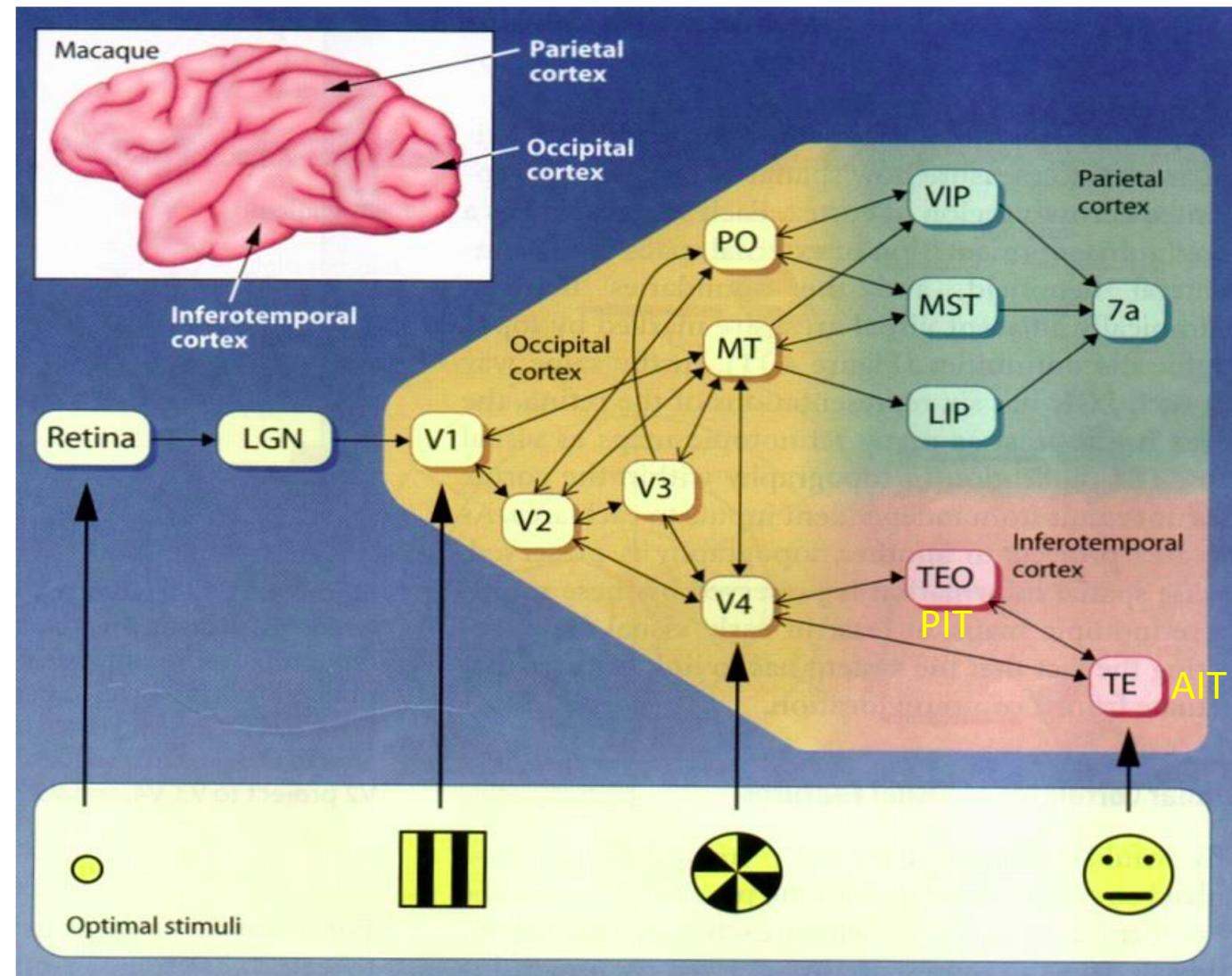
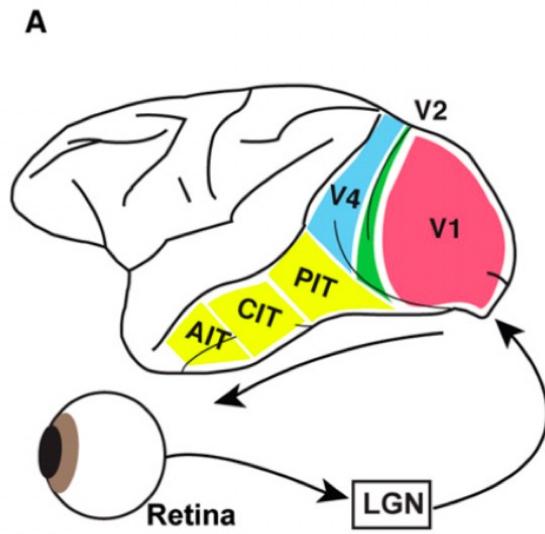
# **Is there any similarity between brain and AI?**

The answer is yes.  
Plenty.

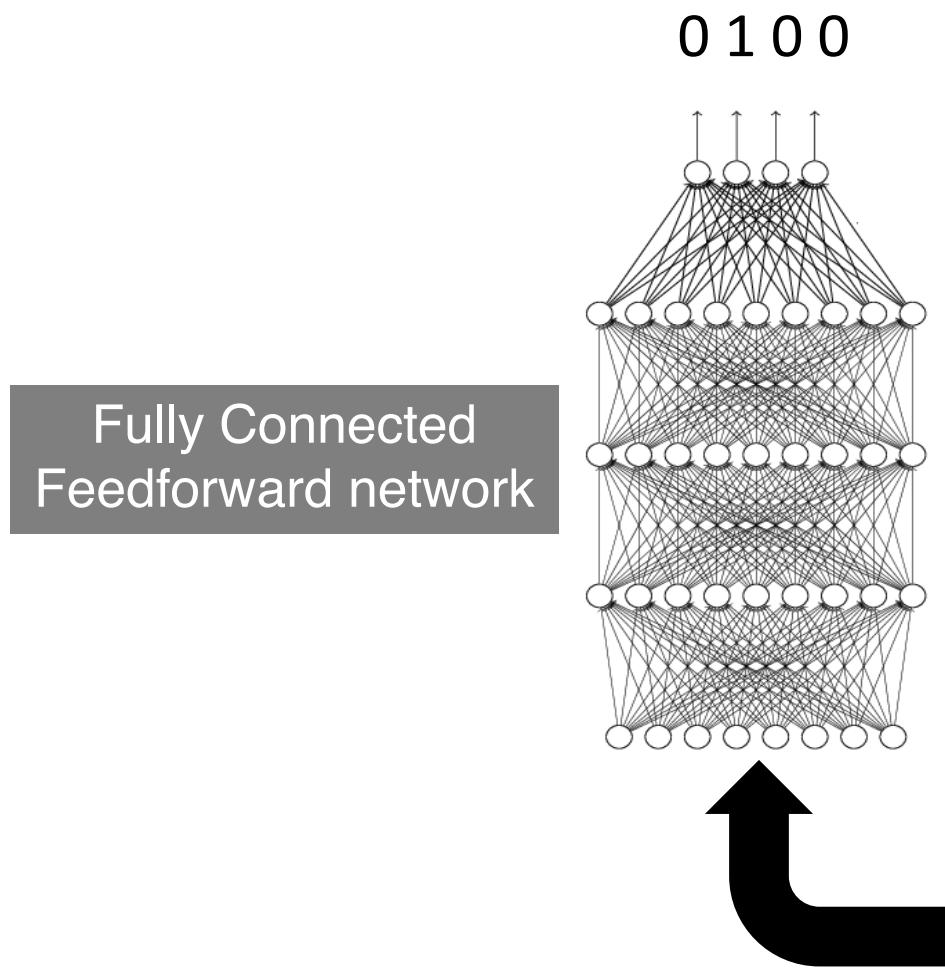
# The ventral visual pathway in brain: for object recognition



# Feature extraction from simple to complex, along the ventral stream



# Convolutional Neural Network (CNN)



# Image process: brain vs. CNN

## 1. Small receptive field vs. small convolutional kernel

A neuron does **not** have to see the whole image to discover the pattern.

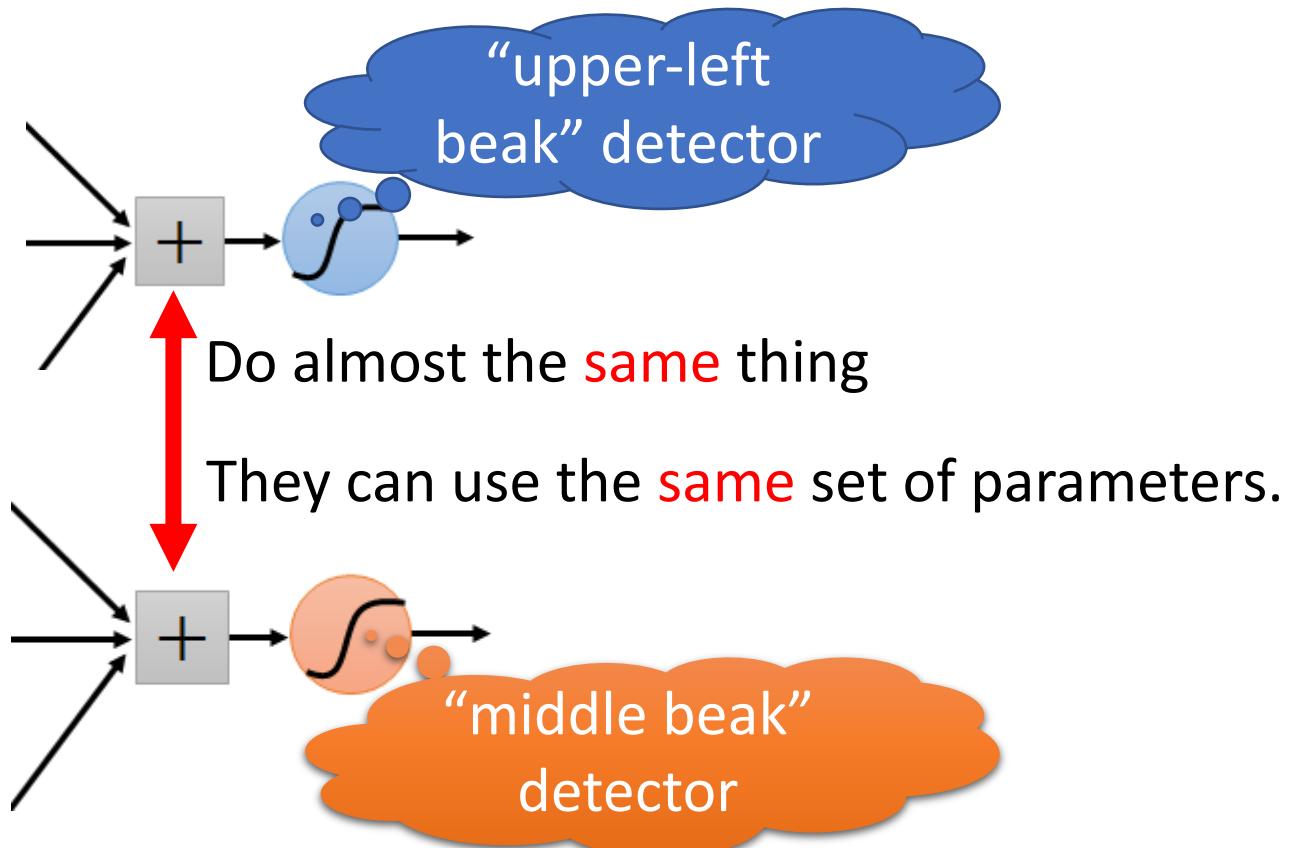
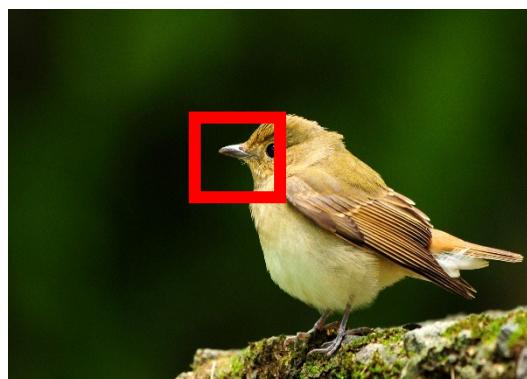
Connecting to small region with less parameters



# Image process: brain vs. CNN

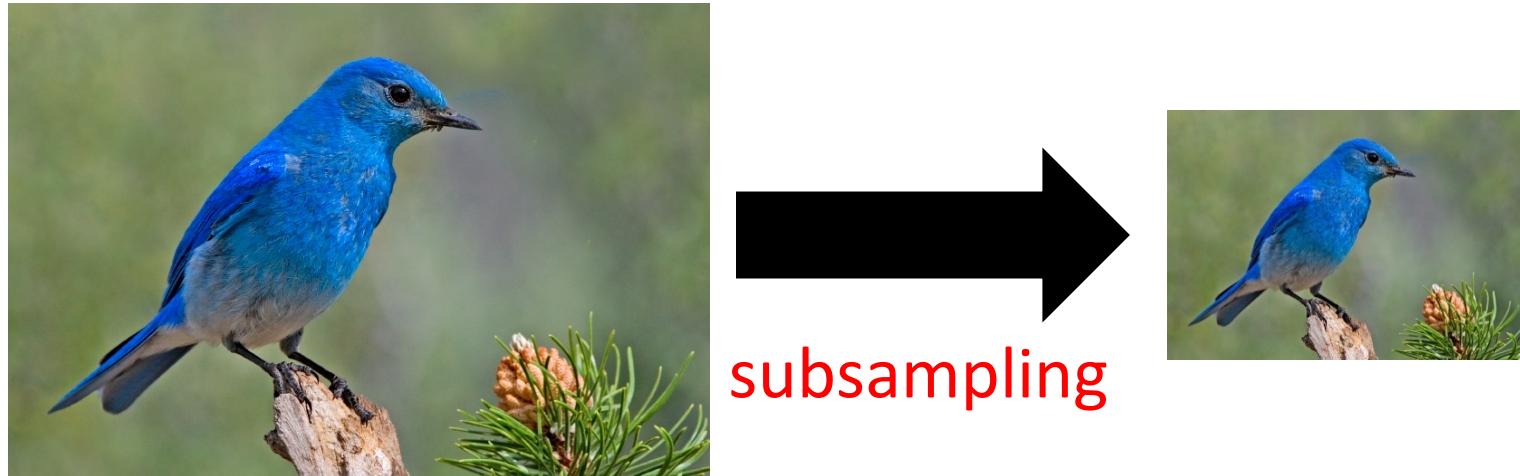
## 2. Identity-preserving transformation

Invariance to position, pose vs. shared convolutional kernel



# Image process: brain vs. CNN

## 3. Invariance to scale and subsampling vs Pooling

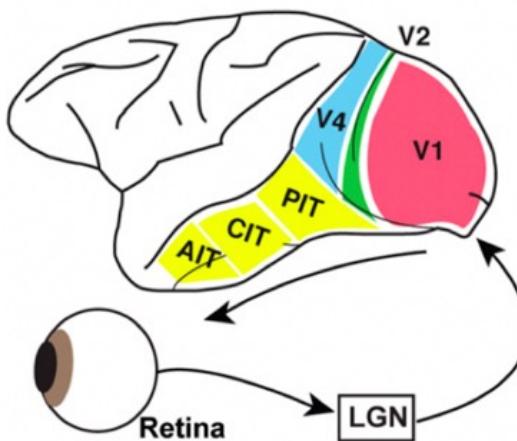
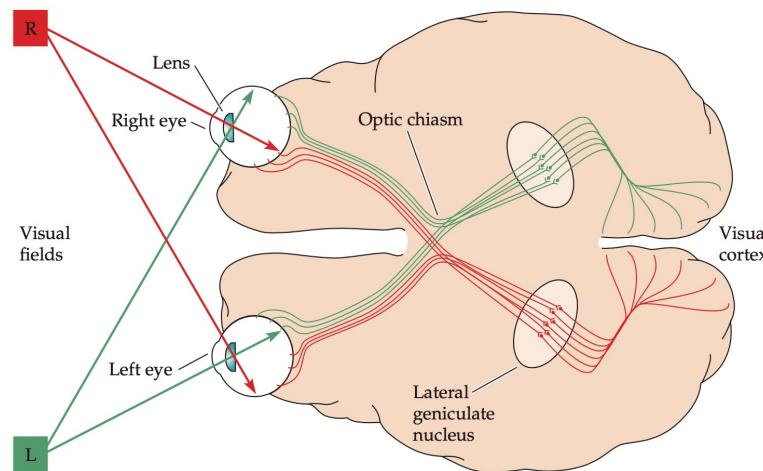


We can subsample the pixels to make image smaller

→ **Less** parameters for the network to process the image

# Image process: brain vs. CNN

4. Both the visual system and CNN are layered and hierarchical.



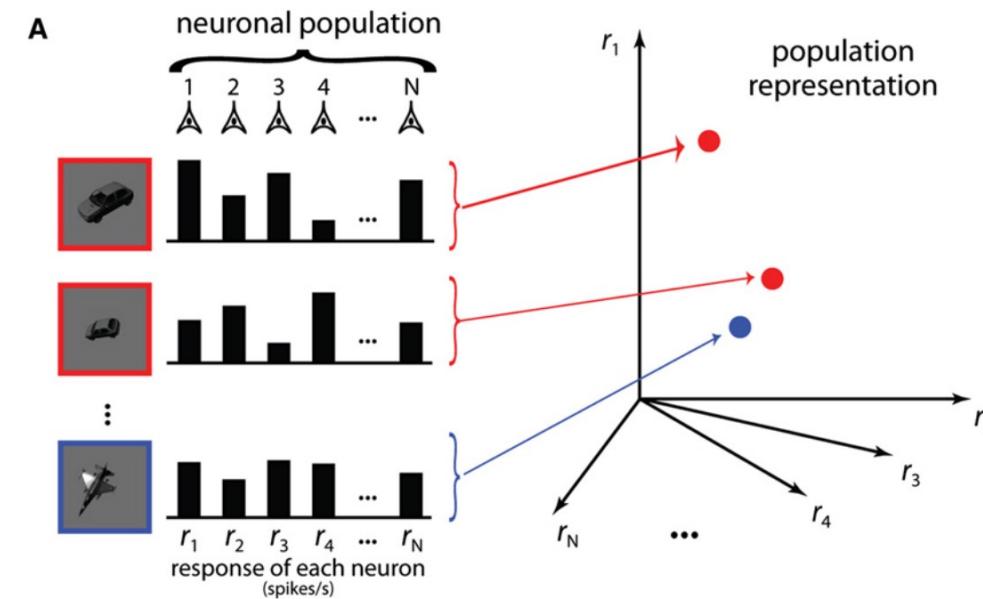
Rods, cones  
Interneurons  
Ganglion cells  
Optic fiber  
LGN  
V1  
Ventral / dorsal pathways

Along the Visual Pathway, feature extraction from simple to complex.

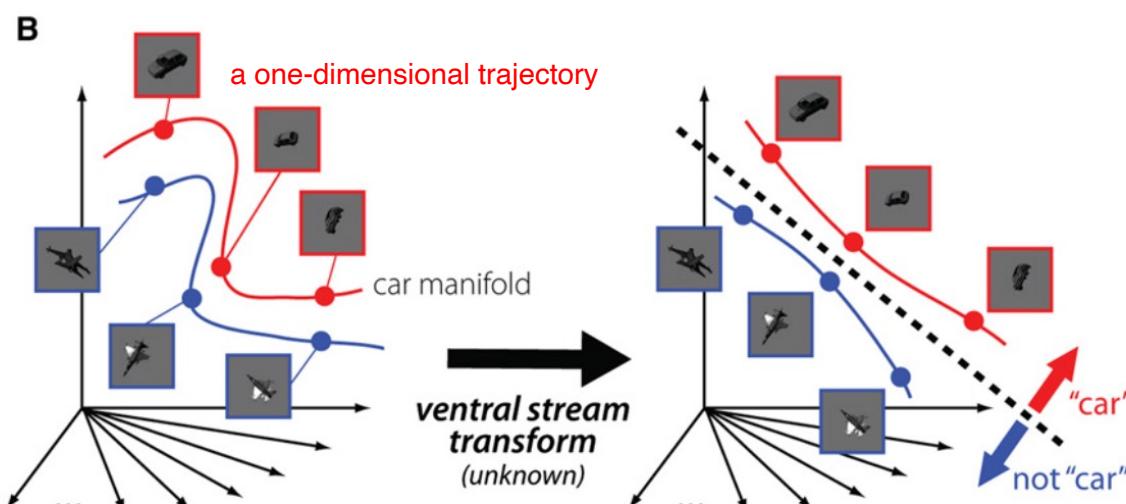
→ **Automatically** learn the hidden features in the image

**Is there any similarity between  
the neural representation in brain and  
AI?**

# What does the neural population representation mean?



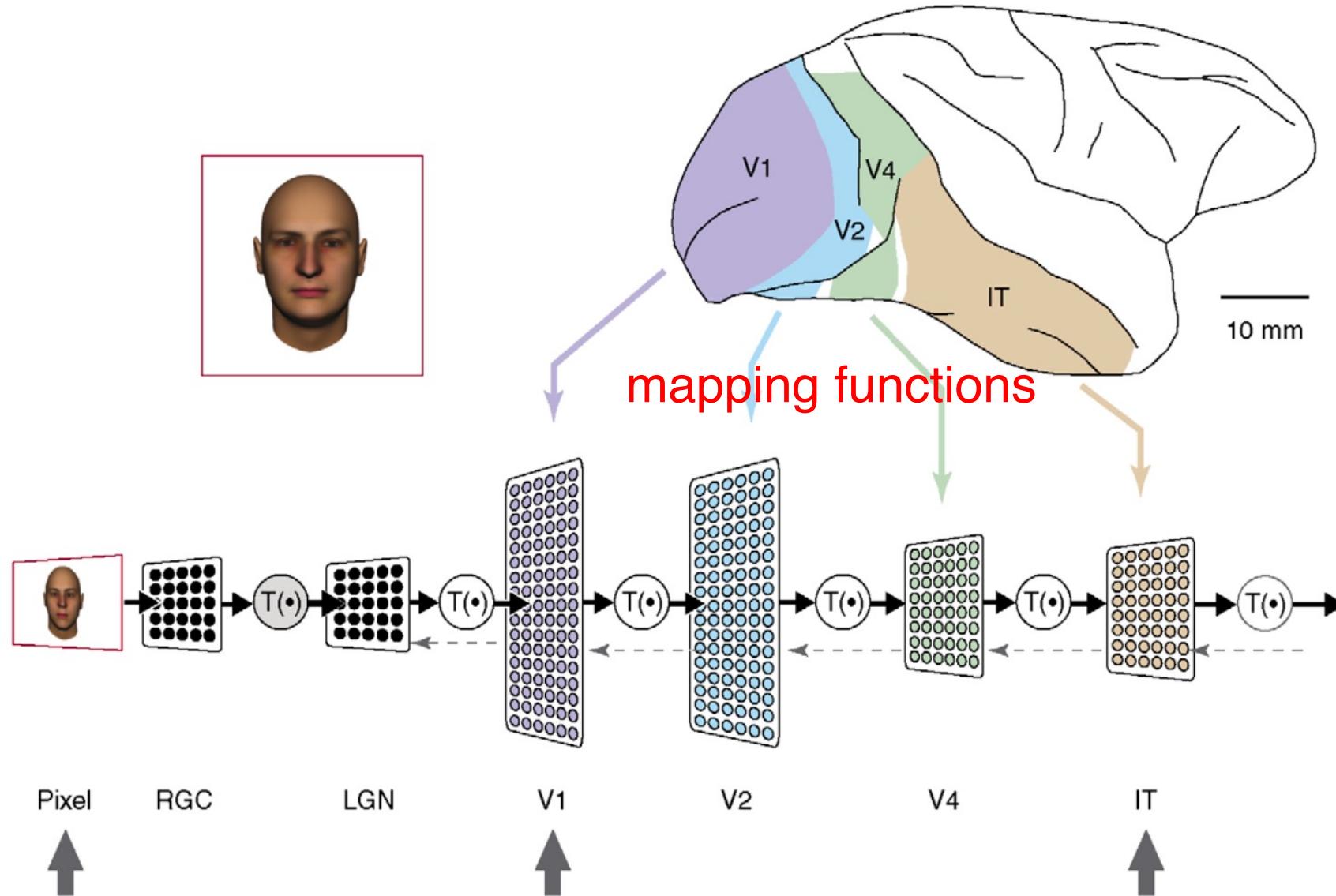
The response pattern of a population of visual neurons (e.g., retinal ganglion cells & V1 neurons) to each image is a point in a very high-dimensional space where each axis is the response level of each neuron.



All possible identity-preserving transformations of an object will form a low-dimensional manifold of points in the population vector space (i.e., a continuous surface).

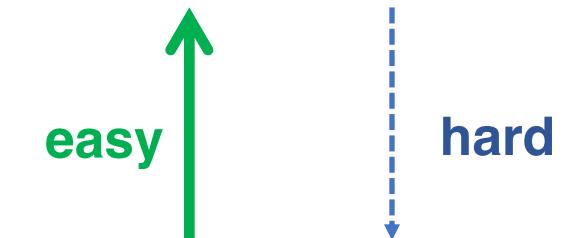
Highly curved and tangled in early visual areas (LGN, V1)  
→ An easy separation of object's manifold in later visual areas (V4, IT)

# Biological neural representation resembles to the artificial neural representation.



## Technical limits

Low-dimensional neuron recordings



High-dimensional CNN feature maps

# Brain score: how well existing models explain the neural data

<http://www.brain-score.org/#leaderboard>

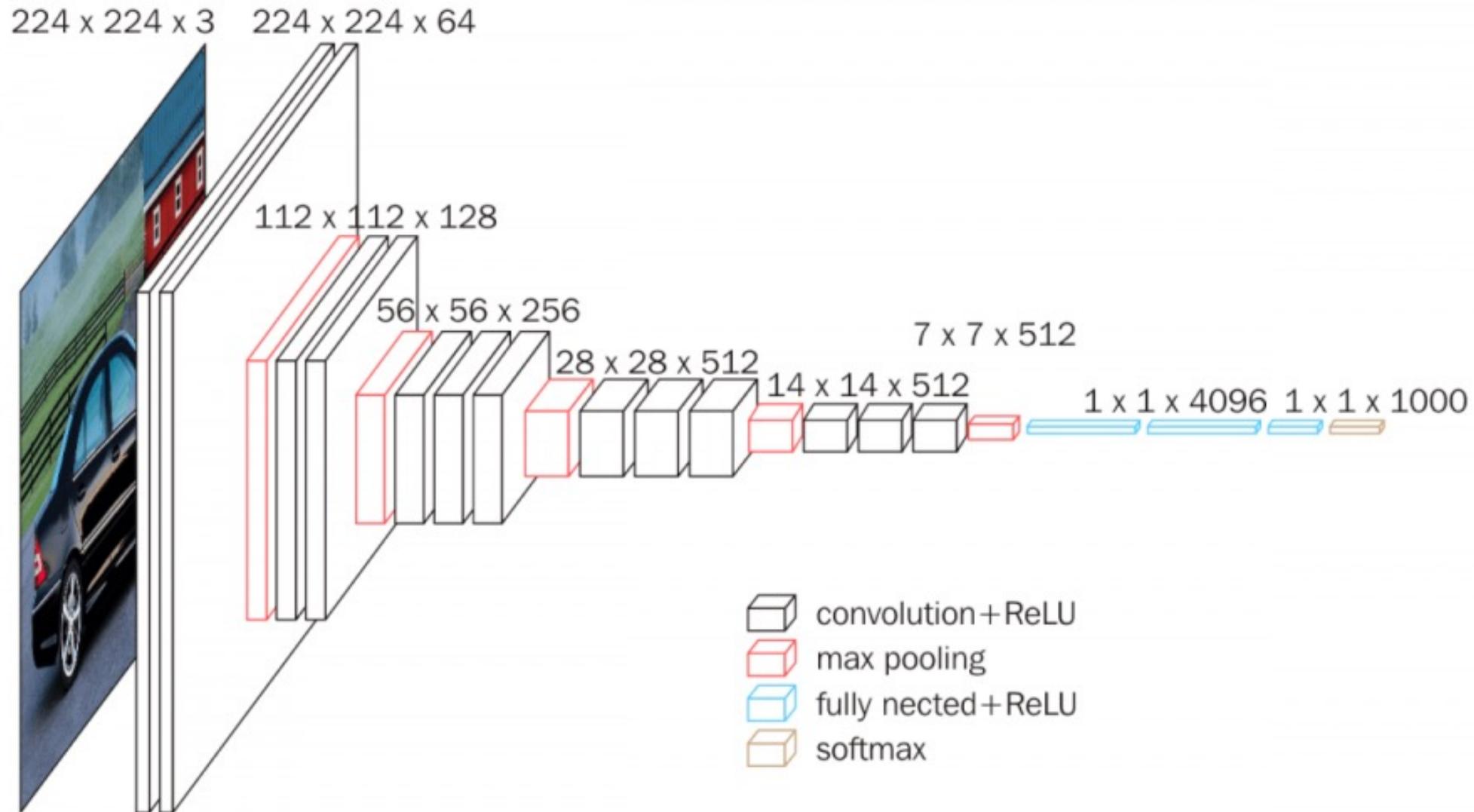
## Sort by average score

Rank	Model	average	V1	V2	V4	IT	behavior	engineering	Deng2009-top1
1	efficientnet-b0 <i>Tan et al., 2019</i>	.442	.215	.317	.556	.547	.573		
2	efficientnet-b6 <i>Tan et al., 2019</i>	.435	.263	.295	.563	.541	.513		
3	efficientnet-b2 <i>Tan et al., 2019</i>	.434	.213	.317	.569	.547	.526		
4	efficientnet-b4 <i>Tan et al., 2019</i>	.434	.228	.286	.575	.543	.535		
5	CORnet-S <i>Kubilius et al., 2018</i>	.417	.294	.242	.581	.423	.545	.747	.747
6	vgg-19 <i>Simonyan et al., 2014</i>	.408	.347	.341	.610	.248	.494	.711	.711
7	resnet-50-robust <i>Santurkar et al., 2019</i>	.408	.378	.365	.537	.243	.515		
8	resnet-101_v1 <i>He et al., 2015</i>	.407	.266	.341	.590	.274	.561	.764	.764
9	vgg-16 <i>Simonyan et al., 2014</i>	.406	.355	.336	.620	.259	.461	.715	.715
10	resnet-152_v1 <i>He et al., 2015</i>	.405	.282	.338	.598	.277	.533	.768	.768

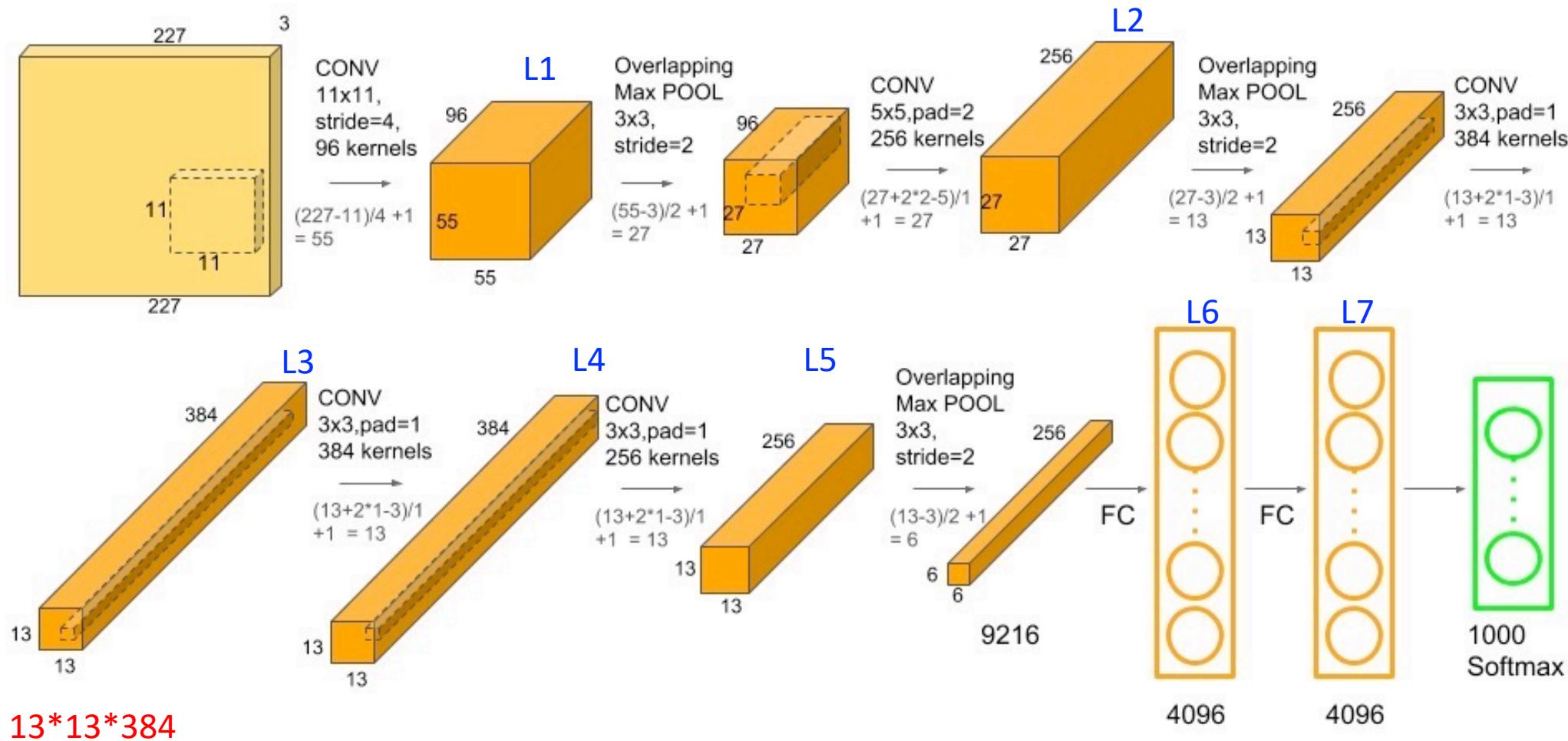
## Sort by V4 score

Model	average	V1	V2	V4	IT	behavior	engineering	Deng2009-top1	v1
vgg-16 <i>Simonyan et al., 2014</i>	.406	.355	.336	.620	.259	.461	.715	.715	
vgg-19 <i>Simonyan et al., 2014</i>	.408	.347	.341	.610	.248	.494	.711	.711	
xception <i>Chollet et al., 2016</i>	.384	.245	.306	.610	.249	.508	.790	.790	
densenet-169 <i>Huang et al., 2016</i>	.404	.281	.322	.601	.274	.543	.759	.759	
resnet-50-pytorch <i>He et al., 2015</i>	.399	.289	.317	.600	.259	.528	.752	.752	
resnet-101_v2 <i>He et al., 2015</i>	.404	.274	.332	.599	.263	.555	.774	.774	
resnet50-SIN_IN <i>Geirhos et al., 2019</i>	.404	.282	.324	.599	.276	.541	.746	.746	
densenet-201 <i>Huang et al., 2016</i>	.402	.277	.325	.599	.273	.537	.772	.772	
resnet-152_v1 <i>He et al., 2015</i>	.405	.282	.338	.598	.277	.533	.768	.768	
resnet50-SIN_IN_IN <i>Geirhos et al., 2019</i>	.397	.275	.321	.596	.273	.523	.767	.767	18

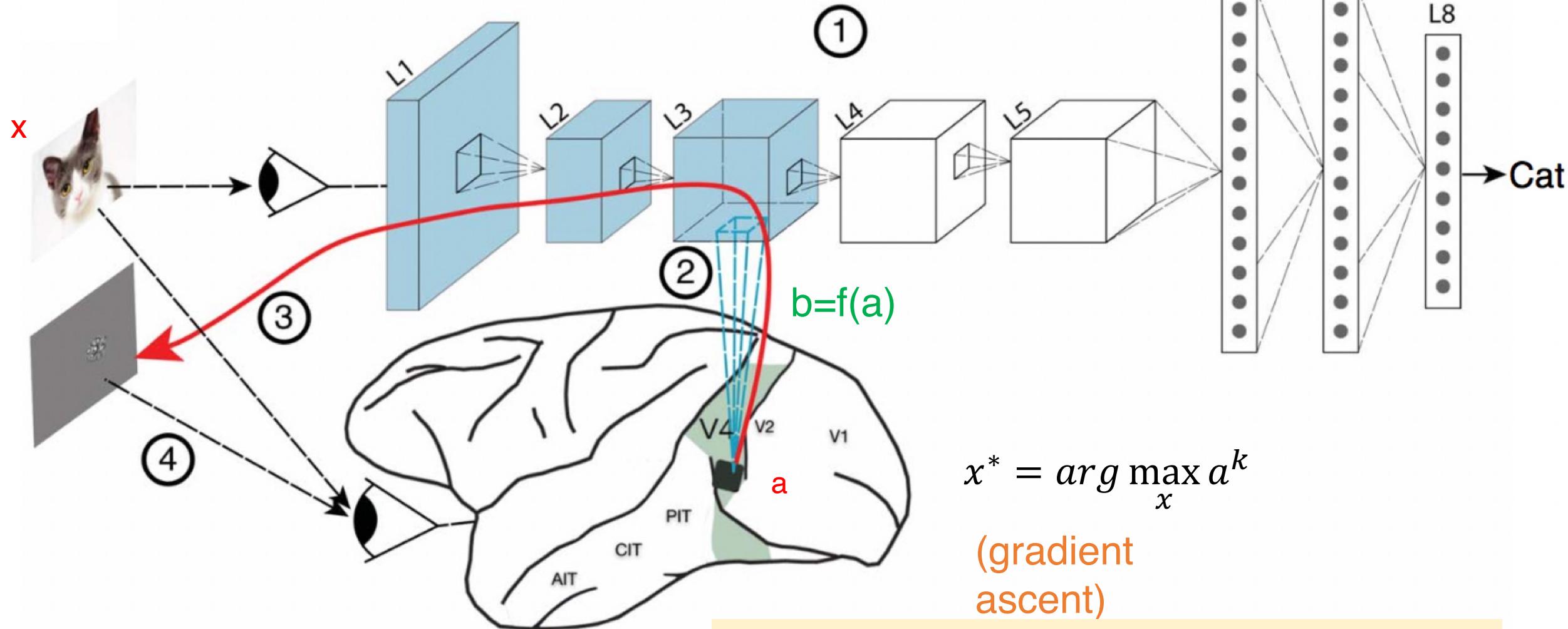
# Dimension of the neural population in VGG-16



# Dimension of the neural population in AlexNet



# A mapping function from L3 to V4



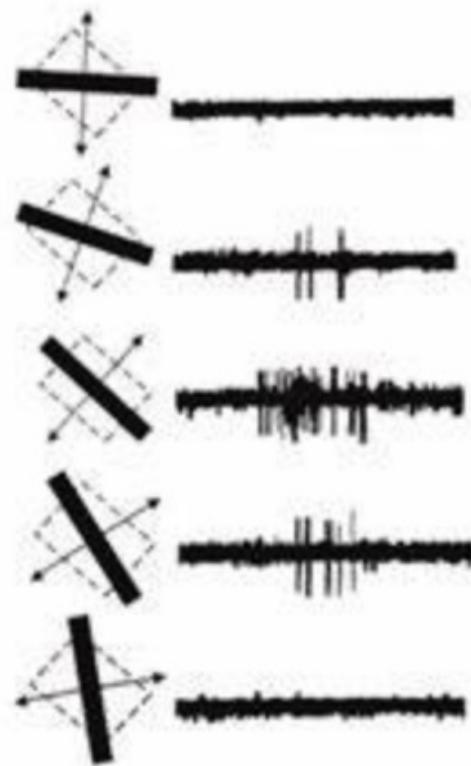
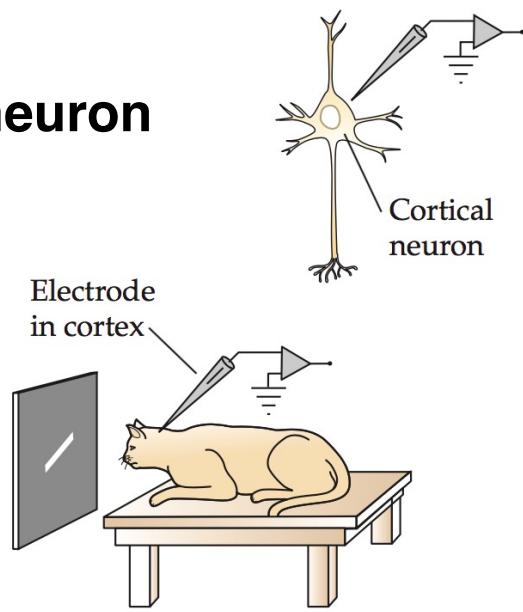
$$x^* = \arg \max_x a^k$$

(gradient ascent)

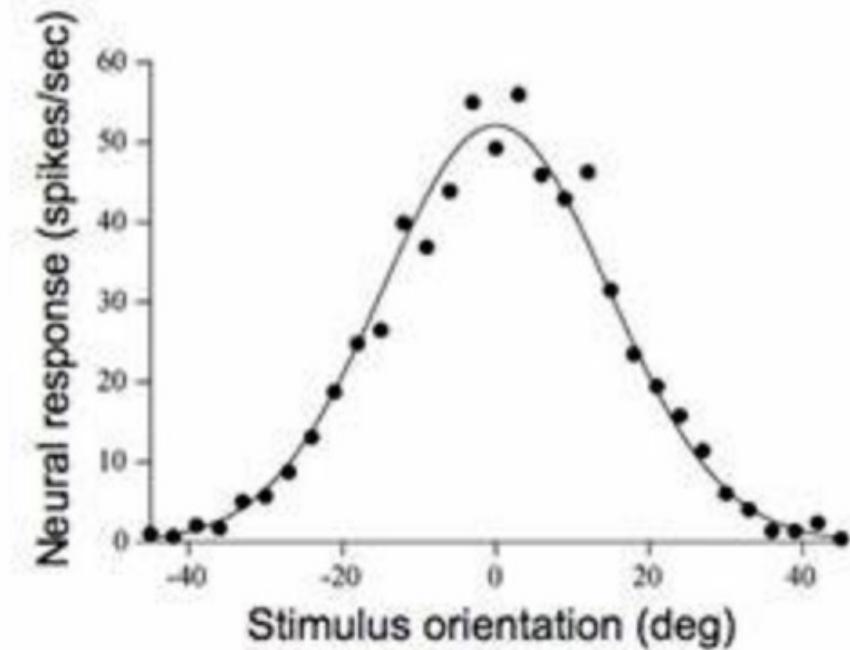
This framework allows to generate images by gradient ascent in ANN to **maximize** biological neural population activity.

# Why we want to find the image to maximize neuronal activity?

V1 neuron



Tuning curve



Hubel, D. H. 1982. *Nature* 299: 515–524.

Hubel, D. H., and Wiesel, T. N. 1959.  
*J. Physiol.* 148: 574–591.

Hubel, D. H., and Wiesel, T. N. 1962.  
*J. Physiol.* 160: 106–154.

Hubel, D. H., and Wiesel, T. N. 1968.  
*J. Physiol.* 195: 215–243.

David H. Hubel & Torsten N. Wiesel

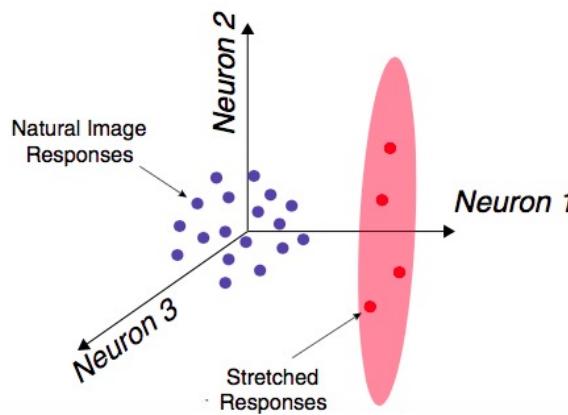
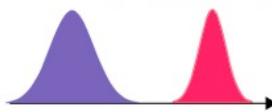
**Nobel Prize** for Physiology or Medicine in 1981

**How about V4 and IT?**

$$x^* = \arg \max_x a^k$$

### Maximal Neural Drive (Stretch)

*Neuron 1 (target) Responses*



*Example Site 1*



*Example Site 2*

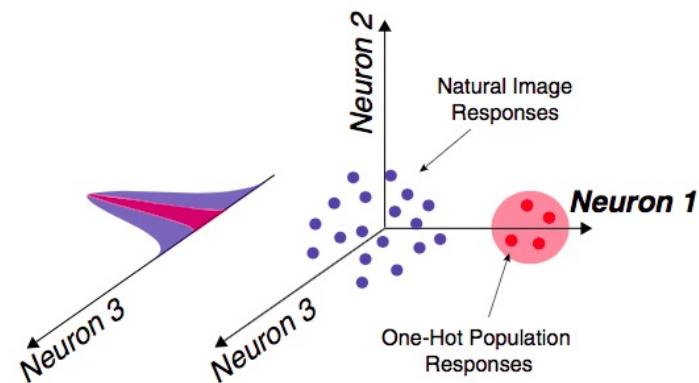
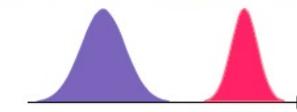


*Example Site 3*



### One-Hot-Population Control

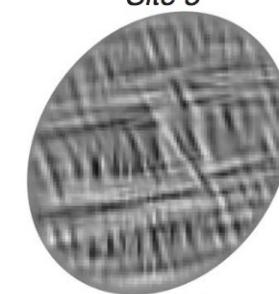
*Neuron 1 (target) Responses*



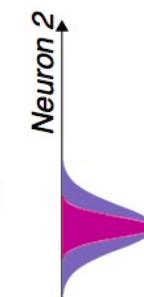
*Example Site 4*



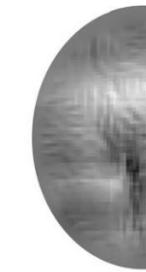
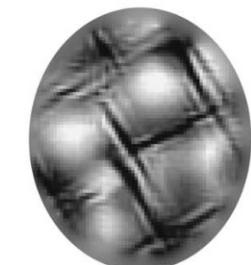
*Example Site 5*

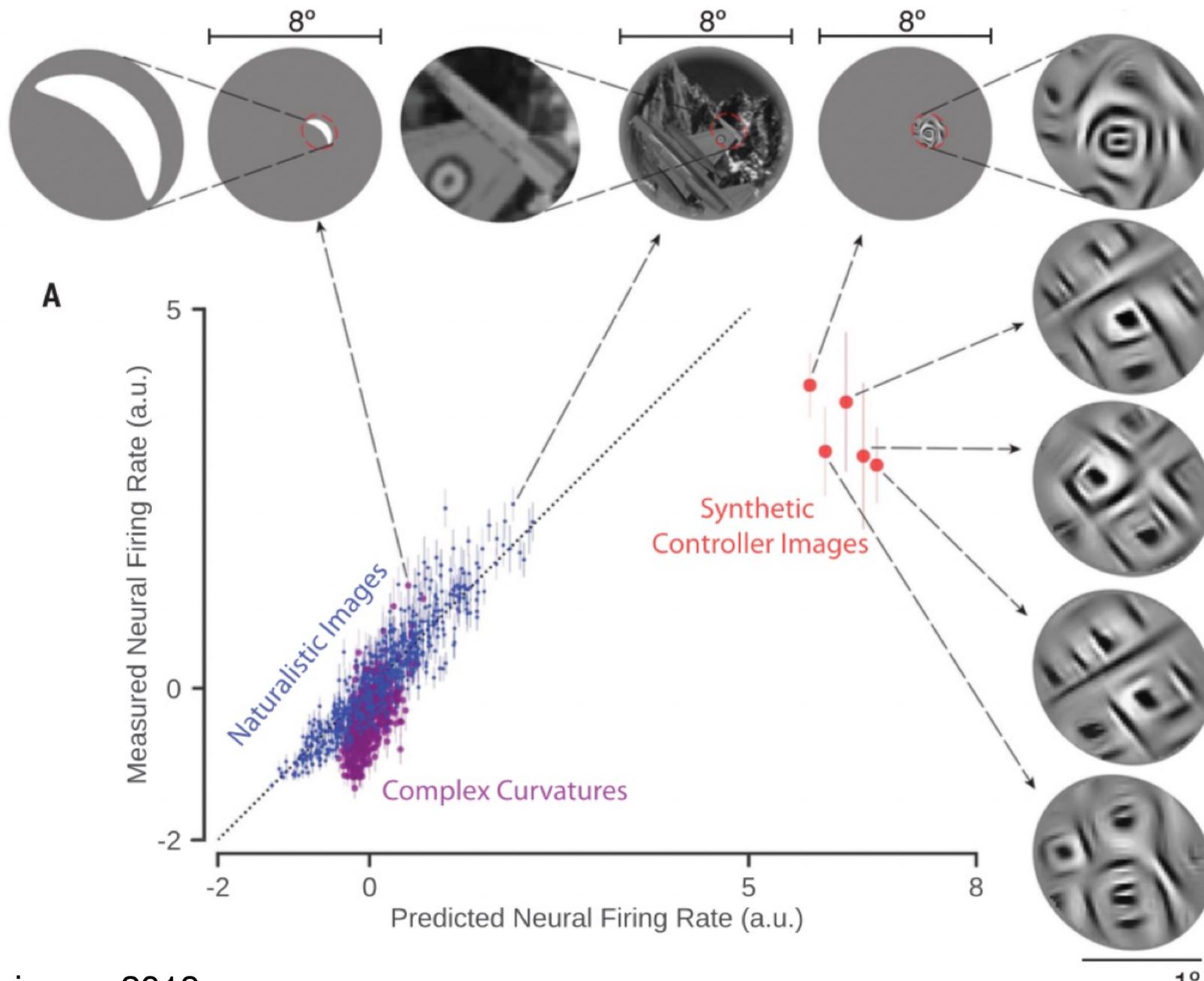


$$x^* = \arg \max_x \frac{e^{a^k}}{\sum_k e^{a^k}}$$



*Example Site 6*





$$x^* = \arg \max_x a^k$$

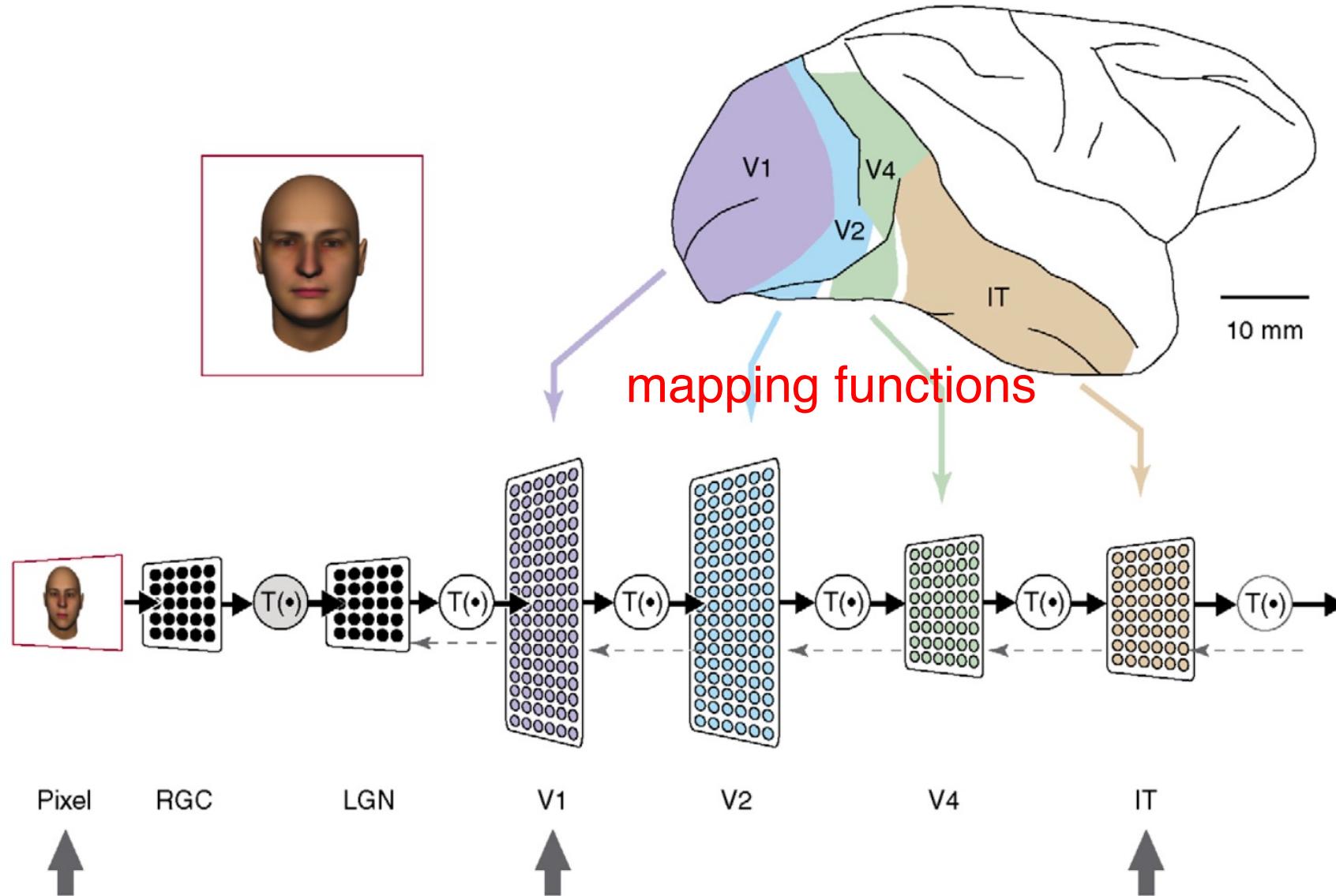
(gradient ascent)

**Can we ascending dimensions from the  
low-dimension recorded neurons in brain  
to high-dimension artificial neurons in  
ANN?**

Please no video recording,  
since this study is ongoing and not published yet.

Thank you.

# Biological neural representation resembles to the artificial neural representation.



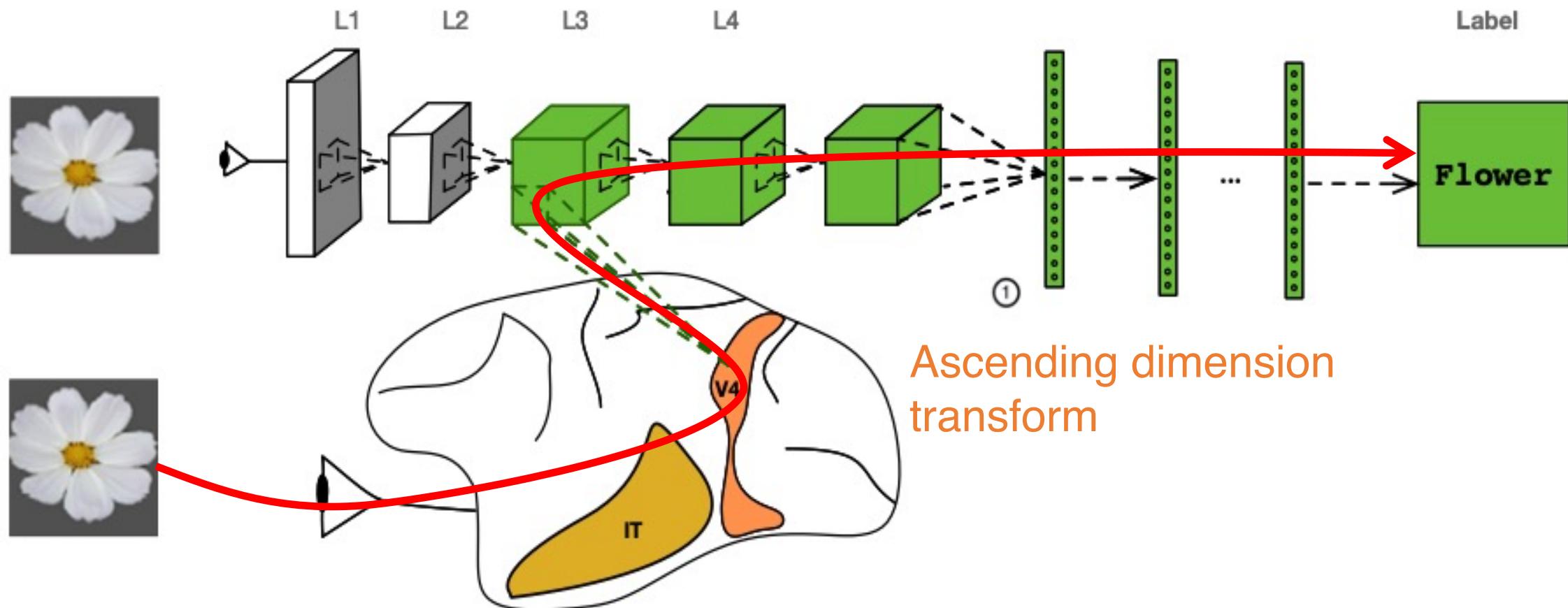
## Technical limits

Low-dimensional  
neuron recordings

easy ↑  
hard ↓

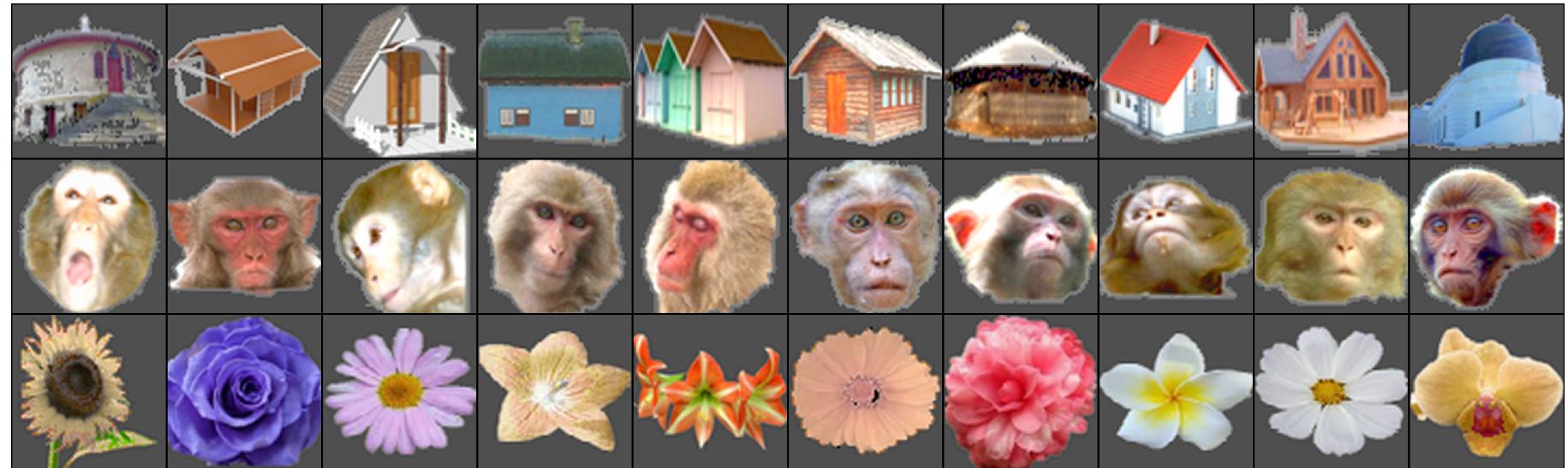
High-dimensional  
CNN feature maps

# A mapping function from V4 to L3



This framework would allow  
1) to recognize object, and even  
2) to reconstruct visual image  
by biological neural population activity via ANN

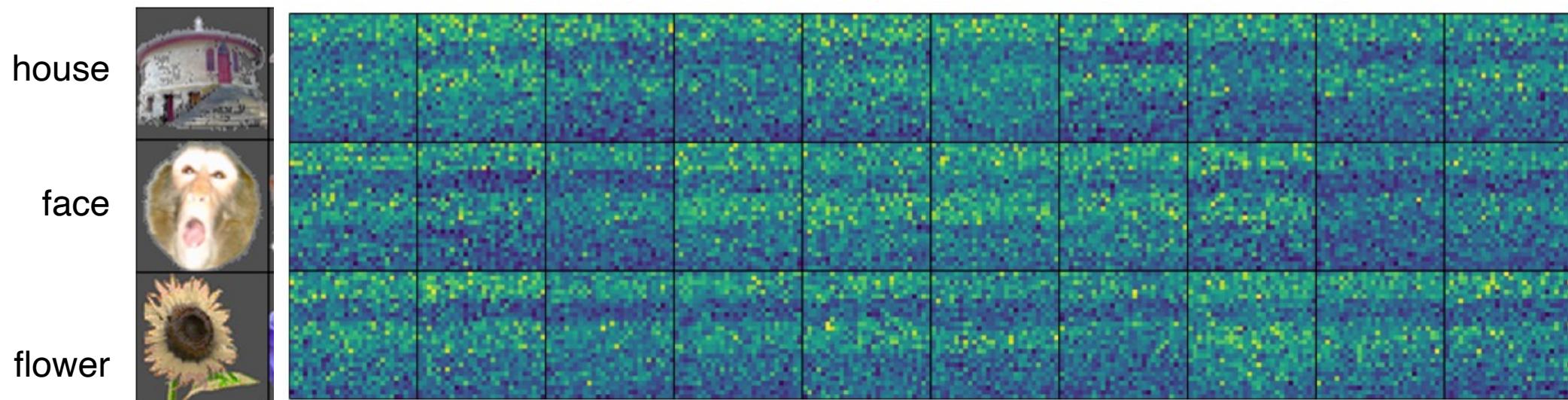
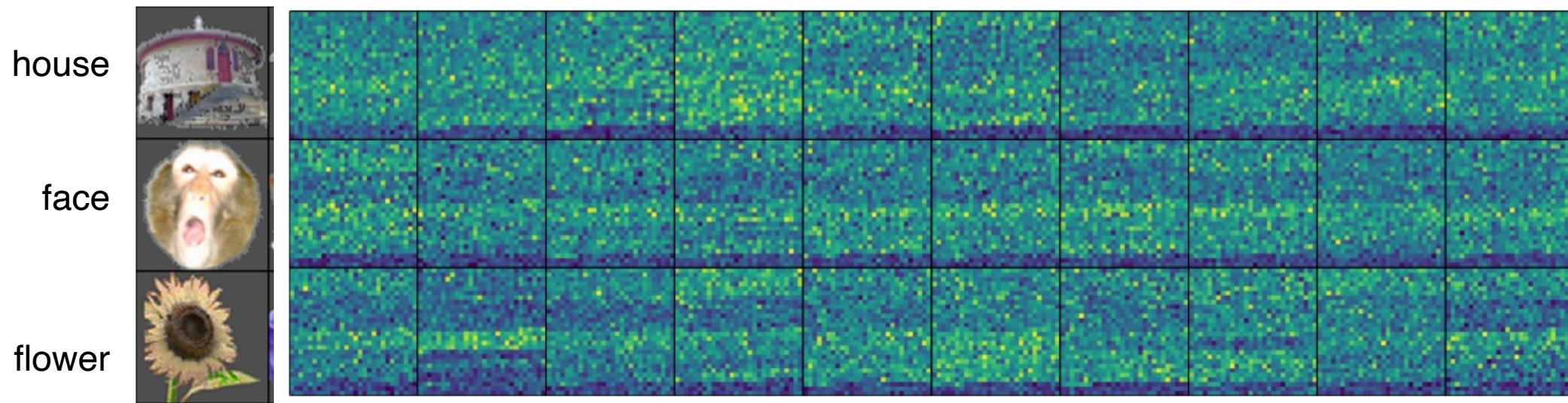
**Image  
presented to  
monkeys**



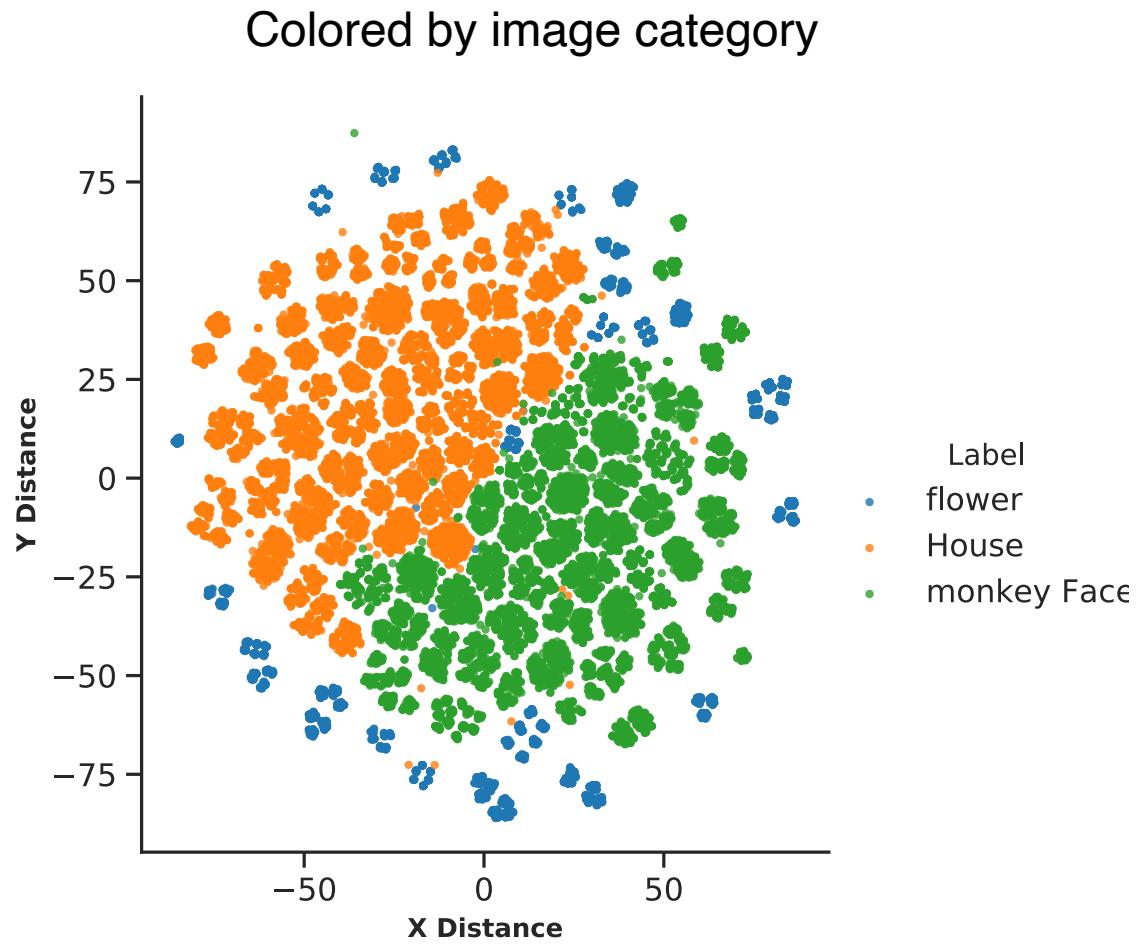
**ImageNet  
to pre-train  
Alexnet**



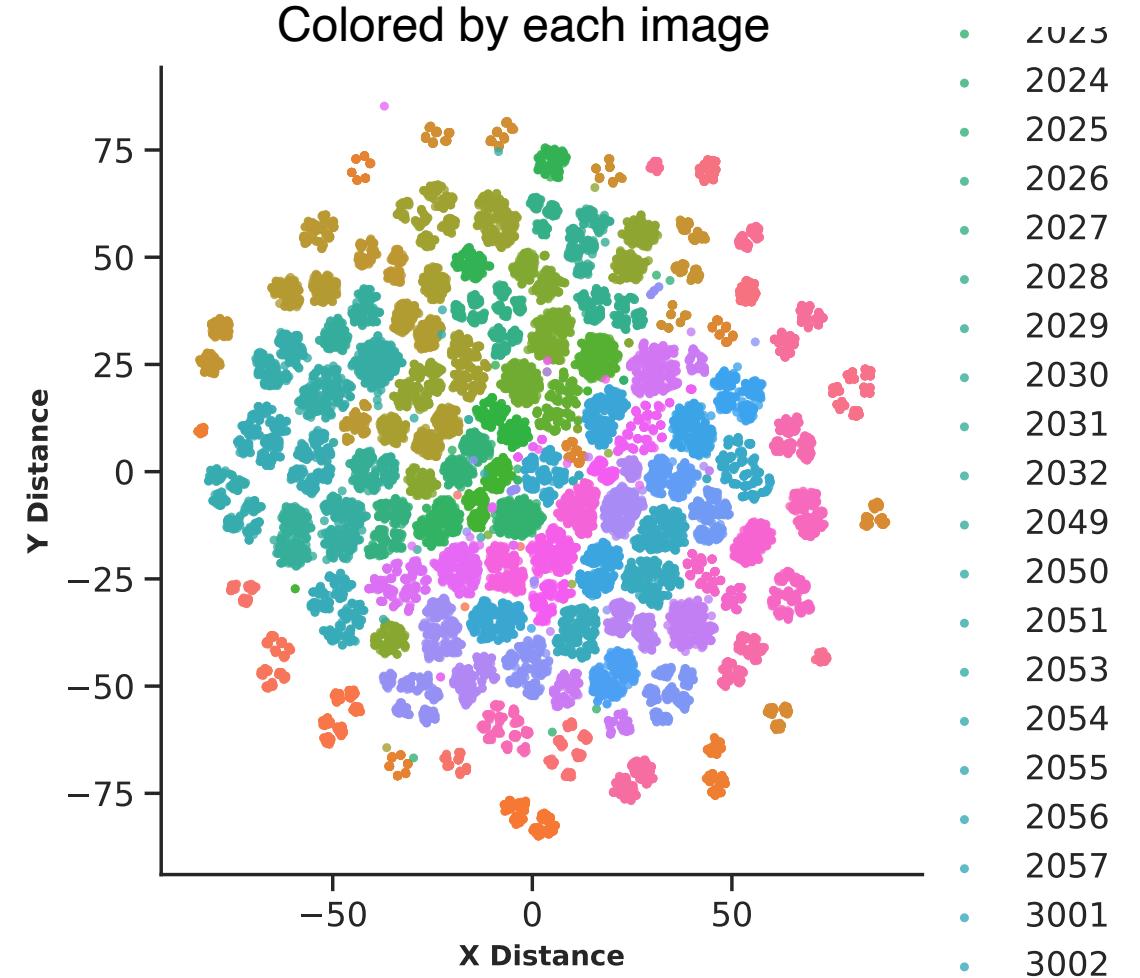
# Neural responses in V4 and IT



# t-SNE for the firing rate of V4 neurons



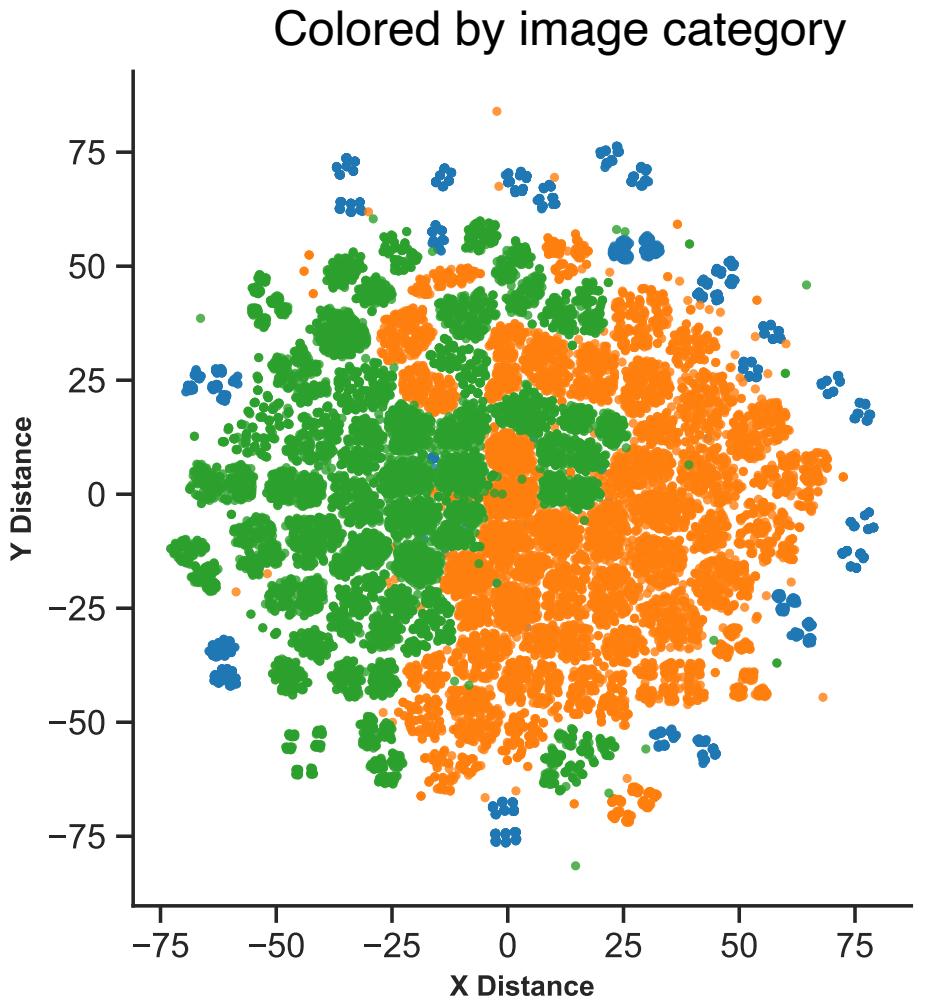
V4 0-224 ms



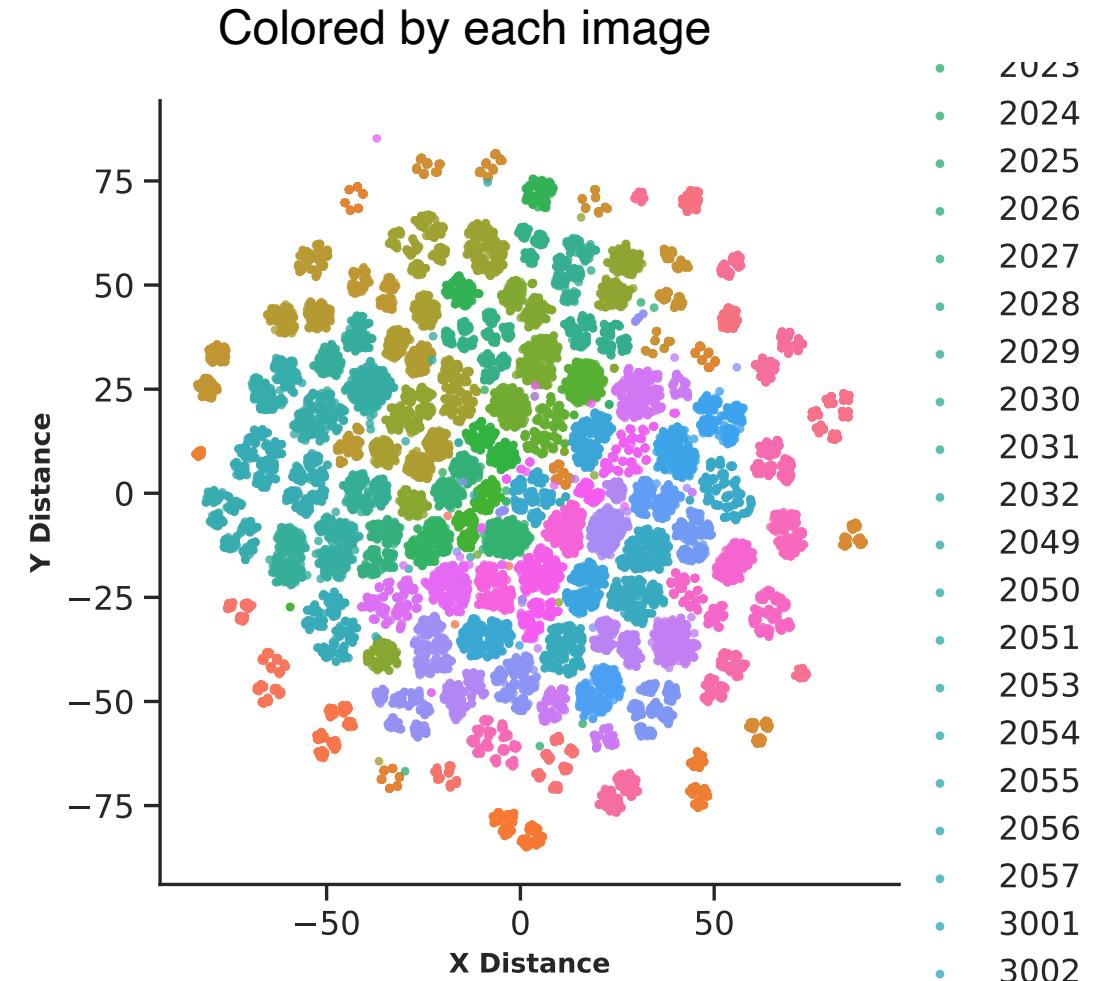
V4 0-224 ms

30

# t-SNE for the firing rate of IT neurons



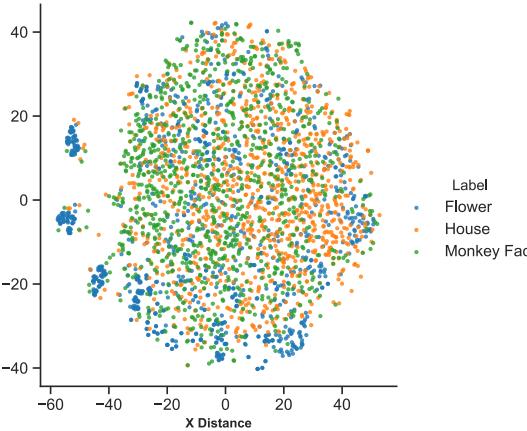
Teo 0- 224ms



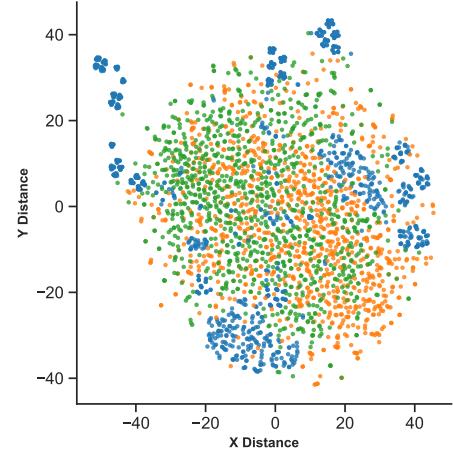
# t-SNE for the firing rate of V4 and IT

10 neurons

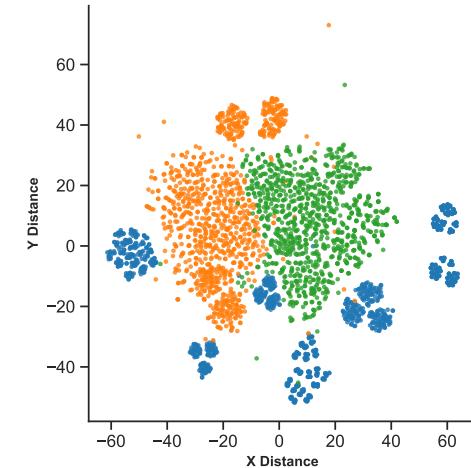
V4



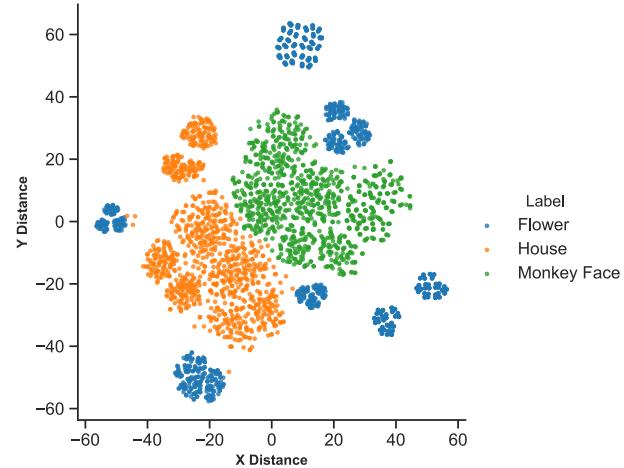
50 neurons



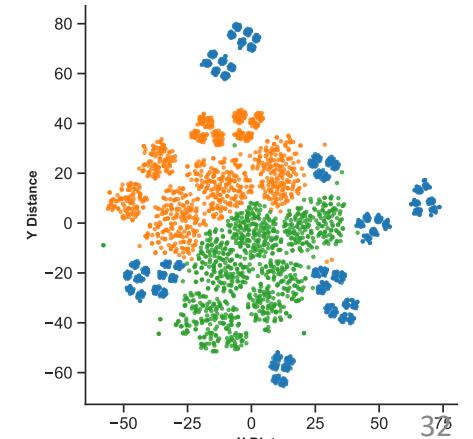
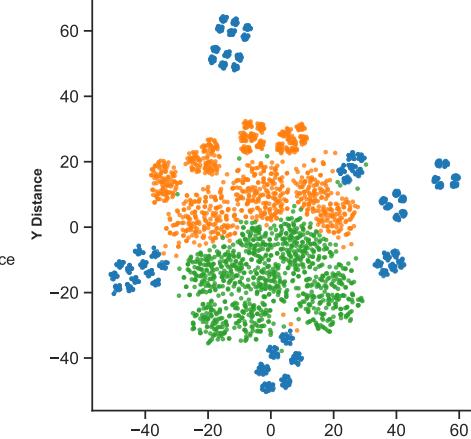
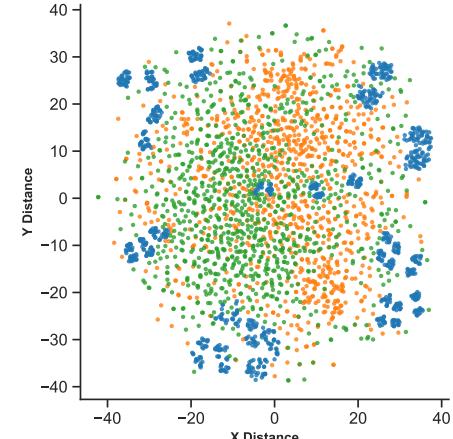
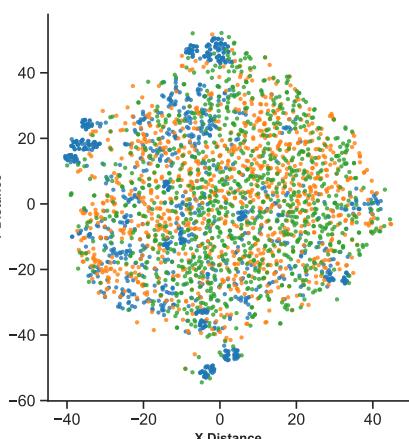
200 neurons



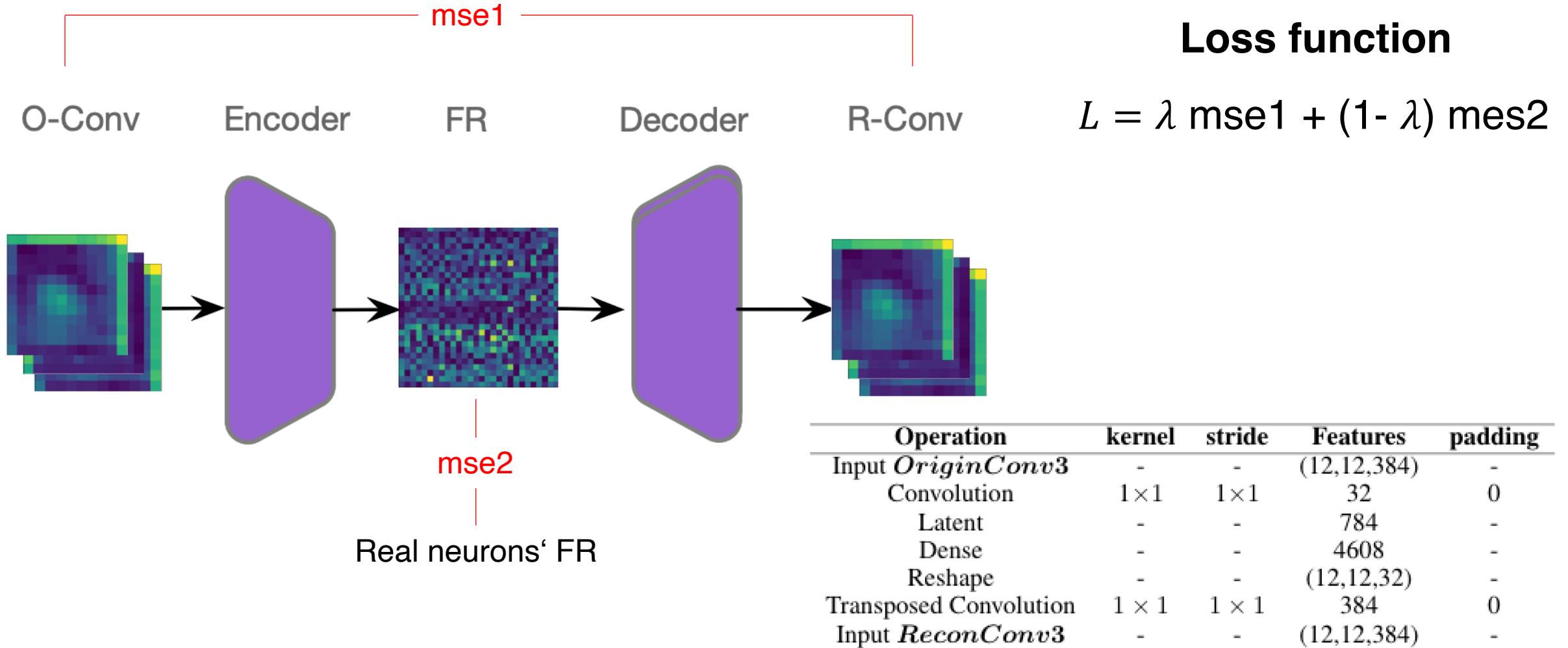
400 neurons



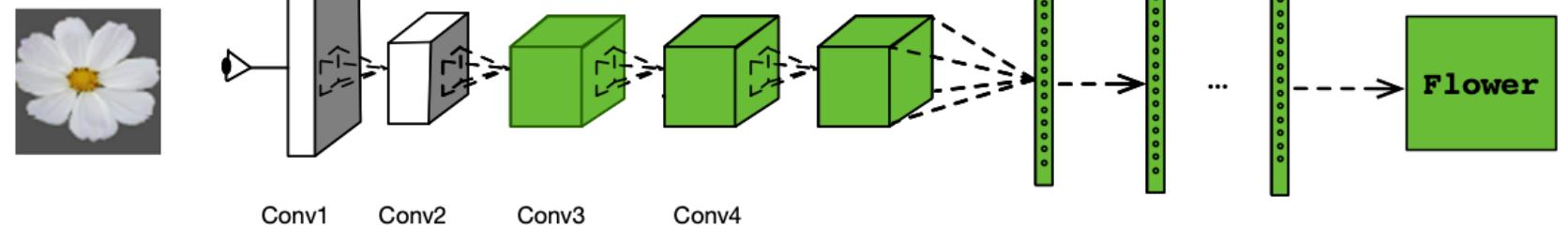
Teo



# Autoencoder allows bidirectional transform between V4 and L3



Object recognition  
by AlexNet



Object recognition  
by V4 neurons

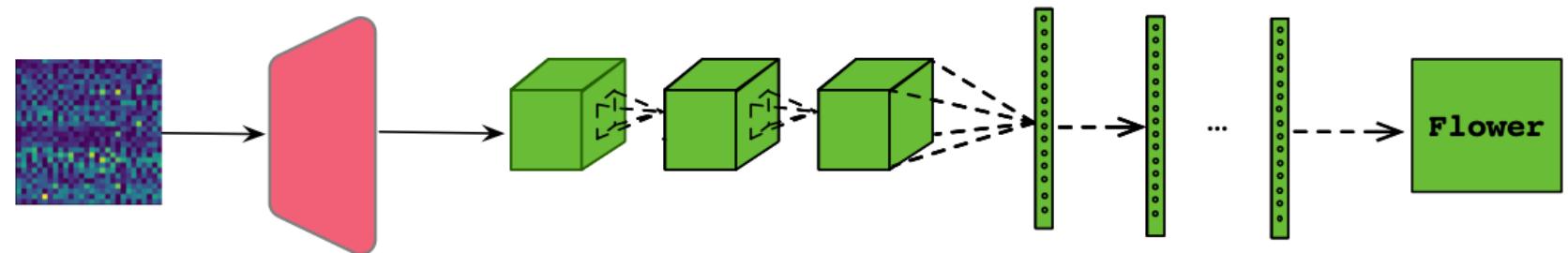


Image generation  
by AE

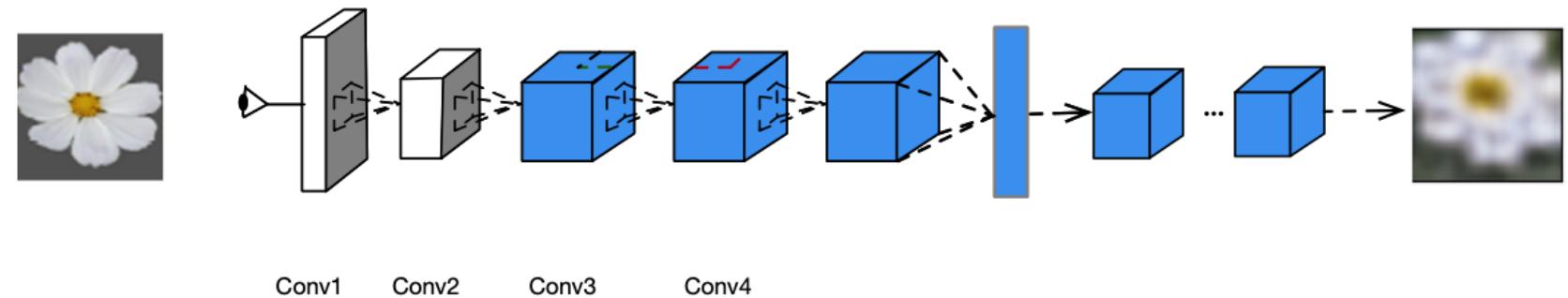
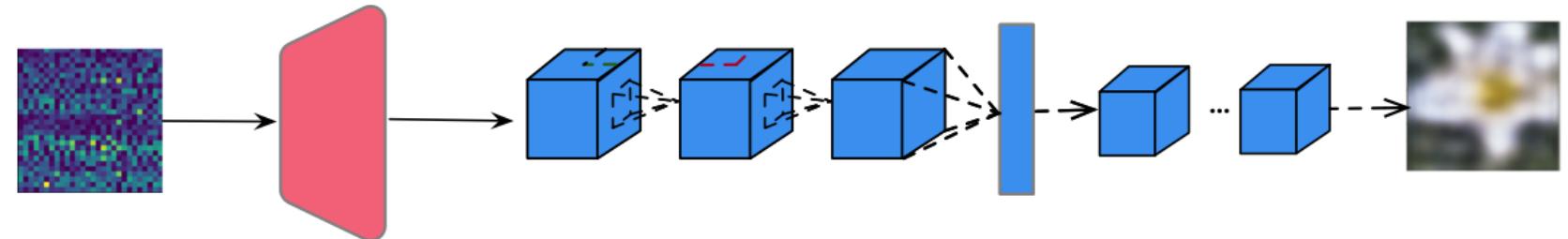
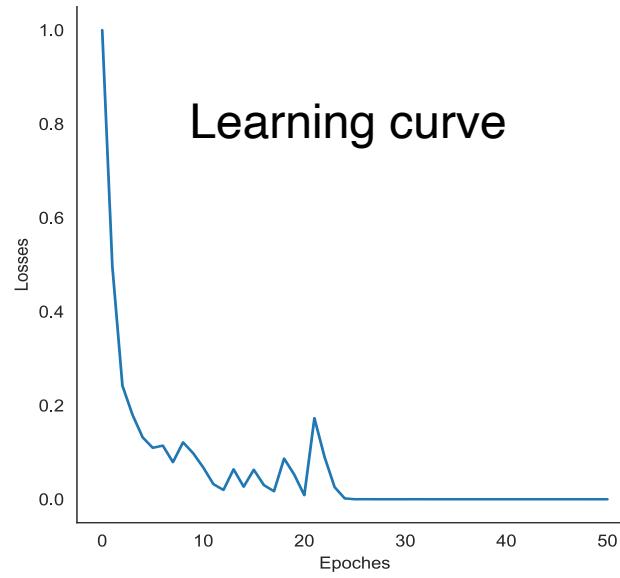


Image generation  
by V4 neurons



# Preliminary results: AlexNet vs Model with V4



Recognition Performance

Model/Metrics	ACCURAY	AUROC	AUPRC
Alexnet	0.80	0.85	0.78
Model with V4	0.70	0.72	0.68

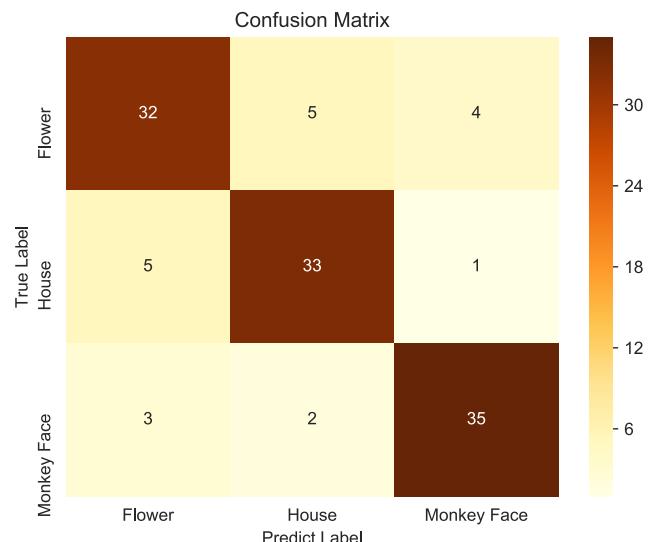


Image reconstruction: examples

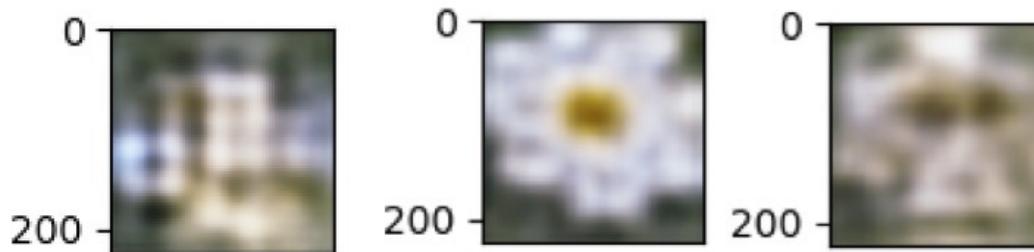
Reconstructed



Ground-truth

# Preliminary results: image reconstruction

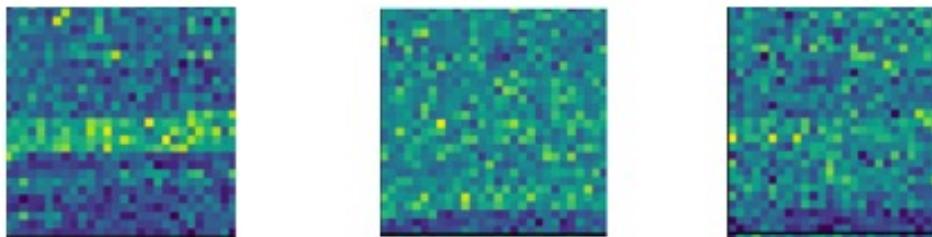
Reconstructed images  
By AE



Ground-truth images



Firing rate in  
biological neurons



Reconstructed images  
By biological neurons



# Take-home message

- **Ascending dimension transformation via auto-encoder**

Auto-encoder allows the transformation between biological and artificial neural representations.

- **Generalization**

The trained Auto-encoder can be generalized to the unseen images.

- **Hybrid AI and brain allows object recognition and image reconstruction**

It might drive BCI applications to next stage.

- **AI can be a powerful tool for neuroscientists**

However, it requires collaborations from multidisciplinary fields, including neuroscience, computer science, cognitive science, and psychology.

# Other directions emerging in combining AI and neuroscience

## ➤ Recurrent circuits in brain

- Jonas Kubilius et al. (2019), Brain-like object recognition with high-performing shallow recurrent ANNs, NeurIPS
- Kohitij Kar et al. (2019), Evidence that recurrent circuits are critical to the ventral stream's execution of core object recognition behavior, Nature Neurosci

## ➤ Sparsity

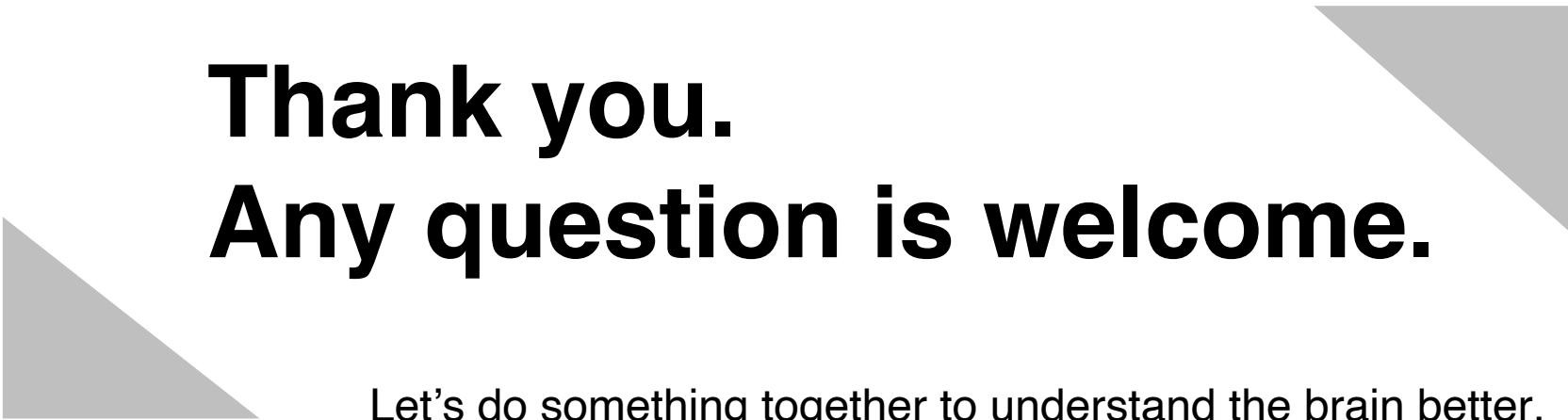
- Bryan Tripp (2017), Similarities and differences between stimulus tuning in the inferotemporal visual cortex and convolutional networks, IJCNN
- Qingtian Zhang et al. (2019) A hierarchical sparse coding model predicts acoustic feature encoding in both auditory midbrain and cortex, PLoS Comp Bio

## ➤ Top-down & bottom-up

- Sarthak Mittal et al. (2020), Learning to combine top-down and bottom-up signals in recurrent neural networks with attention over modules, ICML

## ➤ Adversarial examples for human and AI

- Ian J. Goodfellow et al. (2015), explaining and harnessing adversarial examples, ICLR
- Gamaleldin F. Elsayed et al. (2018), Adversarial Examples that Fool both Computer Vision and Time-Limited Humans, NeurIPS



**Thank you.  
Any question is welcome.**

Let's do something together to understand the brain better.

# Data

Table 1: Original Datasets

Dataset name / class	ImageNet	Monkey seeing	V4 Neuron	IT Neuron
raining set	10625	70	14000	14000
Testing set	900	24	4800	4800

Table 2: ImageNet: 3 Classes of Image.

Dataset / class	Flower	house	monkey	all
Training set	3425	3600	3600	10625
Testing set	300	300	300	900

Table 3: Monkey seeing:3 Classes Image

Dataset / class	Flower	house	monkey	all
Training set	10	30	30	70
Testing set	4	10	10	24

Table 4: IT Neuron:3 Classes of Neural Firing Rate

Dataset / class	Flower	house	monkey	all
Training set	4400	8800	8800	14000
Testing set	400	800	800	4800

Table 5: V4 Neuron:3 Classes of Neural Firing Rate

Dataset / class	Flower	house	monkey	all
Training set	2000	6000	6000	14000
Testing set	800	2000	2000	4800