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Linear multifractional multistable motion: LePage series representation and modulus of continuity

HERMINE BIERMÉ AND CÉLINE LACAUX

Abstract - In this paper, we obtain an upper bound of the modulus of continuity of linear multifractional multistable random motions. Such processes are generalizations of linear multifractional α -stable motions for which the stability index α is also allowed to vary in time. In the case of linear multifractional α -stable motions, we improve the recent result of [2]. The main idea is to consider some conditionnally sub-Gaussian LePage series representations to fit the framework of [5].

Key words and phrases: stable and multistable random fields, modulus of continuity.

Mathematics Subject Classification (2010): 60G17 60G22 60G52

1 Introduction

Self-similar random fields are required to model persistent phenomena in internet traffic, hydrology, geophysics or financial markets, e.g. [1, 22]. The fractional Brownian motion ([15, 9]) provides the most famous self-similar model. Nevertheless, in image modeling, in finance or in biology for example, the phenomena under study are rarely Gaussian. Then, α -stable random processes have been proposed as an alternative to Gaussian modeling, since they allow to model data with heavy tails, such as in internet traffic [16]. The linear fractional stable motion, which has been proposed in [21, 14], is one of the numerous stable extensions of the fractional Brownian motion. Let us recall how this self-similar random motion can be defined through a stochastic integral representation. To this way, let us consider $H_1 \in (0,1)$, $\alpha_1 \in (0,2)$ and M_{α_1} a real-valued symmetric α_1 -stable random measure with Lebesgue control measure (see [17] p.281 for details on such measures). Then, a linear fractional stable motion is defined by

$$X_{\alpha_1, H_1}(t) = \int_{\mathbb{D}} f_+(\alpha_1, H_1, t, \xi) M_{\alpha_1}(d\xi), \quad t \in \mathbb{R}$$
 (1.1)

where f_+ is defined by

$$f_{+}(\alpha_{1}, H_{1}, t, \xi) = (t - \xi)_{+}^{H_{1} - 1/\alpha_{1}} - (-\xi)_{+}^{H_{1} - 1/\alpha_{1}}$$
(1.2)

with for $c \in \mathbb{R}$,

$$(x)_+^c = \begin{cases} x^c & \text{if } x > 0\\ 0 & \text{if } x \le 0. \end{cases}$$

Since the self-similarity property is a global property which can be too restrictive for applications, a multifractional generalization $X_{\alpha_1,h}$ of this process has also been introduced by [18] to model internet traffic, by replacing H_1 by a real function h with values on (0,1). Some necessary and sufficient conditions for the stochastic continuity of the linear multifractional stable motion $X_{\alpha_1,h}$ have been given in [18] and its Hölder sample path regularity has been studied in [19]. The Hölder sample path properties have also been improved in [2] by establishing upper and lower bounds for the modulus of continuity. In the following, we will improve the upper bound, using the results we established in [5]. Let us mention that in the case where $h \equiv H_1$ is constant, that is when $X_{\alpha_1,h}$ is a linear fractional stable motion, sample path regularity properties have previously been studied in [17, 20, 10].

Moreover, the framework of [5] allows to study $X_{\alpha_1,h}$ as well as some multistable generalizations for which the stability index α_1 is also allowed to vary with t. Multistable processes have been defined in [7] using sums over Poisson processes or in [6] using a Klass-Ferguson LePage series.

In this paper we consider a random field S_m defined using a Lepage series representation of the linear fractional α_1 -stable motion and such that

$$S_m(\alpha(t), h(t), t), \quad t \in \mathbb{R}$$

is a linear multifractional multistable motion. This auxiliary random field S_m allows to study the variations due to the functions α , h and to the position t separately. Then, to study sample path regularity of linear multistable motions, our first step is to establish an upper bound for the modulus of continuity of the field S_m considering a conditionnally sub-Gaussian representation and applying [5]. The main property of sub-Gaussian random variables, which have been introduced by [8], is that their tail distributions decrease exponentially as the Gaussian ones. This property is one of the main tool used in [5] to study the sample path regularity property of conditionnally sub-Gaussian random series.

The paper is organized as follows. Section 2 introduces LePage series random fields under study. An upper bound of their modulus of continuity and a rate of convergence are stated in Section 3. Section 4 focuses on linear multifractional multistable motions. Some technical proofs are postponed to the appendix for reader convenience.

2 LePage series models

In order to define LePage series, let us introduce some notation.

Hypothesis 2.1 Let $(g_n)_{n\geq 1}$, $(\xi_n)_{n\geq 1}$ and $(T_n)_{n\geq 1}$ be three independent sequences of random variables satisfying the following conditions.

1. $(g_n)_{n\geq 1}$ is a sequence of independent identically distributed (i.i.d.) real-valued symmetric sub-Gaussian random variables, that is such that there exists $s \in [0, +\infty)$ for which

$$\forall \lambda \in \mathbb{R}, \ \mathbb{E}(e^{\lambda g_n}) \le e^{\frac{s^2 \lambda^2}{2}}.$$
 (2.3)

2. $(\xi_n)_{n\geq 1}$ is a sequence of i.i.d. random variables with common law

$$\mu(d\xi) = m(\xi)d\xi$$

equivalent to the Lebesgue measure (that is such that $m(\xi) > 0$ for almost every ξ).

3. T_n is the nth arrival time of a Poisson process with intensity 1.

Let us now introduce the random field $(S_m(\alpha, H, t))_{(\alpha, H, t) \in (0,2) \times (0,1) \times \mathbb{R}}$ we study in this paper.

Proposition 2.1 (LePage series representation) Assume that Hypothesis 2.1 is fulfilled and let f_+ be defined by (1.2). Then, for any $(\alpha, H, t) \in (0, 2) \times (0, 1) \times \mathbb{R}$, the sequence

$$S_{m,N}(\alpha, H, t) = \sum_{n=1}^{N} T_n^{-1/\alpha} f_+(\alpha, H, t, \xi_n) m(\xi_n)^{-1/\alpha} g_n, \quad N \ge 1$$
 (2.4)

converges almost surely and its limit is denoted by

$$S_m(\alpha, H, t) := \sum_{n=1}^{+\infty} T_n^{-1/\alpha} f_+(\alpha, H, t, \xi_n) m(\xi_n)^{-1/\alpha} g_n.$$
 (2.5)

Proof. Let $(\alpha, H, t) \in (0, 2) \times (0, 1) \times \mathbb{R}$. Then, since Hypothesis 2.1 holds, the variables

$$W_n := f_+(\alpha, H, t, \xi_n) m(\xi_n)^{-1/\alpha} g_n, \quad n \ge 1,$$

are i.i.d., symmetric and such that

$$\mathbb{E}(|W_1|^{\alpha}) = \mathbb{E}(|g_1|^{\alpha}) \int_{\mathbb{R}} |f_+(\alpha, H, t, \xi)|^{\alpha} d\xi < +\infty,$$

since g_1 and ξ_1 are independent (see e.g. [17]). Therefore, by Theorem 5.1 of [13], the sequence

$$\left(\sum_{n=1}^{N} T_n^{-1/\alpha} W_n\right)_{N>1}$$

converges almost surely as $N \to +\infty$, that is $(S_{m,N}(\alpha, H, t))_{N \ge 1}$ converges almost surely.

Let us conclude this section by some remarks.

Remark 2.1 According to Proposition 5.1 of [5], the finite dimensional distributions of S_m do not depend on m as soon as Condition 2 of Hypothesis 2.1 holds. Moreover, when studying the sample path regularity of S_m , Proposition 5.1 of [5] allows us to change m by a more convenient function \tilde{m} if necessary.

Remark 2.2 When $\alpha = \alpha_1 \in (0,2)$ is fixed, $(S_m(\alpha_1, H, t))_{(H,t)\in(0,1)\times\mathbb{R}}$ is an α_1 -stable symmetric random field, which can also be represented as an integral under an α_1 -stable random measure M_{α_1} with Lebesgue control measure. More precisely, for every $\alpha_1 \in (0,2)$,

$$(S_m(\alpha_1, H, t))_{(H,t)\in(0,1)\times\mathbb{R}} \stackrel{fdd}{=} d_{\alpha_1}(Y_{\alpha_1}(H, t))_{(H,t)\in(0,1)\times\mathbb{R}}$$
 (2.6)

where $\stackrel{fdd}{=}$ means equality of finite distributions and

$$Y_{\alpha_1}(H,t) := \int_{\mathbb{R}} f_+(\alpha_1, H, t, \xi) M_{\alpha_1}(d\xi), \quad (H,t) \in (0,1) \times \mathbb{R}, \tag{2.7}$$

for M_{α_1} a real-valued symmetric α_1 -stable random measure with Lebesgue control measure and

$$d_{\alpha_1} := \mathbb{E}(|g_1|^{\alpha_1})^{1/\alpha_1} \left(\int_0^{+\infty} \frac{\sin x}{x^{\alpha_1}} dx \right)^{1/\alpha_1}.$$
 (2.8)

One can check Equation (2.6) following the proof of Proposition 5.1 of [5] or Proposition 4.2 of [4], which is a consequence of Lemma 4.1 of [11].

3 Sample path properties

Several papers [20, 10, 18, 19, 2] have already investigated sample path properties of the linear fractional stable motion X_{α_1,H_1} defined by Equation (1.1) or of its multifractional generalization $X_{\alpha_1,h}$ defined on \mathbb{R} by

$$X_{\alpha_1,h}(t) := Y_{\alpha_1}(h(t),t), \quad t \in \mathbb{R}$$
(3.9)

where $\alpha_1 \in (0,2)$, Y_{α_1} is given by (2.7) and h is a function with values in (0,1). In the following, we improve the upper bound of the global modulus of continuity of $X_{\alpha_1,h}$ stated in [2]. Our first step is to establish an upper bound for the global modulus of continuity of the field S_m defined by (2.5) on a compact set K of $(0,2) \times (0,1) \times \mathbb{R}$. To obtain our upper bound, we use

the results we established in [5] on conditionally sub-Gaussian random series.

Let us first recall (see [17] for example) that the α_1 -stable random process $X_{\alpha_1,H_1} = (Y_{\alpha_1}(H_1,t))_{t\in\mathbb{R}}$ is unbounded almost surely on each compact set with non-empty interior when $H_1 < 1/\alpha_1$. A similar result holds for S_m as stated in the following proposition.

Proposition 3.1 Assume that $K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [a, b] \subset (0, 2) \times (0, 1) \times \mathbb{R}$ with $0 < \alpha_1 \le \alpha_2 < 2$, $0 < H_1 \le H_2 < 1$ and a < b.

- 1. If $H_1 < 1/\alpha_1$, then the random field S_m is almost surely unbounded on K.
- 2. If $H_1 = 1/\alpha_1$, then S_m does not have almost surely continuous sample paths on the compact set K.

Proof. By Equation (2.6)

$$(S_m(\alpha_1, H_1, t))_{t \in \mathbb{R}} \stackrel{fdd}{=} d_{\alpha_1}(X_{\alpha_1, H_1}(t))_{t \in \mathbb{R}}, \tag{3.10}$$

where d_{α_1} is defined by Equation (2.8) and X_{α_1,H_1} is the linear fractional stable motion given by (1.1).

Let us first assume that $H_1 < 1/\alpha_1$. Then, since a < b, by Corollary 10.2.4 of [17], $(S_m(\alpha_1, H_1, t))_{t \in \mathbb{R}}$ is unbounded almost surely on the compact set [a, b]. It follows that

$$\sup_{(\alpha,H,t)\in K} |S_m(\alpha,H,t)| = +\infty \text{ a.s.}$$

since $\sup_{(\alpha,H,t)\in K} |S_m(\alpha,H,t)| \ge \sup_{t\in[a,b]} |S_m(\alpha_1,H_1,t)|$.

Let us now assume that $H_1 = 1/\alpha_1$ (which implies that $\alpha_1 > 1$). Then,

$$X_{\alpha_1,H_1} = (M_{\alpha_1}([0,t))\mathbf{1}_{t>0} + M_{\alpha_1}((t,0])\mathbf{1}_{t<0})_{t\in\mathbb{R}}$$

is a Lévy α_1 -stable motion and by Equation (3.10), so is the process $(S_m(\alpha_1, H_1, t))_{t \in \mathbb{R}}$. Since $\alpha_1 < 2$, the stable motion $(S_m(\alpha_1, 1/\alpha_1, t))_{t \in \mathbb{R}}$ is not a Brownian motion and then does not have almost surely continuous sample paths (see Exercice 2.7 p.64 of [12] for instance). This concludes the proof.

Therefore, it remains to study the sample paths on a compact set

$$K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [-A, A] \subset (0, 2) \times (0, 1) \times \mathbb{R}$$

such that $H_1 > 1/\alpha_1$, which implies that $\alpha_1 \in (1,2)$ and $H_1 > 1/2$.

The main result of this paper is the following theorem, which states an upper bound for the modulus of continuity of S_m on K, and for some m a rate of uniform convergence on K for the series $S_{m,N}$ defined by (2.4).

Theorem 3.1 Assume that Hypothesis 2.1 is fulfilled. Let $S_{m,N}$ and S_m be defined by (2.4) and (2.5) and let us consider the compact set

$$K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [-A, A] \subset (1, 2) \times (1/2, 1) \times \mathbb{R}$$

with A > 0 and $H_1 > 1/\alpha_1$.

1. As $N \to +\infty$, the series $(S_{m,N})_{N\geq 1}$ converges uniformly on K to S_m and almost surely

$$\sup_{\substack{x,x' \in K \\ x \neq x'}} \frac{|S_m(x) - S_m(x')|}{\tau(x - x')\sqrt{|\log(\tau(x - x'))| + 1}} < +\infty$$

with
$$\tau(z) = |\alpha| + |H| + |t|^{H_1 - 1/\alpha_1}$$
 for $z = (\alpha, H, t) \in \mathbb{R}^3$.

2. For $\eta > 0$, let us consider $m = m_{\eta}$ defined by

$$m_{\eta}(\xi) = c_{\eta} |\xi|^{-1} \left(1 + |\log(|\xi|)|\right)^{-1-\eta},$$
 (3.11)

with $c_{\eta} > 0$ such that $\int_{\mathbb{R}} m_{\eta}(\xi) d\xi = 1$. Then, almost surely

$$\sup_{N\geq 1} N^{\varepsilon} \sup_{x\in K} \left| S_{m_{\eta},N}(x) - S_{m_{\eta}}(x) \right| < +\infty$$

for any $\varepsilon \in (0, 1/\alpha_2 - 1/2)$.

Proof. For all $x = (\alpha, H, t) \in (0, 2) \times (0, 1) \times \mathbb{R}$ and all integer $n \geq 1$, we consider

$$V_{m,n}(x) := f_{+}(\alpha, H, t, \xi_n) m(\xi_n)^{-1/\alpha}, \tag{3.12}$$

so that

$$S_{m,N}(x) = \sum_{n=1}^{N} T_n^{-1/\alpha} V_{m,n}(x) g_n$$
 and $S_m(x) = \sum_{n=1}^{+\infty} T_n^{-1/\alpha} V_{m,n}(x) g_n$.

Let us also remark that for all $x = (\alpha, H, t) \in (0, 2) \times (0, 1) \times \mathbb{R}$,

$$\mathbb{E}(|V_{m,n}(x)|^{\alpha}) = \int_{\mathbb{R}} |f_{+}(\alpha, H, t, \xi)|^{\alpha} d\xi < +\infty.$$

Note that if in Equation (2.3) the sub-Gaussian parameter s of g_n is less than 1, Equation (2.3) also holds for s=1. Moreover, if s is greater than 1 we may write $V_{m,n}(x)g_n=(sV_{m,n}(x))g_n/s$ so that g_n/s is sub-Gaussian with parameter 1. Hence without loss of generality we may and will assume that s=1. It follows that $(g_n)_{n\geq 1}$, $(T_n)_{n\geq 1}$ and $(V_{m,n})_{n\geq 1}$ are three independent sequences that satisfy Assumption 4 in [5] on $(0,2)\times(0,1)\times\mathbb{R}$. Then, by Theorem 4.2 of [5], the result follows once we prove $\mathbb{E}\left(|V_{m,1}(x_0)|^2\right)<+\infty$

for some $x_0 \in K$ and Equation (15) of [5] for p = 1, namely (in our setting) if there exists r > 0 such that

$$\mathbb{E}\left(\left[\sup_{\substack{x,x'\in K\\0<||x-x'||\leq r}} \frac{|V_{m,1}(x)-V_{m,1}(x')|}{\tau(x-x')}\right]^{2}\right)<+\infty.$$
(3.13)

The following proposition, whose proof is postponed to the appendix, allows to find some m satisfying such conditions.

Proposition 3.2 There exists a finite deterministic constant $c_{3,1}(K) > 0$ such that a.s. for all $x, x' \in K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [-A, A]$,

$$|V_{m,1}(x) - V_{m,1}(x')| \le c_{3,1}(K)\tau(x - x')h_{m,K}(\xi_1),$$

with, for almost every $\xi \in \mathbb{R}$,

$$h_{m,K}(\xi) = \max \left(m(\xi)^{-1/\alpha_1}, m(\xi)^{-1/\alpha_2} \right) (1 + |\log m(\xi)|)$$

$$\times \left(\mathbf{1}_{|\xi| \le e} + |\xi|^{-1 + H_2 - 1/\alpha_2} \log |\xi| \mathbf{1}_{|\xi| > e} \right).$$
(3.14)

Let us first consider $m = m_{\eta}$ given by (3.11) for some $\eta > 0$. In view of Proposition 3.2, since $V_{m_{\eta},1}(\alpha, H, 0) = 0$ for all $(\alpha, H, 0) \in K$, up to use a finite covering of K, it is enough to prove that there exists r > 0 with

$$\mathbb{E}\left(h_{m_{\eta},K}(\xi_1)^2\right) < +\infty,\tag{3.15}$$

for $K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [-A, A]$ with $\alpha_2 - \alpha_1 \le r$. One has

$$\mathbb{E}(h_{m_{\eta},K}(\xi_{1})^{2}) = \int_{\mathbb{R}} h_{m_{\eta},K}(\xi)^{2} m_{\eta}(\xi) d\xi$$
$$= \int_{|\xi| \le e} + \int_{|\xi| > e} := I_{1} + I_{2}.$$

On the one hand,

$$I_{1} = \int_{|\xi| \leq e} m_{\eta}(\xi) \max(m_{\eta}(\xi)^{-2/\alpha_{1}}, m_{\eta}(\xi)^{-2/\alpha_{2}}) (1 + |\log(m_{\eta}(\xi))|)^{2} d\xi$$

$$\leq c_{3,2}(\eta, K) \int_{|\xi| \leq e} |\xi|^{-1 + 2/\alpha_{2}} (1 + |\log(|\xi|)|)^{(1+\eta)(2/\alpha_{1}-1)} (1 + |\log(m_{\eta}(\xi))|)^{2} d\xi,$$

with $c_{3,2}(\eta, K)$ a positive finite constant. It follows that $I_1 < +\infty$ since $\alpha_2 > 0$. On the other hand,

$$I_{2} = \int_{|\xi|>e} m_{\eta}(\xi) \max(m_{\eta}(\xi)^{-2/\alpha_{1}}, m_{\eta}(\xi)^{-2/\alpha_{2}}) (1 + |\log(m_{\eta}(\xi))|)^{2} |\xi|^{2(H_{2}-1/\alpha_{2})-2} \log(|\xi|)^{2} d\xi$$

$$\leq c_{3,3}(\eta, K) \int_{|\xi|>e} |\xi|^{2(H_{2}+1/\alpha_{1}-1/\alpha_{2})-3} \log(|\xi|)^{(1+\eta)(2/\alpha_{1}-1)+2} (1 + |\log(m_{\eta}(\xi))|)^{2} d\xi,$$

with $c_{3,3}(\eta, K)$ a positive finite constant. Since $\alpha_1 > 1$, note that $\alpha_2 - \alpha_1 < 1 - H_2$ implies that $H_2 + 1/\alpha_1 - 1/\alpha_2 < H_2 + \alpha_2 - \alpha_1 < 1$ and thus $I_2 < +\infty$. Therefore choosing $r \in (0, 1 - H_2)$, Equation (3.15) and then (3.13) hold for $m = m_{\eta}$. By Theorem 4.2 of [5], $(S_{m_{\eta},N})_{N \geq 1}$ and $S_{m_{\eta}}$ satisfy 1. and 2. of the theorem.

Since for almost every $\xi \in \mathbb{R}$ the map $(\alpha, H, t) \mapsto f_+(\alpha, H, t, \xi)$ is continuous on K, by Assertion 2. of Proposition 5.1 of [5], S_m satisfies Assertion 1. whatever m is.

Remark 3.1 Assertion 2. in Theorem 3.1 holds for any m satisfying Equation (3.15) instead of m_n .

4 Linear multifractional multistable and stable motions

From now on let us consider $\alpha : \mathbb{R} \mapsto (0,2)$ and $h : \mathbb{R} \mapsto (0,1)$ two continuous functions. Under Hypothesis 2.1, by Proposition 2.1, we may consider the linear multifractional multistable motion defined on \mathbb{R} by

$$\tilde{S}_m(t) := S_m(\alpha(t), h(t), t), \tag{4.16}$$

with S_m given by (2.5).

4.1 Regularity and rate of convergence

We may also define $\tilde{S}_{m,N}(t) := S_{m,N}(\alpha(t),h(t),t)$, for all $N \geq 1$. The following theorem is a direct consequence of Theorem 3.1.

Theorem 4.1 Let us consider $\alpha : \mathbb{R} \mapsto (0,2)$ and $h : \mathbb{R} \mapsto (0,1)$ two continuous functions and two real numbers a < b. Then let us set

$$\alpha_1 = \min_{t \in [a,b]} \alpha(t), \ \alpha_2 = \max_{t \in [a,b]} \alpha(t) \ \ and \ \ H_1 = \min_{t \in [a,b]} h(t).$$

Assume that $H_1 > 1/\alpha_1$ and that α and h are $(H_1 - 1/\alpha_1)$ -Hölder continuous functions on [a, b].

1. Then, as $N \to +\infty$, the series $(\tilde{S}_{m,N})_{N\geq 1}$ converges uniformly on [a,b] to \tilde{S}_m and almost surely

$$\sup_{\substack{t,t'\in[a,b]\\t\neq t'}} \frac{\left|\tilde{S}_m(t)-\tilde{S}_m(t')\right|}{|t-t'|^{H_1-1/\alpha_1}\sqrt{|\log|t-t'||+1}} < +\infty.$$

2. Moreover if $m = m_{\eta}$ is defined by (3.11) with $\eta > 0$, then, almost surely

$$\sup_{N\geq 1} N^{\varepsilon} \sup_{t\in[a,b]} \left| \tilde{S}_{m_{\eta},N}(t) - \tilde{S}_{m_{\eta}}(t') \right| < +\infty$$

for any $\varepsilon \in (0, 1/\alpha_2 - 1/2)$.

Note that one can use $\tilde{S}_{m_{\eta},N}$ to simulate $\tilde{S}_{m_{\eta}}$. The error of approximation is then given by N^{ε} .

4.2 Stochastic integral and series representation

Assuming that α is a constant function equal to α_1 , we have already seen that $\tilde{S}_m \stackrel{fdd}{=} d_{\alpha_1} X_{\alpha_1,h}$ where $X_{\alpha_1,h}$ is the linear multifractional α_1 -stable motion defined by (3.9) and d_{α_1} is given by (2.8). Using the previous theorem we will prove the following one.

Theorem 4.2 Let $\alpha_1 \in (0,2)$ and $h: \mathbb{R} \mapsto (0,1)$ be a continuous function. Let us also consider $X_{\alpha_1,h}$ the linear multifractional α_1 -stable motion defined by (3.9) and two real numbers a < b. If $H_1 := \min_{t \in [a,b]} h(t) > 1/\alpha_1$ and if h is $(H_1 - 1/\alpha_1)$ -Hölder continuous on [a,b], then there exists a continuous modification $X_{\alpha_1,h}^*$ of $X_{\alpha_1,h}$ such that almost surely

$$\sup_{\substack{t,t' \in [a,b] \\ t \neq t'}} \frac{\left| X_{\alpha_1,h}^*(t) - X_{\alpha_1,h}^*(t') \right|}{|t - t'|^{H_1 - 1/\alpha_1} \sqrt{|\log|t - t'|| + 1}} < +\infty.$$

Proof. Let $\alpha : \mathbb{R} \to (0,2)$ be the constant function equal to α_1 and let \tilde{S}_m be defined by (4.16). Since $\tilde{S}_m \stackrel{fdd}{=} d_{\alpha_1} X_{\alpha_1,h}$ with $d_{\alpha_1} \neq 0$ defined by (2.8), by Theorem 4.1, we already know that a.s.

$$\sup_{\substack{t,t' \in [a,b] \cap \mathcal{D} \\ t \neq t'}} \frac{|X_{\alpha_1,h}(t) - X_{\alpha_1,h}(t')|}{|t - t'|^{H_1 - 1/\alpha_1} \sqrt{|\log|t - t'|| + 1}} < +\infty,$$

where \mathcal{D} is the dense set of dyadic real numbers. Moreover, since h is continuous with values in (0,1), the stochastic continuity of the linear multifractional α_1 -stable motion $X_{\alpha_1,h}$ has been established in [19]. This implies that there exists a modification $X_{\alpha_1,h}^*$ of $X_{\alpha_1,h}$ such that

$$\sup_{\substack{t,t' \in [a,b]\\t \neq t'}} \frac{\left| X_{\alpha_1,h}^*(t) - X_{\alpha_1,h}^*(t') \right|}{|t - t'|^{H_1 - 1/\alpha_1} \sqrt{|\log|t - t'|| + 1}} < +\infty,$$

see e.g. Section D.2 of [5] for the construction of $X_{\alpha_1,h}^*$. Then, the proof is complete.

In [2], using a wavelet series expansion, under our assumptions of Proposition 3.9, the authors obtained a continuous modification $X_{\alpha_1,h}^*$ satisfying a.s. for all $\eta > 0$,

$$\sup_{\substack{t,t' \in [a,b]\\t \neq t'}} \frac{\left| X_{\alpha_1,h}^*(t) - X_{\alpha_1,h}^*(t') \right|}{\left| t - t' \right|^{H_1 - 1/\alpha_1} \left(\left| \log |t - t'| \right| + 1 \right)^{2/\alpha_1 + \eta}} < +\infty.$$

Since $1/2 < 2/\alpha_1$, our result is sharper. Moreover it is quasi-optimal since, for $\eta > 0$, one can find h such that a.s.

$$\sup_{\substack{t,t'\in[a,b]\\t\neq t'}} \frac{\left|X_{\alpha_{1},h}^{*}(t) - X_{\alpha_{1},h}^{*}(t')\right|}{|t - t'|^{H_{1} - 1/\alpha_{1}} \left(\left|\log|t - t'|\right| + 1\right)^{-\eta}} = +\infty,$$

by Theorem 6.1 of [2]. Let us also quote that following our method based on [5], one may obtain an upper bound for the global modulus of continuity of linear fractional stable sheets, which is sharper than the one given in [3].

A Proof of Proposition 3.2

Let us consider $K = [\alpha_1, \alpha_2] \times [H_1, H_2] \times [-A, A] \subset (1, 2) \times (1/2, 1) \times \mathbb{R}$ such that $1/\alpha_1 < H_1 \le H_2 < 1$. Let us note that it is enough to prove Proposition 3.2 for A large enough. Then, in this proof, we assume, without loss of generality that A > e (so that $\log \xi > 1$ for $\xi > A$).

For all $x = (\alpha, H, t) \in K$, we set

$$\beta(x) = H - 1/\alpha \in (0,1)$$

and remark that $\beta(x) \in [\beta_1, \beta_2] \subset (0, 1)$ with

$$\beta_1 = H_1 - 1/\alpha_1$$
 and $\beta_2 = H_2 - 1/\alpha_2$.

Moreover, for all $x = (\alpha, H, t) \in K$ and all $\xi \in \mathbb{R}$, let us note that

$$f_+(\alpha, H, t, \xi) = g(\beta(x), t, \xi)$$

with g defined on $(0,1) \times \mathbb{R} \times \mathbb{R}$ by

$$g(\beta, t, \xi) := (t - \xi)_+^{\beta} - (-\xi)_+^{\beta}.$$

Let us now consider $x = (\alpha, H, t) \in K$ and $x' = (\alpha', H', t') \in K$. Then, by (3.12),

$$V_{m,n}(x) - V_{m,n}(x') = \left(g(\beta(x), t, \xi_n) m(\xi_n)^{-1/\alpha} - g(\beta(x'), t', \xi_n) m(\xi_n)^{-1/\alpha'} \right).$$

Proposition 3.2 follows from the following lemma, which proof is given at the end of this section.

Lemma A.1 Let $0 < \beta_1 \le \beta_2 < 1$ and A > e.

1. There exists a finite positive constant $c_1(A, \beta_1, \beta_2)$ such that for all $\beta, \beta' \in [\beta_1, \beta_2]$, all $t, t' \in [-A, A]$ and all $\xi \in \mathbb{R}$,

$$|g(\beta, t, \xi) - g(\beta', t', \xi)| \le c_1(A, \beta_1, \beta_2) (|t - t'|^{\beta_1} + |\beta - \beta'|) h_{A,1}(\xi, \beta_2)$$

with

$$h_{A,1}(\xi,c) = \mathbf{1}_{|\xi| \le 2A} + |\xi|^{c-1} \log |\xi| \, \mathbf{1}_{|\xi| > 2A}.$$

2. Moreover, there exists a finite positive constant $c_2(A, \beta_1)$ such that for all $\beta \in [\beta_1, \beta_2]$ and $t \in [-A, A]$,

$$|g(\beta, t, \xi)| \le c_2(A, \beta_1) h_{A,2}(\xi, \beta_2)$$

with

$$h_{A,2}(\xi,c) = \mathbf{1}_{|\xi| \le 2A} + |\xi|^{c-1} \mathbf{1}_{|\xi| > 2A}.$$

Setting for almost every $\xi \in \mathbb{R}$

$$\begin{cases} F_1(x, x', \xi) &:= |g(\beta(x), t, \xi) - g(\beta(x'), t', \xi)| m(\xi)^{-1/\alpha}, \\ F_2(x, x', \xi) &:= |g(\beta(x'), t', \xi)| |m(\xi)^{-1/\alpha} - m(\xi)^{-1/\alpha'}|, \end{cases}$$

we then have

$$|V_{m,1}(x) - V_{m,1}(x')| \le F_1(x, x', \xi_1) + F_2(x, x', \xi_1).$$

Before we apply Lemma A.1 to bound F_1 and F_2 , let us remark that for all $\xi \in \mathbb{R}$,

$$h_{A,2}(\xi,\beta_2) \le h_{A,1}(\xi,\beta_2) \le c_3(A,\beta_2) \Big(\mathbf{1}_{|\xi| \le e} + |\xi|^{\beta_2 - 1} \log |\xi| \mathbf{1}_{|\xi| > e} \Big)$$
 (A.17)

with $c_3(A, \beta_2)$ a finite positive constant, which does not depend on ξ . Then, combining this remark with Lemma A.1, for almost every $\xi \in \mathbb{R}$,

$$F_1(x, x', \xi) \le c_1(A, \beta_1, \beta_2)c_3(A, \beta_2) \Big(|t - t'|^{\beta_1} + |\beta(x) - \beta(x')| \Big) h_{m,K}(\xi)$$

with $h_{m,K}$ defined by Equation (3.14). Since $\alpha_1 > 1$, by definition of the function β , it follows that for almost every $\xi \in \mathbb{R}$,

$$F_1(x, x', \xi) \le c_1(A, \beta_1, \beta_2)c_3(A, \beta_2)\tau(x - x')h_{m,K}(\xi),$$

with $\tau(x - x') = |t - t'|^{\beta_1} + |H - H'| + |\alpha - \alpha'|$.

Moreover, applying Assertion 2 of Lemma A.1, Equation (A.17) and the mean value theorem, for almost every $\xi \in \mathbb{R}$,

$$F_2(x, x', \xi) \le c_2(A, \beta_1)c_3(A, \beta_2) |\alpha - \alpha'| h_{m,K}(\xi).$$

In view of the previous computations, we have: almost surely,

$$|V_{m,1}(x) - V_{m,1}(x')| \le c_{3,1}(K)\tau(x-x')h_{m,K}(\xi_1)$$

with $c_{3,1}(K) := c_3(A, \beta_2)(c_1(A, \beta_1, \beta_2) + c_2(A, \beta_1))$. This concludes the proof of Proposition 3.2.

We conclude this section by the proof of Lemma A.1.

Proof. [Proof of Lemma A.1] Let $0 < \beta_1 < \beta_2 < 1$ and A > e. Let $\beta, \beta' \in [\beta_1, \beta_2] \subset (0, 1)$ and $t, t' \in [-A, A]$. Let us write for all $\xi \in \mathbb{R}$,

$$|g(\beta, t, \xi) - g(\beta', t', \xi)| \le g_1(\beta', t, t', \xi) + g_2(\beta, \beta', t, \xi)$$

with

$$\begin{cases} g_1(\beta', t, t', \xi) &:= |g(\beta', t', \xi) - g(\beta', t, \xi)| \\ g_2(\beta, \beta', t, \xi) &:= |g(\beta', t, \xi) - g(\beta, t, \xi)|. \end{cases}$$

Step 1: Control of g_1 . Let us note that if t = t', $g_1(\beta', t, t', \xi) = 0$ for all $\xi \in \mathbb{R}$. Then, in this step, we assume now, without loss of generality that t < t'. This implies that

$$g_1(\beta', t, t', \xi) = \begin{cases} 0 & \text{if } \xi \ge t' \\ (t' - \xi)^{\beta'} & \text{if } t \le \xi < t' \\ \left| (t - \xi)^{\beta'} - (t' - \xi)^{\beta'} \right| & \text{if } \xi < t. \end{cases}$$

Let $\xi \in \mathbb{R}$ with $|\xi| > 2A$. If $\xi < 0$ it follows that $\xi < t < t'$. Since $\beta' > 0$, applying the mean value theorem,

$$g_1(\beta', t, t', \xi) \le \beta' |t - t'| |c_{\xi, t, t'} - \xi|^{\beta' - 1}$$

with $c_{\xi,t,t'} \in (t,t') \subset [-A,A]$. Moreover, since $|\xi| > 2A$

$$\left|c_{\xi,t,t'} - \xi\right| \ge |\xi| - \left|c_{\xi,t,t'}\right| \ge |\xi| - A \ge |\xi|/2$$

and then

$$g_1(\beta', t, t', \xi) \le 2^{1-\beta'} |t - t'| |\xi|^{\beta'-1}$$

since $\beta' \in (0,1)$. Therefore, for $|\xi| > 2A$,

$$g_1(\beta', t, t', \xi) \le 4A|t - t'|^{\beta_1} |\xi|^{\beta_2 - 1}$$
 (A.18)

since $|t - t'| \le 2A$, $\beta' \in [\beta_1, \beta_2] \subset (0, 1)$ and 2A > 1.

Now let $\xi \in \mathbb{R}$ with $|\xi| \leq 2A$. Since $0 < \beta' < 1$, we have

$$\left|a^{\beta'} - b^{\beta'}\right| \le \left|a - b\right|^{\beta'}$$

for all $a, b \ge 0$. By definition of g, it follows that

$$g_1(\beta', t, t', \xi) \le \left| (t' - \xi)_+ - (t - \xi)_+ \right|^{\beta'} \le \left| t' - t \right|^{\beta'} \le 2A \left| t' - t \right|^{\beta_1}$$

since $-A \le t < t' \le A$, $0 < \beta_1 \le \beta' < 1$ and A > 1. From this last inequality and Equation (A.18), we deduce that for all $\xi \in \mathbb{R}$,

$$g_1(\beta', t, t', \xi) \le 4A|t - t'|^{\beta_1} h_{A,2}(\xi, \beta_2)$$
 (A.19)

with $h_{A,2}(\xi, \beta_2) = \mathbf{1}_{|\xi| \le 2A} + |\xi|^{\beta_2 - 1} \mathbf{1}_{|\xi| > 2A}$.

Step 2: Control of g_2 . Let us recall that for all $\xi \in \mathbb{R}$,

$$g_2(\beta, \beta', t, \xi) = \left| (t - \xi)_+^{\beta'} - (t - \xi)_+^{\beta} + (-\xi)_+^{\beta} - (-\xi)_+^{\beta'} \right|.$$

Then, applying the mean value theorem, for all $\xi \in \mathbb{R}$,

$$g_2(\beta, \beta', t, \xi) \le |\beta - \beta'| \sup_{\beta_1 \le c \le \beta_2} |(t - \xi)_+^c \log(t - \xi)_+ - (-\xi)_+^c \log(-\xi)_+|$$

where for c > 0,

$$(x)_{+}^{c} \log(x)_{+} = \begin{cases} x^{c} \log x & \text{if } x > 0 \\ 0 & \text{if } x \le 0 \end{cases}$$

Let us first consider $\xi \in [-2A, 2A]$. Then, $(-\xi)_+ \in [0, 2A]$ and $(t - \xi)_+ \in [0, 3A]$ since $t \in [-A, A]$. Therefore,

$$g_2(\beta, \beta', t, \xi) \le \tilde{c}_1(A, \beta_1, \beta_2) |\beta - \beta'| \tag{A.20}$$

with

$$\tilde{c}_1(A, \beta_1, \beta_2) = 2 \max_{\beta_1 \le c \le \beta_2} \max_{0 < u \le 3A} u^c |\log u| = 2 \max \left(\frac{1}{\mathrm{e}\beta_1}, (3A)^{\beta_2} \log(3A) \right) < +\infty.$$

Let us now assume that $\xi < -2A$. Then, $\xi < t$ and

$$g_2(\beta, \beta', t, \xi) \le |\beta - \beta'| \sup_{\beta_1 \le c \le \beta_2} |(t - \xi)^c \log(t - \xi) - (-\xi)^c \log(-\xi)|$$

with $t - \xi > 0$ and $-\xi > 0$. Let us remark that $-\xi \in (-\xi/2, -3\xi/2)$ since $-\xi > 0$ and that

$$-\xi/2<-A-\xi\leq t-\xi\leq A-\xi<-3\xi/2$$

since $t \in [-A, A]$ and $\xi < -2A$. Then, for each $c \in [\beta_1, \beta_2] \subset (0, 1)$, by the mean value theorem,

$$|(t-\xi)^c \log(t-\xi) - (-\xi)^c \log(-\xi)| \le |u_{t,\xi,c}|^{c-1} (c|\log u_{t,\xi,c}|+1)$$

with $u_{t,\xi,c} \in (-\xi/2, -3\xi/2)$. Since $u_{t,\xi,c} \in (-\xi/2, -3\xi/2)$ and $-\xi/2 > A > e$, we get

$$|(t-\xi)^c \log(t-\xi) - (-\xi)^c \log(-\xi)| \le 4|\xi|^{\beta_2-1} \log|\xi|$$

for all $c \in [\beta_1, \beta_2] \subset (0, 1)$. Hence, for $\xi < -2A$,

$$g_2(\beta, \beta', t, \xi) \le 4|\beta - \beta'||\xi|^{\beta_2 - 1} \log |\xi|.$$

Note that this last inequality still holds for $\xi > 2A$ since in this case, $g_2(\beta, \beta', t, \xi) = 0$.

Then, we have proved that for all $\xi \in \mathbb{R}$,

$$g_2(\beta, \beta', t, \xi) \le \tilde{c}_2(A, \beta_1, \beta_2) |\beta - \beta'| h_{A,1}(\xi, \beta_2)$$
 (A.21)

with $\tilde{c}_2(A, \beta_1, \beta_2) = \max(\tilde{c}_1(A, \beta_1, \beta_2), 4)$ and

$$h_{A,1}(\xi,\beta_2) = \mathbf{1}_{|\xi| \le 2A} + |\xi|^{\beta_2 - 1} \log |\xi| \mathbf{1}_{|\xi| > 2A}.$$

Step 3: Proof of Assertion 1. It follows from Equations (A.19) and (A.21) choosing $c_1(A, \beta_1, \beta_2) = \tilde{c}_2(A, \beta_1, \beta_2) + 4A \in (0, +\infty)$ and using the fact that $h_{A,2}(\xi, \beta_2) \leq h_{A,1}(\xi, \beta_2)$ since A > e.

Step 4: Proof of Assertion 2. Let us remark that

$$g(\beta', t', \xi) = g(\beta', t', \xi) - g(\beta', 0, \xi)$$

since $g(\beta', 0, \xi) = (-\xi)_+^{\beta'} - (-\xi)_+^{\beta'} = 0$. Hence, applying Equation (A.19) with t = 0 and $\beta' = \beta$,

$$|g(\beta', t', \xi)| \le 4A|t'|^{\beta_1} h_{A,2}(\xi, \beta_2) \le 4A^{\beta_1+1} h_{A,2}(\xi, \beta_2),$$

which concludes the proof.

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